

# Designing a real-time Health-care system

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## System Requirement

- **Task:** Design a healthcare system using RTOS with the following requirements:
  - A touch LCD as input that can control the system and give commands. Every LCD command is represented in 4 bytes. LCD is connected to the micro-controller through UART with speed 9600 bps [Bit per second]. (Reading 4 bytes and processing the command takes 2 ms)
  - Blood pressure sensor with new data every 25ms. (Reading the sensor and processing its data takes 3 ms)
  - Heart beat detector with new data every 100ms. (Reading the sensor and processing its data takes 1.5 ms)
  - Temperature sensor with new data every 10ms. (Reading the sensor and processing its data takes 2.5 ms)
  - Alert siren. (Activate or Deactivate the siren takes 1 ms)

System consists of the following tasks:

LCD: execution time 2ms

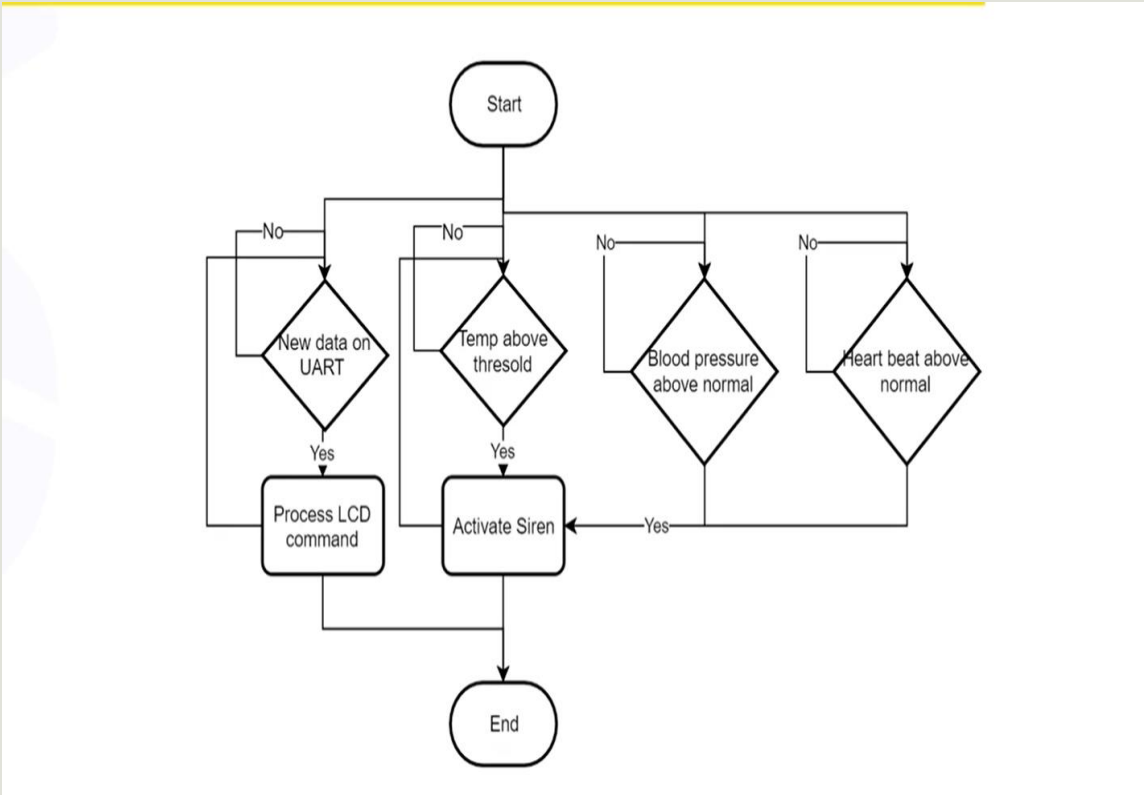
Blood pressure sensor: new data every 25ms-execution time 3ms

Heart-beat detector: new data every 100ms-execution time 1.5ms

Temperature sensor: new data every 10ms-execution time 2.5ms

Alert siren: execution time 1ms

# System flow chart



**Number of tasks needed:**

5-Tasks are needed as following:

**Task 1:** Blood pressure sensor- Reading

**Task 2:** Heart-beat detector - Reading

**Task 3:** Temperature sensor - Reading

**Task 4:** Sending LCD input to UART

**Task 5:** Alert siren

Tasks' parameters: (priority-periodicity-deadline):

**T1:Blood pressure sensor**

{Priority:2  
,Periodicity:10ms  
,Deadline:10ms }

**T2:Heart-beat detector**

{Priority:2  
,Periodicity:50ms  
,Deadline:50ms }

**T3:Temperature sensor**

{Priority:2  
,Periodicity:5ms  
,Deadline:5ms }

**T4:LCD & UART**

{Priority:3  
,Periodicity:50ms  
,Deadline :50ms }

**T5:Alert siren**

{Priority:1  
,Periodicity:suspended on event  
,Deadline:2ms }

miro

### **System tick rate:**

Systick value = total execution time of all tasks.

According to the following information:

LCD and UART: execution time 2ms

Blood pressure sensor: execution time 3ms

Heart-beat detector: execution time 1.5ms

Temperature sensor: execution time 2.5ms

Alert siren: execution time 1ms

Then:

System tick rate= 3ms + 1.5ms+ 2.5ms+ 2ms+ 1ms= **10ms**

**Calculations: (Hyper period-CPU load):**

(1)- Hyperperiod:

Hyperperiod (H) = LCM(Pi)

Hyperperiod= **100ms.**

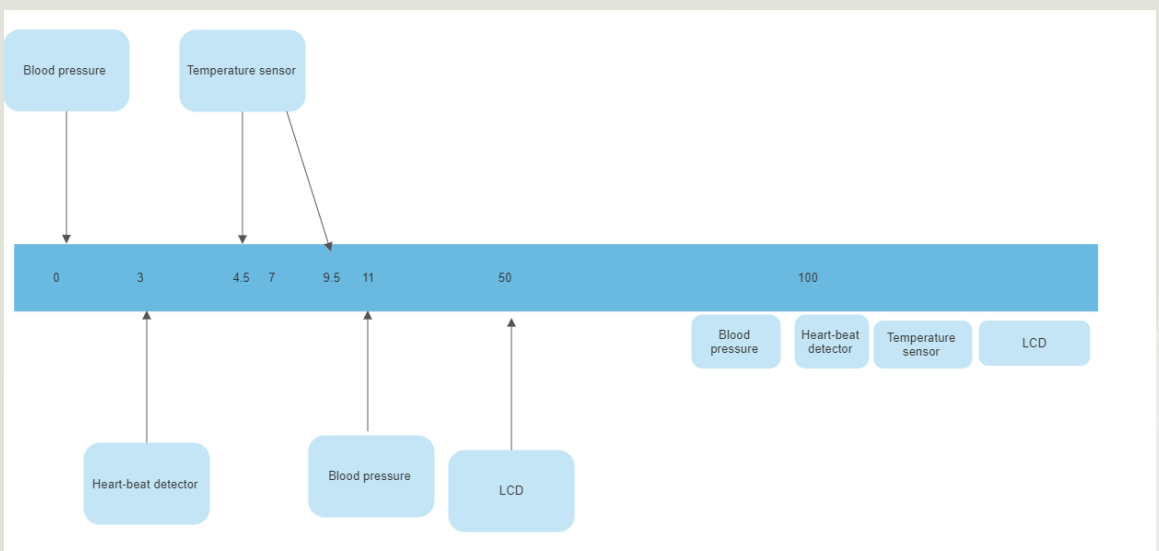
(2) CPU load:

CPU load (U) = E/H

$E = (E1+E2+E3+E4+E5+E6) = (3*10 + 1.5*2 + 2.5*20 + 2*2) = 87$

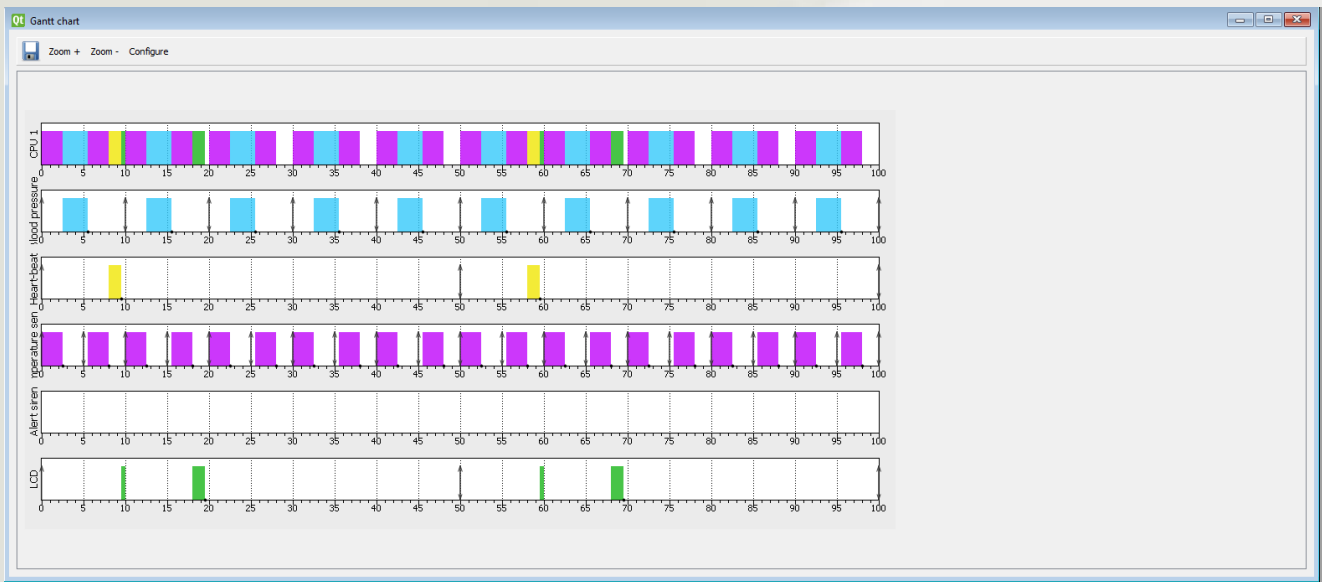
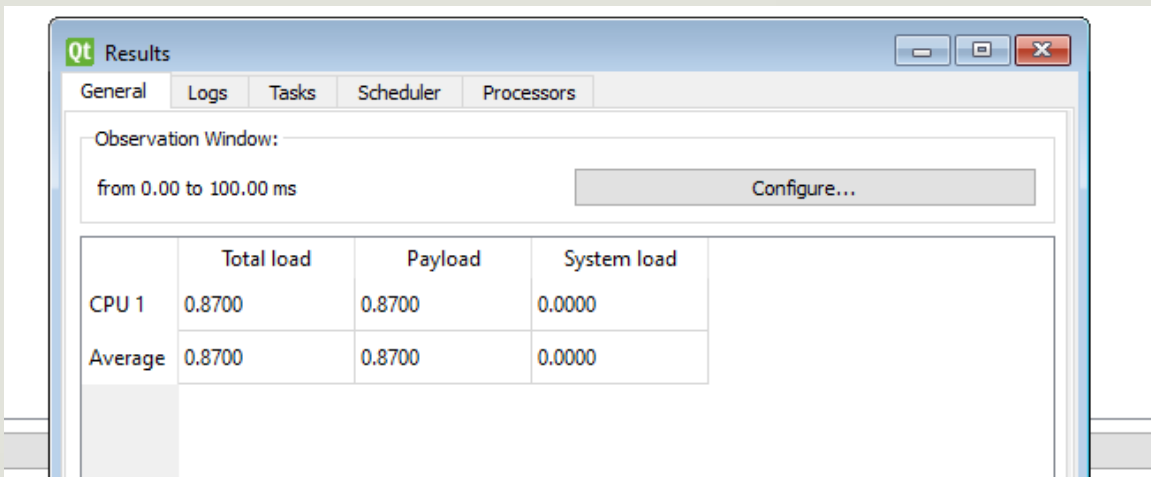
$U = 87/100 = 0.87\%$

**Timeline manually :**





**Simso Model :**



### **Comments on the results and analysis:**

- \* The simulation verifies the same output as the analytical calculations CPU load=87%
- \* it's already obvious that the system is heavily loaded!
- \* The system is schedulable as no task has missed its deadline.
- \* The Alert siren task is suspended upon event (as getting threshold value reading from the sensors)