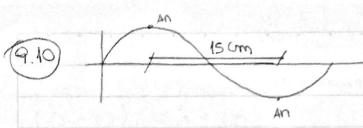
y=34 M=KN 1 y= + 1 = 24 andos mecanicas Y(x,t) = Asen27 (x/x-t/t), Y(x,t) = Asen(xx-wt) (9,4) Y(x,t) = 2.153 sen (2x-628.t) $A = 2.10^3 \text{ m}$, $f = \frac{\omega}{2\pi} = \frac{628}{2\pi} = 100 \text{ Hz}$, $V = \frac{\omega}{K} = \frac{628}{2} = 314 \text{ m/s}$ (9.6) Y(X,t)=0,06 sem (211 x +411 t) $A = 0.06 \,\text{m}$; $\lambda = 2\pi = 2\pi_{\text{m}} = 1 \,\text{m}$; $V = \omega = 4\pi = 2 \,\text{m/s}$ » De propogo hour la esqueida (27x+47t) Y(x,t) = 24 (x,t) = 0,06000(211X+411t). 411 Para que sea el molor máximo, el cos () delse ser máximo tombreis y eso se lopa al considerar ser módulo (cos())-1 19(x,t) = 0,06.00 (20x+4nt).411 = 0,06.41 = 0,75m/s 4(x,t) = 2Asen(kx) cos (wt) (99) 4(x1t)=2.0,0025. Sen (0,759x)(0)(942t) (enelst) a) Posición de la modo Xnodo = n. II = n. 1 b) Posición de las antinadas Xaminado = (2n+1) / = (n+1/2) / 2 ×nodo = n. 1,33 n=0,1,2,... X411nodo = (2n+1).0,66 n=0,1,2,...



a)
$$\times \text{nod}_{0} = n \cdot \frac{\lambda}{2} \times n^{2} - \times n^{2} = (n+1) \frac{\lambda}{2} - n \cdot \frac{\lambda}{2} = \frac{\lambda}{2} \text{ els}^{2}$$

$$x_0^2 - x_0^4 = \frac{\lambda}{2} = 0.15 \text{ m}$$

b)
$$\lambda = 0.3m$$
, $A = 2A = 0.85cm \Rightarrow A = 9.425cm$

$$V = \frac{X}{M} = \frac{1}{2M} + \frac{X}{M} = \frac{1}{2M} = \frac{1}{2M$$

c)
$$\psi(x,t) = 2A \text{ Sem}(kx) \cos(\omega t)$$

 $\psi(x,t) = -2A \text{ Sem}(kx) \text{ sem}(\omega t) \cdot \omega$

$$|\dot{\psi}(x,t)| = |2A\omega| = |2.0,0085 \text{ m}.2 \text{ T}.$$
 $|= 0,71 \text{ m/s} + \text{Vmx}.$ $|= 0,71 \text{ m/s}.$

d)
$$|X_{nodo} - X_{4mi \, nodo}| = |n \frac{\lambda}{2} - (n + 1/2) \frac{\lambda}{2}| = \frac{\lambda}{4} = 0,075 \, \text{m}$$

$$\begin{array}{c|c} 0 & 512 = 2 = \boxed{4T_1} = 2 & T_1 \\ \hline 2 & 250 & T_2 & T_2 \end{array}$$

(2)
$$256 = D$$
 | t_2 | $= D$ | t_2 | $2L \sqrt{\frac{1}{2}}$ | $4\rho_{\text{Hd}}$ | $4\rho_{\text{$

HOUR NO

b)
$$f = \frac{n}{2L} f / M = 14000 Hz = 34.$$

a)
$$f_0 = \frac{\sigma}{2L} \rightarrow \sigma = 2Lf_0 = 96m/s$$

Acustica