Suggested Solutions. Nov. 12 2023

Question 1:

Question Z:

$$(2) - A^{\dagger} C B^{-1}$$
.

$$(3) | 6r - 3.$$

$$(4) \qquad \begin{bmatrix} \frac{19}{11} \\ -\frac{5}{11} \end{bmatrix}$$

(5)
$$\frac{1}{\sqrt{6}}\begin{bmatrix}1\\2\\1\end{bmatrix}$$
 or $-\frac{1}{\sqrt{6}}\begin{bmatrix}1\\2\\1\end{bmatrix}$.

Question 3.

(a) A hasis for
$$C(A)$$
: $\left\{\begin{bmatrix}1\\0\\-1\\2\end{bmatrix},\begin{bmatrix}2\\1\\0\end{bmatrix},\begin{bmatrix}3\\3\end{bmatrix}\right\}$

A basis for
$$C(A^T)$$
: $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$
or $\left\{ \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$
A basis for $N(A)$: $\left\{ \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} -3 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$

A basis for
$$N(A^T)$$
:
$$\left\{ \begin{bmatrix} -5 \\ 13 \\ -3 \\ 1 \end{bmatrix} \right\}$$

$$\begin{pmatrix}
b \\
2 \\
1 \\
2
\end{pmatrix}$$

Question 4:

Gaussian Eliminations give:

$$\begin{bmatrix} 1 & -1 & -1 & 2 & 2 \\ 2 & a & 1 & 1 & a \\ -1 & 1 & a & 1 & -a-1 & -2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & -1 & -1 & 1 & 2 & 2 \\ 0 & a+2 & 3 & 1 & -3 & a-4 \\ 0 & 0 & a-1 & 1 & 0 & 0 \end{bmatrix}$$

- . If a = -2, then rank A = 2 * 3 = rank(A;B), AX = B has no solution.
- · If a = 1 and a = -1, AX = B has a unique solution

$$\begin{bmatrix} 1 & -1 & -1 & 1 & 2 \\ 0 & a+2 & 3 & 1 & -3 \\ 0 & 0 & a-1 & 1 & 1-a \end{bmatrix} = \Rightarrow \quad X = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & -1 & 1 & 2 \\ 0 & a+2 & 3 & 1 & a-4 \\ 0 & 0 & a-1 & 0 \end{bmatrix} \Rightarrow X = \begin{bmatrix} \frac{3a}{a+2} \\ \frac{a-4}{a+2} \\ 0 \end{bmatrix}$$

· If a=1, Ax = B has infinitely many solutions.

$$\begin{bmatrix} 1 & -1 & -1 & 2 \\ 0 & 3 & 3 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \times = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + k_1 \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 & -1 & 1 & 2 \\ 0 & 3 & 3 & 1 & -3 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \implies X = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + k_2 \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

=>
$$\times = \begin{bmatrix} 1 & 1 \\ -k_1-1 & -k_2-1 \\ k_1 & k_2 \end{bmatrix}$$
, k_1 , k_2 arbitrary constants.

Question 5:

$$T(cx+Y) = \begin{bmatrix} t_{Y} A^{T}(cx+Y) \\ t_{Y} B^{T}(cx+Y) \end{bmatrix}$$

$$= c \begin{bmatrix} tv(A^TX) \\ tv(B^TX) \end{bmatrix} + \begin{bmatrix} tv(A^TX) \\ tv(B^TY) \end{bmatrix}$$

$$= c T(X) + T(Y).$$

$$= W_2 \qquad W_3$$

(b)
$$T(V_i) = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = 1 \cdot \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$T(V_2) = \begin{bmatrix} -1 \\ 0 \end{bmatrix} = -1 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 0 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$T(V_3) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$T(V_4) = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = 0 \begin{bmatrix} 0 \\ 0 \end{bmatrix} + 1 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix} + -1 \cdot \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Therefore, the matrix representation of T with respect to

$$V_1, V_2, V_3, V_4$$
 and W_1, W_2, W_3 is: $\begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 \end{bmatrix}$.

(c) Since
$$T(A) = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$
, $T(B) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, $T(C) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$,

We can take X to be

$$= \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & -\frac{1}{2} \end{bmatrix} - \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{2} - \frac{2}{2} \\ 1 - \frac{1}{2} \end{bmatrix}.$$

Question 6.

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Apply Elementary Row and Column Operations to A and E to obtain $D_1 = \begin{bmatrix} Ir & 0 \\ 0 & 0 \end{bmatrix}$ for A and $D_2 = \begin{bmatrix} Is & 0 \\ 0 & 0 \end{bmatrix}$

Where r = rank A s = rank B.

Let M = [AB]. Then M can be converted

to $M_1 = \begin{bmatrix} P_1 & C_1 \\ O & P_2 \end{bmatrix}$ via elementary row and column operations.

Furthermore, the pivots in D, and Dz can be used to eliminate the nonzero entries in C, to obtain

$$M_{2} = \begin{bmatrix} J_{r} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{2} \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

In conclusion,

rank $M = rank M_1 = rank M_2 = r + s + rank C_2 \ge r + s$ = rank A + rank C

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