

题 号	1	2	3	4	5	6	7
分 值	12 分	15 分	24 分	14 分	15 分	10 分	10分

本试卷共 ( 7 ) 大题, 满分 ( 100 ) 分.

This 2-hour long test includes 7 questions. Write ***all your answers*** on the examination book.

1. (12 points, 2 points each) Label the following statements as **True** or **False**. No need to justify. (12 分, 2 分一道) 判断正误, 不需要说明理由.

(a) If  $A$  and  $B$  are invertible, then  $BA$  is invertible.

如果  $A$  和  $B$  是可逆矩阵, 则  $BA$  也是可逆矩阵.

(b) Let  $A$  be an  $m \times n$  matrix with rank  $n$ , then  $Ax = b$  is solvable for all  $b \in \mathbb{R}^m$ .

设  $A$  为  $m \times n$  矩阵且秩为  $n$ , 则对于任意的  $b \in \mathbb{R}^m$ ,  $Ax = b$  都是可解的.

(c) If  $x_p$  is a particular solution to  $Ax = b$ , then  $x_p$  is always in the row space of  $A$ .

如果  $x_p$  是  $Ax = b$  的一个特解, 那么  $x_p$  一定在矩阵  $A$  的行空间里.

(d) Let the vectors  $v_1, v_2, v_3$  be linearly independent. If  $w_1 = v_1, w_2 = v_1 + v_2, w_3 = v_1 + v_2 + v_3$ , then  $w_1, w_2, w_3$  are linearly independent.

假定向量  $v_1, v_2, v_3$  线性无关. 如果  $w_1 = v_1, w_2 = v_1 + v_2, w_3 = v_1 + v_2 + v_3$ , 则  $w_1, w_2, w_3$  线性无关.

(e) The transformation that takes  $x$  to  $2x + 1$  is a linear transformation (from  $\mathbb{R}^1$  to  $\mathbb{R}^1$ ).

变换把  $x$  变为  $2x + 1$  是线性变换 (从  $\mathbb{R}^1$  到  $\mathbb{R}^1$ ).

(f) If the row space of  $A$  is the same as the column space of  $A$ , then the nullspace of  $A$  and the left nullspace of  $A$  must be the same.

如果矩阵  $A$  的行空间和列空间相同, 则  $A$  的零空间和左零空间必定相同.

**Solution.** (a) True (b) False (c) False (d) True (e) False (f) True.

2. (15 points, 5 points each ) Fill in the blanks. (15 分, 5 分一道) 填空题.

(a) If  $\begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & a+2 \\ 1 & a & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$  has no solution, then  $a = \underline{-1}$ .

如果  $\begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & a+2 \\ 1 & a & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$  无解, 那么  $a = \underline{-1}$ .

(b) Suppose  $A$  is a  $4 \times 3$  matrix, and  $\text{rank } A = 2$ , and  $B = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 0 \\ -1 & 0 & 3 \end{bmatrix}$ ,  
then  $\text{rank } (AB) = \underline{2}$ .

如果  $A$  是一个  $4 \times 3$  矩阵, 且  $\text{rank } A = 2$ ,  $B = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 2 & 0 \\ -1 & 0 & 3 \end{bmatrix}$ , 则  
 $\text{rank } (AB) = \underline{2}$ .

(c) Let  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 3 & 0 & 0 \\ 0 & -4 & 5 & 0 \\ 0 & 0 & -6 & 7 \end{bmatrix}$ , and  $B = (I+A)^{-1}(I-A)$ , then  $(I+B)^{-1} =$   
 $\underline{\frac{1}{2}(I+A)}$  (Here  $I$  is the  $4 \times 4$  identity matrix).

设  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -2 & 3 & 0 & 0 \\ 0 & -4 & 5 & 0 \\ 0 & 0 & -6 & 7 \end{bmatrix}$ ,  $B = (I+A)^{-1}(I-A)$ , 那么  $(I+B)^{-1} =$   
 $\underline{\frac{1}{2}(I+A)}$  (这里  $I$  是  $4 \times 4$  单位矩阵).

3. (24 points) Let

$$A = \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 1 & 2 & 2 & 2 & 3 \\ -1 & -2 & 0 & 2 & 3 \end{bmatrix}.$$

(a) Find the complete solution to  $Ax = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ .

(b) Find the complete solution to  $Ax = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ .

(c) Find the rank of  $A$  and dimensions of the four fundamental subspaces of  $A$ .

(d) Find bases of the four fundamental subspaces of  $A$ .

(24 分) 设

$$A = \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 1 & 2 & 2 & 2 & 3 \\ -1 & -2 & 0 & 2 & 3 \end{bmatrix}.$$

(a) 求  $Ax = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$  的所有解.

(b) 求  $Ax = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$  的所有解.

(c) 求  $A$  的秩和矩阵  $A$  的四个基本子空间的维数.

(d) 求矩阵  $A$  的四个基本子空间的基.

**Solution.** Let's put the matrix

$$\begin{bmatrix} 1 & 2 & 1 & 0 & 0 & b_1 \\ 1 & 2 & 2 & 2 & 3 & b_2 \\ -1 & -2 & 0 & 2 & 3 & b_3 \end{bmatrix}$$

into Reduced Row Echelon Form.

We get

$$\begin{bmatrix} 1 & 2 & 1 & 0 & 0 & b_1 \\ 0 & 0 & 1 & 2 & 3 & b_2 - b_1 \\ 0 & 0 & 1 & 2 & 3 & b_3 + b_1 \end{bmatrix}$$

followed by

$$\begin{bmatrix} 1 & 2 & 0 & -2 & -3 & 2b_1 - b_2 \\ 0 & 0 & 1 & 2 & 3 & b_2 - b_1 \\ 0 & 0 & 0 & 0 & 0 & 2b_1 - b_2 + b_3 \end{bmatrix}.$$

(a) We read the special solutions as follows:

$$x_1 = \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, x_2 = \begin{bmatrix} 2 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}, x_3 = \begin{bmatrix} 3 \\ 0 \\ -3 \\ 0 \\ 1 \end{bmatrix}.$$

The complete solution to  $Ax = 0$  is  $x = c_1x_1 + c_2x_2 + c_3x_3$  for  $c_1, c_2, c_3 \in \mathbb{R}$ .

(b) Let

$$x_p = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Then  $Ax_p = (1, 2, 0)^T$ , so that the complete solution to  $Ax = (1, 2, 0)^T$  is  $x = x_p + c_1x_1 + c_2x_2 + c_3x_3$  for  $c_1, c_2, c_3 \in \mathbb{R}$ .

(c) We see there are two pivot columns in the Reduced Row Echelon Form of  $A$  and so the rank of  $A$  is 2. Thus

$$\dim C(A) = \dim C(A^T) = 2, \quad \dim N(A) = 5 - 2 = 3, \quad \dim N(A^T) = 3 - 2 = 1.$$

(d) To give a basis for  $A$  we read off the columns corresponding to pivot columns in the Reduced Row Echelon Form of  $A$ :

$$\left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \right\}.$$

We have already computed a basis for  $N(A)$  in (a):  $\{x_1, x_2, x_3\}$ .

To give a basis for  $C(A^T)$ , we find two independent rows:

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \\ 2 \\ 3 \end{bmatrix} \right\}.$$

To give a basis for  $N(A^T)$ , we read off the coefficients of the relation  $2b_1 - b_2 + b_3 = 0$ :

$$\left\{ \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \right\}.$$

4. (14 points) Let

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 6 & 4 \\ 0 & 4 & 11 \end{bmatrix}.$$

(a) Find the symmetric factorization of  $A = LDL^T$ .

(b) Use the Gauss-Jordan method to find  $A^{-1}$ .

(14 分) 假设

$$A = \begin{bmatrix} 1 & 2 & 0 \\ 2 & 6 & 4 \\ 0 & 4 & 11 \end{bmatrix}.$$

(a) 求  $A$  的一个  $LDL^T$  分解.

(b) 用高斯约旦方法求  $A$  的逆矩阵,  $A^{-1}$ .

**Solution.** (a) The symmetric factorization of  $A$  is:

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & 2 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}$$

(b) The inverse of  $A$  is

$$\begin{bmatrix} \frac{25}{3} & -\frac{11}{3} & \frac{4}{3} \\ -\frac{11}{3} & \frac{11}{6} & -\frac{2}{3} \\ \frac{4}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix}.$$

5. (15 points) Let

$$A = \begin{bmatrix} -1 & 1 & 0 \\ 1 & -2 & 1 \\ 1 & -1 & 2 \\ 1 & -1 & -2 \end{bmatrix}, \quad b = \begin{bmatrix} 2 \\ -2 \\ -1 \\ 3 \end{bmatrix}.$$

- (a) Explain why  $Ax = b$  is inconsistent.
- (b) Find the least squares solution to  $Ax = b$ .
- (c) Split  $b$  into a column space component  $x_c$  and a left nullspace component  $x_l$ , i.e.,  $b = x_c + x_l$ .

(15 分) 设

$$A = \begin{bmatrix} -1 & 1 & 0 \\ 1 & -2 & 1 \\ 1 & -1 & 2 \\ 1 & -1 & -2 \end{bmatrix}, \quad b = \begin{bmatrix} 2 \\ -2 \\ -1 \\ 3 \end{bmatrix}.$$

- (a) 说明为什么线性方程组  $Ax = b$  没有解.
- (b) 求  $Ax = b$  的最小二乘解.
- (c) 把  $b$  分解成一个列空间分量  $x_c$  和一个左零空间分量  $x_l$ , 换言之,  $b = x_c + x_l$ .

**Solution.** (a) Gaussian elimination shows that  $Ax = b$  is inconsistent.

(b) We consider the normal equations:

$$A^T A \hat{x} = A^T b.$$

$$\begin{bmatrix} 4 & -5 & 1 \\ -5 & 7 & -2 \\ 1 & -2 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2 \\ 4 \\ -10 \end{bmatrix}.$$

$$\hat{x} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}.$$

(c)

$$b = \begin{bmatrix} 2 \\ -2 \\ -1 \\ 3 \end{bmatrix} = A\hat{x} + (b - A\hat{x}) = \begin{bmatrix} 0 \\ -2 \\ -2 \\ 2 \end{bmatrix} + \begin{bmatrix} 2 \\ 0 \\ 1 \\ 1 \end{bmatrix} = x_c + x_l.$$

6. (10 points) The space of all  $2 \times 2$  real matrices, denoted  $\mathbb{R}^{2 \times 2}$ , has the four basis “vectors”

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

Define the transformation of transposing from  $\mathbb{R}^{2 \times 2}$  to  $\mathbb{R}^{2 \times 2}$  as follows:

$$T(X) = X^T.$$

(a) Show that  $T$  is a linear transformation.

(b) Find the matrix  $A$  representing  $T$  with respect to the above basis for  $\mathbb{R}^{2 \times 2}$ .

(c) Explain why  $A^2 = I$ .

(10 points) 包含所有  $2 \times 2$  实矩阵的向量空间  $\mathbb{R}^{2 \times 2}$  有以下四个基向量

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}.$$

从  $\mathbb{R}^{2 \times 2}$  到  $\mathbb{R}^{2 \times 2}$  的转置变换定义如下:

$$T(X) = X^T.$$

(a) 证明  $T$  是一个线性变换.

(b) 找出线性变换  $T$  在上述基向量组下的矩阵表示,  $A$ .

(c) 为什么有  $A^2 = I$ ? 说明理由.

**Solution.** (a) By definition. (b) The matrix representation is

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

(c)  $A$  is a permutation matrix, which is formed by exchanging the second row and third row of the 4 by 4 identity matrix, therefore  $A^2 = I$ .



7. (10 points)

(a) Let  $v_1, v_2, \dots, v_m$  be linearly independent vectors in  $\mathbb{R}^n$  ( $n > m$ ), and

$$A = \begin{bmatrix} v_1^T \\ v_2^T \\ \vdots \\ v_m^T \end{bmatrix}.$$

It follows that  $A$  is an  $m \times n$  matrix with rank  $m$ . Let

$$w_1, w_2, \dots, w_{n-m}$$

be a sequence of linearly independent vectors in  $\mathbb{R}^n$  satisfying

$$Aw_j = 0, \quad j = 1, 2, \dots, n-m.$$

Show that

$$v_1, v_2, \dots, v_m, w_1, w_2, \dots, w_{n-m}$$

are linearly independent.

(b) Let  $A$  be an  $n \times n$  real matrix and  $A^T$  be its transpose. Show that the column spaces of  $A^T A$  and  $A^T$  are the same, i.e.,  $C(A^T A) = C(A^T)$ .

(10 分)

(a) 如果  $v_1, v_2, \dots, v_m$  是  $\mathbb{R}^n$  中的线性无关向量( $n > m$ ). 假定

$$A = \begin{bmatrix} v_1^T \\ v_2^T \\ \vdots \\ v_m^T \end{bmatrix}.$$

由此可见,  $A$  是一个  $m \times n$  行满秩矩阵. 如果  $\mathbb{R}^n$  中线性无关向量组

$$w_1, w_2, \dots, w_{n-m}$$

满足  $Aw_j = 0, \quad j = 1, 2, \dots, n-m$ . 证明:

$$v_1, v_2, \dots, v_m, w_1, w_2, \dots, w_{n-m}$$

线性无关.

(b) 设  $A$  为一个  $n \times n$  实矩阵,  $A^T$  为它的转置. 证明:  $A^T A$  和  $A^T$  的列空间相同, 换言之,  $C(A^T A) = C(A^T)$ .

**Solution.** (a) Suppose

$$a_1 v_1 + a_2 v_2 + \cdots + a_m v_m + b_1 w_1 + b_2 w_2 + \cdots + b_{n-m} w_{n-m} = 0.$$

If we let  $a_1 v_1 + a_2 v_2 + \cdots + a_m v_m = v$  and  $b_1 w_1 + b_2 w_2 + \cdots + b_{n-m} w_{n-m} = w$ , the above equality becomes

$$v + w = 0.$$

Note that  $v \in C(A^T)$  and  $w \in N(A)$ . Taking inner product of  $v$  with respect to both sides of the equation above to obtain

$$v^T(v + w) = v^T 0 = 0.$$

Since  $C(A^T)$  and  $N(A)$  are a pair of orthogonal complements,  $v$  is orthogonal to  $w$ , the above equation becomes  $v^T v = 0$ , this only happens when  $v = 0$ . It follows immediately that  $w = 0$ . In other words,

$$a_1 v_1 + a_2 v_2 + \cdots + a_m v_m = 0, \quad b_1 w_1 + b_2 w_2 + \cdots + b_{n-m} w_{n-m} = 0.$$

Since  $v_1, v_2, \cdots, v_m$  and  $w_1, w_2, \cdots, w_{n-m}$  are linearly independent, therefore all  $a$ 's and  $b$ 's are zero. Thus

$$v_1, v_2, \cdots, v_m, w_1, w_2, \cdots, w_{n-m}$$

are linearly independent.

(b) Since the column space of  $A^T A$  is contained in the column space of  $A^T$ , it is sufficient to prove that  $\dim C(A^T A) = \dim C(A^T)$ . We know that  $\dim(C(A^T)) = \text{rank}(A)$  and that

$$\dim C(A^T) + \dim N(A) = n, \quad \dim C(A^T A) + \dim N(A^T A) = n.$$

Since the nullspaces of  $A^T A$  and  $A$  are the same, and therefore  $\dim N(A^T A) = \dim N(A)$ . The above equalities imply that

$$\dim C(A^T A) = \dim C(A^T).$$

This completes the proof.