

Computability and Complexity  
COSC 4200

NP-Complete Problems

# Polynomial-Time Reductions

## Definition

We say that  $A$  is *polynomial-time mapping reducible* to  $B$ , and write  $A \leq_P B$ , if there is a polynomial-time computable function  $f : \Sigma^* \rightarrow \Sigma^*$  such that for all  $w \in \Sigma^*$ ,

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Two implications:

$$\begin{aligned} w \in A &\Rightarrow f(w) \in B \\ f(w) \in B &\Rightarrow w \in A \end{aligned}$$

Or equivalently:

$$\begin{aligned} w \in A &\Rightarrow f(w) \in B \\ w \notin A &\Rightarrow f(w) \notin B \end{aligned}$$

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**Proof.** ③  $\Rightarrow$  ② and ②  $\Rightarrow$  ① are trivial.

To see ①  $\Rightarrow$  ③, assume ① is true and let  $B$  be an NP-complete problem with  $B \in P$ .

- Let  $A \in NP$  be arbitrary.
- Then  $A \leq_P B$  because  $B$  is NP-complete.
- Because  $B \in P$ , we have  $A \in P$  as well.

Therefore  $P = NP$ .



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- 2 Every NP-complete problem is in P.
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## Corollary

*The following are equivalent:*

- 1 Some NP-complete problem is not in P.
- 2 Every NP-complete problem is not in P.
- 3  $P \neq NP$ .

# Satisfiability

A *propositional formula* is a sentence made from variables, operators  $\wedge$ ,  $\vee$ , and  $\neg$ , and parentheses. An example is

$$\phi = (x_1 \vee (x_2 \wedge x_3)) \wedge \neg(x_3 \wedge x_4).$$

A *3CNF formula* is a propositional formula consisting of the conjunction of a number of disjunctive clauses with at most 3 literals. An example of this is

$$\phi = (x_1 \vee x_2 \vee \neg x_3) \wedge (x_2 \vee x_5) \wedge (\neg x_1 \vee x_4 \vee x_5)$$

# Satisfiability

An *assignment* for a formula  $\phi$  is a true/false setting of  $\phi$ 's variables.

An assignment *satisfies*  $\phi$  if it makes  $\phi$  evaluate to true in the standard way.

A formula  $\phi$  is *satisfiable* if it has a satisfying assignment.

We define two satisfiability decision problems:

$$\text{SAT} = \{\phi \mid \phi \text{ is a satisfiable formula}\}$$

$$3\text{SAT} = \{\phi \mid \phi \text{ is a satisfiable 3CNF formula}\}$$

Cook-Levin Theorem (1971, 1973)

3SAT is NP-complete.

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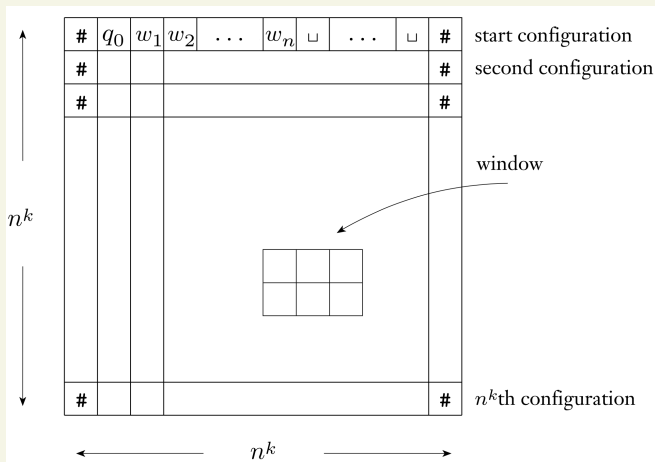
- There is a polynomial-time nondeterministic Turing machine for  $A$ .
- The reduction from  $A$  to 3SAT expresses the computation of the nondeterministic Turing machine as a formula.
- We will first show  $A \leq_P \text{SAT}$  and then we'll modify our proof to get  $A \leq_P \text{3SAT}$ .

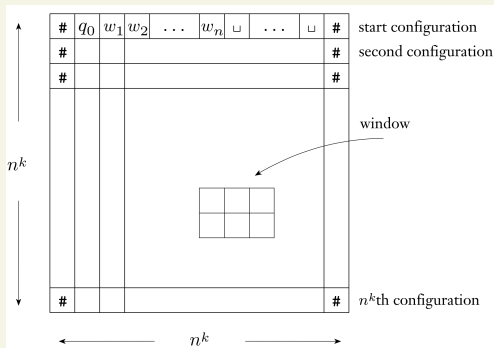


**Proof.** Let  $A \in \text{NP}$ . There is a nondeterministic TM that decides  $A$  in  $n^k$  time for some constant  $k$ .

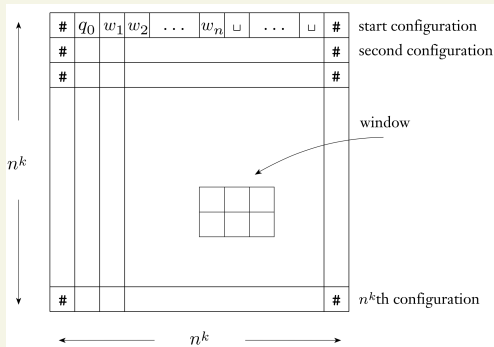
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A *tableau* for  $N$  on  $w$  is an  $n^k \times n^k$  table whose rows are the configurations of a branch of the computation of  $N$  on input  $w$ .

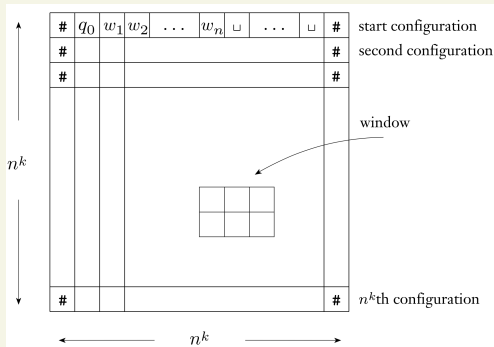




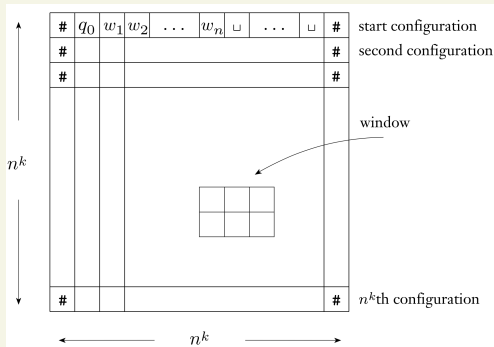
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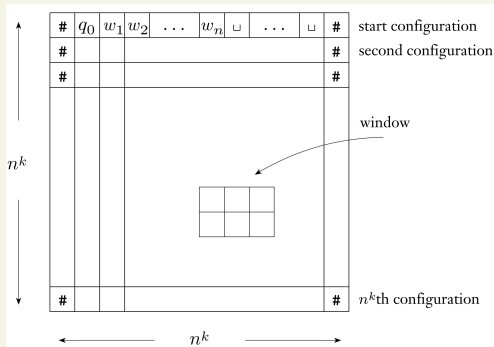
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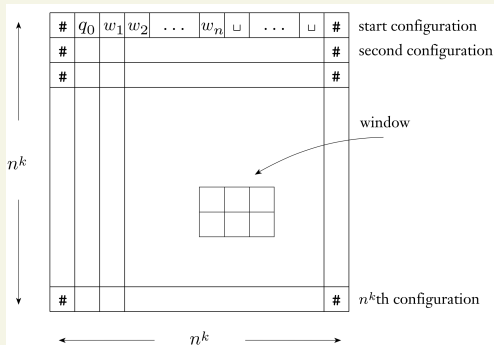
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- A tableau is *accepting* if any row is an accepting configuration.



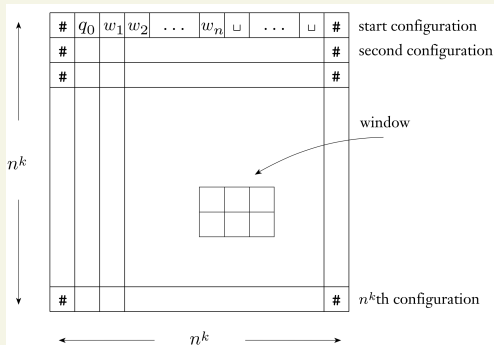
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- A tableau is *accepting* if any row is an accepting configuration.
- Every accepting computation path of  $N$  corresponds to an accepting tableau.



Our reduction  $f$  will take an input  $w$  and produce a formula  $\phi$ .

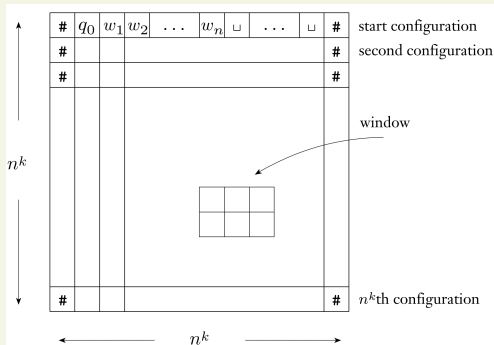
- Let  $C = Q \cup \Gamma \cup \{\#\}$ , where  $Q$  is the set of states and  $\Gamma$  is the tape alphabet.





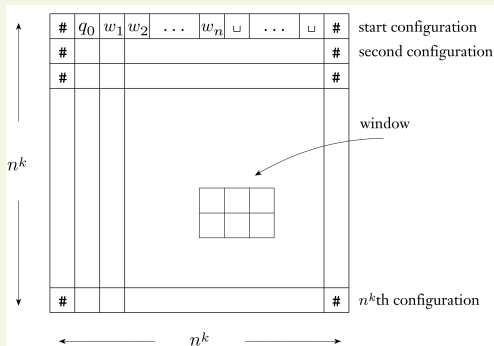
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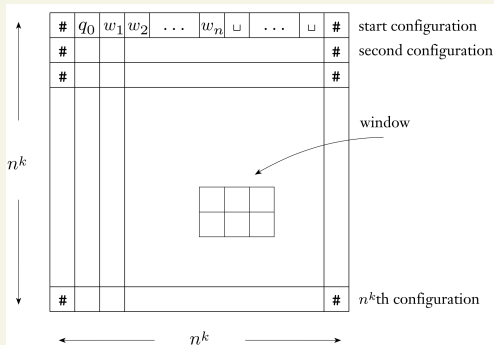
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- Each of the  $(n^k)^2$  entries of a tableau is called a *cell*.



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- Each of the  $(n^k)^2$  entries of a tableau is called a *cell*.
- $cell[i, j]$  is the cell in row  $i$  and column  $j$ .
- If  $x_{i,j,s} = 1$ , it means  $cell[i, j]$  contains an  $s$ .

Our formula  $\phi$  will be the conjunction of four parts:

$$\phi = \phi_{\text{cell}} \wedge \phi_{\text{start}} \wedge \phi_{\text{move}} \wedge \phi_{\text{accept}}$$

We will define these four parts separately.

Recall the variable  $x_{i,j,s}$  corresponds to placing an  $s$  in  $\text{cell}[i,j]$ .

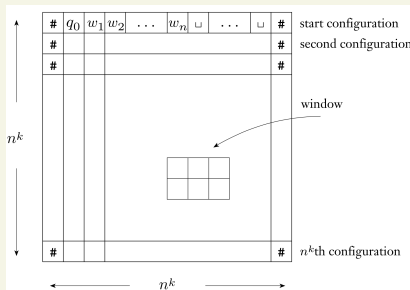
The formula  $\phi_{\text{cell}}$  ensures that exactly one variable is turned on for each cell.

$$\phi_{\text{cell}} = \bigwedge_{1 \leq i,j \leq n^k} \left[ \left( \bigvee_{s \in C} x_{i,j,s} \right) \wedge \left( \bigwedge_{\substack{s,t \in C \\ s \neq t}} (\overline{x_{i,j,s}} \vee \overline{x_{i,j,t}}) \right) \right]$$

The first part ensures that some variable is turned on. The second part ensures that only one variable is turned on.

Note that  $\phi_{\text{cell}}$  has size  $O(n^{2k})$  and may be computed in time  $O(n^{2k})$ .

$\phi_{\text{start}}$

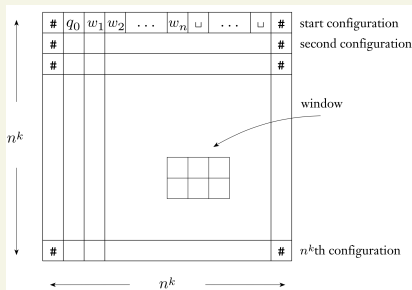


The formula  $\phi_{\text{start}}$  ensures the first row of the tableau is the start configuration of  $N$  on  $w$ .

$$\begin{aligned} \phi_{\text{start}} = & x_{1,1,\#} \wedge x_{1,2,q_0} \wedge \\ & x_{1,3,w_1} \wedge x_{1,4,w_2} \wedge \cdots \wedge x_{1,n+2,w_n} \wedge \\ & x_{1,n+3,\sqcup} \wedge \cdots \wedge x_{1,n^k-1,\sqcup} \wedge x_{1,n^k,\#} \end{aligned}$$

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$\phi_{\text{accept}}$

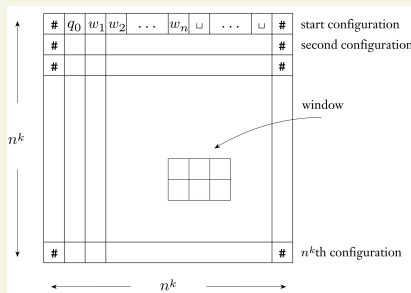


The formula  $\phi_{\text{accept}}$  ensures that an accepting computation appears in the tableau. The accept state  $q_{\text{accept}}$  must appear in the tableau.

$$\phi_{\text{accept}} = \bigvee_{1 \leq i, j \leq n^k} x_{i,j,q_{\text{accept}}}$$

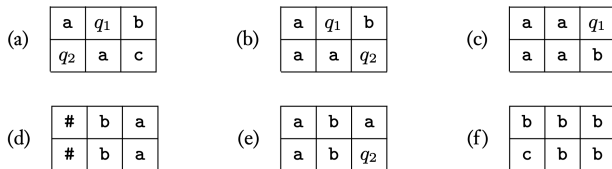
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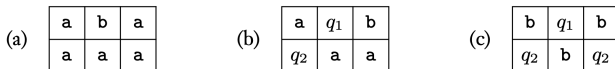


The formula  $\phi_{\text{move}}$  ensures that each row of tableau is a configuration that follows the configuration in the previous row by one move of  $N$ 's transition function. The formula ensures that each  $2 \times 3$  window of cells is legal.

Suppose  $\delta(q_1, a) = \{(q_1, b, R)\}$  and  $\delta(q_1, b) = \{(q_2, c, L), (q_2, a, R)\}$ .



**FIGURE 7.39**  
Examples of legal windows



**FIGURE 7.40**  
Examples of illegal windows

The  $(i, j)$ -window has  $cell[i, j]$  in the upper central position. Let the six cells of the window be  $a_1, \dots, a_6$ . Then we define

$$\psi_{i,j} = \bigvee_{\substack{a_1, \dots, a_6 \\ \text{is a legal window}}} \left( \begin{array}{c} x_{i,j-1,a_1} \wedge x_{i,j,a_2} \wedge x_{i,j+1,a_3} \wedge \\ x_{i+1,j-1,a_1} \wedge x_{i+1,j,a_2} \wedge x_{i+1,j+1,a_3} \end{array} \right)$$

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Finally, we define

$$\phi_{\text{move}} = \bigwedge_{\substack{1 \leq i \leq n^k \\ 1 \leq j \leq n^k}} \psi_{i,j}.$$

Note that  $\phi_{\text{move}}$  has size  $O(n^{2k})$  and may be computed in time  $O(n^{2k})$ .

Our reduction  $f$  outputs the formula

$$\phi = \phi_{\text{cell}} \wedge \phi_{\text{start}} \wedge \phi_{\text{move}} \wedge \phi_{\text{accept}}.$$

Each of the four parts of  $\phi$  is computable in  $O(n^{2k})$  time, so  $\phi$  is computable in  $O(n^{2k})$  time. Thus  $f$  is polynomial-time computable.

We have

$$\begin{aligned}w \in A &\iff N \text{ accepts } w \\&\iff \text{there is an accepting computation history of } N \text{ on } w \\&\iff \text{there is an accepting tableau for } N \text{ on } w \\&\iff \phi \text{ is satisfiable.}\end{aligned}$$

Therefore  $A \leq_m \text{SAT}$  via  $f$ .

We now modify the reduction to get  $A \leq_m 3\text{SAT}$ . In

$$\phi = \phi_{\text{cell}} \wedge \phi_{\text{start}} \wedge \phi_{\text{move}} \wedge \phi_{\text{accept}},$$

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To get 3CNF formulas we use additional variables to split each clause with more than 3 literals into multiple clauses that have 3 literals. For example, the clause  $(a_1 \vee a_2 \vee a_3 \vee a_4)$  is replaced by  $(a_1 \vee a_2 \vee z) \wedge (\bar{z} \vee a_3 \vee a_4)$ , where  $z$  is a new variable.



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More generally, a clause

$$(a_1 \vee a_2 \vee \dots \vee a_l)$$

with  $l$  literals is replaced by  $l - 2$  clauses:

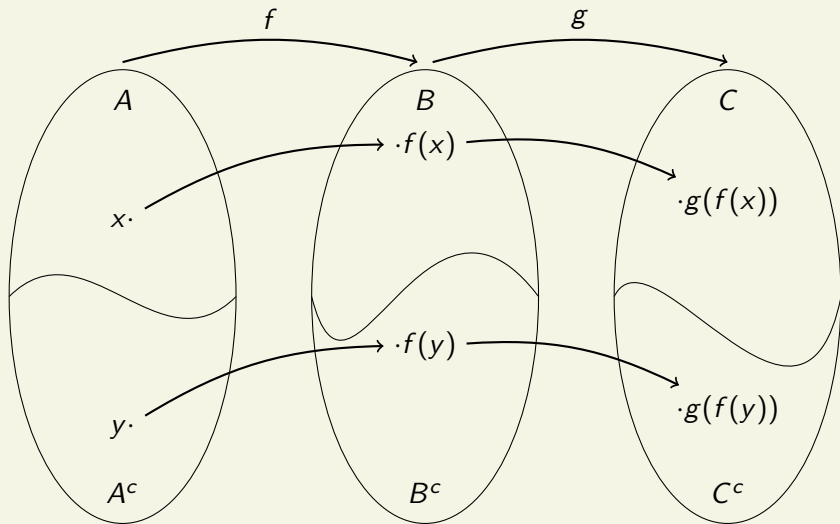
$$(a_1 \vee a_2 \vee z_1) \wedge (\bar{z}_1 \vee a_3 \vee z_2) \wedge (\bar{z}_2 \vee a_4 \vee z_3) \wedge \dots \wedge (\bar{z}_{l-3} \vee a_{l-1} \vee a_l)$$

where the  $z_i$ 's are new variables.  $\square$

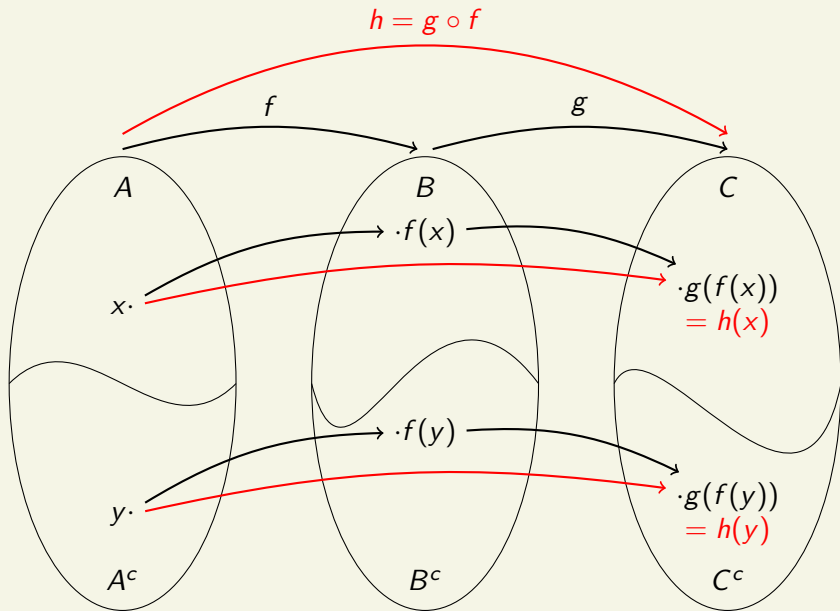
We have shown that 3SAT is NP-complete. We can use the following lemma to build on this to show more problems are NP-complete.

#### Lemma

$\leq_P$  is transitive. That is, if  $A \leq_P B$  and  $B \leq_P C$ , then  $A \leq_P C$ .



$$A \leq_P B \text{ via } f \text{ and } B \leq_P C \text{ via } g \Rightarrow A \leq_P C \text{ via } h = g \circ f$$



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**Proof.** Let  $f$  be the reduction from  $A$  to  $B$  and let  $g$  be the reduction from  $B$  to  $C$ . Then

- $I \in A \Leftrightarrow f(I) \in B$  for all instances  $I$ ,
- $J \in B \Leftrightarrow g(J) \in C$  for all instances  $J$ ,
- $f$  is computable in some polynomial  $p(n)$  time, and
- $g$  is computable in some polynomial  $q(n)$  time.

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Let  $n = |I|$ . To compute  $h(I)$  we need at most

- $p(n)$  time to compute  $f(I)$ .
- $q(p(n))$  time to compute  $g(f(I))$  because  $|f(I)| \leq p(n)$ .

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Therefore  $A \leq_P C$  via  $h$ .  $\square$

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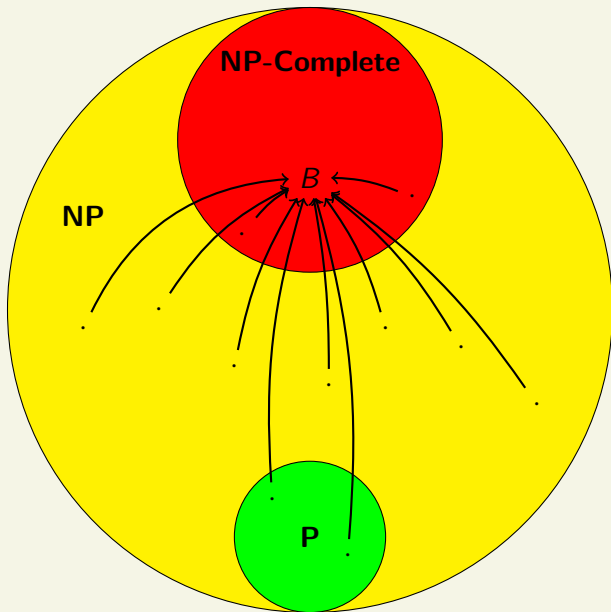
**Proof.** Because  $B$  is NP-complete,  $A \leq_P B$  for every  $A \in \text{NP}$ . By transitivity and  $B \leq_P C$ , we have  $A \leq_P C$  for every  $A \in \text{NP}$ .  $\square$

## Corollary

*Let  $B, C \in \text{NP}$ . If  $B$  is NP-complete and  $B \leq_P C$ , then  $C$  is also NP-complete.*

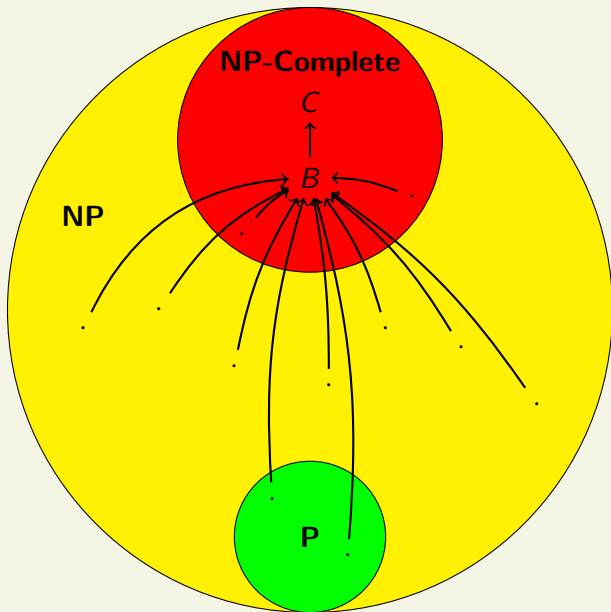
**Proof.** Because  $B$  is NP-complete,  $A \leq_P B$  for every  $A \in \text{NP}$ . By transitivity and  $B \leq_P C$ , we have  $A \leq_P C$  for every  $A \in \text{NP}$ .  $\square$

To prove that a problem  $B \in \text{NP}$  is NP-complete, we don't have to reduce every problem in NP to it. We may select any NP-complete problem  $A$  and show that  $A \leq_P B$ .

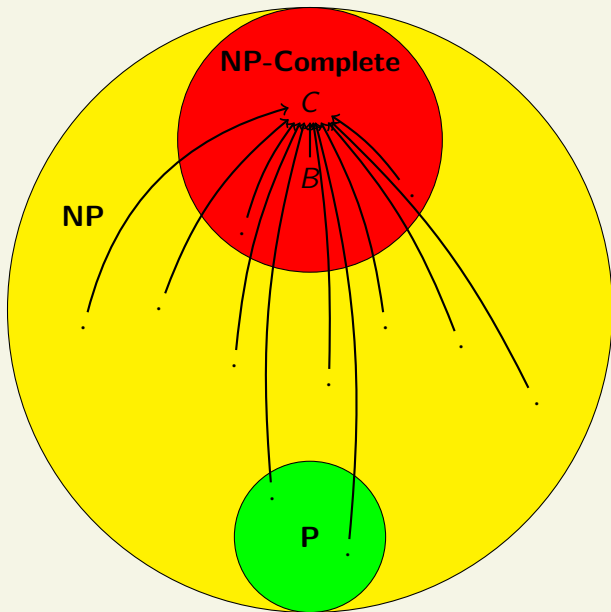


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Here is the method of showing a problem  $B$  is NP-complete.

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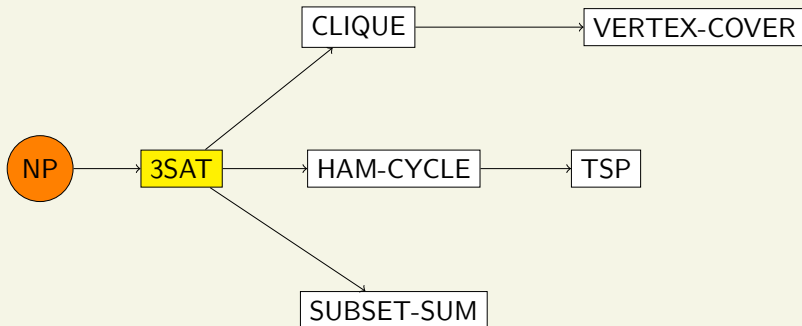
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Finally, we have to verify that the mapping is polynomial-time computable. Usually this doesn't require formal analysis of the algorithm.

Plan for NP-completeness reductions:



# Clique

In a graph  $G = (V, E)$ , a *clique* is a fully interconnected subset of the vertices. That is, a clique is a set  $V' \subseteq V$  such that for all  $u, v \in V'$ ,  $(u, v) \in E$ . The clique decision problem is

$$\text{CLIQUE} = \{ \langle G, k \rangle \mid G \text{ has a clique of size } k \}.$$

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However, it is easy to see that  $\text{CLIQUE} \in \text{NP}$ . The clique itself is a witness. So  $\langle G, k \rangle \in \text{CLIQUE} \iff (\exists V') |V'| = k$  and  $V'$  is a clique in  $G$ .

## Theorem

CLIQUE *is* NP-complete.

**Proof.** We will show  $3\text{SAT} \leq_P \text{CLIQUE}$ . Let  $\phi = C_1 \wedge \dots \wedge C_k$  be a 3CNF formula, where each  $C_i$  is a clause with at most 3 literals. We construct a graph  $G$  as follows.



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For each clause  $C_i = (l_1^{(i)} \vee l_2^{(i)} \vee l_3^{(i)})$  we put vertices  $v_1^{(i)}, v_2^{(i)}, v_3^{(i)}$  in  $G$ . (If  $C_i$  has 1 or 2 literals, we put 1 or 2 vertices in  $G$ .)

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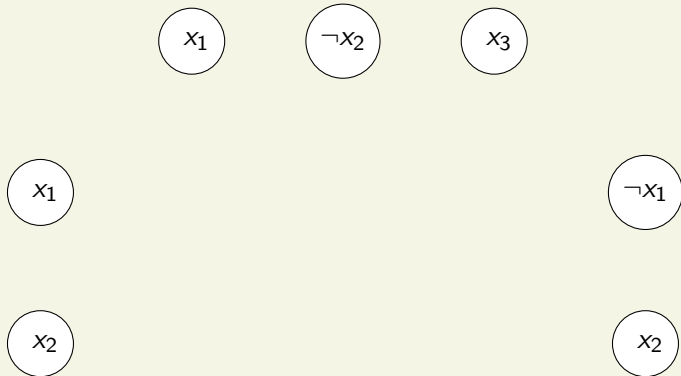
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- 1  $i \neq j$ . In other words,  $v_a^{(i)}$  and  $v_b^{(j)}$  correspond to literals in different clauses.
- 2  $l_a^{(i)} \neq \neg l_b^{(j)}$ . In other words, the corresponding literals are consistent.

For example, consider the formula

$$\phi = (x_1 \vee \neg x_2 \vee x_3) \wedge (x_1 \vee x_2) \wedge (\neg x_1 \vee x_2).$$

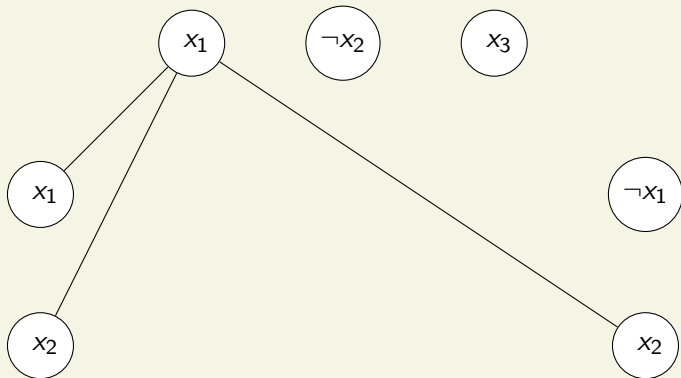
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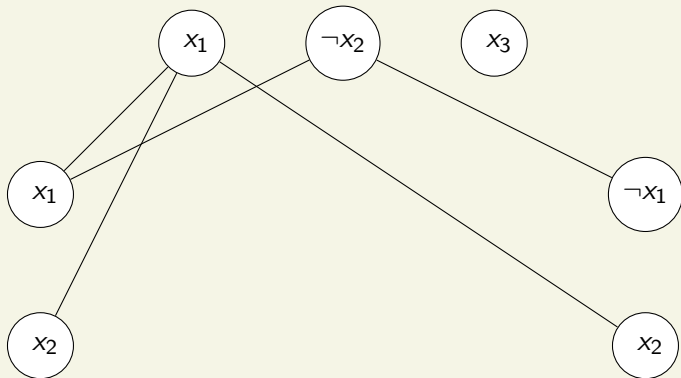
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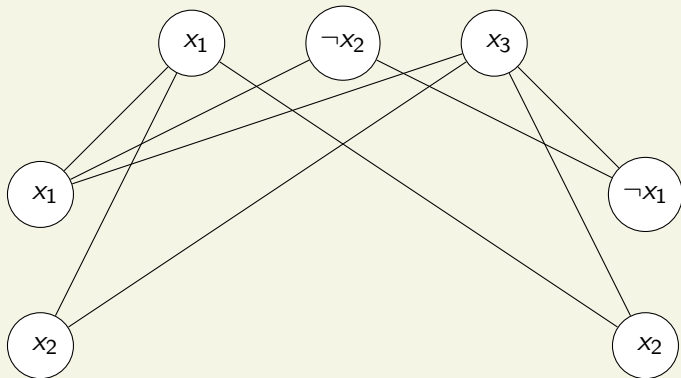
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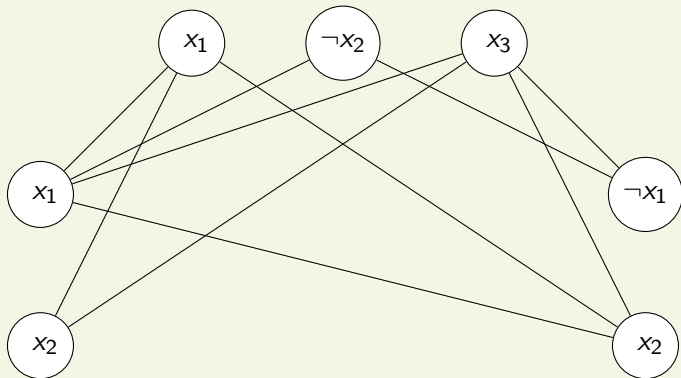
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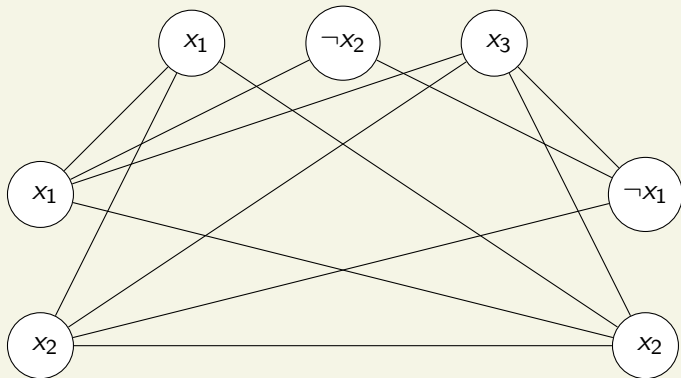
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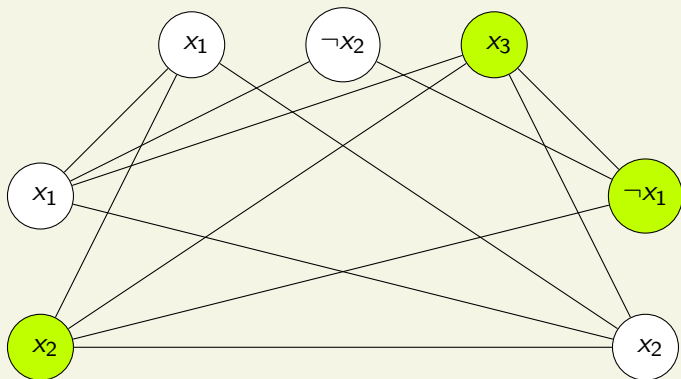
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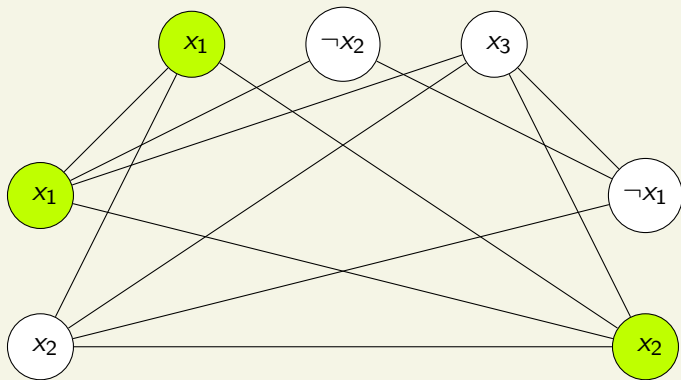
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This shows  $\phi \in 3\text{SAT} \Rightarrow \langle G, k \rangle \in \text{CLIQUE}$ .

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This assignment satisfies at least one literal in each clause of  $\phi$ . Therefore,  $\langle G, k \rangle \in \text{CLIQUE} \Rightarrow \phi \in \text{3SAT}$ .

We have shown

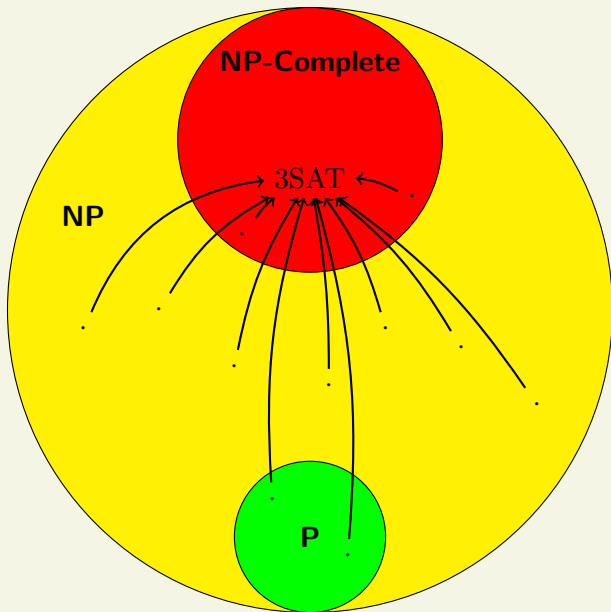
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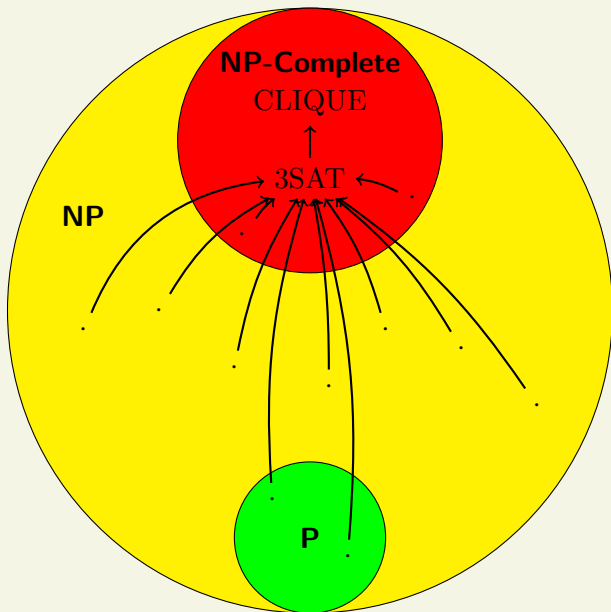
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Since the mapping  $\phi \mapsto \langle G, k \rangle$  can be computed in polynomial time, we have that  $3\text{SAT} \leq_P \text{CLIQUE}$ .

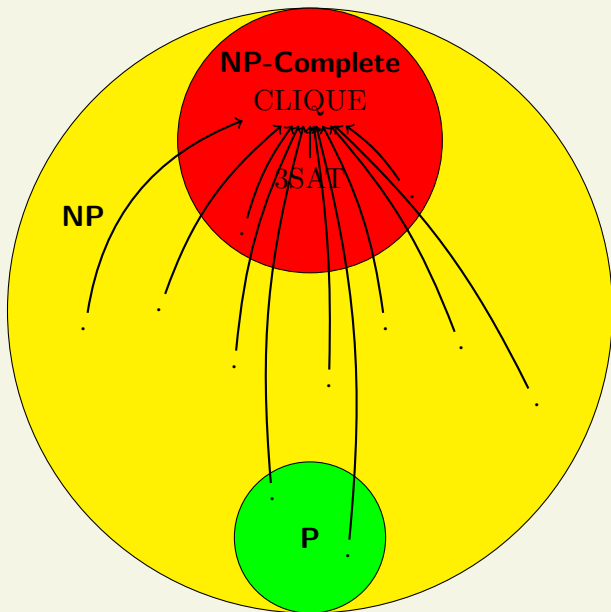
Since 3SAT is NP-complete, CLIQUE is NP-complete as well.  $\square$



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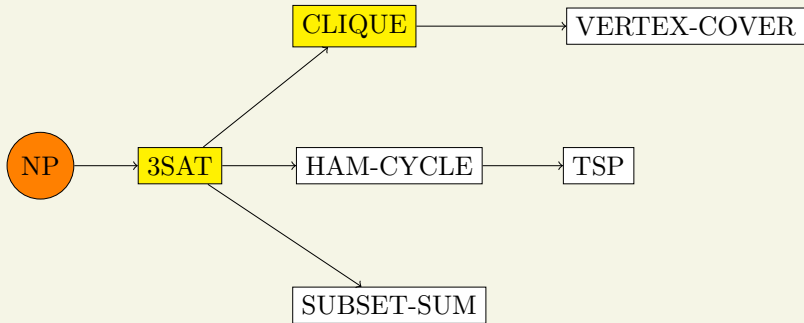


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Plan for NP-completeness reductions:





# Vertex Cover

A *vertex cover* of a graph  $G = (V, E)$  is a subset  $V' \subseteq V$  such that if  $(u, v) \in E$ , then  $u \in V'$  or  $v \in V'$  (or both). In other words, a vertex cover is a subset of the vertices that touches all edges in the graph. The decision problem is

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Note that  $V$ , the set of all vertices in the graph, is always a vertex cover. Also, if  $V'$  is a vertex cover and  $V'' \supseteq V'$ , then  $V''$  is also a vertex cover. The goal is to determine if small vertex covers exist.

## Theorem

VERTEX-COVER is NP-complete.

**Proof.** To see that VERTEX-COVER  $\in$  NP, note that  $\langle G, k \rangle \in \text{VERTEX-COVER} \iff (\exists V') |V'| \leq k$  and  $V'$  is a vertex cover for  $G$ . The set  $V'$  is the witness and all we have to do is check if  $V'$  covers all the edges, which can be done in polynomial time.

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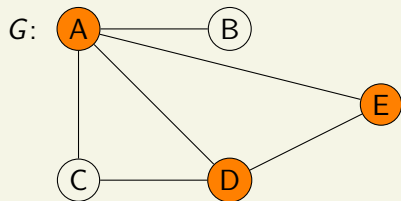
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To show completeness, we will reduce CLIQUE to VERTEX-COVER. Given a graph  $G = (V, E)$ , we define the complementary graph  $\bar{G} = (V, \bar{E})$ , where

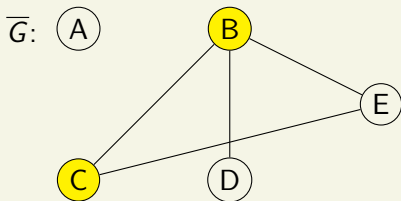
$$\bar{E} = \{(u, v) \in V \times V \mid (u, v) \notin E \text{ and } u \neq v\}.$$

We claim that  $G$  has a clique of size  $k$  if and only if  $\bar{G}$  has a vertex cover of size  $|V| - k$ .

# Examples

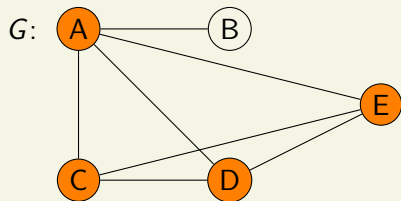


$\{A, D, E\}$  is a clique of size 3

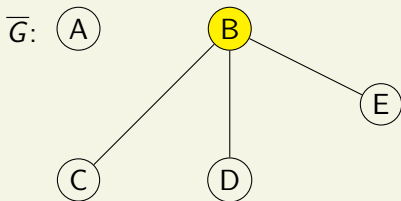


$\{B, C\}$  is a vertex cover of size 2

# Examples

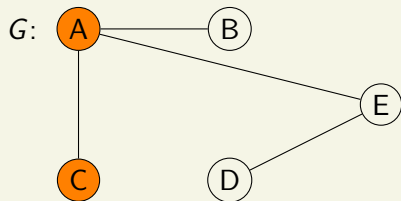


$\{A, C, D, E\}$  is a clique of size 4

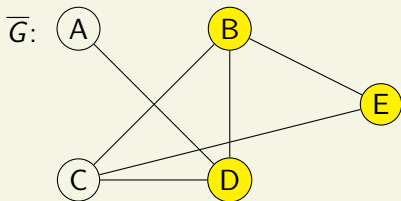


$\{B\}$  is a vertex cover of size 1

# Examples

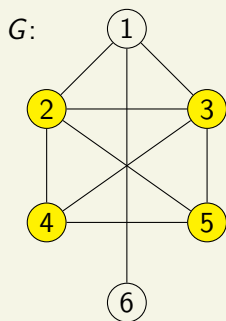


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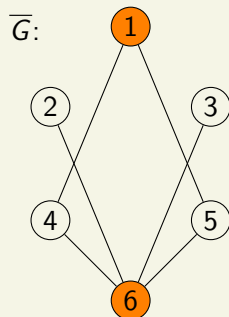


$\{B, D, E\}$  is a vertex cover of size 3

# Examples



$V' = \{2, 3, 4, 5\}$   
is a clique of size 4



$V - V' = \{1, 6\}$   
is a vertex cover of size 2



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Since  $(u, v) \in \bar{E}$  was arbitrary, we have shown that  $V - V'$  is a vertex cover in  $\bar{G}$ .

Suppose that  $G$  has a clique  $V'$  with  $|V'| = k$ . We claim that  $V - V'$  is a vertex cover in  $\bar{G}$ .

To see this, let  $(u, v) \in \bar{E}$  be any edge in  $\bar{G}$ . Then  $(u, v) \notin E$ , so at least one of the two vertices is not in the clique: at least one of  $u, v$  is not in  $V'$ . Therefore at least one of  $u$  or  $v$  is in  $V - V'$ .

Since  $(u, v) \in \bar{E}$  was arbitrary, we have shown that  $V - V'$  is a vertex cover in  $\bar{G}$ .

Since  $|V - V'| = |V| - k$ , this shows

$$\langle G, k \rangle \in \text{CLIQUE} \Rightarrow \langle \bar{G}, |V| - k \rangle \in \text{VERTEX-COVER}.$$

Now suppose that  $\bar{G}$  has a vertex cover  $V'$  with  $|V'| = |V| - k$ .  
Then for all  $u, v \in V$ , we have

$$(u, v) \in \bar{E} \Rightarrow u \in V' \text{ or } v \in V'.$$

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$$|V - V'| = |V| - |V'| = |V| - (|V| - k) = k,$$

so  $G$  has a clique of size  $k$ .

Now suppose that  $\bar{G}$  has a vertex cover  $V'$  with  $|V'| = |V| - k$ . Then for all  $u, v \in V$ , we have

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This is equivalent to saying that for all  $u, v$  with  $u \neq v$ ,

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which means that  $V - V'$  is a clique in  $G$ . Notice that

$$|V - V'| = |V| - |V'| = |V| - |V| + k = k,$$

so  $G$  has a clique of size  $k$ . This shows

$$\langle \bar{G}, |V| - k \rangle \in \text{VERTEX-COVER} \Rightarrow \langle G, k \rangle \in \text{CLIQUE}.$$

We have shown that for any graph  $G = (V, E)$  and number  $k$ ,

$$\langle G, k \rangle \in \text{CLIQUE} \iff \langle \bar{G}, |V| - k \rangle \in \text{VERTEX-COVER}.$$

Since the mapping  $\langle G, k \rangle \mapsto \langle \bar{G}, |V| - k \rangle$  can be computed in polynomial time, we have  $\text{CLIQUE} \leq_P \text{VERTEX-COVER}$ . □

Plan for NP-completeness reductions:

