

# CECS 229 Programming Assignment #7

## Due Date:

Sunday, 12/10 @ 11:59 PM

## Instructions:

1. In `helpers.py`, copy-paste implementation for the following functions from your `pa6.py`:
  - `gram_schmidt()`
  - `_ref()`
  - `rank()`
2. In `structures.py`, copy-paste the implementation of the missing `Matrix` methods from `pa5.py`.
3. Complete the programming problems in the file named `pa7.py`. You may test your implementation on your Repl.it workspace by running `main.py`.
4. When you are satisfied with your implementation,
  - Submit your Repl.it workspace
  - Download the file `pa7.py` and submit it to the appropriate CodePost auto-grader folder.

## Objectives:

1. Apply the QR-factorization of a matrix  $A$  to solve the system of equations  $A\vec{x} = \vec{b}$ .
2. Create a function that computes the determinant of an  $n \times n$  `Matrix` object.
3. Use the Python built-in function `numpy.linalg.eig()` to find the eigenvalues and eigenvectors of a matrix.
4. Create a function that computes the singular value decomposition of a `Matrix` object.

## Notes:

Unless otherwise stated in the FIXME comment, you may not change the outline of the algorithm provided and you may not use any built-in functions that perform the entire algorithm or replaces a part of the algorithm, unless otherwise stated.

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## Problem 1:

### Background:

In this problem, you will implement a solver for the system of linear equations  $A\vec{x} = \vec{b}$  where

- $A$  is an  $n \times n$  matrix whose columns are linearly independent

- $\vec{x} \in \mathbb{R}^n$
- $\vec{b} \in \mathbb{R}^n$

To implement the solver, you must apply the following theorem:

### THM | QR-Factorization

If  $A \in \mathbb{R}^{m \times n}$  matrix with linearly independent columns  $\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n$ , then there exists,

1. an  $m \times n$  matrix  $Q$  whose columns  $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$  are orthonormal, and
2. an  $n \times n$  matrix  $R$  that is upper triangular and whose entries are defined by,

$$r_{ij} = \begin{cases} \langle \vec{u}_i, \vec{a}_j \rangle & \text{for } i \leq j \\ 0 & \text{for } i > j \end{cases}$$

such that  $A = QR$ . This referred to as the QR factorization (or decomposition) of matrix  $A$ .

To find matrices  $Q$  and  $R$  from the QR Factorization Theorem, we apply Gram-Schmidt process to the columns of  $A$ . Then,

- the columns of  $Q$  will be the orthonormal vectors  $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_n$  returned by the Gram Schimdt process, and
- the entries  $r_{ij}$  of  $R$  will be computed using each column  $\vec{u}_i$  as defined in the theorem.

### Your Task:

Assuming  $A \in \mathbb{R}^{n \times n}$  is a `Matrix` object, and  $\vec{b} \in \mathbb{R}^n$  is a `Vec` object, finish the implementation of the function `qr_solve(A, b)` which uses the QR-factorization of  $A$  to compute and return the solution to the system  $A\vec{x} = \vec{b}$ .

- INPUT:
  - `A` : `Matrix` object
  - `b` : `Vec` object
- OUTPUT:
  - `Vec` object representing the solution to the system  $A\vec{x} = \vec{b}$ .

### HINT:

If  $A = QR$ , then  $A\vec{x} = \vec{b}$  becomes  $QR\vec{x} = \vec{b}$ . What happens if we multiply both sides of the equation by the transpose of  $Q$ ? i.e., What does  $Q^tQR\vec{x} = Q^t\vec{b}$  simplify to?

```
In [ ]: def qr_solve(A : Matrix, b: Vec):
    """
    Solves the system of equations Ax = b by using the
    QR factorization of Matrix A
    :param A: Matrix of coefficients of the system
    :param b: Vec of constants
    :return: Vec solution to the system
```

```

"""
# Constructing U
# U should be the set of orthonormal vectors returned
# by applying Gram-Schmidt Process to the columns of A
U = None # FIXME: Replace with the appropriate line
n = len(U)

# Constructing Q
# Q should be the matrix whose columns are the elements
# of the vector in set U
Q = Matrix([[None for j in range(n)] for i in range(n)])
for j in range(n):
    pass # FIXME: Replace with the appropriate line

# Constructing R
R = Matrix([[0 for j in range(n)] for i in range(n)])
for j in range(n):
    for i in range(n):
        if i <= j:
            pass # FIXME: Replace with the appropriate line

# Constructing the solution vector x
b_star = Q.transpose() * b
x = [None for i in range(n)]
# FIXME: find the components of the solution vector
#         and replace them into elements of x
return Vec(x)

```

## Problem 2:

Implement the helper function `_submatrix(A, i, j)` which creates and returns the sub-matrix that results from omitting row  $i$ -th row and  $j$  column of `A`.

- INPUT:
  - `A`: `Matrix` object representing an  $m \times n$  matrix
  - `i`: int index of a row of `A` satisfying  $1 \leq i \leq m$
  - `j`: int index of a column of `A` satisfying  $1 \leq j \leq n$
- OUTPUT:
  - `Matrix` object of the sub-matrix

```

In [ ]: def _submatrix(A : Matrix, i : int, j : int):
        """
        constructs the sub-matrix of an mxn Matrix A that
        results from omitting the i-th row and j-th column;
        i and j satisfy that 0 <= i <= m, and 0 <= j <= n
        :param A: Matrix object
        :param i: int index of row to omit
        :param j: int index of column to omit
        :return: Matrix object representing the sub-matrix
        """
        m, n = A.dim()
        pass # FIXME: Implement this function

```

**Problem 3:**

Finish the implementation of the function `determinant(A)` which computes the determinant of  $n \times n$  matrix `A`.

- INPUT:
  - `A: Matrix` object
- OUTPUT:
  - the determinant as a `float` value

```
In [ ]: def determinant(A: Matrix):
        """
        computes the determinant of square Matrix A;
        Raises ValueError if A is not a square matrix.
        :param A: Matrix object
        :return: float value of determinant
        """
        m, n = A.dim()
        if m != n:
            raise ValueError(f"Determinant is not defined for Matrix with dimension {m}x{n}")
        if n == 1:
            return None # FIXME: Return the correct value
        elif n == 2:
            return None # FIXME: Return the correct value
        else:
            d = 0
            # FIXME: Update d so that it holds the determinant
            #           of the matrix. HINT: You should apply a
            #           recursive call to determinant()
            return d
```

**Problem 4:**

Implement the function `eigen_wrapper(A)` which uses Python built-in function `numpy.linalg.eig()` to create a dictionary with eigenvalues of `Matrix A` as keys, and their corresponding list of eigenvectors as values.

- INPUT:
  - `A: Matrix` object
- OUTPUT:
  - Python dictionary

```
In [ ]: def eigen_wrapper(A: Matrix):
        """
        uses numpy.linalg.eig() to create a dictionary with
        eigenvalues of Matrix A as keys, and their corresponding
        list of eigenvectors as values.
        :param A: Matrix object
        :return: Python dictionary
```

```
"""
pass # FIXME: Implement this function
```

### Problem 5:

Finish the implementation of function `svd(A)` so that it returns the singular value decomposition of  $A$ . Recall that the singular value decomposition of a matrix  $A \in \mathbb{R}_{m \times n}$  consists of matrices,

- $\Sigma \in \mathbb{R}_{m \times n}$ : a diagonal matrix whose main diagonal hold the singular values of  $A^T A$  in decreasing order,

$$\begin{bmatrix} \sigma_1 & 0 & 0 & \cdots & 0 \\ 0 & \sigma_2 & 0 & \cdots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & \sigma_r & 0 \\ 0 & \cdots & \cdots & \cdots & 0 \end{bmatrix}$$

i.e.,  $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r$  where  $r = \text{number of eigenvalues of } A^T A$

- $V \in \mathbb{R}_{n \times n}$ : the matrix whose columns are the eigenvectors of  $A^T A$ . The order of the columns corresponds to the order of the singular values, i.e. the first column is the eigenvector corresponding to the largest singular value  $\sigma_1$ , the second column is the eigenvector corresponding to  $\sigma_2$ , etc.
- $U \in \mathbb{R}_{m \times m}$ : the matrix whose columns are given by  $\vec{u}_j = \frac{1}{\sigma_j} A \vec{v}_j$

#### • INPUT:

- `A`: Matrix object

#### • OUTPUT:

- tuple with Matrix objects `(U, Sigma, V)`

```
In [ ]: def svd(A: Matrix):
        """
        computes the singular value decomposition of Matrix A;
        returns Matrix objects U, Sigma, and V such that
            1. V is the Matrix whose columns are eigenvectors of A.transpose() * A
            2. Sigma is a diagonal Matrix of singular values of A.transpose() * A
               appearing in descending order along the main diagonal
            3. U is the Matrix whose j-th column u_j satisfies A * v_j = sigma_j * u_j
               where sigma_j is the j-th singular value in decreasing order and v_j is
               the j-th column vector of V
            4. A = U * Sigma * V.transpose()
        :param A: Matrix object
        :return: tuple with Matrix objects; (U, Sigma, V)
        """
        m, n = A.dim()
```

```

aTa = A.transpose() * A
eigen = eigen_wrapper(aTa)

# Constructing V
# V should be the mxm matrix whose columns
# are the eigenvectors of matrix A.transpose() * A
eigenvectors = list(eigen.values())
V = Matrix([[None for j in range(n)] for i in range(n)])
for j in range(1, n + 1):
    pass # FIXME: Replace this with the line that will
          # correctly build the entries of V

# Constructing Sigma
# Sigma should be the mxn matrix of singular values.
singular_values = None # FIXME: Replace this so that singular_values
                        # holds a list of singular values of A
                        # in decreasing order
Sigma = Matrix([[0 for j in range(n)] for i in range(m)])
for i in range(1, m + 1):
    pass # FIXME: Replace this with the line that will correctly
          # build the entries of Sigma

# Constructing U
# U should be the matrix whose j-th column is given by
# A * vj / sj where vj is the j-th eigenvector of A.transpose() * A
# and sj is the corresponding j-th singular value
U = Matrix([[None for j in range(m)] for i in range(m)])
for j in range(1, m + 1):
    pass # FIXME: Replace this with the line that will
          # correctly build the entries of U
return (U, Sigma, V)

```