PSO-NeuralNet Document

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1 Network Description

Artificial Neural Network: Dataset- MNIST, Training Data - $42,\!000,$ Test Data- $10,\!000$

Layer	Number of Nodes	Layer Dim	Weight Dim	Bias Dim	Activation
Input	784	784x1	None	None	None
Hidden 1	16	16x1	16x784	16x1	ReLU
Hidden 2	16	16x1	16x16	16x1	ReLU
Output	10	10x1	10x16	10x1	Sigmoid

Table 1: Artificial Neural Network Structure

2 Forward Propagation

The notations that have been used in forward propagation is described below:

- \bullet $Z^{[i]} = Output of i^{th} Layer of Neural Network$
- \bullet $A^{[i]} = Activation of i^{th} Layer of Neural Network$
- $\bullet X = input$

- $W^{[i]} = Weight from (i-1)^{th} to i^{th} Layer of Neural Network$
- \bullet b^[i] = Biases for ith Layer of Neural Network

3 Back Propagation

```
Algorithm 2 Back Propagation in Neural Network
```

```
1: procedure Backpropagation(X, Y)
         dZ^{[3]} = A^{[3]} - Y
                                                                     ▷ Derivatives Calculation
         dW^{[3]} = (1/m) dZ^{[3]} A^{[2].T}
 3:
         dB^{[3]} = (1/m) \text{ np.sum}(dZ^{[3]}, \text{ axis=1, Keepdims} = \text{True})
 4:
         dZ^{[2]} = W^{[3].T}.dZ^{[3]} * DReLU(Z^{[2]})
         dW^{[2]} = (1/m) dZ^{[2]}.A^{[1].T}
         dB^{[2]} = (1/m) np.sum(dZ^{[2]}, axis=1, Keepdims = True)
 7:
         dZ^{[1]} = W^{[2]} \cdot \hat{T} \cdot dZ^{[2]} * DReLU(Z^{[1]})
         dW^{[1]} = (1/m) dZ^{[1]}.X^{T}
 9:
         dB^{[1]} = (1/m) \text{ np.sum}(dZ^{[1]}, \text{ axis}=1, \text{ Keepdims} = \text{True})
10:
11:
         W^{[1]} = W^{[1]} - 0.01 * dW^{[1]}
                                                                            ▷ Parameter Update
12:
         b^{[1]} = b^{[1]} - 0.001 * dB^{[1]}
13:
         W^{[2]} = W^{[1]} - 0.01 * dW^{[2]}
14:
         b^{[2]} = b^{[1]} - 0.001 * dB^{[2]}
15:
         W^{[3]} = W^{[1]} - 0.01 * dW^{[3]}
16:
         b^{[3]} = b^{[1]} - 0.001 * dB^{[3]}
18: end procedure
```

The notations that have been used in back propagation is described below:

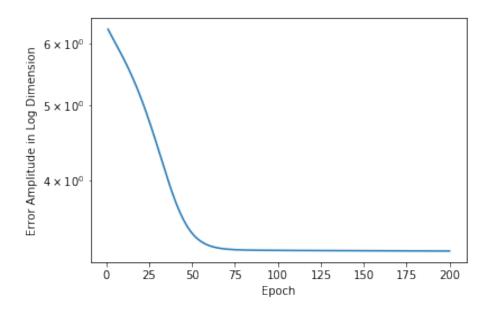
- $dZ^{[i]} = Derivative of Z of ith Layer of Neural Network$
- $A^{[i].T} = Transpose of A^{[i]}$
- dW^[i] = Derivative of W of ith Layer of Neural Network
- dB^[i] = Derivative of B of ith Layer of Neural Network

4 Loss Function for Neural Network

```
Algorithm 3 Loss Function in Neural Network
```

```
1: procedure LossFunction(Y)
2: RETURN \frac{1}{m} \sum_{i=1}^m (-Y^{(i)} \log(\hat{Y^{(i)}}) - (1-Y^{(i)}) \log(1-\hat{Y^{(i)}})
3: end procedure
```

5 Performance of Back Propagation



6 Particle Swarm Optimization as a replacement of Backpropagation in Neural Network

Main Equation of Particle Swarm Optimization -

```
\begin{split} WV_{ij}(t) &= \text{Intertia Component} \\ r_1c_1(P_{ij}(t) - x_{ij}(t)) &= \text{Cognitive Component} \\ r_2c_2(g_j(t) - x_{ij}(t)) &= \text{Social Component} \\ c_1, c_2 &= \text{Acceleration Coefficients} \\ W &= \text{Inertia Coefficient} \\ t, t(t+1) &= \text{timestamps} \\ V_{ij}(t) &= j^{th} \text{ velocity component of } i^{th} \text{ particle} \\ P_{ij}(t) &= j^{th} \text{ component of } i^{th} \text{ particle's best position} \\ x_{ij}(t) &= j^{th} \text{ component of } i^{th} \text{ particle's current position} \\ r_1, r_2 &= N(\mu, \sigma^2) \end{split}
```

For determining the value of W, c_1 and c_2 , I've used Constriction coefficients proposed by Clerc and Kennedy, 2002.

Let,
$$\phi = \phi_1 + \phi_2 \ge 4$$

$$0 < \kappa < 1$$

$$\chi = \frac{2\kappa}{\left|2 - \phi - \sqrt{\phi^2 - 4\phi}\right|}$$

Commonly, $\kappa=1,\,\phi_{\ 1}=2.05,\,\phi_{2}=2.05$

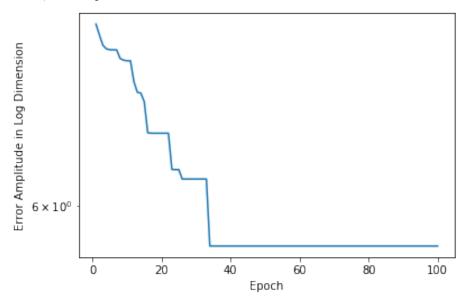
So, Finally,

$$W = \chi, C_1 = \kappa \phi_1, C_2 = \kappa \phi_2$$

And for Velocity and Position Update,

$$V_{ij}(t+1) = WV_{ij}(t) + r_1c_1(P_{ij}(t) - x_{ij}(t)) + r_2c_2(g_j(t) - x_{ij}(t))$$
$$x_{ij}(t+1) = x_{ij}(t) + V_{ij}(t+1)$$

Performance of PSO is shown in the following graph. Swarm Population Size = 50, Total Epochs = 100.



Algorithm 4 Particle Swarm Optimization in Neural Network

```
1: procedure InitializeParticle(nVar, nPop)
        globalBestPosition \leftarrow \vec{0} of dimension (nVar x 1)
 2:
 3:
        globalBestCost \leftarrow None
 4:
        for each particle<sub>(i)</sub> in range(1, nPop) do
            particle<sub>(i)</sub>.position \leftarrow N(\mu, \sigma^2) of dimension (nVar x 1)
 5:
            particle_{(i)}.velocity \leftarrow \vec{0} \text{ of dimension (nVar x 1)}
 6:
 7:
            particle_{(i)}.cost \leftarrow None
            particle_{(i)}.bestPosition \leftarrow particle_{(i)}.position
 8:
 9:
            particle_{(i)}.bestCost \leftarrow particle_{(i)}.cost
10:
        end for
11: end procedure
    procedure InitializeParameters(NeuralNetwork, X, Y, maxIt, nPop)
        nVar \leftarrow NeuralNetwork.numWeights + NeuralNetwork.numBiases
13:
14:
        \phi_1 \leftarrow 2.05
15:
        \phi_2 \leftarrow 2.05
16:
        \phi \leftarrow \phi_1 + \phi_2
17:
        \chi \leftarrow \frac{2\pi}{\left|2 - \phi - \sqrt{\phi^2 - 4\phi}\right|}
18:
        maxIt \leftarrow 100
19:
        nPop \leftarrow 50
20:
21:
        \mathbf{w} \leftarrow \chi
22:
        wdamp \leftarrow 0.99
        c_1 \leftarrow \chi.\phi_1
23:
        c_2 \leftarrow \chi.\phi_2
24:
25: end procedure
    procedure COSTPSO(NeuralNetwork, particle)
27:
        NeuralNetwork.weights gets particle.position.slice
28:
        NeuralNetwork.biases gets particle.position.slice
        NeuralNetwork.ForwardPropagation(X)
29:
        RETURN NeuralNetwork.Loss(Y)
30:
31: end procedure
32:
    procedure InitializeSwarm(NeuralNetwork)
        for each particle<sub>(i)</sub> in range(1, nPop) do
33:
34:
             particle_{(i)}.cost = COSTPSO(NeuralNetwork, particle_{(i)})
            if particle(i).bestCost < globalBestCost then
35:
                 globalBestPosition = particle_{(i)}.bestPosition
36:
                 globalBestCost = particle_{(i)}.bestCost
37:
38:
            end if
        end for
39:
40: end procedure
```

Algorithm 5 Particle Swarm Optimization in Neural Network

```
1: procedure PSOLOOP(NeuralNetwork)
         for each epoch<sub>(i)</sub> in range(1, maxIt) do
 2:
 3:
              for each particle_{(j)} in range(1, nPop) do
                   V_{j}(t+1) \leftarrow \widetilde{W}V_{j}(t) + r_{1}c_{1}(P_{j}(t) - x_{j}(t)) + r_{2}c_{2}(g(t) - x_{j}(t))
 4:
                   x_{\mathbf{j}}(t+1) \leftarrow x_{\mathbf{j}}(t) + V_{\mathbf{j}}(t+1)
 5:
                   particle_{(i)}.cost \leftarrow COSTPSO(NeuralNetwork,particle_i)
 6:
                   if particle_{(j)}.cost < particle_{(j)}.bestCost then
 7:
                       particle_{(j)}.bestPoition \leftarrow particle_{(j)}.position
 8:
 9:
                       particle_{(j)}.besCost \leftarrow particle_{(j)}.cost
                       \mathbf{if} \ \mathrm{particle}_{(j)}.\mathrm{bestCost} < \mathrm{globalBestCost} \ \mathbf{then}
10:
                            globalBestPosition \leftarrow particle_{(j)}.bestPosition
11:
                            globalBestCost \leftarrow particle_{(i)}.cost.bestCost
12:
                       end if
13:
14:
                  end if
              end for
15:
16:
         end for
17: end procedure
```