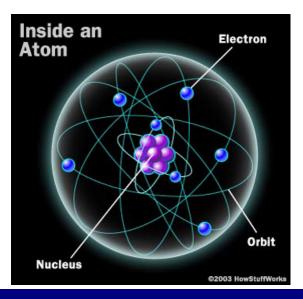
### **Solid Sturcture**

```
 \begin{split} & \text{Graphics3D}\big[\text{Join}\big[\big\{\text{GrayLevel}\,[0.25]\,,\,\,\text{Specularity}\big[\text{White}\,,\,\,10\big]\big\}\,,\\ & \text{Table}\big[\text{Sphere}\big[\big\{\text{i}\,,\,\,\text{j}\,,\,\,\text{k}\big\},\,\,0.2\big]\,,\,\,\big\{\text{i}\,,\,\,1,\,\,5\big\},\,\,\big\{\text{j}\,,\,\,1,\,\,5\big\}\,,\,\,\big\{\text{k}\,,\,\,1,\,\,5\big\}\big]\big]\,,\\ & \text{Lighting} \rightarrow \text{"Neutral"},\,\,\text{Boxed} \rightarrow \text{False}\big] \end{split}
```

#### **Atom**



### **Uniform electric field**

```
 \begin{aligned} &\text{plot} = \text{StreamPlot}[\{1,\,0\},\,\{x,\,0,\,5\},\,\{y,\,0,\,5\}]; \\ &\text{Manipulate}\big[\text{Module}\big[\big\{\text{work, potential, primitives}\big\},\,\text{work} = 1 \,(\text{p[[1]]}-\text{ax}); \\ &\text{potential} = 1 \,(\text{p0x}-\text{p[[1]]}); \\ &\text{primitives} = \text{Graphics}\big[\big\{\text{Red, PointSize}[0.03],\,\text{Point}[\{\text{ax, ay}\}], \\ &\text{Blue, Point}\big[\big\{\text{bx, by}\big\}\big],\,\text{Black, Line}\big[\text{AppendTo}\big[\text{points, p}\big]\big]\big\}\big]; \\ &\text{Grid}\big[\big\{\big\{\text{Show}\big[\text{primitives, plot, ImageSize} \rightarrow \text{Medium}\big],\,\text{SpanFromLeft}\big\}, \\ &\text{\{"Work", "Potential"},\, \big\{\text{work, potential}\big\}\big\}\big]\big],\, \big\{\big\{\text{ax, 0.5, "x_A"}\big\},\,\text{InputField}\big\}, \\ &\{\big\{\text{ay, 4, "y_A"}\big\},\,\text{InputField}\big\},\, \big\{\big\{\text{bx, 4, "x_B"}\big\},\,\text{InputField}\big\},\, \big\{\big\{\text{by, 4, "y_B"}\big\},\,\text{InputField}\big\}, \\ &\{\big\{\text{p0x, 5, "p_0_x"}\big\},\,\text{InputField}\big\},\, \big\{\big\{\text{p0y, 0, "p_0_y"}\big\},\,\text{InputField}\big\}, \\ &\{\big\{\text{p, \{ax, ay}\}\big\},\,\text{Locator}\big\},\, \big\{\big\{\text{points, }\{\{\text{ax, ay}\}\}\big\},\,\text{None}\big\},\,\text{TrackedSymbols} \rightarrow \{\text{p}\}\big] \end{aligned}
```

## **Longitudinal Wave**

```
Manipulate [With [\{A = 1., \omega = 2. \pi\}, Graphics [\{PointSize[0.02], Red, Point@(Table[<math>\{A Sin[\omega t + \phi], 0\}, \{\phi, 0, 2\pi, 0.1\pi\}] + Table[<math>\{i, 0\}, \{i, 0, 20\}])}, Axes \rightarrow True, AxesOrigin \rightarrow {0, 0}, PlotRange \rightarrow {\{-1, 21\}, All\}], {t, 0, 5, 0.001}
```

#### **Tranverse Wave**

```
Manipulate [With [\{A = 1., \omega = 2. \pi\}, Graphics [\{PointSize[0.02], Red,\}
     Point@ (Table [\{0, A Sin[\omega t + \phi]\}, \{\phi, 0, 2\pi, 0.1\pi\}] + Table [\{i, 0\}, \{i, 0, 20\}])\},
    Axes \rightarrow True, AxesOrigin \rightarrow {0, 0}, PlotRange \rightarrow {{0, 20}, {-1, 1}}], {t, 0, 2, 0.001}]
```

### Ampere Force

```
Manipulate[Module[{magneticField, current, wire, force},
   (*magnetic field*)
  magneticField = {Arrowheads[{{Small, 0.3}, {Small, 0.7}}],
     Arrow /@ Transpose@Flatten[Table[\{i, j, \#\}, \{i, \{-1.5, 0, 1.5\}\},
              {j, \{-1.5, 0, 1.5\}} & /@ {\{-3, 3\}, \{\{1\}, \{2, 3\}, \{4\}\}\}};
   (*points of current*)
  current[l_, \theta_, \phi_] :=
    current[l, \theta, \phi] = \{-0.5 l \{Sin[\theta] Cos[\phi], Sin[\theta] Sin[\phi], Cos[\theta]\},\
       0.5 l {Sin[\theta] Cos[\phi], Sin[\theta] Sin[\phi], Cos[\theta]}};
   (*wire*)
  wire = {Blue, Arrowheads[{{Medium, 0.9}}], Arrow[Tube@current[length, theta, phi]]};
   (*Ampere force*)
   force =
    {\text{Red, Arrow}[\{0, 0, 0\}, \text{Cross}[\#2 - \#1) \&@@ current[length, theta, phi], \{0, 0, 1\}]\}};
   (*graphics*)
  Graphics3D[{magneticField, wire, force},
    Axes \rightarrow False, PlotRange \rightarrow \{\{-2, 2\}, \{-2, 2\}, \{-3, 3\}\},\
    AxesLabel -> \{x, y, z\}, SphericalRegion \rightarrow True, Boxed \rightarrow False]]
 , {length, 0, 2, 0.1}, {theta, 0, \pi, 0.05 \pi}, {phi, 0, 2 \pi, 0.1 \pi}]
```

## Simple Harmonic resonance

## ■ 同方向同频率, 不同振幅和初相位

```
Manipulate [Module[\{x1, x2, x\}, x1[t_]] := A1 Sin[\omega t + \alpha 1];
   x2[t_] := A2 Sin[\omega t + \alpha 2];
   x[t_] := x1[t] + x2[t];
   Plot[\{x1[t], x2[t], x[t]\}, \{t, 0, \tau\},
    PlotLegends \rightarrow \{ "x_1(t)", "x_2(t)", "x(t)" \}, PlotRange <math>\rightarrow \{-10, 10\} ] ],
  \{A1, 0, 10\}, \{A2, 0, 10\}, \{\omega, 0, 10\}, \{\alpha1, 0, 2\pi\}, \{\alpha2, 0, 2\pi\}, \{\tau, 0.1, 10.\}
```

# ■ 同方向,不同频率

```
Manipulate [Module[x1, x2, x], x1[t_] := ACos[\omega1t];
  x2[t] := A Cos[\omega 2 t];
  x[t_] := x1[t] + x2[t];
  Plot[x1[t], x2[t], x[t]], \{t, 0, t\}, PlotLegends \rightarrow \{"x1(t)", "x2(t)", "x(t)"\}],
 \{A, 0, 5\}, \{\omega 1, 0, 10\}, \{\omega 2, 0, 10\}, \{\tau, 0.1, 10. \pi\}
```

## ■ 垂直方向, 同频率, 不同振幅和相位差

```
Manipulate \left[ \text{ContourPlot} \left[ \frac{x^2}{A1^2} + \frac{y^2}{A2^2} - 2x \frac{y}{A1A2} \right] = \sin[\alpha^2 - \alpha^1] = \sin[\alpha^2 - \alpha^1]^2,
   \{x, -A1, A1\}, \{y, -A2, A2\}, PlotRange \rightarrow \{\{-5.5, 5.5\}, \{-5.5, 5.5\}\}\
 {A1, 0.01, 5}, {A2, 0.01, 5}, {\alpha1, 0.1, 2\pi}, {\alpha2, 0.1, 2\pi}
Manipulate \lceil Module \lceil \{x1, x2\}, x1[t_{-}] := A1 Cos[2 \pi t + \alpha 1] \}
   x2[t] := A2 Cos[2 \pi t + \alpha 2];
   Graphics[Line@Rest@AppendTo[points, {x1[t], x2[t]}],
    PlotRange \rightarrow \{\{-5, 5\}, \{-5, 5\}\}\], {A1, 0.01, 5}, {A2, 0.01, 5}, {\alpha1, 0.1, 2\pi},
  \{\alpha 2, 0.1, 2\pi\}, \{t, 0.001, 1, 0.001\}, \{\{points, \{\}\}, None\}, Button["Reset", points = \{\}\}\}
   t = 0.001; ], TrackedSymbols :> {t}]
```

# ■ 垂直方向,不同频率(李萨如图)

```
Manipulate [Module [\{x1, x2\}, x1[t_{-}] := A1 \cos[2 \pi f1 t + \alpha 1];
  x2[t_] := A2 Cos[2 \pi f2 t + \alpha 2];
  Graphics[Line@Rest@AppendTo[points, {x1[t], x2[t]}],
    PlotRange \rightarrow \{\{-5, 5\}, \{-5, 5\}\}\}, {A1, 0.01, 5}, {A2, 0.01, 5},
 \{\alpha 1, 0.1, 2\pi\}, \{\alpha 2, 0.1, 2\pi\}, \{\{\text{points}, \{\}\}, \text{None}\}, \{f1, 0.001, 10\}, \}
 {f2, 0.001, 10}, {t, 0.001, 5, 0.001}, Button["Reset", points = {};
  t = 0.001; ], TrackedSymbols :> {t}]
```

### Chaotic oscillator

```
\label{eq:with_signal_state} \mbox{With} \left[ \left\{ \delta = 1, \ \gamma = 1, \ \omega = 1, \ \tau = 200 \right\}, \ \mbox{eqn} = \mbox{x''[t]} + \delta \mbox{x'[t]} - \mbox{x[t]} + \mbox{x[t]} \wedge \mbox{3} = \mbox{\gamma} \mbox{Cos}[\omega \mbox{t]}; \right.
  sol1 = NDSolve[\{eqn, x'[0] = 1, x[0] = 3\}, x, \{t, 0, \tau\}];
  sol2 = NDSolve[{eqn, x'[0] == 1, x[0] == 3.1}, x, {t, 0, \tau}];
  GraphicsRow[
    {\text{Plot}[\text{Evaluate}[(x[t] /. #[[1]]) \& /@ \{\text{sol1}, \text{sol2}\}], \{t, 0, \tau\}, \text{PlotLegends} \rightarrow \text{Automatic}],}
      ParametricPlot[Evaluate[\{x[t], x'[t]\} /. #[[1]] & /@ \{sol1, sol2\}], \{t, 0, \tau\}]}]]
```