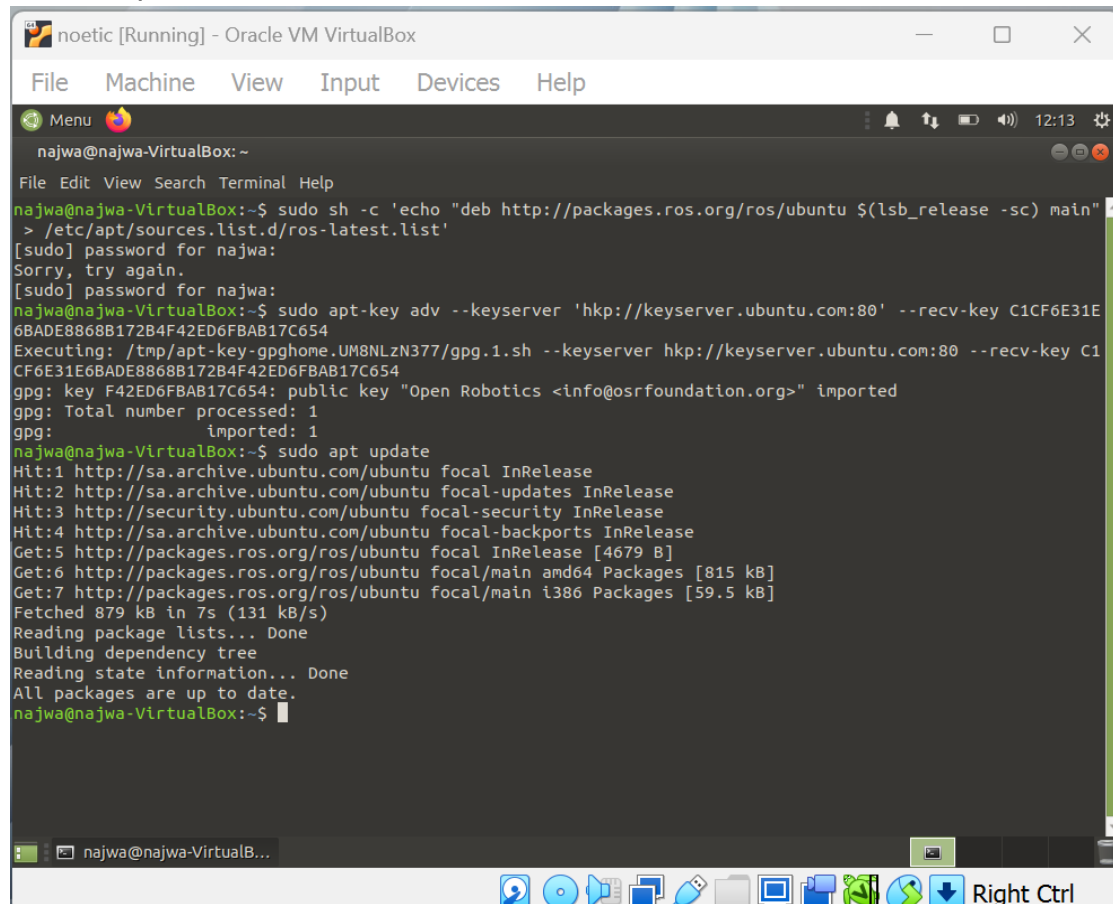The first task is to download and install the ros robot operating system

1-Setup my sources.list

2-Set up my keys
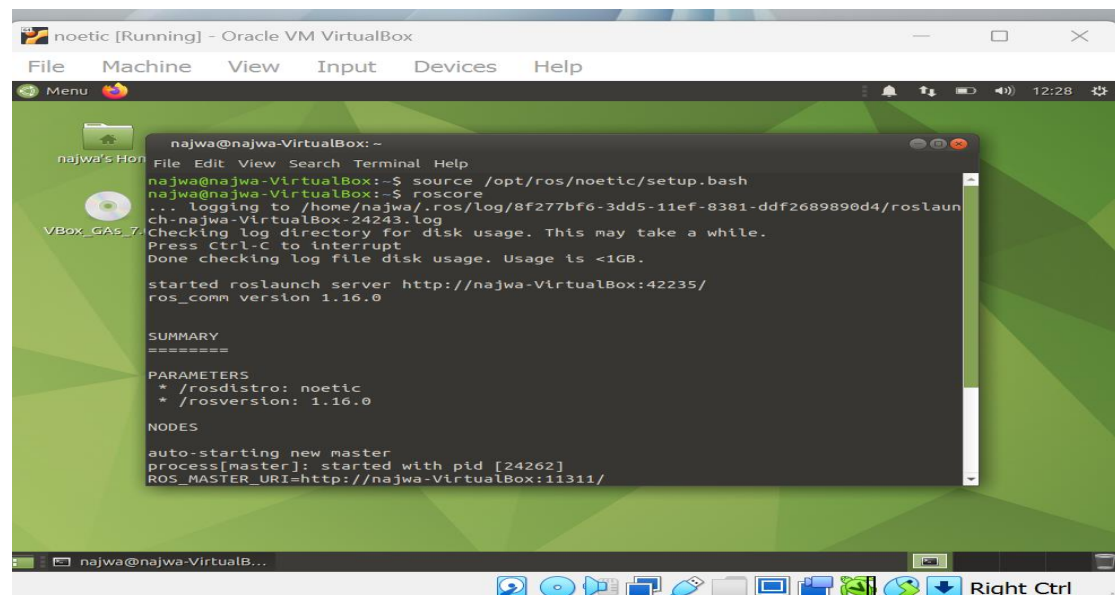
3-installaion

4-Desktop-Full Install
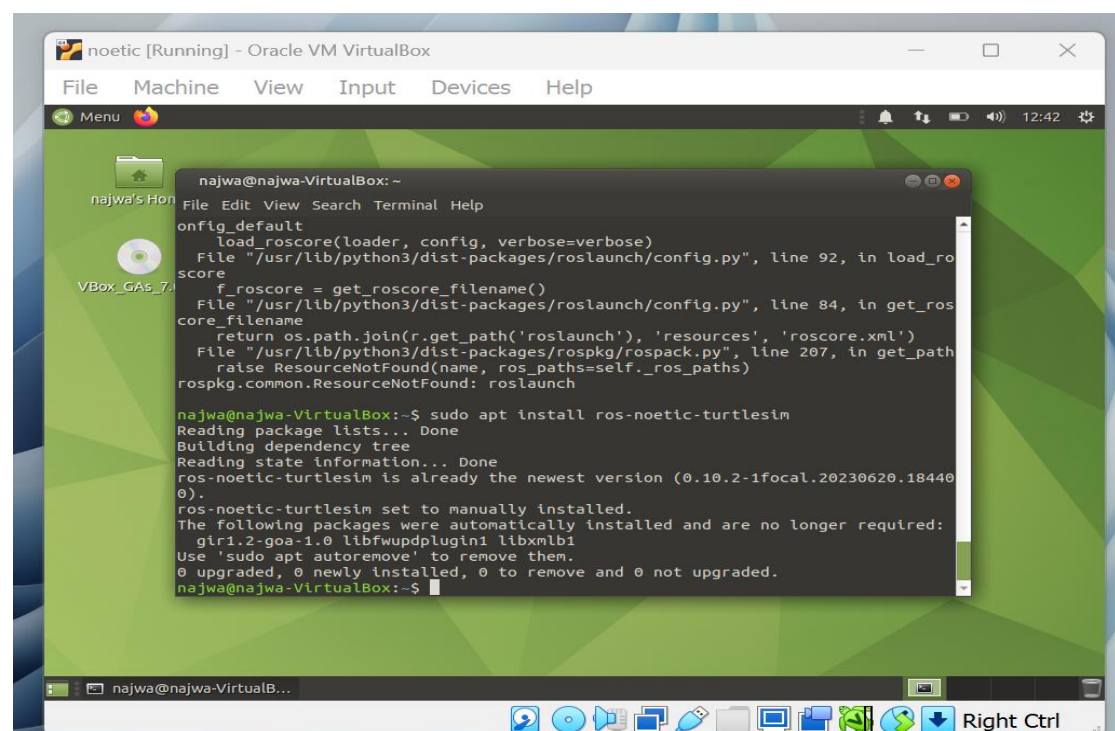
5. Environment setup