



CMPS 460 – Spring 2022

MACHINE LEARNING

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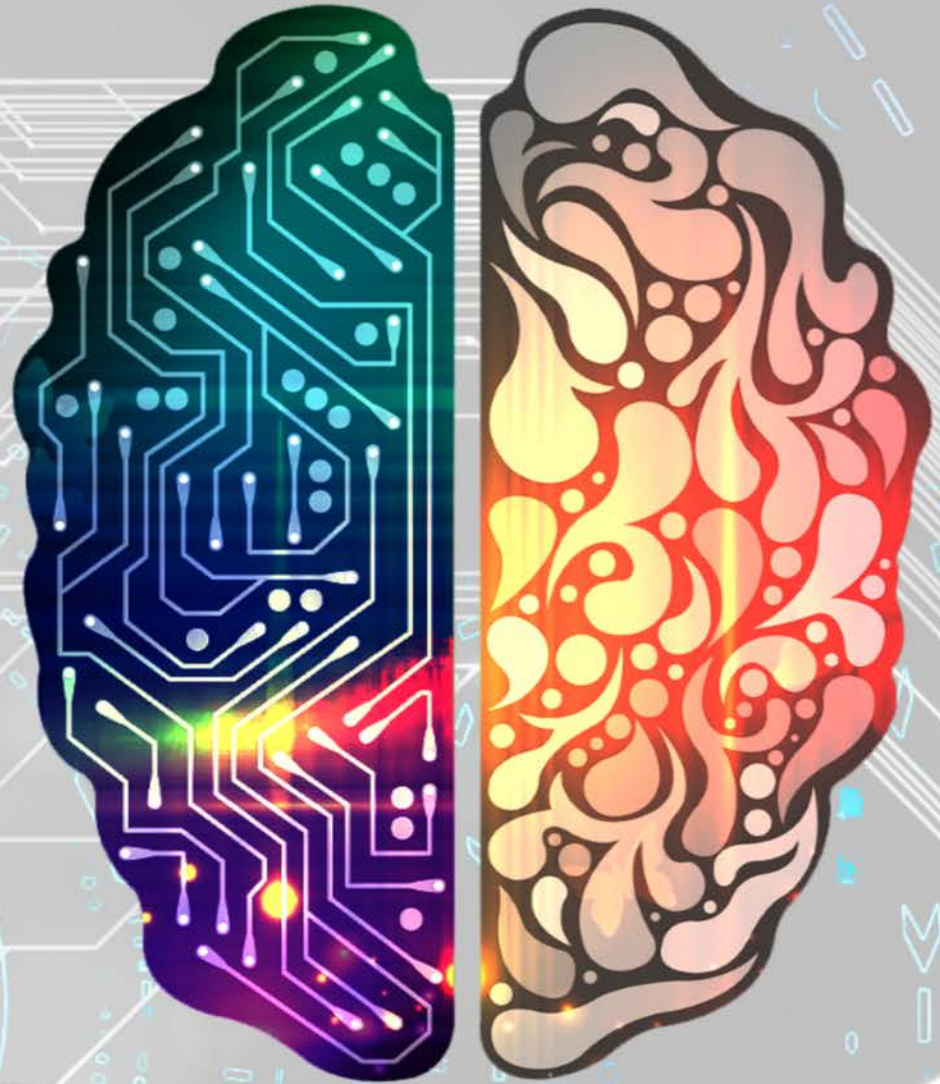


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7.b

Linear Models: Weight Regularization



Chapter 7:
7.3

Optimization Framework

Objective function

Loss function
measures how well classifier fits training data

Regularizer
prefers solutions that generalize well

$$\min_{\mathbf{w}, b} L(\mathbf{w}, b) = \min_{\mathbf{w}, b} \sum_{n=1}^N \mathbb{I}(y_n(\mathbf{w}^T \mathbf{x}_n + b) < 0) + \lambda R(\mathbf{w}, b)$$

$l(y_n, \hat{y}_n)$

λ : parameter that controls the importance of the regularization term

- Different loss function approximations
 - easier to optimize
- Regularizer
 - prevents overfitting/prefers simple models.

Surrogate loss functions

- 0-1 Loss

$$\ell^{(0/1)}(y, \hat{y}) = \mathbf{1}[y\hat{y} \leq 0]$$

- Hinge Loss

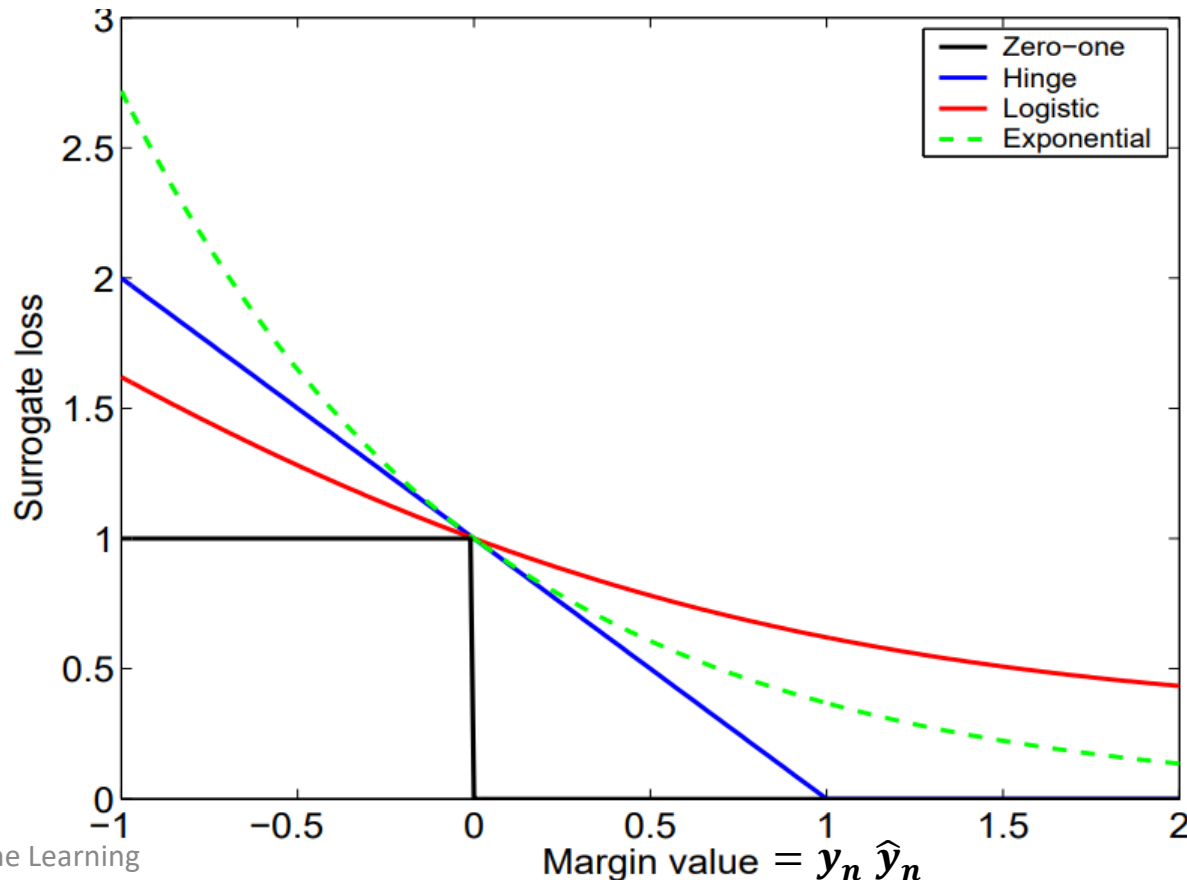
$$\ell^{(\text{hin})}(y, \hat{y}) = \max\{0, 1 - y\hat{y}\}$$

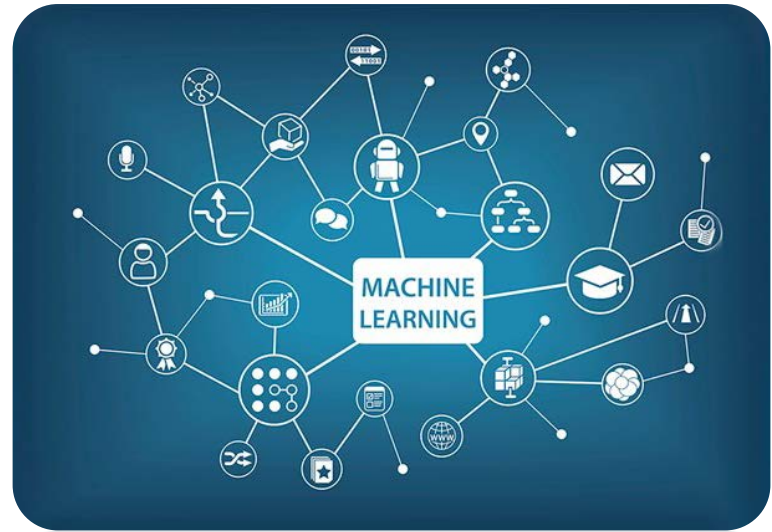
- Logistic Loss

$$\ell^{(\text{log})}(y, \hat{y}) = \frac{1}{\log 2} \log(1 + \exp[-y\hat{y}])$$

- Exponential loss

$$\ell^{(\text{exp})}(y, \hat{y}) = \exp[-y\hat{y}]$$

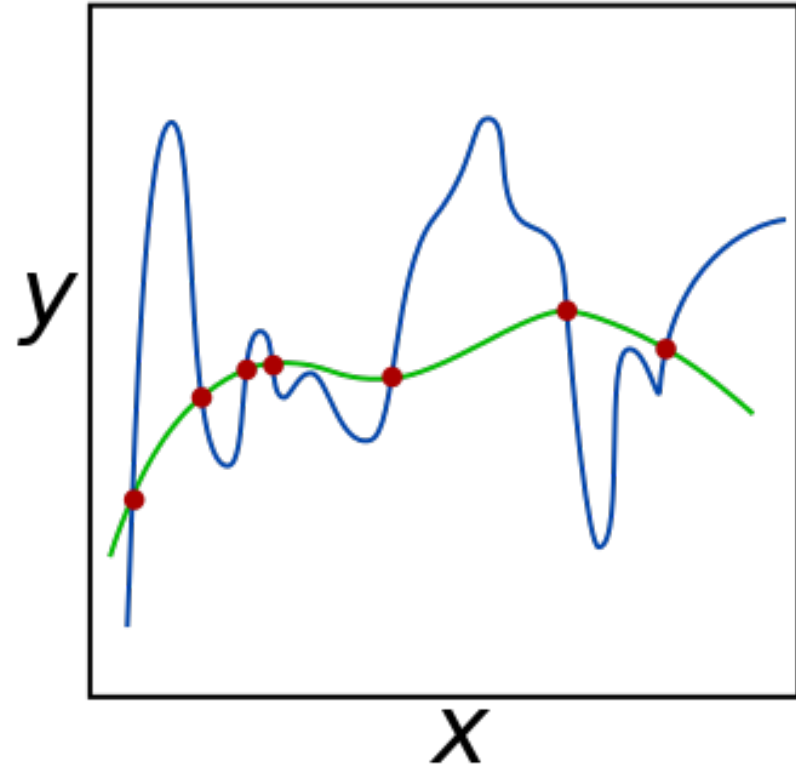




Weight Regularization

Regularization

- A technique to improve the generalizability of a learned model.
- Without bounds on complexity of the function space, model tends to overfit training data.
- Introduces a penalty for exploring certain regions of the function space.



The Regularizer Term

- Goal: find simple solutions
- Ideally, we want most entries of w to be zero, so prediction depends only on a small number of features.
- Formally, we want to minimize:

$$R^{cnt}(\mathbf{w}, b) = \sum_{d=1}^D \mathbb{I}(w_d \neq 0)$$

- That's NP-hard!
- So we use approximations instead.
 - e.g., we encourage w_d 's to be small

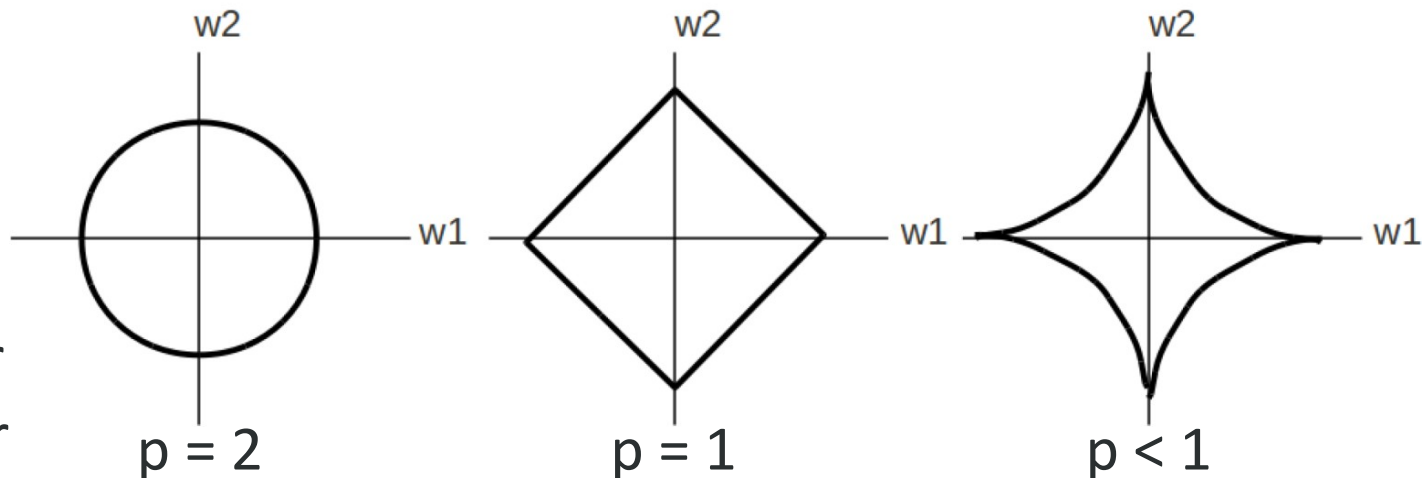
Norm-based Regularizers

- l_p norms can be used as regularizers.

$$||\mathbf{w}||_2^2 = \sum_{d=1}^D w_d^2$$

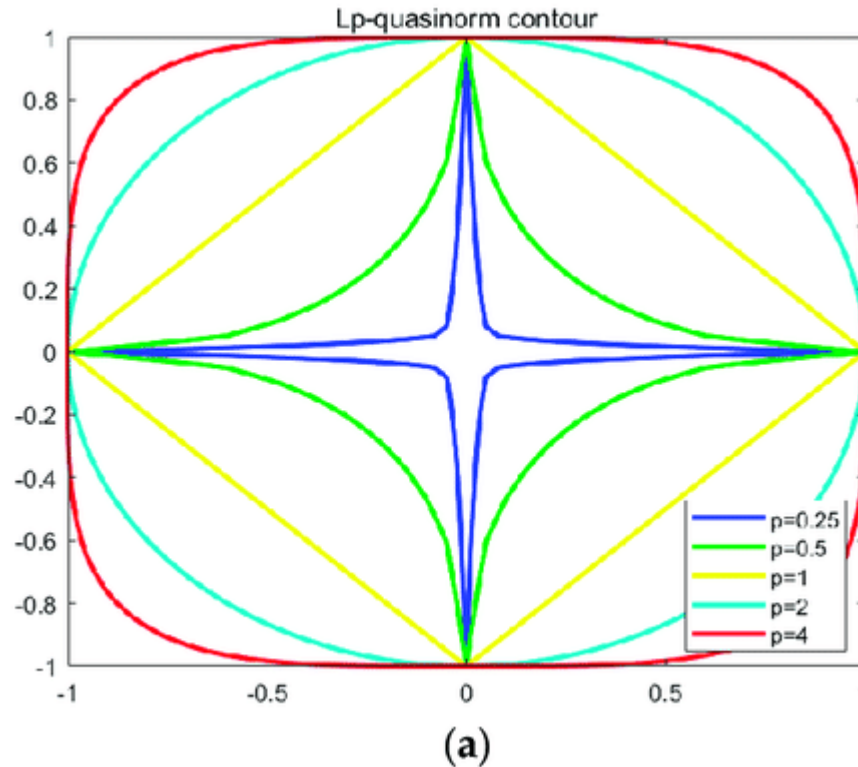
$$||\mathbf{w}||_1 = \sum_{d=1}^D |w_d|$$

$$||\mathbf{w}||_p = \left(\sum_{d=1}^D w_d^p \right)^{1/p}$$



Contour
plots for

Norm-based Regularizers



https://www.researchgate.net/publication/331855021_An_Efficient_Image_Reconstruction_Framework_Using_Total_Variation_Regularization_with_Lp-Quasinorm_and_Group_Gradient_Sparsity/figures?lo=1

Norm-based Regularizers

- l_p norms can be used as regularizers.

$$\begin{aligned} ||\mathbf{w}||_2^2 &= \sum_{d=1}^D w_d^2 \\ ||\mathbf{w}||_1 &= \sum_{d=1}^D |w_d| \\ ||\mathbf{w}||_p &= \left(\sum_{d=1}^D w_d^p \right)^{1/p} \end{aligned}$$

- Smaller p favors sparse vectors w
 - i.e. most entries of w are close or equal to 0
- $p < 1$: norm is non convex and hard to optimize!
- l_1 norm: encourages sparse w , convex, but not smooth at axis points
- l_2 norm: convex, smooth, easy to optimize