Attila Nagy

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INTRODUCTION

I have a background in telecommunication, automotive industry and machine learning. In the recent years I have developed an interest in deep learning through self-studies, that led to my previous job at RumbleStrip. We worked on adaptive spoilers for the heavy truck industry to lower fuel consumption. Before that, I worked with self-driving cars at Volvo Cars in Active-Safety, and with 3G networks at Nokia Siemens Networks in Budapest. Currently I am working on PacketCore at Ericsson.

My technical interest mostly rotates around open-source software development, cryptography, Linux, machine and deep learning, functional programming, and a little bit of web-development. In my working environment, I tend to be social and discuss books and podcasts I read and listened recently.

My current greatest endeavour is to start my own company and work as a freelancer.

WORK

HiQ, Consultant at Ericsson

Software Developer, Sweden, Full-time

Functional Tester, System Tester, DevOps Roles:

C++, TTCN Programming: Applications: LTE, PacketCore

RumbleStrip 09/2017 - 10/2019

Software Architect and Developer, Sweden, Full-time

SW Architect, Algorithm Developer Roles:

Programming: Python, C, Matlab

Applications: Adaptive Roof-Deflector, Data-Analysis

ÅF, Consultant at Volvo Cars

07/2014 - 07/2016

Self-Driving Car Engineering, Sweden, Full-time

Self-Driving Car Developer, Unit Tester Roles:

Matlab, Simulink, Python, C++ Programming:

Applications:Active-Safety, Data-Analysis, Sensor-Fusion, Mapping, Logging

Nokia Siemens Networks

08/2009 - 08/2012

04/2020 - Now

Software Engineer, Hungary, Full-time

Scrum Master, Functional Tester, Unit Tester, DevOps Roles:

C/C++, Python, Perl, BASH, TNSDL, LDAP Programming:

GDB, Valgrind, oProfile Debugging:

EDUCATION

freeCodeCamp Certificates

https://www.freecodecamp.org/ (Click on certificate)

01/2020 - 03/2020

Certificate 1: Responsive Web Design

Certificate 2: JavaScript Algorithms and Data Structures

Certificate 3: Front End Libraries

Deep Learning Nanodegree

 $Udacity,\ www.udacity.com$

01/2017 - 06/2017

Assigment 1: Vanilla Neural Network from scratch

Assigment 2: Image Classification by Convolutional Neural Network

Assigment 3: TV script generation by Recurrent Neural Network

Assigment 4: Language-translation by Recurrent Neural Network

Assignment 5: Face image generation by Generative Adversarial Networks Source-code: https://github.com/NagyAttila/Udacity_DLND_Assignments

MSc. Computer Science

Chalmers University of Technology, Sweden

09/2012 - 04/2014

Specialization: Distributed Systems and Networks

Thesis' Title: Energy Efficient, High-speed Communication in Wireless Sensor Networks

Thesis' Keywords: Opportunistic Routing, Bulk-transfer, TinyOS, nesC

Student Project: Carolo Cup, Germany, self-driving miniature cars, team leader Research Project: Power consumtion disaggregation and clsassification with SVM

ERASMUS Scholarship

University of Applied Sciences Ravensburg-Weingarten, Germany

09/2008 - 01/2009

Field: Embedded Systems

BSc. Electrical Engineering

Obuda University, Hungary

09/2004 - 06/2009

Specialization: Embedded Systems

Thesis' Title: Robot Simulation isepspacenGL Environment Thesis' Keywords: Industrial robot simulation, OpenGL, C++.

Student Project: Remote-controlled miniature car via bluetooth, 8-bit Atmega micro-controller

LANGUAGES

English Swedish Hungarian

INTEREST

Technical: machine learning

free/open-source software blockchain technology functional programming

Sports: rock climbing

slacklining running yoga

PROJECTS

HiQ, Consultant at Ericsson

04/2020 - Now

After 10 years I am back in Telecom working on the next generation of telecommunication networks. Most of my work currently involves development on the PacketCore network, Functional Testing using TTCN and System Tests.

RumbleStrip

09/2017 - 10/2019

Working with adaptive roof-deflectors for trucks using machine learning, AWS and embedded systems to lower fuel consumption. Mostly worked with a Bayesian Regression model for predicting the optimal position of the roof- deflector. But earlier at the proof of concept stage we experimented with a variant of K-Nearest- Neighbour algorithm, Decision Trees and Deep Neural Networks. At the end due to the lack of available data and limitations in our product's HW, we decided to use a Bayesian Regression model. Sensor data was collected using Python on a RaspberryPi, stored in AWS, and evaluated in Matlab. Later, our model was prototyped in an embedded environment on a STM32 board, and field tested using LINAK-LA32 actuators on Volvo trucks.

ÅF, Consultant at Volvo Cars

07/2014 - 07/2016

I worked as a SW developer in Active Safety in the Sensor Fusion team using Matlab and Simulink. My work mostly involved post-processing of sensory data for our particle filter algorithm, that fused our positions from the GPS sensor and the IMU.

Nokia Siemens Networks

08/2009 - 08/2012

As part of the HLR and DXA teams for 3G development, I worked in a cross-functional team, doing testing, coding and maintenance using C++ and Python.

REFERENCES

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David Andersson

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From: Volvo Cars