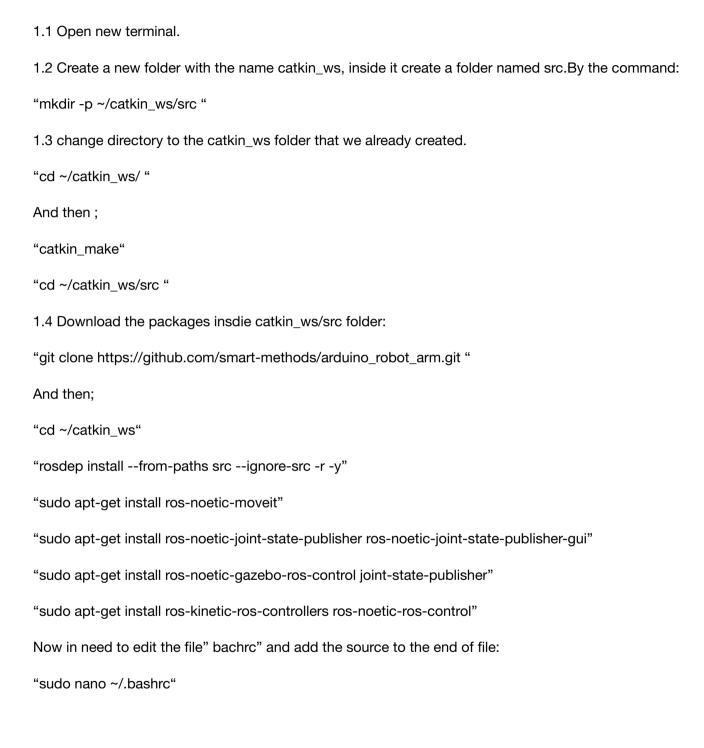
The steps to install robot arm package and RIVz.



At the end add this line:

"source /home/nada/catkin_ws/devel/setup.bash"

press ctrl + o to save the changes with the command:

"source ~/.bashrc"

Now launch RIVz by the command:

"roslaunch robot_arm_pkg check_motors.launch"

