Coursera's Development of Real-Time Systems

Peer-graded Assignment: Assignment 4

Requirement

1- Simulation assignment

Consider the tasks T1(3, 0.5), T2(4, 1.5, 3), T3(7, 1.0, 5) and the EDF scheduler.

A sporadic job arrives at t=50 having the execution time of 10 and a relative deadline of 30.

Create the sporadic task in SimSo by selecting: "generate task set" and then list of act.

Dates to the release time

- -Use SimSo to schedule the task set and provide a report answering the following questions:
 - What is the minimum/maximum/average response time of all tasks?
 - Is any task missing the deadline? Which task? Where?
 - Is the sporadic job meeting its deadline?
 - What is the response time for the sporadic job?

Consider the tasks T1(3, 0.5), T2(4, 1.5, 3), T3(7, 1.0, 5) and the RM scheduler.

A sporadic job arrives at t=50 having the execution time of 10 and a relative deadline of 30.

Create the sporadic task in SimSo by selecting: "generate task set" and then list of act.

Dates to the release time

- -Use SimSo to schedule the task set and provide a report answering the following questions:
 - What is the minimum/maximum/average response time of all tasks?
 - Is any task missing the deadline? Which task? Where?
 - Is the sporadic job meeting its deadline?
 - What is the response time for the sporadic job?
 - Which scheduler is better is better in this example; EDF or RM?

Task1- EDF Scheduler

Gene	ral Sch	eduler	Proc	essors	Tasks					
id	Name	Task t	type	Abort	on miss	Act. Date (ms)	Period (ms)	List of Act. dates (ms)	Deadline (ms)	WCET (ms)
1	TASK T1	Periodi	c *	✓ Yes		0.0	3.0	-	3.0	0.5
2	TASK T2	Periodi	c v	✓ Yes		0.0	4.0	-	3.0	1.5
3	TASK T3	Periodi	c v	✓ Yes		0.0	7.0	-	5.0	1.0
4	TASK T4	Sporadi	ic 🔻	✓ Yes				50.0	30	10
<										>

• What is the minimum/maximum/average response time of all tasks?

Task	min	avg	max	std dev
TASK T1	0.500	0.676	1.500	0.294
TASK T2	1.500	1.700	2.000	0.245
TASK T3	1.000	1.967	3.500	0.921
TASK T4	29.000	29.000	29.000	0.000

- Is any task missing the deadline? Which task? Where?
 - No deadline is missed
- Is the sporadic job meeting it's deadline?
 - Yes
- What is the response time for the sporadic job?
 - Min = 29 & avg = 29 & max = 29

<u>Task2 – RM Scheduler</u>

General	Scheduler	Processors	Tasks				
Name	Task type	Abort on miss	Act. Date (ms)	Period (ms)	List of Act. dates (ms)	Deadline (ms)	WCET (ms)
TASK T1	Periodic	▼ ✓ Yes	0	3	-	3	0.5
TASK T2	Periodic	▼ ✓ Yes	0	4	-	3	1.5
TASK T3	Periodic	▼ ✓ Yes	0	7	-	5	1
TASK T4	Sporadic	✓ Yes	-	-	50.0	30	10

• What is the minimum/maximum/average response time of all tasks?

Task	min	avg	max	std dev
TASK T1	0.500	0.500	0.500	0.000
TASK T2	1.500	1.840	2.000	0.233
TASK T3	1.000	1.900	3.000	0.860
TASK T4				

- Is any task missing the deadline? Which task? Where?
 - Sporadic job miss deadline at t = 80
- Is the sporadic job meeting its deadline?
 - No it isn't
- What is the response time for the sporadic job?
 - T=30
- Which scheduler is better is better in this example; EDF or RM?
 - EDF as non of the task missed the deadline

1- Programming Assignment

In this programming assignment, you will handle aperiodic jobs.

- Here create a task "matrixtask" containing the functionality given in Assignment 2.
- Add a software timer in main() to trigger a software interrupt every 5 seconds.
- Define a Timer callback function outside main() with the following functionality:

```
/* A variable to hold a count of the number of times the timer expires. */
    long lExpireCounters = 0;
 3 void vTimerCallback(TimerHandle t pxTimer)
4 ▼ {
 5
      printf("Timer callback!\n");
      xTaskCreate((pdTASK_CODE)aperiodic_task, (signed char *)"Aperiodic",
        configMINIMAL_STACK_SIZE, NULL, 2, &aperiodic_handle);
7 long lArrayIndex;
     const long xMaxExpiryCountBeforeStopping = 10;
      /* Optionally do something if the pxTimer parameter is NULL. */
     configASSERT(pxTimer);
10
11
      /* Increment the number of times that pxTimer has expired. */
12
      lExpireCounters += 1;
      /* If the timer has expired 10 times then stop it from running. */
13
      if (lExpireCounters == xMaxExpiryCountBeforeStopping) {
      /* Do not use a block time if calling a timer API function from a
15 +
        timer callback function, as doing so could cause a deadlock! */
        xTimerStop(pxTimer, 0);
17
18
     }
19 }
20
```

-Create an aperiodic task using the following functionality:

The following questions should be solved with programming and the questions should be answered in a report:

- Is the system fast enough to handle all aperiodic tasks? Why?
- If not, solve this problem without alter the functionality of any task
- What is the response time of the aperiodic task?
- Provide a screenshot of the running system

Task Solution :-

- Is the system fast enough to handle all aperiodic tasks? Why?
 - No, as Matrix Task consume most of cpu time as it has the highest priority

```
🧝 Problems 👨 Tasks 📮 Console 🗶 🔳 Properties ై AVR Device Explorer 👔 AVR Supported MCUs 🔣 Debugger Console 喙 Debug
<terminated> (exit value: -1) RTOSDemo.exe [C/C++ Application] C:\Users\Nada\Desktop\FreeRTOSv10.0.1\FreeRTOS\Demo\WIN32-MingW\Debug\
Matrix Task Started !
Matrix Task Number of ticks = 1381
Matrix Task Started !
Matrix Task Number of ticks = 1370
Matrix Task Started !
Matrix Task Number of ticks = 1374
Matrix Task Started !
Timer callback!
Aperiodic task started!
Matrix Task Number of ticks = 1371
Matrix Task Started !
Matrix Task Number of ticks = 1371
Matrix Task Started !
Matrix Task Number of ticks = 1375
Matrix Task Started !
Matrix Task Number of ticks = 1372
Matrix Task Started !
Timer callback!
Aperiodic task started!
Matrix Task Number of ticks = 1377
Matrix Task Started !
Matrix Task Number of ticks = 1386
Matrix Task Started !
Matrix Task Number of ticks = 1370
Matrix Task Started !
Timer callback!
Aperiodic task started!
Matrix Task Number of ticks = 1379
```

- If not, solve this problem without alter the functionality of any task
 - By increasing of aperiodic Task priority to be equal to matrix task priority

```
🥵 Problems 🙇 Tasks 📮 Console 🗶 🔟 Properties 👫 AVR Device Explorer 👫 AVR Supported MCUs 🔣 Debugger Console
<terminated> (exit value: -1) RTOSDemo.exe [C/C++ Application] C:\Users\Nada\Desktop\FreeRTOSv10.0.1\FreeRTOS\Demo\WIN32-M
 Matrix Task Started !
Matrix Task Number of ticks = 1382
Matrix Task Started !
Matrix Task Number of ticks = 1373
Matrix Task Started !
Matrix Task Number of ticks = 1379
Matrix Task Started !
Timer callback!
Aperiodic task started!
Matrix Task Number of ticks = 1785
Matrix Task Started !
Aperiodic task done!
Aperiodic Task Response Time = 2462
Matrix Task Number of ticks = 2154
Matrix Task Started !
Matrix Task Number of ticks = 1372
Matrix Task Started !
Timer callback!
Aperiodic task started!
Matrix Task Number of ticks = 2128
Matrix Task Started !
Aperiodic task done!
Aperiodic Task Response Time = 2496
Matrix Task Number of ticks = 1847
Matrix Task Started !
Matrix Task Started !
Aperiodic task started!
```

- What is the response time of the aperiodic task? 2.5 Sec
- Provide a screenshot of the running system

```
Problems  Task  Console  Properties  AVR Device Explorer  AVR Device Exp
```