

```

[> with(DifferentialGeometry) : with(LieAlgebras) : with(Library) :
> DGsetup([x, t, u], N);
                                     frame name: N (1)
[
N > Gamma := evalDG([t*D_x + D_u, x*D_x + 3*t*D_t - 2*u*D_u, D_t, D_x])
                                     Γ := [t D_x + D_u, x D_x + 3 t D_t - 2 u D_u, D_t, D_x] (2)
[
N > L := LieAlgebraData(Gamma, Alg1)
                                     L := [[e1, e2] = -2 e1, [e1, e3] = -e4, [e2, e3] = -3 e3, [e2, e4] = -e4] (3)
[
N > DGsetup(L)
                                     Lie algebra: Alg1 (4)

```

```

Alg1 > MultiplicationTable("LieTable");
                                     (5)
                                     [
                                     |'  e1   e2   e3   e4
                                     --- --- --- --- ---
e1 |'  0  -2 e1  -e4   0
e2 |'  2 e1   0  -3 e3  -e4
e3 |'  e4   3 e3   0    0
e4 |'  0    e4   0    0
                                     ]
> A := DerivedAlgebra( );
                                     A := [-2 e1, -e4, -3 e3] (6)
[
Alg1 > C := Center( );
                                     C := [ ] (7)
[
Alg1 > B := [e1, e3, e4]
                                     B := [e1, e3, e4] (8)
> for i from 1 to 3 do LieBracket(B[1], B[i]) end do;
                                     0 e1
                                     -e4
                                     0 e1 (9)
[
Alg1 > for i from 1 to 3 do LieBracket(B[2], B[i]) end do;
                                     e4
                                     0 e1
                                     0 e1 (10)
[
Alg1 > for i from 1 to 3 do LieBracket(B[3], B[i]) end do;
                                     0 e1
                                     0 e1
                                     0 e1 (11)

```

Since $Z(\mathfrak{g}') = \langle e4 \rangle$. $\langle e4 \rangle$ is the only one dimensional ideal.

Quotient Algebra:-

Since we have found a 1 dimentional Ideal of \mathfrak{g} i.e.

$\langle e4 \rangle$, so let $I = \langle e4 \rangle$, then Quotient Algebra is defined as $\frac{g}{I} := \langle e1 + \langle e4 \rangle, e2 + \langle e4 \rangle, e3 + \langle e4 \rangle \rangle$

which is constructed with the help of complementary bases. As $[e2, e1] = 2e1$ and $[e2, e3] = -3e3$, where $\lambda = 2$ and $\mu = -3$. Thus by lemma 2.2.2 one dimensional ideals of $g/\langle e4 \rangle$ are $\langle e1 \rangle$ and $\langle e3 \rangle$. Thus 2-dimensional ideals of g are $\langle e1, e4 \rangle$ and $\langle e3, e4 \rangle$.

```
Alg1 > h1 := [e4] : m1 := [e1, e2, e3] :
Alg1 > QuotientAlgebra(h1, m1);
L2 := [[e1, e2] = -2 e1, [e2, e3] = -3 e3] (12)
```

For 3-dimensional ideals of g :

```
Alg1 > h2 := [e1, e4] : m2 := [e2, e3] :
Alg1 > QuotientAlgebra(h2, m2);
[[e1, e2] = -3 e2] (13)
```

```
Alg1 > h3 := [e3, e4] : m3 := [e1, e2] :
Alg1 > QuotientAlgebra(h3, m3);
[[e1, e2] = -2 e1] (14)
```

hence,

all the ideals of g are $\langle \rangle$, $\langle e4 \rangle$, $\langle e1, e4 \rangle$, $\langle e3, e4 \rangle$, $\langle e1, e3, e4 \rangle$ and $\langle e1, e2, e3, e4 \rangle$.

Therefore, the 1-dimensional subalgebras of g are

$\langle e4 \rangle$, $\langle e1 + ae4 \rangle$, $\langle e3 + be4 \rangle$, $\langle e1 + ce3 + de4 \rangle$ and $\langle e2 + fe1 + ge3 + he4 \rangle$.

>

Subalgebras:

Here we use this formula

$$g := (x, y) \mapsto y + s \cdot \text{LieBracket}(x, y) + \frac{1}{2!} \cdot s^2 \cdot \text{LieBracket}(x, \text{LieBracket}(x, y)) + \frac{1}{3!} \cdot s^3 \cdot \text{LieBracket}(x, \text{LieBracket}(x, \text{LieBracket}(x, y)))$$

But we ignore the higher terms of this formula.

```
Alg1 > g := (x, y) \mapsto y + s \cdot \text{LieBracket}(x, y)
g := (x, y) \mapsto y + s \text{ DifferentialGeometry:-LieBracket}(x, y) (15)
```

```
Alg1 > X := [e2 + f \cdot e1 + g \cdot e3 + h \cdot e4] :
```

```
Alg1 > X1 := SubalgebraNormalizer(X);
X1 := [e4, \frac{1}{3} \frac{e2}{a} + e3, e1] (16)
```

The adjoint group thus factorizes as $e^{ad \langle e4 \rangle} e^{ad \langle e3 \rangle} e^{ad \langle e1 \rangle} e^{ad \langle X \rangle}$, and $\langle X, e1, e3, e4 \rangle$ is a basis of g with X normalizing the ideal $\langle e1, e3, e4 \rangle$.

```
Alg1 > X := [e1 + c \cdot e3 + d \cdot e4]
X := [e1 + c e3 + d e4] (17)
```

```
Alg1 > X1 := SubalgebraNormalizer(X);
X1 := [e4, \frac{e1}{c} + e3] (18)
```

```
Alg1 > X2 := SubalgebraNormalizer(X1);
X2 := [e4, e3, e1] (19)
```

```
Alg1 > X3 := SubalgebraNormalizer(X2);
X3 := [e4, e3, e2, e1] (20)
```

The adjoint group thus factorizes as $e^{ad\langle e2\rangle}e^{ad\langle e3\rangle}e^{ad\langle e4\rangle}e^{ad\langle X\rangle}$.

$$\begin{aligned} \text{Alg1} &> \text{LieBracket}(e4, e1 + c \cdot e3 + d \cdot e4) \\ &0 \ e1 \end{aligned} \quad (21)$$

So, X and e4 commute, we only need to compute conjugates under $e^{ad\langle e2\rangle}e^{ad\langle e3\rangle}$.

$$\begin{aligned} \text{Alg1} &> g(e3, e1 + c \cdot e3 + d \cdot e4) \\ &e1 + c \ e3 + d \ e4 + s \ e4 \end{aligned} \quad (22)$$

So, $\langle X \rangle \sim \langle e1 + ce3 \rangle$.

$$\begin{aligned} \text{Alg1} &> g(e2, e1 + c \cdot e3) \\ &e1 + c \ e3 + s \ (2 \ e1 - 3 \ c \ e3) \end{aligned} \quad (23)$$

So, $\langle X \rangle \sim \langle e1 + ce3 \rangle \sim \langle e^{2s}e1 + ce^{-3s}e3 \rangle \sim \langle e1 + ce^{-5s}e3 \rangle = \langle e1 + \epsilon e3 \rangle$, where $\epsilon = + - 1$.

$$\begin{aligned} \text{Alg1} &> X := [e3 + b \cdot e4] \\ &X := [e3 + b \ e4] \end{aligned} \quad (24)$$

$$\begin{aligned} \text{Alg1} &> X1 := \text{SubalgebraNormalizer}(X); \\ &X1 := [e4, e3, 2 \ b \ e1 + e2] \end{aligned} \quad (25)$$

The adjoint group thus factorizes as $e^{ad\langle e4\rangle}e^{ad\langle e2\rangle}e^{ad\langle e1\rangle}e^{ad\langle X\rangle}$.

$$\begin{aligned} \text{Alg1} &> g(e1, e3 + b \cdot e4) \\ &e3 + b \ e4 - s \ e4 \end{aligned} \quad (26)$$

So, $\langle X \rangle \sim \langle e3 \rangle$.

$$\begin{aligned} \text{Alg1} &> X := [e1 + a \cdot e4] \\ &X := [e1 + a \ e4] \end{aligned} \quad (27)$$

$$\begin{aligned} \text{Alg1} &> X1 := \text{SubalgebraNormalizer}(X); \\ &X1 := \left[\frac{1}{3} \ \frac{e2}{a} + e3, e4, e1 \right] \end{aligned} \quad (28)$$

$$\begin{aligned} \text{Alg1} &> g(e2, e1 + a \cdot e4) \\ &e1 + a \ e4 + s \ (2 \ e1 - a \ e4) \end{aligned} \quad (29)$$

So, $\langle X \rangle \sim \langle e1 \rangle$. Also, $\langle X \rangle \sim \langle e2 \rangle$. Thus representatives of for conjugacy classes of 1-dimensional subalgebras are $\langle e4 \rangle, \langle e1 \rangle, \langle e3 \rangle, \langle e1 + e3 \rangle, \langle e1 - e3 \rangle$ and $\langle e2 \rangle$.

2-dimensional subalgebras:

$$\begin{aligned} \text{Alg1} &> P := [[e1], [e2], [e3], [e4], [e1 + e3], [e1 - e3]] \\ &P := [[e1], [e2], [e3], [e4], [e1 + e3], [e1 - e3]] \end{aligned} \quad (30)$$

$$\begin{aligned} \text{Alg1} &> \text{for } i \text{ from } 1 \text{ to } 6 \text{ do } \text{SubalgebraNormalizer}(P[i]) \text{ end do;} \\ &[e4, e2, e1] \\ &[e2] \\ &[e4, e3, e2] \\ &[e4, e3, e2, e1] \\ &[e4, e1 + e3] \\ &[e4, -e1 + e3] \end{aligned} \quad (31)$$

$$\text{Alg1} > h1 := [e4]: m1 := [e2, e1, e3]:$$

$$\begin{aligned} \text{Alg1} &> \text{QuotientAlgebra}(h1, m1) \\ &[[e1, e2] = 2 \ e2, [e1, e3] = -3 \ e3] \end{aligned} \quad (32)$$

By Lemma 4.2, the conjugacy classes of 1-dimensional subalgebras of $N\langle e4 \rangle / \langle e4 \rangle$ as $\langle e2' \rangle, \langle e1' \rangle,$

$\langle e3' \rangle, \langle e1' + e3' \rangle, \langle e1' - e3' \rangle$.

Hence, the 2-dimensional subalgebras obtained by extending $\langle e4 \rangle$ are $\langle e4, e2 \rangle, \langle e4, e1 \rangle, \langle e4, e3 \rangle, \langle e4, e1 + e3 \rangle$ and $\langle e4, e1 - e3 \rangle$.

Since, $N\langle e1 \rangle = \langle e4, e2, e1 \rangle$ and $N\langle e1 \rangle / \langle e1 \rangle = \langle e2', e4' \rangle$, by Lemma 4.1 the 1-dimensional subspaces of $N\langle e1 \rangle / \langle e1 \rangle$ are $\langle e2' \rangle$ and $\langle e4' \rangle$. Thus the 2-dimensional subalgebras obtained by extending $\langle e1 \rangle$ are $\langle e1, e2 \rangle$ and $\langle e1, e4 \rangle$.

Also, $N\langle e3 \rangle / \langle e3 \rangle = \langle e4', e2' \rangle$, by Lemma 4.1 the 1-dimensional subspaces are $\langle e4' \rangle$ and $\langle e2' \rangle$. Thus the 2-dimensional subalgebras obtained by extending $\langle e3 \rangle$ are $\langle e3, e4 \rangle$ and $\langle e2, e3 \rangle$.

Hence, representatives for classes of 2 dimensional subalgebras of \mathfrak{g} are $\langle e4, e2 \rangle, \langle e4, e1 \rangle, \langle e4, e3 \rangle, \langle e4, e1 + e3 \rangle, \langle e4, e1 - e3 \rangle, \langle e2, e3 \rangle$ and $\langle e1, e4 \rangle$.

3-dimensional subalgebras:

```
Alg1 > Q := [[e1, e2], [e4, e1], [e3, e2], [e4, e3], [e4, e2], [e4, e1 + e3], [e4, e1
              - e3]]
Q := [[e1, e2], [e4, e1], [e3, e2], [e4, e3], [e4, e2], [e4, e1 + e3], [e4, e1 - e3]] (33)
```

```
Alg1 > for i from 1 to 7 do SubalgebraNormalizer(Q[i]) end do;
              [e2, e1]
              [e4, e3, e2, e1]
              [e3, e2]
              [e4, e3, e2, e1]
              [e2, e4]
              [e4, e3, e1]
              [e4, e3, e1] (34)
```

```
Alg1 > h1 := [e4, e1] : m1 := [e2, e3] :
```

```
Alg1 > QuotientAlgebra(h1, m1)
              [[e1, e2] = -3 e2] (35)
```

```
Alg1 > h2 := [e4, e3] : m2 := [e1, e2] :
```

```
Alg1 > QuotientAlgebra(h2, m2)
              [[e1, e2] = -2 e1] (36)
```

By using Lemma 4.1, 3-dimensional subalgebras obtained by extending $\langle e4, e1 \rangle$ are $\langle e4, e1, e2 \rangle$ and $\langle e4, e1, e3 \rangle$.

Similarly for $\langle e4, e3 \rangle$, extensions are $\langle e4, e3, e1 \rangle$ and $\langle e4, e3, e2 \rangle$.

Hence, representatives for classes of 3-dimensional subalgebras are $\langle e4, e1, e2 \rangle, \langle e4, e1, e3 \rangle$ and $\langle e4, e3, e2 \rangle$.