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## Apple Leaf Disease Identification and Classification using ResNet Models

With the rapid growth of the fruit industry, apple leaf diseases have increasingly impacted apple yield and farmers' economic income. Traditional disease identification requires expertise and time, making automated detection crucial. Convolutional Neural Networks (CNN) are widely used for plant disease recognition due to their strong generalization, robustness, and automatic feature extraction. In this study, we analyzed apple leaf diseases using image segmentation and machine learning. We processed images by converting them to LAB color space, applying Otsu segmentation, and extracting disease spots. A Support Vector Machine (SVM) classifier and deep learning models like ResNet-18, ResNet-34, and VGG-16 were used for classification. ResNet-18 achieved the highest accuracy of 98.5%, outperforming other models. These findings provide an effective approach for large-scale, automated plant disease identification [3].

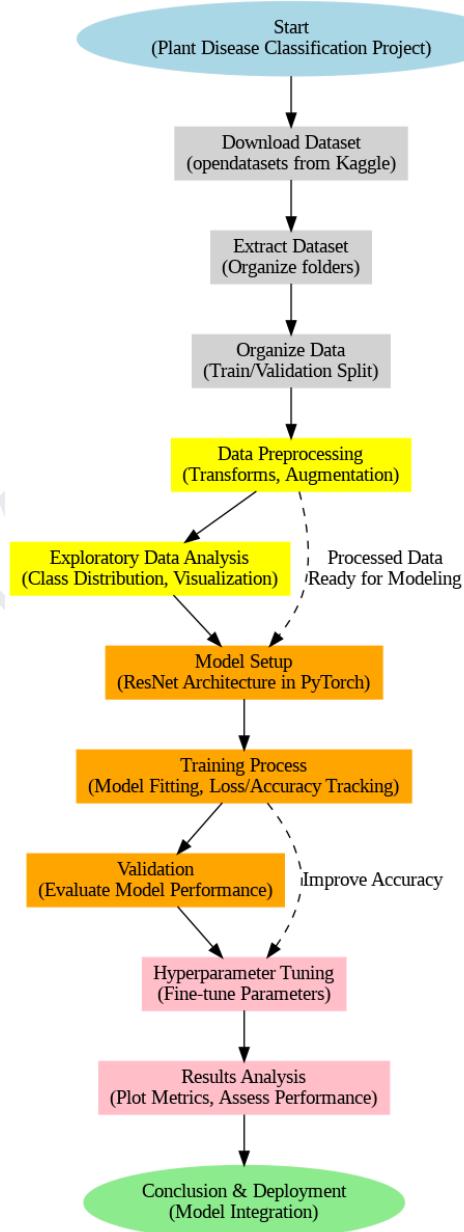
---

## References

- [3]:Li, Xin, and Laxmisha Rai. "Apple Leaf Disease Identification and Classification Using ResNet Models." *2020 IEEE 3rd International Conference on Electronic Information and Communication Technology (ICEICT)*, IEEE, Nov. 2020, <https://doi.org/10.1109/iceict51264.2020.9334214>. Accessed 28 Feb. 2025.
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## Description for Apple Leaf Disease Prediction Using Resnet Architecture:

The notebook presents a deep learning approach to identifying plant diseases using a ResNet model. It utilizes a dataset of plant leaf images, applying data augmentation techniques to enhance model robustness. A custom ResNet architecture is implemented, and the model is trained using a one-cycle learning rate policy. The training process includes monitoring metrics such as training and validation loss to prevent overfitting. The final model achieves an impressive accuracy of 99.2% on the validation set, demonstrating its effectiveness in classifying plant diseases.



Code:

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```
pip install torchsummary
Requirement already satisfied: torchsummary in /usr/local/lib/python3.11/dist-packages (1.5.1)

[ ] !pip install opendatasets

Collecting opendatasets
  Downloading opendatasets-0.1.22-py3-none-any.whl.metadata (9.2 kB)
Requirement already satisfied: tqdm in /usr/local/lib/python3.11/dist-packages (from opendatasets) (4.67.1)
Requirement already satisfied: kaggle in /usr/local/lib/python3.11/dist-packages (from opendatasets) (1.6.17)
Requirement already satisfied: click in /usr/local/lib/python3.11/dist-packages (from opendatasets) (8.1.8)
Requirement already satisfied: six<1.10 in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (1.17.0)
Requirement already satisfied: certifi>2023.7.22 in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (2025.1.31)
Requirement already satisfied: python-dateutil in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (2.8.2)
Requirement already satisfied: requests in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (2.32.3)
Requirement already satisfied: pytz in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (2023.4.1)
Requirement already satisfied: bleach in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (8.0.4)
Requirement already satisfied: text-unidecode<1.3 in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (2.3.0)
Requirement already satisfied: webencodings in /usr/local/lib/python3.11/dist-packages (from kaggle>opendatasets) (0.5.1)
Requirement already satisfied: charset-normalizer<4,>2 in /usr/local/lib/python3.11/dist-packages (from requests>kaggle>opendatasets) (3.4.1)
Requirement already satisfied: idna<4,>2.5 in /usr/local/lib/python3.11/dist-packages (from requests>kaggle>opendatasets) (3.18)
Downloading opendatasets-0.1.22-py3-none-any.whl (15 kB)
Installing collected packages: opendatasets
Successfully installed opendatasets-0.1.22
```

```
[ ] import opendatasets as od
[ ] import opendatasets as od
od.download("https://www.kaggle.com/datasets/vipooooool/new-plant-diseases-dataset")
→ Please provide your Kaggle credentials to download this dataset. Learn more: http://kaggle.com/username/nairitdas24mai0097
Your Kaggle Key: .....
Dataset URL: https://www.kaggle.com/datasets/vipooooool/new-plant-diseases-dataset
Downloading new-plant-diseases-dataset.zip to ./new-plant-diseases-dataset
100% |██████████| 2.70G/2.70G [02:05<00:00, 23.1MB/s]
```

```
[ ] import os # for working with files
import numpy as np # for numerical computations
import pandas as pd # for working with dataframes
import torch # Pytorch module
import matplotlib.pyplot as plt # for plotting informations on graph and images using tensors
import torch.nn as nn # for creating neural networks
from torch.utils.data import DataLoader # for dataloaders
from PIL import Image # for checking images
import torch.nn.functional as F # for functions for calculating loss
import torchvision.transforms as transforms # for transforming images into tensors
from torchvision.utils import make_grid # for data checking
from torchvision.datasets import ImageFolder # for working with classes and images
from torchsummary import summary # for getting the summary of our model

%matplotlib inline

# Define extract_path with the actual path where the dataset was extracted
extract_path = "new-plant-diseases-dataset" # Replace with the correct path

print("Dataset extracted successfully to:", extract_path)
```

```
[ ] data_dir = "new-plant-diseases-dataset/New Plant Diseases Dataset (Augmented)/New Plant Diseases Dataset (Augmented)"  
train_dir = data_dir + "/train"  
valid_dir = data_dir + "/valid"  
diseases = os.listdir(train_dir)
```

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```
# unique plants in the dataset
print(f"Unique Plants are: \n{plants}")

# number of unique plants
print("Number of plants: {}".format(len(plants)))

# number of unique diseases
print("Number of diseases: {}".format(NumberOfDiseases))

# Number of images for each disease
nums = {}
for disease in diseases:
    nums[disease] = len(os.listdir(train_dir + '/' + disease))

# converting the nums dictionary to pandas dataframe passing index as plant name and number of images as column
img_per_class = pd.DataFrame(nums.values(), index=nums.keys(), columns=["no. of images"])
img_per_class
```

Number of plants: 14

Number of diseases: 26

	no. of images
Potato__Early_blight	1939
Squash__Powdery_mildew	1736

```
# converting the nums dictionary to pandas dataframe passing index as plant name and number of images as column
img_per_class = pd.DataFrame(nums.values(), index=nums.keys(), columns=["no. of images"])
img_per_class
```

Tomato\_\_Early\_blight 1920

Corn\_(maize)\_\_Cercospora\_leaf\_spot\_Gray\_leaf\_spot 1642

Apple\_\_Black\_rot 1987

Tomato\_\_Spider\_mites Two-spotted\_spider\_mite 1741

Potato\_\_Late\_blight 1939

Raspberry\_\_healthy 1781

Apple\_\_healthy 2008

Tomato\_\_Target\_Spot 1827

Grape\_\_Black\_rot 1888

Tomato\_\_Leaf\_Mold 1882

Peach\_\_healthy 1728

Tomato\_\_Tomato\_Yellow\_Leaf\_Curl\_Virus 1961

Orange\_\_Huanglongbing\_(Citrus\_greening) 2010

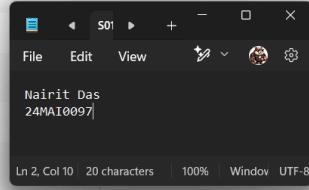
Tomato\_\_Septoria\_leaf\_spot 1745

Corn\_(maize)\_\_healthy 1859

Potato\_\_healthy 1824

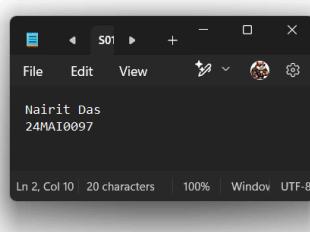
Peach\_\_Bacterial\_spot 1838

Tomato\_\_Late\_blight 1851



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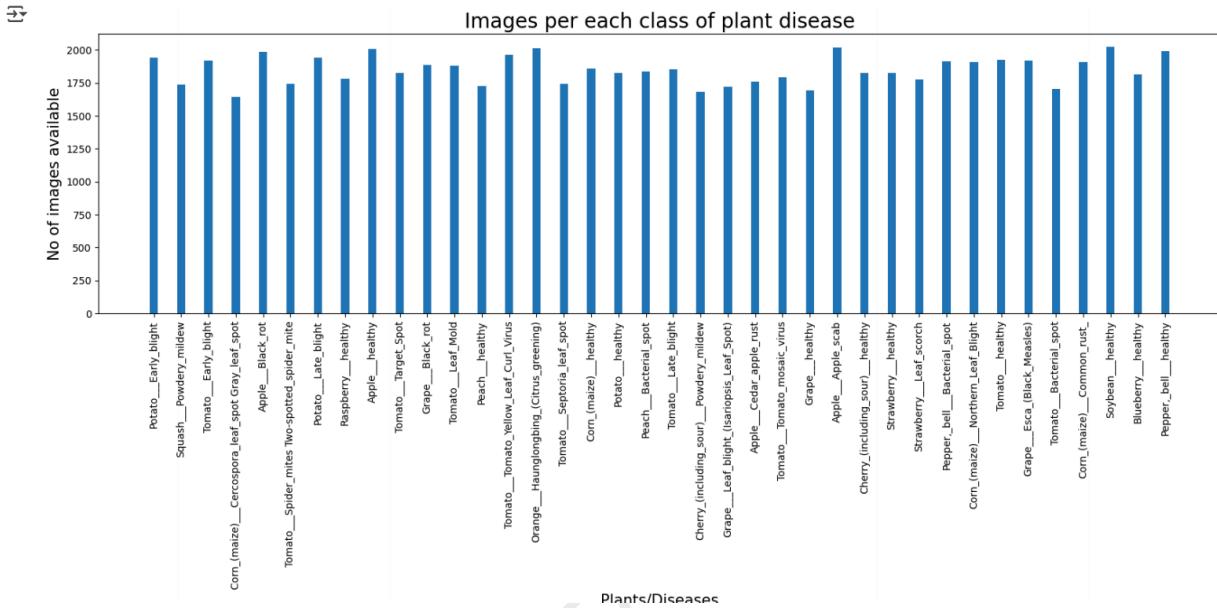
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```
[ ] # plotting number of images available for each disease
index = list(range(len(nums))) # Use the length of 'nums' for the index
plt.figure(figsize=(20, 5))
plt.bar(index, list(nums.values()), width=0.3) # Convert nums.values() to a list
plt.xlabel('Plants/Diseases', fontsize=15) # Increased fontsize for x-axis label
plt.ylabel('No of images available', fontsize=15) # Increased fontsize for y-axis label
plt.xticks(index, list(nums.keys()), fontsize=10, rotation=90) # Increased fontsize for x-axis ticks
plt.title('Images per each class of plant disease', fontsize=20) # Increased fontsize for title
plt.show() # Added to display plot
```



```
▶ n_train = 0
for value in nums.values():
    n_train += value
print(f"There are {n_train} images for training")
```

There are 70295 images for training

```
[ ] # datasets for validation and training
train = ImageFolder(train_dir, transform=transforms.ToTensor())
valid = ImageFolder(valid_dir, transform=transforms.ToTensor())
```

```
[ ] img, label = train[0]
print(img.shape, label)
```

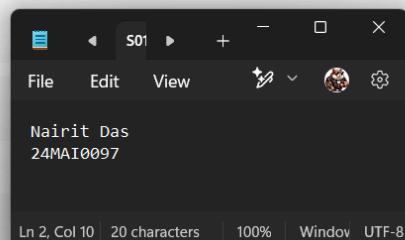
torch.Size([3, 256, 256]) 0

```
[ ] # total number of classes in train set
len(train.classes)
```

38

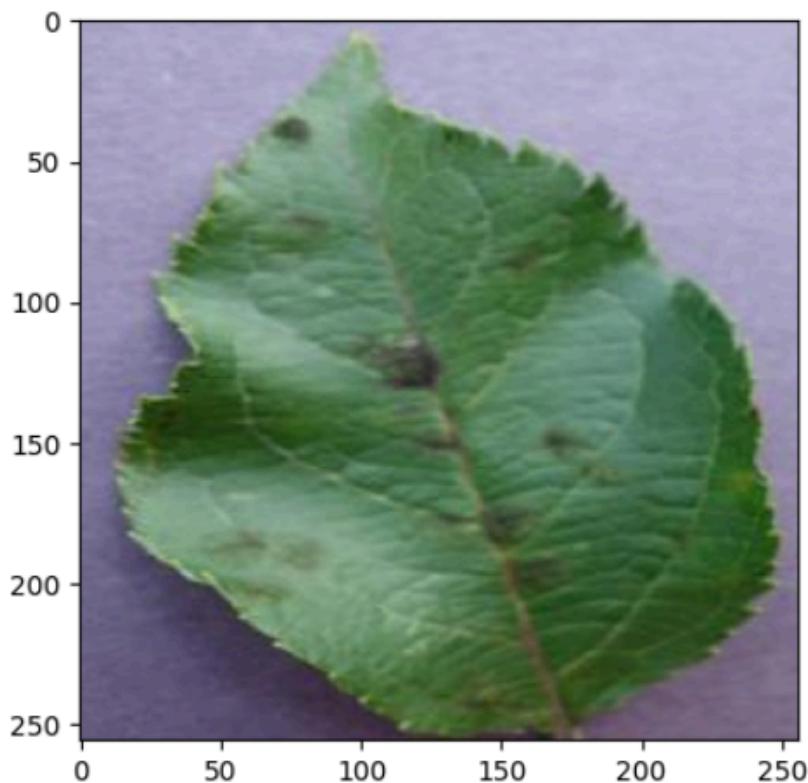
```
[ ] # for checking some images from training dataset
def show_image(image, label):
    print("Label :" + train.classes[label] + "(" + str(label) + ")")
    plt.imshow(image.permute(1, 2, 0))
```

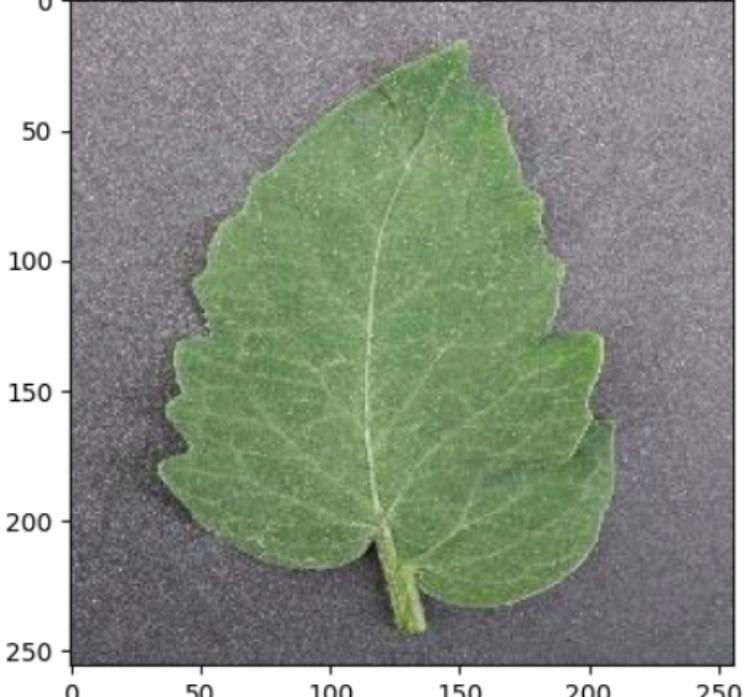
```
[ ] show_image(*train[0])
```

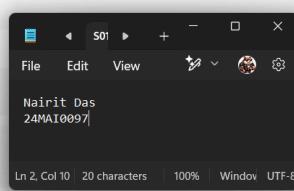


```
show_image(*train[0])
```

Label :Apple\_\_Apple\_scab(0)



```
show_image(*train[70000])  
Label : Tomato__healthy(37)  
  
# Setting the seed value  
random_seed = 7  
torch.manual_seed(random_seed)  
<torch._C.Generator at 0x7f8da26111f0>  
# setting the batch size  
batch_size = 32  
  
# DataLoaders for training and validation  
train_dl = DataLoader(train, batch_size, shuffle=True, num_workers=2, pin_memory=True)  
valid_dl = DataLoader(valid, batch_size, num_workers=2, pin_memory=True)  
  
# helper function to show a batch of training instances  
def show_batch(data):  
    for images, labels in data:  
        fig, ax = plt.subplots(figsize=(30, 30))  
        ax.set_xticks([]); ax.set_yticks([])  
        ax.imshow(make_grid(images, nrow=8).permute(1, 2, 0))  
        break  
  
# Images for first batch of training  
show_batch(train_dl)
```



```

④ # Images for first batch of training
show_batch(train_dl)



```

```

⑤ # for moving data into GPU (if available)
def get_default_device():
    """Pick GPU if available, else CPU"""
    if torch.cuda.is_available():
        return torch.device("cuda")
    else:
        return torch.device("cpu")

# for moving data to device (CPU or GPU)
def to_device(data, device):
    """Move tensor(s) to chosen device"""
    if isinstance(data, (list, tuple)):
        return [to_device(x, device) for x in data]
    return data.to(device, non_blocking=True)

# for loading in the device (GPU if available else CPU)
class DeviceDataLoader():
    """Wrap a dataloader to move data to a device"""
    def __init__(self, dl, device):
        self.dl = dl
        self.device = device

    def __iter__(self):
        """Yield a batch of data after moving it to device"""
        for b in self.dl:
            yield to_device(b, self.device)

    def __len__(self):
        """Number of batches"""
        return len(self.dl)

```

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```

[ ] device = get_default_device()
device

[ ] device(type='cuda')

[ ] # Moving data into GPU
train_dl = DeviceDataLoader(train_dl, device)
valid_dl = DeviceDataLoader(valid_dl, device)

[ ] class SimpleResidualBlock(nn.Module):
    def __init__(self):
        super().__init__()
        self.conv1 = nn.Conv2d(in_channels=3, out_channels=3, kernel_size=3, stride=1, padding=1)
        self.relu1 = nn.ReLU()
        self.conv2 = nn.Conv2d(in_channels=3, out_channels=3, kernel_size=3, stride=1, padding=1)
        self.relu2 = nn.ReLU()

    def forward(self, x):
        out = self.conv1(x)
        out = self.relu1(out)
        out = self.conv2(out)
        return self.relu2(out) + x # ReLU can be applied before or after adding the input

[ ] # for calculating the accuracy
def accuracy(outputs, labels):
    _, preds = torch.max(outputs, dim=1)
    return torch.tensor(torch.sum(preds == labels).item() / len(preds))

# base class for the model
class ImageClassificationBase(nn.Module):

[ ] # base class for the model
class ImageClassificationBase(nn.Module):

    def training_step(self, batch):
        images, labels = batch
        out = self(images)           # Generate predictions
        loss = F.cross_entropy(out, labels) # Calculate loss
        return loss

    def validation_step(self, batch):
        images, labels = batch
        out = self(images)           # Generate prediction
        loss = F.cross_entropy(out, labels) # Calculate loss
        acc = accuracy(out, labels)   # Calculate accuracy
        return {"val_loss": loss.detach(), "val_accuracy": acc}

    def validation_epoch_end(self, outputs):
        batch_losses = [x["val_loss"] for x in outputs]
        batch_accuracy = [x["val_accuracy"] for x in outputs]
        epoch_loss = torch.stack(batch_losses).mean() # Combine loss
        epoch_accuracy = torch.stack(batch_accuracy).mean() # Combine accuracy
        return {"val_loss": epoch_loss, "val_accuracy": epoch_accuracy} # Combine accuracies

    def epoch_end(self, epoch):
        print("Epoch {}, last_lr: {:.5f}, train_loss: {:.4f}, val_loss: {:.4f}, val_acc: {:.4f}.format(
            epoch, result['lrs'][-1], result['train_loss'], result['val_loss'], result['val_accuracy']))

```

```

# Architecture for training

# convolution block with BatchNormalization
def ConvBlock(in_channels, out_channels, pool=False):
    layers = [nn.Conv2d(in_channels, out_channels, kernel_size=3, padding=1),
              nn.BatchNorm2d(out_channels),
              nn.ReLU(inplace=True)]
    if pool:
        layers.append(nn.MaxPool2d(4))
    return nn.Sequential(*layers)

# resnet architecture
class ResNet9(ImageClassificationBase):
    def __init__(self, in_channels, num_diseases):
        super().__init__()

        self.conv1 = ConvBlock(in_channels, 64)
        self.conv2 = ConvBlock(64, 128, pool=True) # out_dim : 128 x 64 x 64
        self.res1 = nn.Sequential(ConvBlock(128, 128), ConvBlock(128, 128))

        self.conv3 = ConvBlock(128, 256, pool=True) # out_dim : 256 x 16 x 16
        self.conv4 = ConvBlock(256, 512, pool=True) # out_dim : 512 x 4 x 44
        self.res2 = nn.Sequential(ConvBlock(512, 512), ConvBlock(512, 512))

        self.classifier = nn.Sequential(nn.MaxPool2d(4),
                                       nn.Flatten(),
                                       nn.Linear(512, num_diseases))

    def forward(self, xb): # xb is the loaded batch
        out = self.conv1(xb)
        out = self.conv2(out)
        out = self.res1(out) + out

```

```

        out = self.res2(out) + out
        out = self.classifier(out)
        return out

[ ] # defining the model and moving it to the GPU
model = to_device(ResNet9(3, len(train.classes)), device)
model

ResNet9(
    (conv1): Sequential(
        (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
        (2): ReLU(inplace=True)
    )
    (conv2): Sequential(
        (0): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
        (2): ReLU(inplace=True)
        (3): MaxPool2d(kernel_size=4, stride=4, padding=0, dilation=1, ceil_mode=False)
    )
    (res1): Sequential(
        (0): Sequential(
            (0): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
            (2): ReLU(inplace=True)
        )
        (1): Sequential(
            (0): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
            (2): ReLU(inplace=True)
        )
    )
    (conv3): Sequential(
        (0): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
        (2): ReLU(inplace=True)
    )
    (conv4): Sequential(
        (0): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
        (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
        (2): ReLU(inplace=True)
        (3): MaxPool2d(kernel_size=4, stride=4, padding=0, dilation=1, ceil_mode=False)
    )
    (res2): Sequential(
        (0): Sequential(
            (0): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
            (2): ReLU(inplace=True)
        )
        (1): Sequential(
            (0): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
            (1): BatchNorm2d(512, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
            (2): ReLU(inplace=True)
        )
    )
    (classifier): Sequential(
        (0): MaxPool2d(kernel_size=4, stride=4, padding=0, dilation=1, ceil_mode=False)
        (1): Flatten(start_dim=1, end_dim=-1)
        (2): Linear(in_features=512, out_features=38, bias=True)
    )
)

[ ] # getting summary of the model
INPUT_SHAPE = (3, 256, 256)
print(summary(model.cuda(), (INPUT_SHAPE)))

```

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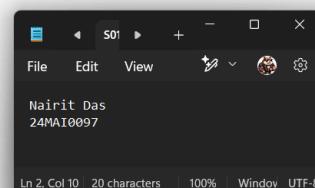
```

[ ] -----	Layer (type)	Output Shape	Param #
Conv2d-1	[ -1, 64, 256, 256]	1,792	
BatchNorm2d-2	[ -1, 64, 256, 256]	128	
ReLU-3	[ -1, 64, 256, 256]	0	
Conv2d-4	[ -1, 128, 256, 256]	73,856	
BatchNorm2d-5	[ -1, 128, 256, 256]	256	
ReLU-6	[ -1, 128, 256, 256]	0	
MaxPool2d-7	[ -1, 128, 64, 64]	0	
Conv2d-8	[ -1, 128, 64, 64]	147,584	
BatchNorm2d-9	[ -1, 128, 64, 64]	256	
ReLU-10	[ -1, 128, 64, 64]	0	
Conv2d-11	[ -1, 128, 64, 64]	147,584	
BatchNorm2d-12	[ -1, 128, 64, 64]	256	
ReLU-13	[ -1, 128, 64, 64]	0	
Conv2d-14	[ -1, 256, 64, 64]	295,168	
BatchNorm2d-15	[ -1, 256, 64, 64]	512	
ReLU-16	[ -1, 256, 64, 64]	0	
MaxPool2d-17	[ -1, 256, 16, 16]	0	
Conv2d-18	[ -1, 512, 16, 16]	1,180,160	
BatchNorm2d-19	[ -1, 512, 16, 16]	1,024	
ReLU-20	[ -1, 512, 16, 16]	0	
MaxPool2d-21	[ -1, 512, 4, 4]	0	
Conv2d-22	[ -1, 512, 4, 4]	2,359,808	
BatchNorm2d-23	[ -1, 512, 4, 4]	1,024	
ReLU-24	[ -1, 512, 4, 4]	0	
Conv2d-25	[ -1, 512, 4, 4]	2,359,808	
BatchNorm2d-26	[ -1, 512, 4, 4]	1,024	
ReLU-27	[ -1, 512, 4, 4]	0	
MaxPool2d-28	[ -1, 512, 1, 1]	0	
Flatten-29	[ -1, 512]	0	
Linear-30	[ -1, 38]	19,494	

Total params: 6,589,734

```
[ ] -----  
[ ] Total params: 6,589,734  
[ ] Trainable params: 6,589,734  
[ ] Non-trainable params: 0  
-----  
Input size (MB): 0.75  
Forward/backward pass size (MB): 343.95  
Params size (MB): 25.14  
Estimated Total Size (MB): 369.83  
-----  
None
```

```
[ ] # for training  
@torch.no_grad()  
def evaluate(model, val_loader):  
    model.eval()  
    outputs = [model.validation_step(batch) for batch in val_loader]  
    return model.validation_epoch_end(outputs)  
  
def get_lr(optimizer):  
    for param_group in optimizer.param_groups:  
        return param_group['lr']  
  
def fit_OneCycle(epochs, max_lr, model, train_loader, val_loader, weight_decay=0,  
                 grad_clip=None, opt_func=torch.optim.SGD):  
    torch.cuda.empty_cache()  
    history = []  
  
    optimizer = opt_func(model.parameters(), max_lr, weight_decay=weight_decay)  
    # scheduler for one cycle learning rate  
    sched = torch.optim.lr_scheduler.OneCycleLR(optimizer, max_lr, epochs=epochs, steps_per_epoch=len(train_loader))
```





```
for epoch in range(epochs):
    # Training
    model.train()
    train_losses = []
    lrs = []
    for batch in train_loader:
        loss = model.training_step(batch)
        train_losses.append(loss)
        loss.backward()

        # gradient clipping
        if grad_clip:
            nn.utils.clip_grad_value_(model.parameters(), grad_clip)

        optimizer.step()
        optimizer.zero_grad()

        # recording and updating learning rates
        lrs.append(get_lr(optimizer))
        sched.step()

    # validation
    result = evaluate(model, val_loader)
    result['train_loss'] = torch.stack(train_losses).mean().item()
    result['lrs'] = lrs
    model.epoch_end(epoch, result)
    history.append(result)

return history
```

```

%%time
history = [evaluate(model, valid_dl)]
history

→ CPU times: user 54.6 s, sys: 5.97 s, total: 1min
Wall time: 1min 10s
[{'val_loss': tensor(3.6378, device='cuda:0'), 'val_accuracy': tensor(0.0282)}]

epochs = 2
max_lr = 0.01
grad_clip = 0.1
weight_decay = 1e-4
opt_func = torch.optim.Adam

%%time
history += fit_OneCycle(epochs, max_lr, model, train_dl, valid_dl,
                        grad_clip=grad_clip,
                        weight_decay=1e-4,
                        opt_func=opt_func)

→ Epoch [0], last_lr: 0.00812, train_loss: 0.7494, val_loss: 0.5536, val_acc: 0.8310
Epoch [1], last_lr: 0.00000, train_loss: 0.1250, val_loss: 0.0271, val_acc: 0.9916
CPU times: user 15min 26s, sys: 15min 47s, total: 31min 14s
Wall time: 31min 31s

def plot_accuracies(history):
    accuracies = [x['val_accuracy'] for x in history]
    plt.plot(accuracies, '-x')
    plt.xlabel('epoch')
    plt.ylabel('accuracy')
    plt.title('Accuracy vs. No. of epochs');

def plot_losses(history):
    train_losses = [x.get('train_loss') for x in history]
    val_losses = [x['val_loss'] for x in history]
    plt.plot(train_losses, '-bx')
    plt.plot(val_losses, '-rx')
    ...
    ...

```

Nairit Das  
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```

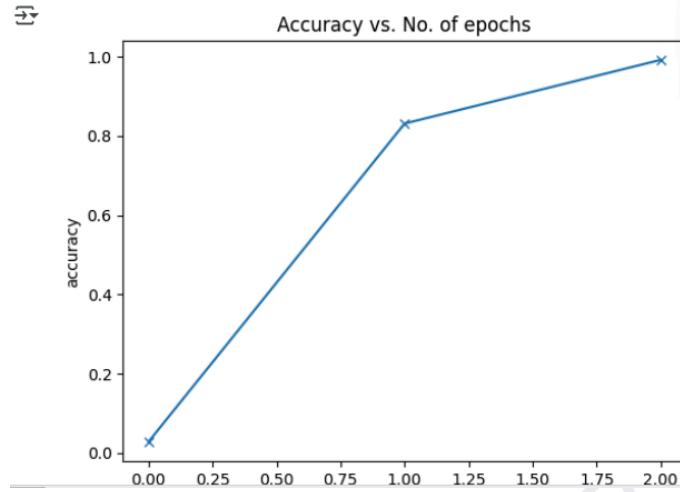
plt.ylabel('loss')
plt.legend(['Training', 'Validation'])
plt.title('Loss vs. No. of epochs');

def plot_lrs(history):
    lrs = np.concatenate([x.get('lrs', []) for x in history])
    plt.plot(lrs)
    plt.xlabel('Batch no.')
    plt.ylabel('Learning rate')
    plt.title('Learning Rate vs. Batch no.');

```

#### VALIDATION ACCURACY

```
plot_accuracies(history)
```



#### VALIDATION LOSS

<https://colab.research.google.com/drive/1gX0cDbx6rk6t8flgaccUQ8zAfqYmAsP8#scrollTo=LmXoUt-P7031&printMode=true>

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RESNET.ipynb - Colab

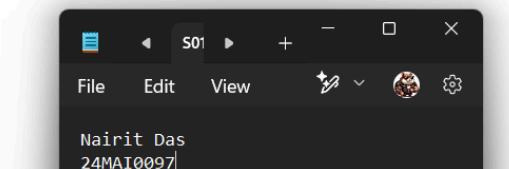
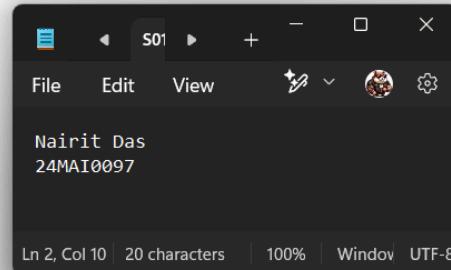
```

# This is formatted as code

def plot_losses(history):
    train_losses = [x.get('train_loss') for x in history]
    val_losses = [x['val_loss'].cpu().numpy() for x in history] # Move tensors to CPU and convert to NumPy
    plt.plot(train_losses, '-bx')
    plt.plot(val_losses, '-rx')
    plt.xlabel('epoch')
    plt.ylabel('loss')
    plt.legend(['Training', 'Validation'])
    plt.title('Loss vs. No. of epochs');

plot_lrs(history)

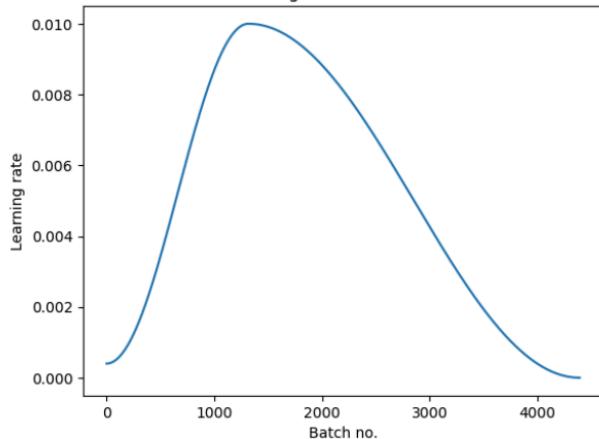
```



```
plot_lrs(history)
```



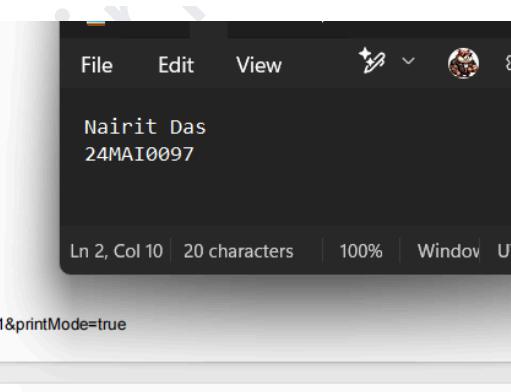
Learning Rate vs. Batch no.



```
test_dir = "new-plant-diseases-dataset/test"
test = ImageFolder(test_dir, transform=transforms.ToTensor())

def predict_image(img, model):
    """Converts image to array and return the predicted class
       with highest probability"""
    # Convert to a batch of 1
    xb = to_device(img.unsqueeze(0), device)
    # Get predictions from model
    yb = model(xb)
    # Pick index with highest probability
    _, preds = torch.max(yb, dim=1)
    # Retrieve the class label

    return train.classes[preds[0].item()]
s://colab.research.google.com/drive/1gX0cDbx6rk6t8flgaccUQ8zAfqYmAsP#scrollTo=LmXoUt-P7031&printMode=true
```



3/25, 1:18 AM

RESNET.ipynb - Colab

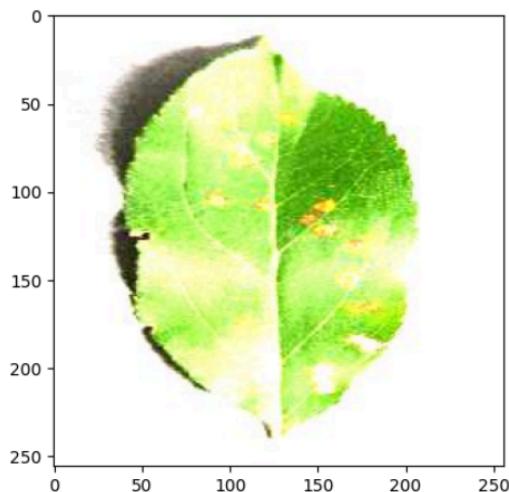
```
#predicting first image
img, label = test[1]
plt.imshow(img.permute(1, 2, 0))
print('Label:', test_images[0], ', Predicted:', predict_image(img, model))
```

Label: AppleCedarRust1.JPG , Predicted: Apple\_\_Cedar\_apple\_rust



```
[51] #predicting first image
    img, label = test[0]
    plt.imshow(img.permute(1, 2, 0))
    print('Label:', test_images[0], ', Predicted:', predict_image(img, model))
```

→ Label: AppleCedarRust1.JPG , Predicted: Apple\_Cedar\_apple\_rust



### Accuracy:

```
Epoch [0], last_lr: 0.00812, train_loss: 0.7494, val_loss: 0.5536, val_acc: 0.8310
Epoch [1], last_lr: 0.00000, train_loss: 0.1250, val_loss: 0.0271, val_acc: 0.9916
CPU times: user 15min 26s, sys: 15min 47s, total: 31min 14s
Wall time: 31min 31s
```

### Link to ALL the codes

LSTM Code:

<https://colab.research.google.com/drive/1zOu4Ig2QMcPtDRedzJwLPUevBGjjSnGS?usp=sharing>

BiLSTM Code:

[https://colab.research.google.com/drive/1434fmGw6Nl0B-ubPEUUx6DPsw--ZiW\\_A?usp=sharing](https://colab.research.google.com/drive/1434fmGw6Nl0B-ubPEUUx6DPsw--ZiW_A?usp=sharing)

RESNET Code:

<https://colab.research.google.com/drive/1gX0cDbx6rk6t8flgaccUQ8zAfqYmAsP8?usp=sharing>