

Tutorial for chapter 5

Key words of chapter 5

Net force

Superposition 重合

Interact

Equilibrium

Stationary

Inertial reference frame

Relative motion

Free body diagram

Gravitational force

Normal force

Negligible

Tension

Frictional force (friction)

Frictionless

Ignore

Massless

Tangent

Ramp 斜坡

Inclined

External force

Internal force

Orthogonal axis
0 垂直的

Review-Newton's three laws

- **Newton's three mechanics laws**

only valid in inertial reference frame (like ground), tension, normal force, gravitational force, frictional force...

- ◆ **Newton's First Law (Law of Inertia)**

- ◆ **Newton's Second Law** $\vec{F}_{net} = m\vec{a}$

$$F_{net,x} = ma_x \quad F_{net,y} = ma_y \quad F_{net,z} = ma_z$$

- ◆ **Newton's Third Law**

When two bodies interact, the forces on the bodies from each other are always **equal** in **magnitude** and **opposite** in **direction**.

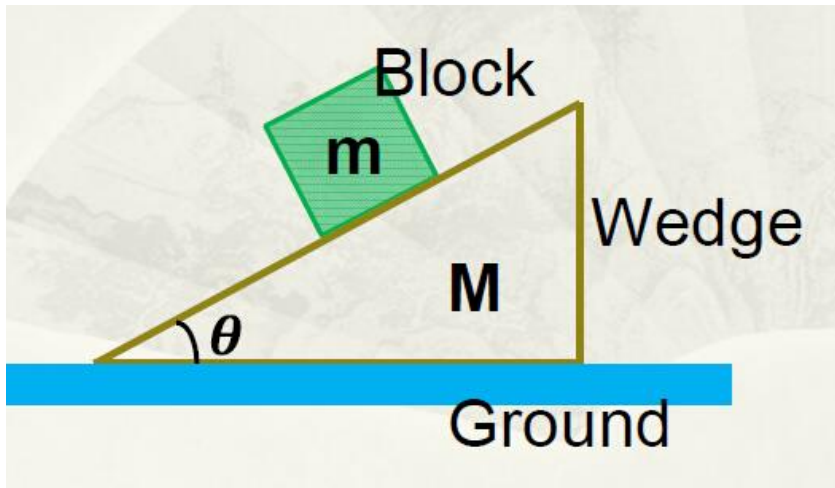
Review—Applying Newton's second law

Applying Newton's second law to relate the net force and the motion of moving objects:

- 1, Identify the target body (or bodies)
- 2, Draw the F.B.D for the targets (tension, normal force, gravitational force, frictional force---)
- 3, Set up a proper coordinates system (be convenient for solving problem)
- 4, Resolving forces along axes , write component equations of Newton's second law and solve the quantities what you want
- 5, When component equations of Newton's second law are not enough to figure out the unknown quantities, you have to find other equations (for example, the relationship between accelerations) by analyzing the motion of each object.

Tutorial Problem 1

As shown in the figure, a block of **mass m** is placed on the inclined plane of a wedge. The wedge is then placed on the ground. The mass of wedge is **M** and the angle between its inclined surface and ground is **θ** .



Given the inclined surface of the wedge and the ground surface are **both frictionless**, find **accelerations** of the wedge and the block **with respect to the ground**.

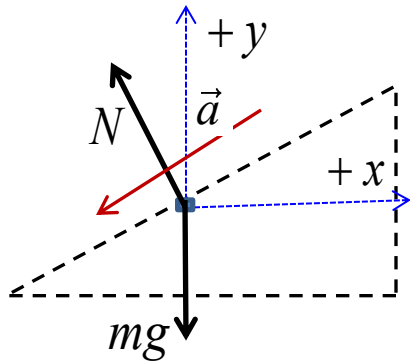
Solution 1

Known: m, M , inclined angle θ

Find: Acceleration $\vec{a}_{B,G}$ with respect to (w.r.t) ground

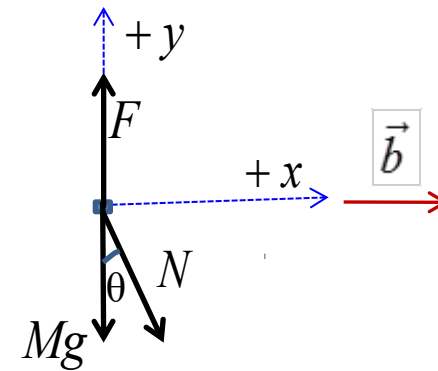
Acceleration \vec{b} with respect to ground

F.B.D of Block



No motion w.r.t wedge \perp inclined plane
w.r.t wedge is $//$ inclined plane
 \vec{a} point down along inclined plane

F.B.D of wedge



Perpendicular to the ground: no motion
So \vec{b} is parallel to the ground
Assuming \vec{b} point $+x$ direction

Set up a coordinates system in which right and vertical up are positive direction

Solution 1

Applying Newton's 2nd law to the wedge:

$$N_x = N \sin \theta = Mb \dots \dots \dots (1)$$

Applying Newton's 2nd law to the block:

$$\vec{N} + \vec{G} = m\vec{a}$$



WRONG!!

\vec{a} is w.r.t wedge, which moves with acceleration, so wedge is **not** an **inertial reference frame**. **Newton's Law can only be applied in inertial reference frame, like ground**

Solution 1

According to relative motion:

$$\vec{a}_{B,G} = \vec{a}_{B,W} + \vec{a}_{W,G} \Rightarrow \vec{a}_{B,G} = \vec{a} + \vec{b} \quad \vec{a}_{B,G} \text{ is acceleration of block w.r.t ground}$$

Applying Newton's 2nd law for the block:

$$\vec{N} + \vec{G} = m\vec{a}_{B,G}$$

$$\begin{aligned} x \text{ component: } N_x + G_x &= ma_{B,Gx} = m(a_x + b_x) \\ -N \sin \theta + 0 &= m(-a \cos \theta + b) \dots \dots \dots (2) \end{aligned}$$

$$\begin{aligned} y \text{ component: } N_y + G_y &= ma_{B,Gy} = m(a_y + b_y) \\ N \cos \theta - mg &= m(-a \sin \theta + 0) \dots \dots \dots (3) \end{aligned}$$

$$N_x = N \sin \theta = Mb \dots \dots \dots (1)$$

Solution 1

Solving
eqs (1),
(2'), (3')

$$\left\{ \begin{array}{l} a = \frac{m+M}{M+m\sin^2\theta} g \sin\theta \\ b = \frac{m\cos\theta}{M+m\sin^2\theta} g \sin\theta \\ N = \frac{M}{M+m\sin^2\theta} mg \cos\theta \end{array} \right.$$

Discussion:

$M \rightarrow \infty$, Wedge almost stuck on the ground,
block slides down like along a fixed inclined plane,
we see:

$$a \rightarrow g \sin\theta$$

$$b \rightarrow 0$$

$$N \rightarrow mg \cos\theta$$

$$\alpha_x = a_x + b_x = -a \cos\theta + b = -\frac{M \cos\theta}{M+m\sin^2\theta} g \sin\theta$$

$$\alpha_y = a_y + b_y = -a \sin\theta + 0 = -\frac{m+M}{M+m\sin^2\theta} g \sin^2\theta$$

$$\tan\phi = \frac{\alpha_y}{\alpha_x} = \frac{m+M}{M} \tan\theta > \tan\theta$$

$$\alpha = \sqrt{\alpha_x^2 + \alpha_y^2} = \sqrt{M^2 \cos^2\theta + (m+M)^2 \sin^2\theta} \frac{g \sin\theta}{M+m\sin^2\theta}$$

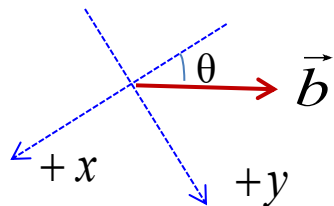
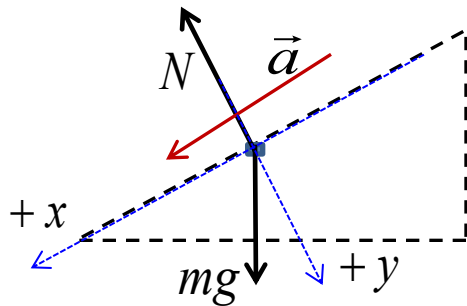
$\phi > \theta$, $\vec{\alpha}$ is not parallel to the inclined plane unless $M \rightarrow \infty$

Solution 1

Alternatively, we can use the coordinate system with axis \perp and \parallel inclined plane for the block, i.e x -axis down along ramp. In this coordinate system:

\vec{a} is in positive x direction.

\vec{b} has two components: $b_x = -b \cos \theta$, $b_y = b \sin \theta$



Applying Newton's 2nd law:

$$\vec{N} + \vec{G}_g = m\vec{a}$$

$$x \text{ component: } N_x + G_x = ma_{BG,x} = m(a_x + b_x)$$

$$0 + mg \sin \theta = m(a - b \cos \theta) \dots \dots \dots (2')$$

$$y \text{ component: } N_y + G_y = ma_{BG,y} = m(a_y + b_y)$$

$$-N + mg \cos \theta = m(0 + b \sin \theta) \dots \dots \dots (3')$$

$$N_x = N \sin \theta = Mb \dots \dots \dots (1)$$

Solution 1

Solving eqs (1), (2'), (3'):

$$a = \frac{m + M}{M + m \sin^2 \theta} g \sin \theta$$

$$b = \frac{m \cos \theta}{M + m \sin^2 \theta} g \sin \theta$$

$$N = \frac{M}{M + m \sin^2 \theta} mg \cos \theta$$

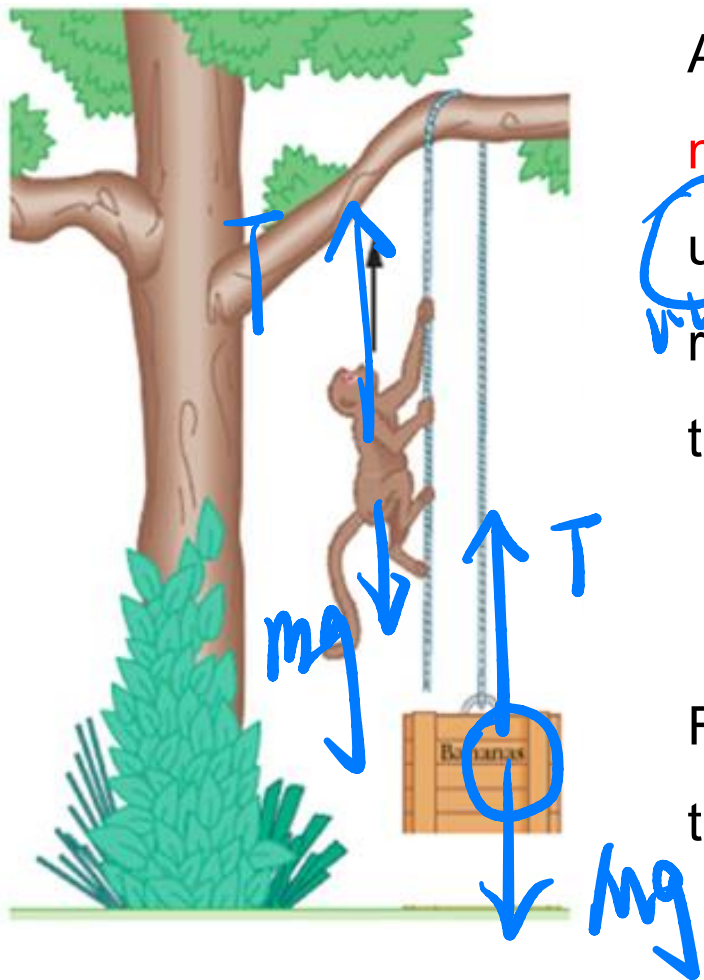
$$a_{BG,x} = a_x + b_x = a - b \cos \theta = g \sin \theta$$

$$a_{BG,y} = a_y + b_y = a + b \sin \theta = g \sin \theta \frac{m \cos \theta \sin \theta}{M + m \sin^2 \theta}$$

$$a_{BG} = \sqrt{\alpha_x^2 + \alpha_y^2} \text{ will give the same answer as in the previous coordinate system}$$

Different coordinates system result the same answer

Tutorial Problem 2



As shown in the figure, a monkey of mass m is climbing on a massless rope with an up acceleration b relative to the rope. The rope runs over a frictionless tree limb with the other end tied with a crate of mass M .

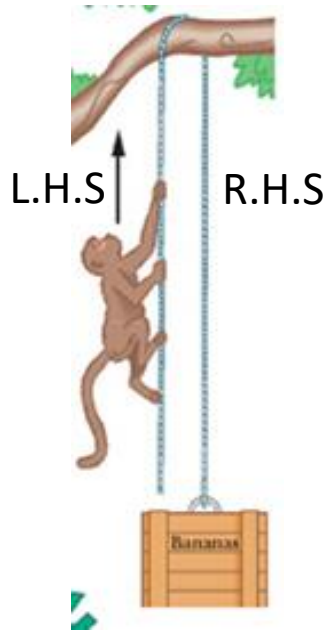
对绳子的加速度
向上为 b

设 \uparrow
 $a \uparrow$

公式列对!

Find the accelerations of the monkey and the crate with respect to the ground.

Solution 2



Known: Mass of Monkey m ,
Mass of crate M ,

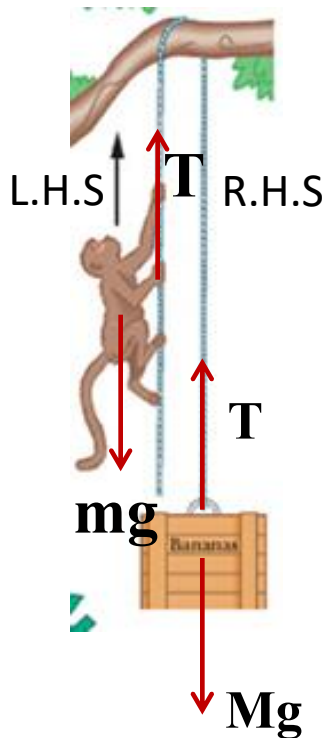
Monkey's acceleration with respect to rope \vec{b}

Find: Acceleration of crate respect to ground \vec{a}_{CG}
Acceleration of monkey respect to ground \vec{a}_{MG}

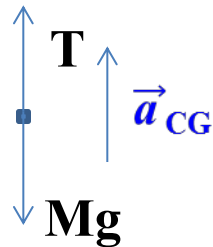
We take the upward to be the positive direction for the monkey and crate. Assuming acceleration of the crate points upward, so does acceleration of the rope with respect to the ground at R.H.S of the tree limb, then the acceleration of the rope with respect to the ground at L.H.S of the tree limb is ?

$$\vec{a}_{RG} = -\vec{a}_{CG}$$

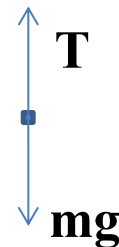
Solution 2



F.B.D of crate:



F.B.D of monkey:



Applying Newton's 2nd law:

$$T - Mg = Ma_{CG} \dots \dots \dots (1)$$

$$T - mg = ma_{MG} \dots \dots \dots (2)$$

According to relative motion:

$$\vec{a}_{MG} = \vec{a}_{MR} + \vec{a}_{RG} = \vec{b} - \vec{a}_{CG}$$

$$\Rightarrow a_{MG} = b - a_{CG} \dots \dots \dots (3)$$

Solution 2

$$(1)+(2)+(3) \Rightarrow a_{CG} = \frac{m-M}{m+M}g + \frac{m}{m+M}b$$

$$a_{MG} = b - a_{CG} = \frac{M-m}{m+M}g + \frac{M}{m+M}b$$

Discussion:

1) Given $b=g/2$, $M=2m$, we have:

$a_{CG} = -g/6$ w.r.t ground, crate's acceleration of $g/6$, downward

$a_{MG} = 2g/3$ w.r.t ground, monkey's acceleration of $2g/3$, upward

2) Given $b=g/2$, $M=m$, we have

$a_{CG} = g/2$ w.r.t ground, crate's acceleration of $g/2$, upward

$a_{MG} = g/2$ w.r.t ground, monkey's acceleration of $g/2$, upward

Summary

Summary:

1) Newton's Law can only be applied in inertia reference frame

we must use the acceleration with respect to the inertia reference frame, like ground.

2) Choose proper coordinate:

Different coordinates system must result the same answer, but a proper coordinates system might be much more convenient in solving problems.

Tutorial for chapter 6

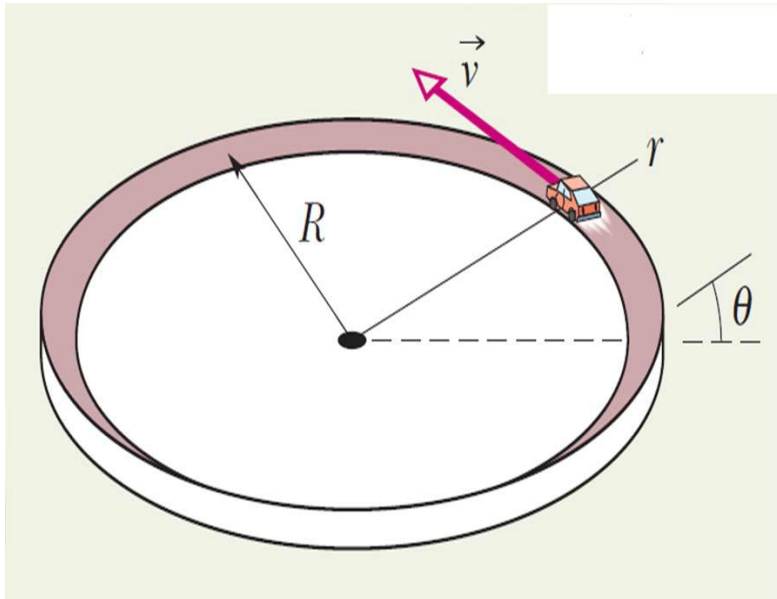
keywords

- Static friction ,
- Kinetic friction,
- Coefficient of friction,
- Fluid,
- Drag force,
- Terminal speed,
- Cross-sectional area,
- Spring force,
- Hooke's law,
- Microscopic,
- Weld,
- Contact,
- Verge,
- sky diver,
- flat track,
- banked track.

Review

- Friction
 - static frictional force and its maximum magnitude, magnitude of kinetic frictional force in relation with normal force,...
- Drag Force
 - Terminal speed
- Spring Force
 - Hooke's law
- Centripetal Force in Uniform Circular Motion
 - The radial component of the net force causing centripetal acceleration

Problem 3



A race car runs around a banked circular track with constant speed v . The bank inclines with an angle θ respect to the **level**. The mass of car is m and the coefficient of the static friction between car's tires and the bank surface is μ_s . The radius of the circular track is R .

Determine the maximum and the minimum speed for the car to remain in the track.



《工作记录》

<http://wanyi0523.photo.pconline.com.cn> 婉妹视角 **VICTORY**

2010.06.20 中国人民解放军总后勤部定远汽车试验场



Solution1:

Direction of the static friction is undetermined. It could either up or down along the banked track.

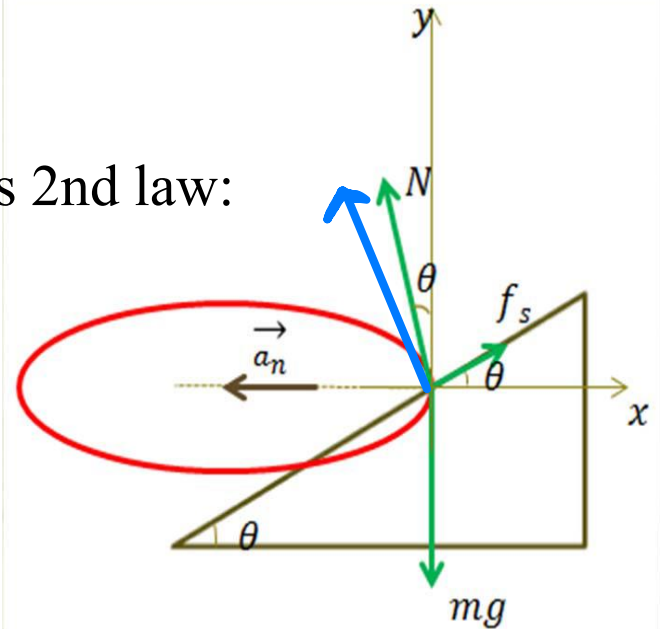
1) f_s up along the banked track

We can get two equations applying Newton's 2nd law:

$$y: N \cos \theta + f_s \sin \theta - mg = 0 \dots (1)$$

$$x: -N \sin \theta + f_s \cos \theta = -n \frac{v^2}{R} \dots (2)$$

符号



Centripetal force is due to a combination of the horizontal components of the normal force and the static friction.

Solution1:

$$(1) + (2) \Rightarrow m \frac{v^2}{R} = mg \tan \theta - f_s \frac{1}{\cos \theta} \text{ as } f_s \text{ increase, } v \text{ decrease.}$$

When $f_s = f_{s,\max} = \mu_s N$, we have minimum v

$$Eq.(1) \Rightarrow \frac{f_{s,\max}}{\mu_s} \cos \theta - mg + f_{s,\max} \sin \theta = 0$$

$$f_{s,\max} = \frac{mg}{\left(\frac{\cos \theta}{\mu_s} + \sin \theta \right)}$$

$$\begin{aligned}
 \Rightarrow m \frac{v_{\min}^2}{R} &= mg \tan \theta - f_{s, \max} \frac{1}{\cos \theta} \\
 &= mg \left(\tan \theta - \frac{1}{\cos \theta} \frac{1}{\frac{\cos \theta}{\mu_s} + \sin \theta} \right) \\
 &= mg \frac{\tan \theta - \mu_s}{1 + \mu_s \tan \theta}
 \end{aligned}$$

$$\therefore v_{\min} = \sqrt{gR \frac{\tan \theta - \mu_s}{1 + \mu_s \tan \theta}}$$

Solution1:

2) f_s down along the banked track

We can get two equations applying Newton's 2nd law:

$$x: -N \sin \theta - f_s \cos \theta = -m \frac{v^2}{R} \dots (2)$$

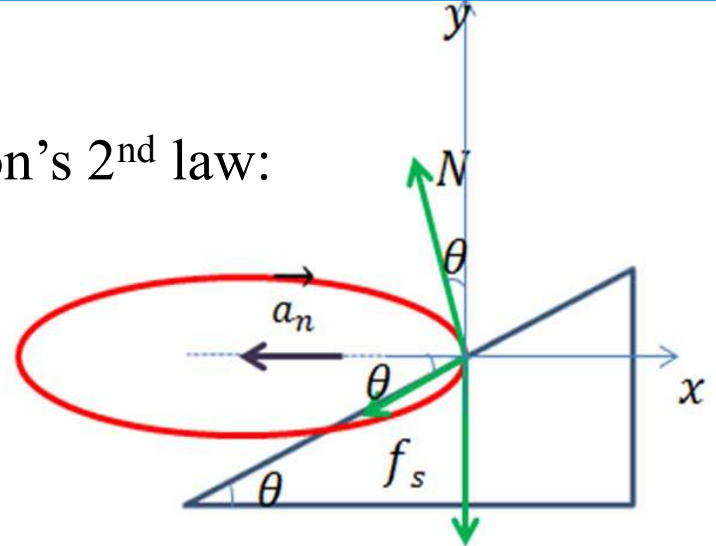
$$y: N \cos \theta - f_s \sin \theta - mg = 0 \dots (1)$$

$$(1), (2) \Rightarrow m \frac{v^2}{R} = mg \tan \theta + f_s \frac{1}{\cos \theta} \text{ as } f_s \text{ increase, } v \text{ increase.}$$

When $f_s = f_{s.\max} = \mu_s N$, we have maximum v .

$$\text{Eq. (1)} \Rightarrow \frac{f_{s.\max}}{\mu_s} \cos \theta - mg - f_{s.\max} \sin \theta = 0$$

$$\text{Therefore, } f_{s.\max} = mg / \left(\frac{\cos \theta}{\mu_s} - \sin \theta \right)$$



$$\begin{aligned}
 \Rightarrow m \frac{v_{\max}^2}{R} &= mg \tan \theta + f_{s, \max} \frac{1}{\cos \theta} \\
 &= mg \left(\tan \theta + \frac{1}{\cos \theta} \frac{1}{\cos \theta / \mu_s - \sin \theta} \right) = mg \frac{\tan \theta + \mu_s}{1 - \mu_s \tan \theta}
 \end{aligned}$$

$$\therefore v_{\max} = \sqrt{gR \frac{\tan \theta + \mu_s}{1 - \mu_s \tan \theta}}$$

summary

Exercise: Ch6-56

$$v_{\min} = \sqrt{gR \frac{\tan \theta - \mu_s}{1 + \mu_s \tan \theta}}$$

$$v_{\max} = \sqrt{gR \frac{\tan \theta + \mu_s}{1 - \mu_s \tan \theta}}$$

极端
情况讨论

We can also meet the conditions of $\mu_s < \tan \theta$ and $\mu_s < \cot \theta$

If static friction is negligible as the sample problem 6-2 discussed in class, we get the speed $v_{\max} = \sqrt{gR \tan \theta}$

Discussion: As the speed of the car increases from the minimum to a maximum, the static friction evolves from a maximum magnitude up along the ramp to a maximum magnitude down along the banked track.