Time: 3 Hours

N.B.

Marks: 80

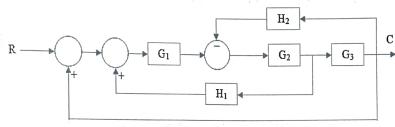
- (1)Question No. 1 is Compulsory (2)
- Answer any THREE questions from remaining five questions (3) Assume suitable data wherever necessary
- Answer any four: 01

[20]

- Explain the advantages of digital control systems. (A) **(B)**
- What are steady state error constants and how they are related with steady state error and 'type' of systems?
- Check the stability of the system with characteristic equation $s^5 + 2 s^4 + 24 s^3 + 48 s^2 + 25 s + 50 = 0$
- Explain the principle of Resistance Temperature Detectors (D)
- Obtain the impulse response of the system with transfer function (E)

$$\frac{10}{s(s+3)(s+5)}$$

02 (A) Find the transfer function (C/R) of the following system using block [10] reduction technique



- (B) What are the time domain specifications of a standard second order [10] system? How do they vary as functions of damping ratio and natural frequency of oscillation? Justify your answer.
- A system is described by $\frac{d^2y}{dt^2} + 4\frac{dy}{dt} + 8y = 8x$ [10] 03 (A) If the tolerance is 2%, calculate all time domain specifications and
 - maximum second peak. The open loop transfer function of a system is given by: [10] $G(s)H(s) = \frac{1}{(s+3)(s+5)(s^2+2s+2)}$

Sketch root locus

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04 (A) Sketch the Bode plot for the system shown below:

[10]

$$G(s)H(s) = \frac{s}{(s+5)^2 (s+20)}$$

- (B) Sketch Nyquist plot for the system shown below, and comment on stability. [10] $G(s)H(s) = \frac{K}{(1+sT_1)(1+sT_2)}$
- 05 (A) Explain in detail: landline telemetry and radio telemetry

[10]

- (B) Explain Data Acquisition System and its use in intelligent instrumentation [10] system.
- Write short notes on any four:

[20]

- (A) Distributed Control System
- (B) AC servomotor
- (C) Potentiometer as a transducer
- (D) HART communication protocol
- (E) Fibre optic instrumentation.