

THE Z-TRANSFORM

DEFINITION:

$$X(z) = \mathcal{Z}\{x(k)\} \triangleq \sum_{k=0}^{\infty} x(k)z^{-k}$$
$$= x(0) + x(1)z^{-1} + x(2)z^{-2} + x(3)z^{-3} + \dots$$

Z-TRANSFORM OF COMMON SIGNALS:

• IMPULSE:

$$\mathcal{Z}\{\delta(k)\} = 1$$

K: time index
T: sampling time

• UNIT STEP:

$$\mathcal{Z}\{\mu(k)\} = \frac{z}{z-1}$$

• UNIT RAMP:

$$\mathcal{Z}\{kT\} = \frac{zT}{(z-1)^2}$$

• EXPONENTIAL:

$$\mathcal{Z}\{e^{-akT}\} = \frac{z}{z - e^{-aT}}$$

• SINUSOID:

$$\mathcal{Z}\{\cos(\omega kT)\} = \frac{z^2 - z\cos(\omega T)}{z^2 - 2z\cos(\omega T) + 1}$$

Z-TRANSFORM OPERATIONS:

0~2 properties are used most often

⑥ SUMMATION AND SCALING:

$$\mathcal{Z}\{ax(k) + by(k)\} = aX(z) + bY(z)$$

① DELAY (BACKWARD SHIFT):

$$\mathcal{Z}\{y(k-n)\} = z^{-n}Y(z)$$

② ADVANCE (FORWARD SHIFT):

$$\mathcal{Z}\{y(k+n)\} = z^n Y(z) - z^n y(0) - \dots - z y(n-1)$$

③ CUMULATIVE SUMMATION ("INTEGRATION"):

$$\mathcal{Z}\left\{\sum_{i=0}^k y(i)\right\} = Y(z) \cdot \frac{z}{z-1}$$

Discrete time integration of y

④ COMPLEX FREQUENCY SHIFT:

$$\mathcal{Z}\{a^k y(k)\} = Y\left(\frac{z}{a}\right)$$

⑤ MULTIPLICATION BY k:

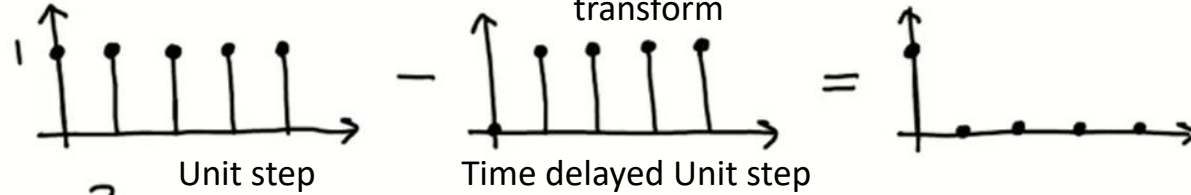
$$\mathcal{Z}\{ky(k)\} = -z \frac{dY(z)}{dz}$$

EXAMPLES OF USING THE Z-TRANSFORM:

Although we can use the table to get the transform of impulse, we will try to get it using properties and step transform

• EXAMPLE 1:

$$\delta(k) = \mu(k) - \mu(k-1)$$



$$\mathcal{Z}\{\delta(k)\} = \mathcal{Z}\{\mu(k) - \mu(k-1)\}$$

$$= \mathcal{Z}\{\mu(k)\} - \mathcal{Z}\{\mu(k-1)\} \quad [\text{PROPERTY 0}]$$

$$= \mathcal{Z}\{\mu(k)\} - z^{-1} \mathcal{Z}\{\mu(k)\} \quad [\text{PROPERTY 1}]$$

$$= \frac{z}{z-1} - z^{-1} \cdot \frac{z}{z-1} \quad [\mathcal{Z}\{\mu(k)\} = \frac{z}{z-1}]$$

$$= \frac{z-1}{z-1} = 1$$

• EXAMPLE 2: Difference equation

$$y(k) = 0,95y(k-1) + r(k); \quad r(k) = \delta(k)$$



We want to calculate the impulse response of the system

$$\mathcal{Z}\{y(k)\} = \mathcal{Z}\{0,95y(k-1) + \delta(k)\} = 0,95\mathcal{Z}\{y(k-1)\} + \mathcal{Z}\{\delta(k)\} \quad [\text{PROPERTY 0}]$$

$$\Rightarrow Y(z) = 0,95z^{-1}Y(z) + 1 \quad [\text{PROPERTY 1}; \mathcal{Z}\{\delta(k)\} = 1]$$

$$\Rightarrow (1 - 0,95z^{-1})Y(z) = 1 \Rightarrow Y(z) = \frac{1}{1 - 0,95z^{-1}} = \frac{z}{z - 0,95}$$

INVERSE Z-TRANSFORM USING TABLES:

• EXAMPLE 1:

$$Y(z) = \frac{z}{z-0,95} ; y(k)?$$

$$\text{IN Z-TRANSFORM TABLE: } \mathcal{Z}\{e^{-akT}\} = \frac{z}{z-e^{-aT}}$$

$$\text{IF } e^{-aT} = 0,95 \Rightarrow e^{-akT} = (e^{-aT})^k = 0,95^k$$

$$\Rightarrow y(k) = \begin{cases} 0, & k < 0 \\ 0,95^k, & k \geq 0 \end{cases} = 0,95^k \mu(k) \quad \text{Because it should be only in the positive time}$$

• EXAMPLE 2:

$$X(z) = \frac{z}{(z-0,5)(z+0,3)} ; x(k)? \quad \text{We divide first by } z$$

$$\frac{X(z)}{z} = \frac{1}{(z-0,5)(z+0,3)} = \frac{A_1}{(z-0,5)} + \frac{A_2}{(z+0,3)} \quad \text{Then use partial fraction expansion}$$

$$A_1 = \frac{1}{z+0,3} \Big|_{z=0,5} = 1,25 ; A_2 = \frac{1}{z-0,5} \Big|_{z=-0,3} = -1,25 \quad \text{We calculate the residuals}$$

$$\Rightarrow \frac{X(z)}{z} = \frac{1,25}{z-0,5} - \frac{1,25}{z+0,3} \Rightarrow X(z) = 1,25 \cdot \frac{z}{z-0,5} - 1,25 \cdot \frac{z}{z+0,3} \quad \text{Multiply by } z$$

$$\Rightarrow x(k) = \begin{cases} 0, & k < 0 \\ 1,25(0,5)^k - 1,25(-0,3)^k, & k \geq 0 \end{cases} = [1,25(0,5)^k - 1,25(-0,3)^k] \mu(k)$$

INVERSE Z-TRANSFORM USING LONG DIVISION:

EXAMPLE:

$$X(z) = \frac{z}{(z-0,5)(z+0,3)} = \frac{z}{z^2 - 0,2z - 0,15} ; \quad x(k)?$$

The idea is to find an infinite series that when multiplied by the denominator will give us the numerator

$$\begin{array}{r} z^2 - 0,2z - 0,15 \overline{) z^{-1} + 0,2z^{-2} + 0,19z^{-3} + \dots} \\ \underline{z^2 - 0,2z - 0,15} \phantom{z^{-3}} \\ 0,2 + 0,15z^{-1} \\ \underline{0,2 - 0,04z^{-1} - 0,03z^{-2}} \\ 0,19z^{-1} + 0,03z^{-2} \end{array}$$

z numerator
denominator

$$\Rightarrow X(z) = z^{-1} + 0,2z^{-2} + 0,19z^{-3} + \dots$$

COMPARE WITH Z-TRANSFORM DEFINITION:

$$X(z) = \mathcal{Z}\{x(k)\} = \sum_{k=0}^{\infty} x(k)z^{-k} = x(0) + x(1)z^{-1} + x(2)z^{-2} + \dots$$

$$\Rightarrow x(k) = 0, 1, 0,2, 0,19, \dots$$

This method is good to find the few first values of a discrete signal but not to find the analytical description of the signal

INVERSE Z-TRANSFORM USING DELAY OPERATION:

EXAMPLE:

Difference equation

Apply impulse to the input

$$y(k) = 0,95y(k-1) + r(k-1); \quad r(k) = \delta(k); \quad y(k)?$$

$$Y(z) = 0,95z^{-1}Y(z) + z^{-1} \cdot 1 \quad [\text{APPLIED Z-TRFM; PROPERTY 1; } Z\{\delta(k)\} = 1]$$

$$\Rightarrow (1 - 0,95z^{-1})Y(z) = z^{-1} \quad \text{Not in the table so we multiply by } z \text{ to power } -1$$

$$\Rightarrow Y(z) = \frac{z^{-1}}{1 - 0,95z^{-1}} = \frac{1}{z - 0,95} = z^{-1} \cdot \underbrace{\left(\frac{z}{z - 0,95} \right)}_{X(z)} = z^{-1}X(z)$$

$$x(k) = 0,95^k \mu(k) \quad [\text{Z-TRFM TABLES}]$$

$$y(k) = x(k-1) \quad [\text{PROPERTY 1}]$$

$$= 0,95^{k-1} \mu(k-1)$$
$$= \begin{cases} 0, & k < 1 \\ 0,95^{k-1}, & k \geq 1 \end{cases}$$

