ICP 5

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700# : 700761149

Google drive link:

https://drive.google.com/file/d/1xr-PQCeZskoDscxQZrOnugvnnu_5H-Ub/view?usp = drive link

Github Link: https://github.com/Nagi-131/ICP-5

```
Autoencoder without hidden layer

from keras.layers import Input, Dense from keras.datasets import model from keras.datasets import mist import numpy as np encoding_dim = 64

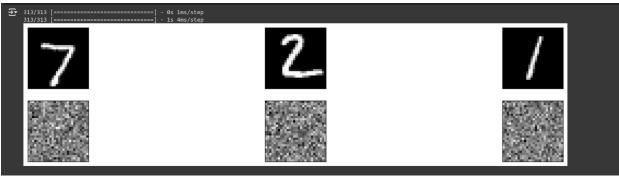
input_img = Input(shape=(784,))

encoded = Dense(encoding_dim_activation='relu')(input_img) decoded = Dense(encoding_dim_activation='sigmoid')(encoded) autoencoder = Model(input_img_activation='sigmoid')(encoded) autoencoder = Model(input_img_accoded) encoded = Model(input_img_accoded) encoded = Input_shape=(encoding_dim_accoded) encoded_input = Input_shape=(encoding_dim_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input_accoded_input
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```
0
       import matplotlib.pyplot as plt
plt.plot(history.history['loss'], color="green")
plt.plot(history.history['val_loss'], color="blue")
       plt.title('model loss')
plt.legend(['train', 'validation'], loc='upper right')
plt.show()
₹
                                                             model loss
                                                                                                — train
                                                                                                      validation
         0.6950
         0.6945
         0.6940
         0.6935
         0.6930
         0.6925
                                                                4
                                                                                     6
                                            2
```

```
→ Epoch 1/10
            =========] - 4s 15ms/step - loss: 0.2323 - val_loss: 0.1497
 Epoch 2/10
             ========] - 4s 18ms/step - loss: 0.1333 - val_loss: 0.1199
 235/235 [==
 Epoch 3/10
           Epoch 4/10
            ========] - 3s 14ms/step - loss: 0.1077 - val_loss: 0.1036
          235/235 [===
          235/235 [===
 Epoch 9/10
 235/235 [==
            =========] - 4s 18ms/step - loss: 0.0953 - val_loss: 0.0937
 Epoch 10/10
 235/235 [===
```





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## analysis of the control of the co
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```
encoder_summary()
autoencoder_compile(optimizer="adam", loss="binary_crossentropy")
history = autoincoder_fit(x_train, x_train, paches, speches, stath, size=256, shuffleerIrme, validation_data=(x_test, x_test))
num_inages = 5
num_inages = 5
num_anden.seed(42)
nanden.seed(42)
nanden.see
```

dense_10 (Dense)

Total params: 50240 (196.25 KB)
Trainable params: 50240 (196.25 KB)
Non-trainable params: θ (0.00 Byte)

Epoch 1/5

Epoch 1/5

Epoch 2/5

Epoch 3/5

Epoch 4/5

Epoch 4/5

Epoch 5/5

Epoch 5/5