

13. Oszillatoren. 正弦波振荡器.

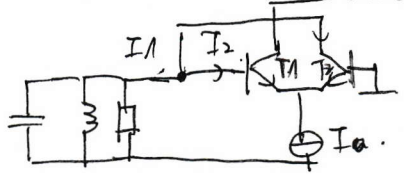
基本原理.

设开环放大倍数 $K(s) = \frac{U_o(s)}{U_i(s)}$, 反馈系数 $F(s) = \frac{U_f(s)}{U_o(s)}$, 闭环 $K_{cl}(s) = \frac{U_o(s)}{U_i(s)}$

$$U_i(s) = U_s(s) + U_f(s) \Rightarrow U_s(s) = U_i(s) - U_f(s)$$

$$K_{cl}(s) = \frac{U_o}{U_i - U_f(s)} = \frac{U_o/U_i}{1 - \frac{U_f(s)}{U_i(s)}} = \frac{K(s)}{1 - F(s) \cdot K(s)} \Rightarrow \text{自激振荡 } F(s)K(s) = 1, \text{ 则没有输入电路也能振荡.}$$

Beispielerschaltung



$$I_1 = -I_2 \Rightarrow I_1 + I_2 = 0 \Rightarrow U_1 + U_2 = 0.$$

$$Y_1 = \frac{1}{R} + j\omega C + \frac{1}{j\omega L} \quad Y_2 \text{ 用节点信号分析 (线性化等效)}$$

$$Y_2 = \frac{1}{R_{eq1}} + g_{m2}.$$

$$i_2 = \frac{U}{2} g_{m2} \cdot (-1) = -\frac{U}{2} g_{m2} \Rightarrow Y_2 = -\frac{g_{m2}}{2} = -\frac{I_0}{4U_T}$$

$$\Rightarrow \frac{1}{R} = \frac{I_0}{4U_T}, \quad I_0 = \frac{4U_T}{R}, \quad j\omega C + \frac{1}{j\omega L} = 0 \Rightarrow -\omega^2 CL + 1 = 0 \Rightarrow \omega_c = \frac{1}{\sqrt{LC}}$$

非线性分析. 由路方程

$$I_1 = \frac{U}{R} + \frac{1}{L} \int U dt + C \frac{dU}{dt} \quad I_2 = \frac{I_0}{2} (1 - \tanh \frac{U}{2U_T})$$

$$\Rightarrow I_1 + I_2 = 0, \quad \frac{dI_1}{dt} + \frac{dI_2}{dt} = 0 \quad 0 = \frac{1}{R} \frac{dU}{dt} + \frac{1}{L} U + C \frac{d^2 U}{dt^2} - \frac{I_0}{4U_T} (1 - \tanh^2 \frac{U}{2U_T}) \frac{dU}{dt}$$

$$\Rightarrow U + \frac{1}{R} [1 - \frac{I_0 R}{4U_T} (1 - \tanh^2 (\frac{U}{2U_T}))] \frac{dU}{dt} + LC \frac{d^2 U}{dt^2} = 0$$

$$\Rightarrow \frac{d^2 U}{dt^2} + \frac{1}{RC} [1 - \frac{I_0 R}{4U_T} (1 - \tanh^2 (\frac{U}{2U_T}))] \frac{dU}{dt} + \frac{1}{LC} U = 0$$

产生正弦振荡. $U = U_m \cos \omega t$, $U = U_m \sin \omega t \Rightarrow g_1 e^{j\omega t} + g_2 e^{-j\omega t}$. 其中 $1 - \frac{I_0 R}{4U_T} [1 - \tanh^2 (\frac{U}{2U_T})] = 0$

$$\begin{cases} 0 = \tanh^2 (\frac{U}{2U_T}) \\ 1 = \frac{I_0 R}{4U_T} \end{cases} \Rightarrow \begin{cases} U = 0 \\ I_0 = 4U_T/R \end{cases}$$

$$\Rightarrow U = \hat{U}_1 \sin \omega t, \quad f_1 = \frac{1}{2\pi \sqrt{LC}}$$

非线性网络. 用泰勒级数展开 $(-1)^n$, $N(j\omega)$, 非线性元件的等效. 由线性网络的阻抗.

$$I_2 = F(U) = -\frac{I_0}{2} (1 - \tanh \frac{\hat{U}_1 \sin \omega t}{2U_T}), \quad a_1 = 0, \quad b_1 = -\frac{I_0}{2\pi} \int_0^{2\pi} (1 - \tanh \frac{\hat{U}_1 \sin \omega t}{2U_T}) \sin \omega t dt$$

$$N(j\omega) = \frac{b_1}{\hat{U}_1}, \quad G(j\omega) = \frac{1}{R} + \frac{1}{j\omega C} + j\omega L \Rightarrow \frac{1}{j\omega C} + j\omega L = 0 \Rightarrow f = \frac{1}{2\pi \sqrt{LC}}$$

$$\Rightarrow \frac{b_1}{\hat{U}_1} \cdot R = 1 \Rightarrow b_1 = \frac{\hat{U}_1}{R} = \frac{I_0}{2\pi} \int_0^{2\pi} \tanh \frac{\hat{U}_1 \sin \omega t}{2U_T} \sin \omega t dt.$$

$$1 = \frac{I_0}{\hat{U}_1} \frac{\hat{U}_1}{R} = \frac{I_0}{R} \cdot \frac{2U_T}{\hat{U}_1} \frac{\hat{U}_1}{2U_T} = \frac{I_0}{R} \frac{2U_T}{\hat{U}_1} \frac{\hat{U}_1}{2U_T}$$

$$\rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \int_0^{2\pi} [\tanh(y \sin a)] \sin a da - 1 = 0. \text{ 其中, } y = \frac{\hat{U}_1}{2U_T}, \quad x = \frac{I_0 R}{4U_T}.$$

① \tanh -阶近似 $\tanh(x) \approx x \Rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \cdot y \cdot \frac{1}{2} \cdot 2\pi - 1 = 0, \quad x = 1, \quad y \text{ muss klein sein.}$

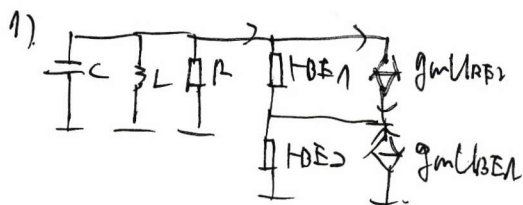
② $\tanh = 2$ 阶. $\tanh(x) \approx x - \frac{x^3}{3} \Rightarrow \frac{x}{y} \cdot \frac{1}{\pi} \int_0^{2\pi} [y \sin^2 a - \frac{y^3 \sin^4 a}{3}] da = \frac{x}{y} \cdot \frac{1}{\pi} \cdot (y \cdot \pi - \frac{y^3}{3} \cdot \frac{3\pi}{8}) - 1 = 0$

③ $\tanh \approx 3$ 阶 $\tanh(x) \approx x - \frac{x^3}{3} + \frac{2x^5}{15}$, $x + x^2 \cdot \frac{2}{15} - \frac{1}{3} \cdot y^4 \cdot \frac{11}{24} - 1 = 0 \Rightarrow x > 1, \quad x < \frac{16}{13}$

大信号 $\tanh(x) = \pm 1 \Rightarrow \hat{U}_1 = \frac{2}{\pi} R I_0$ $I_0 > \frac{4U_T}{R}, \quad \hat{U}_1 = 0, \quad I_0 < \frac{4U_T}{13R} = 42.2 \mu A$ $\frac{1}{4} - 12(1 - \frac{1}{x}) > 0$ $\hat{U}_1 = 63.4 \text{ mV.}$

$$\sin^n x = \begin{cases} \frac{2^{n-1} - 1}{2^{n-1}} \cdot \frac{1}{2} \cdot 2\pi & n=2m \\ 0, & n=2m+1 \end{cases}$$

02-01



$$g_m = \frac{I_0}{2U_T} \quad U_{BE1} = \frac{U}{2} \quad U_{BE2} = -\frac{U}{2}$$

$$1 = \frac{U}{I_2} = \frac{U}{\frac{U}{2} \cdot \frac{I_0}{2U_T}} = \frac{4U_T}{I_0} \quad |A| = |1| \Rightarrow I_0 = \frac{4U_T}{1} = 34.7 \mu A$$

$$g_m = 0.67 mS$$

17 $f_1 = \frac{1}{2\pi\sqrt{LC}} \Rightarrow C = 2.133 nF$

02-02

1) $Z = \frac{1}{j\omega C + \frac{1}{j\omega L + \frac{1}{j\omega C + R}}}$, cp reaktive $Z = j\omega L + \frac{1}{j\omega C + R}$ cp-Verstärkungswirkung
 $\omega_0 = \frac{1}{2\pi\sqrt{LC}} = 100,32 kHz$ $Q = \frac{\omega_0 L}{R} = \frac{1}{\omega_0 R C} = \frac{L}{R\sqrt{LC}} = \frac{1}{R} \cdot \sqrt{\frac{L}{C}} = 1.1$ $\omega_0 = \frac{1}{2\pi\sqrt{LC}}$

2) $U_a = I_D \cdot R_D + U_{ref}$
 $I_D = (U_2 - I_D \cdot R_S) / Z \cdot g_m$ $Z_S = \frac{1}{R_S + \frac{1}{j\omega L + \frac{1}{j\omega C + R}}}$ $Z_S \rightarrow V_1 = R_S$
 $\Rightarrow U_2 = \frac{I_D \cdot Z_S + U_1}{g_m}$ $U_a = U_2 \cdot \frac{g_m R_D}{g_m Z_S + 1} + U_{ref} \Rightarrow V \frac{g_m R_D}{g_m Z_S + 1} + \frac{U_{ref}}{U_2}$
 $Z_S \rightarrow V_2 = \frac{R_S \cdot R}{R_S + R}$

1. Fall $V_1 = 0.367$ 2. Fall $V_2 = 2.11$

3) $K = \frac{U_2}{U_a} = \frac{R_2}{R_1 + R_2} = \frac{1}{1 + \frac{R_1}{R_2}}$

$V_2 = \frac{U_2}{U_a} \cdot K \geq 1$ $\frac{R_1}{R_2} + 1 = V_2$ $\frac{R_1}{R_2} = V_2 - 1 = 1.11$

4) $U_a = U_2 \cdot \frac{1}{1 + \frac{R_1}{R_2}} \cdot U_a + U_{ref}$
 $U_{ref} = I_D \cdot R_S = U_a \frac{R_1}{R_1 + R_2} \Rightarrow U_a = I_D \cdot R_S \cdot (1 + \frac{R_2}{R_1}) = U_a = I_D \cdot R_S \cdot V_2 = 37 \mu V$
 $U_a - U_{ref} = I_D \cdot R_D \Rightarrow U_{ref} = U_a - I_D \cdot R_D = 1.44 \mu V$ $= 1.44 \mu V$

[Zusatz] U_{ref} ist die Differenzspannung zwischen den beiden Eingangsanschlüssen. U_{ref} ist die Differenzspannung zwischen den beiden Eingangsanschlüssen.

02-03

1) $Y_1 = \frac{1}{R} + j\omega C + \frac{1}{j\omega L}$ $f_1 = \frac{1}{2\pi\sqrt{LC}} = 1 MHz$ (1000 + 8.154 Hz)

2) $G(j\omega) = R$ $N(j\omega) = \frac{I_2}{U} = \frac{-I_0}{2\pi\omega_1} \int_0^{2\pi} \tanh(\frac{\omega_1}{2\omega_T} \sin m\tau) \sin m\tau d\tau$
 $|G(j\omega)| \cdot |N(j\omega)| = 1$

3) ans Vorlesung

3.1) $I_0 = \frac{4U_T}{R} = 34.7 \mu A$

3.2) $U_0 = \frac{4U_T}{\sqrt{1 - \frac{4U_T}{R I_0}}} = 38 mV$

3.3) pos. Halbwelle I_2 sperren $I_2 = 0$
 neg. Halbwelle I_1 sperren $I_1 = I_0$

$\boxed{I_0 \rightarrow 0 I_0}$ bei T_1 und T_2 x2.

$2 \cdot \frac{x}{y} \cdot \frac{1}{2} \cdot \int_0^{2\pi} \sin a \cdot 1 > 0$ $y = \frac{4}{2\pi} x$
 $2 \cdot \frac{x}{y} \cdot \frac{1}{2} - 1 = 0$ $x = \frac{I_0 R}{4U_T}$ $y = \frac{I_0}{2U_T}$ $U_1 = 2U_T \cdot \frac{I_0 R}{4U_T} = \frac{I_0 R}{2} = 1.11 mV$