```
#include <iostream>
#include <vector>
#include <queue>
#include <unordered_map>
using namespace std;
struct Node {
    string name;
    string path;
    int clicks;
    Node(string name, string path, int clicks) : name(name), path(path),
clicks(clicks) {}
};
void bfs(const unordered_map<string, vector<string>>& filesystem, const string&
target) {
    queue<Node> q;
    q.push(Node("C:", "C:", 0));
    while (!q.empty()) {
        Node curr = q.front();
        q.pop();
        if (curr.name == target) {
            cout << curr.path << endl;</pre>
            cout << curr.clicks << endl;</pre>
            return;
        if (filesystem.find(curr.name) != filesystem.end()) {
            for (const string& child : filesystem.at(curr.name)) {
                string childPath = curr.path + "\\" + child;
                int childClicks = curr.clicks + 2;
                q.push(Node(child, childPath, childClicks));
    cout << "File not found" << endl;</pre>
    cout << -1 << endl;</pre>
int main() {
    int e;
```

```
cin >> e;
unordered_map<string, vector<string>> filesystem;

for (int i = 0; i < e; i++) {
    string parent, child;
    cin >> parent >> child;
    filesystem[parent].push_back(child);
}

int q;
cin >> q;

for (int i = 0; i < q; i++) {
    string target;
    cin >> target;
    bfs(filesystem, target);
}

return 0;
}
```

```
#include <iostream>
#include <vector>
#include <queue>
using namespace std;

bool isBicolorable(const vector<vector<int>>& graph, int start) {
   int n = graph.size();
   vector<int> color(n, -1); // Initialize all vertices with no color
   color[start] = 0; // Assign the start vertex color 0

   queue<int> q;
   q.push(start);

   while (!q.empty()) {
      int curr = q.front();
   }
}
```

```
q.pop();
        for (int neighbor : graph[curr]) {
            if (color[neighbor] == -1) {
                // Assign a different color to the neighbor
                color[neighbor] = 1 - color[curr];
                q.push(neighbor);
            } else if (color[neighbor] == color[curr]) {
                // If the neighbor has the same color as the current vertex, the
graph is not bicolorable
                return false;
    return true; // All vertices are colored without any conflict
bool isBicolorableGraph(const vector<vector<int>>& graph) {
    int n = graph.size();
    for (int i = 0; i < n; i++) {
        if (!isBicolorable(graph, i))
            return false;
    return true;
int main() {
    int n, e;
    cin >> n >> e;
    vector<vector<int>> graph(n);
    for (int i = 0; i < e; i++) {
        int x, y;
        cin >> x >> y;
        graph[x].push_back(y);
        graph[y].push_back(x);
    if (isBicolorableGraph(graph))
        cout << "YES" << endl;</pre>
    else
```

```
cout << "NO" << endl;
return 0;
}</pre>
```

```
#include <iostream>
#include <vector>
#include <queue>
#include <unordered_map>
using namespace std;
// Structure to represent a chess cell
struct Cell {
   int row;
    int col;
    Cell(int r, int c) : row(r), col(c) {}
};
// Function to check if a cell is valid and within the chessboard limits
bool isValidCell(int row, int col) {
    return (row >= 0 \&\& row < 8 \&\& col >= 0 \&\& col < 8);
// Function to get the minimum number of moves required for the knight to reach
the destination
int getMinMoves(Cell start, Cell dest) {
    // Offsets for the knight's possible moves
    int rowOffsets[] = {-2, -2, -1, -1, 1, 1, 2, 2};
    int colOffsets[] = {-1, 1, -2, 2, -2, 2, -1, 1};
    // Create a visited map to keep track of visited cells
    unordered_map<int, unordered_map<int, bool>> visited;
    // Create a map to store the parent cell for each visited cell
    unordered map<int, unordered map<int, Cell>> parent;
    // Create a queue for BFS traversal
    queue<Cell> q;
```

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// Initialize the starting cell as visited
   visited[start.row][start.col] = true;
   // Enqueue the starting cell
   q.push(start);
   // Perform BFS traversal
   while (!q.empty()) {
       Cell curr = q.front();
        q.pop();
moves
       if (curr.row == dest.row && curr.col == dest.col) {
            return parent[curr.row][curr.col].row;
        // Explore all possible moves from the current cell
        for (int i = 0; i < 8; i++) {
            int newRow = curr.row + rowOffsets[i];
            int newCol = curr.col + colOffsets[i];
            // Check if the new cell is valid and not visited
            if (isValidCell(newRow, newCol) && !visited[newRow][newCol]) {
                visited[newRow][newCol] = true;
                parent[newRow][newCol] = curr;
                q.push(Cell(newRow, newCol));
            }
    return -1;
// Function to print the path from the starting cell to the destination cell
void printPath(Cell start, Cell dest) {
   vector<Cell> path;
   Cell curr = dest;
   // Traverse the parent map to build the path
   while (curr.row != start.row || curr.col != start.col) {
        path.push back(curr);
        curr = parent[curr.row][curr.col];
```

```
// Print the minimum number of moves
    cout << path.size() << endl;</pre>
    for (int i = path.size() - 1; i >= 0; i--) {
        cout << static cast<char>('A' + path[i].row) << path[i].col + 1;</pre>
        if (i > 0) {
            cout << "->";
    }
    cout << endl;</pre>
int main() {
    int q;
    cin >> q;
    for (int i = 0; i < q; i++) {
        string startCell, destCell;
        cin >> startCell >> destCell;
        Cell start(startCell[0] - 'A', startCell[1] - '1');
        Cell dest(destCell[0] - 'A', destCell[1] - '1');
        // Get the minimum number of moves and print the path
        int minMoves = getMinMoves(start, dest);
        printPath(start, dest);
    return 0;
```

```
#include <iostream>
#include <queue>
using namespace std;

// Node structure for BST
struct Node {
   int data;
```

```
Node* left;
    Node* right;
    Node(int value) {
        data = value;
        left = right = nullptr;
};
Node* insertNode(Node* root, int value) {
    if (root == nullptr)
        return new Node(value);
    if (value < root->data)
        root->left = insertNode(root->left, value);
    else
        root->right = insertNode(root->right, value);
    return root;
// Function to perform level-wise traversal of the BST
void levelOrderTraversal(Node* root) {
    if (root == nullptr)
        return;
    queue<Node*> q;
    q.push(root);
    while (!q.empty()) {
        int size = q.size();
        for (int i = 0; i < size; i++) {
            Node* current = q.front();
            q.pop();
            cout << current->data << " ";</pre>
            if (current->left)
                q.push(current->left);
            if (current->right)
                q.push(current->right);
```

```
cout << endl; // Print newline after each level
}

int main() {
  int n;
  cin >> n;

  Node* root = nullptr;

  for (int i = 0; i < n; i++) {
     int value;
     cin >> value;
     root = insertNode(root, value);
}

levelOrderTraversal(root);

return 0;
}
```

```
#include <iostream>
#include <queue>
#include <string>
using namespace std;
// Function to generate binary strings of length up to n
void generateBinaryStrings(int n) {
    queue<string> q;
    q.push("0");
    q.push("1");
    for (int i = 1; i <= n; i++) {
        cout << "Length " << i << ": ";</pre>
        int size = q.size();
        for (int j = 0; j < size; j++) {
            string curr = q.front();
            q.pop();
            cout << curr << " ";</pre>
            q.push(curr + "0");
```

```
q.push(curr + "1");
}

cout << endl;
}

int main() {
   int n;
   cin >> n;
   generateBinaryStrings(n);
   return 0;
}
```

```
#include <iostream>
#include <vector>
#include <queue>
using namespace std;
struct Node {
    int value;
    vector<int> path;
};
void printConversionPath(const vector<int>& path) {
    int n = path.size();
    for (int i = 0; i < n; i++) {
        cout << path[i];</pre>
        if (i != n - 1)
            cout << " -> ";
    cout << endl;</pre>
void bfs(int X, int Y) {
    queue<Node> q;
    Node start;
    start.value = X;
    start.path.push_back(X);
    q.push(start);
```

```
while (!q.empty()) {
        Node curr = q.front();
        q.pop();
        if (curr.value == Y) {
            cout << curr.path.size() - 1 << endl;</pre>
            printConversionPath(curr.path);
            return;
        Node next;
        next.path = curr.path;
        next.value = curr.value * 2;
        next.path.push_back(next.value);
        q.push(next);
        next.value = curr.value - 1;
        next.path.push_back(next.value);
        q.push(next);
int main() {
    int X, Y;
    cin >> X >> Y;
    bfs(X, Y);
    return 0;
```