



z_hand_right_A

z_chest_A

z head left A

y hand left A

y hand right A

y chest A

y head left A

x hand left A

 x hand right Δ
$$y_{\text{obs}} = \Lambda$$
 $x \text{ head left } \wedge$

x_head_left_A
x_chest_A
x_hand_right_A
x_hand_left_A
y_head_left_A
y_chest_A
y_hand_right_A
y_hand_left_A
z_head_left_A
z_chest_A
z_hand_right_A
z_hand_left_A