NALIN LUTHRA

Profile

A curious, polyglot and polymath person who like to learn and solve problem irrespective of field. Notable contribution in research field with mostly crazy ideas, that usually people think are not possible. Learning about new technologies, brain storming on ideas and reading books is everyday job & hobby.

Internship and Industry Experience

Centre of Artificial Intelligence and Robotics (DRDO)

2018

Our task was to develop automated path and its navigation without human pilot drone navigation system.

IIT-Bombay E-Yantra

2017-2018

Our task was to automate flying UAV (Quadcopter), to detect another robot and make it land on the same.

FabHotels (Intern)

2017

Video Editing and Advertisement designing

Tirupati Medicos (Freelancing)

2017

Designed a inventory management and POS system on java and SQL. So multiple shops can share same inventory and information about medicines.

Education

College - BVCOE (IPU)	IT Department	2016-Present
The Air Force School Class 12th	PCMB with Computer Science 94.5%	2016
The Air Force School Class 10th	CGPA - 9.0	2014
Selected Publications		

Vanita Jain, Gopal Chaudhary, **Nalin Luthra**, Akshit Rao, Shlok Walia "Dynamic Handwritten Signature and Machine Learning Based Identification verification for keyless Cryptocurrency Transactions", ICDSSA 2019 Special Issue: Journal of Information and Optimization Sciences (JIOS), <u>Taylor and Francis</u>

Vanita Jain, Gopal Chaudhary, **Nalin Luthra**, Akshit Rao, Harman Singh "How to help Johnny travel in Brimming train?" ICDSSA 2019, Lecture Notes in Electrical Engineering (Springer book series)

Nalin Luthra, Vanita jain, Gopal Chaudhary "Temperature invariant and high precision absolute rotary encoder using photocells on visible light spectrum" IEEE Sensors Journal 2018 (Under Review)

Nalin Luthra, Vanita Jain, Akshit Rao, "Medical Assistance using drone for remote areas", IndiaCom, India 2019

Achievements and Awards

•	IIT-Bombay (E-Yantra), Chaser Drone - Top 10 in India	2018
•	Smart India Hackathon, Grand Final Finalist (Bhopal)	2018
•	Technoxian - WRC (World Robotic Championship), 3rd Position across 300 teams and 20 Countries , Sponsored by Govt. of India, Ministry of Science and Technology, RoboRace	2017
•	Delhi Technical University, LFR 2nd Position	2017
•	Delhi Times Fresh Face college Winner.	2016

Technical Projects

•	PacBot (Indoor Navigation and Visualising physical world using ROS)	2018
•	Indoor navigation	2018
•	Self Driving Car using computer vision and ultrasonic sensors	2017-Present
•	Home Automation (Advance) using Raspberry pi and IOT sensors	2017-2018
•	Eye - Blinking Detection for Security and Surveillance	2017-2018
•	Farming Drone to prevent snakes and other animals enter in the farm land	2018
•	Raspberry Pi - 3 based personal Cloud Storage	2018
•	Own Blockchain (Most simple blockchain for transaction)	2018
•	Home Automation (Basic) simple IOT Switch	2017
•	CNC - Machine using waste	2017
•	Radar using Ultrasonic Sensors	2017
•	Air-Piano and a second a second and a second a second and	2017
•	Drone (Using KK2 flight Controller)	2017
•	Aeroplane (RC Craft)	2017
•	Laptop Controlled Car using ZigBee Communication and self made software using Processing (JAVA). Working radius 1.2 Km.	2017
•	Self Balancing Bot	2017
•	Line Following Robot (Using PID and LDR)	2017
•	DPDT RoboCar	2016
Posi	tions and Leadership Experience	

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Head of Technical Affairs (Indian Society of technical education BVP)	2018-Present
Taken a session on Robotics at DTU under ROSPi-Jam	2018
Head of Robotic Society Electronika (BVP-ISTE)	2017-2018
Leading team of 25 Students to Build Home Automation and Self Driving car	2017-2018
Publicity Head (ACM-BVP)	2017-2018
Teaching Robotics to Students (1st - 4th Year)	2017-2018
Teaching Programming to Students (1st - Year)	2017-2018
Event manager (BVP-ISTE)	2016-2017
Graphic Designer Executive (ACM-BVP)	2016-2017
Event manager Executive (TEDxBVP)	2016-2017
Head Co-curricular The Air Force School Technical Skills	2014-2016

- C/C++, Python, Java, Processing, MATLAB, SQL, JavaScript, HTML, CSS
- Robotics Operating System (ROS), RVIZ , Gazebo and Unreal Engine.
- 3-D Robotic modeling (Unified Robot Description Format (URDF))
- Ardunio, Raspberry pi and 8085 Microprocessor
- Computer Vision (OpenCV & Depth Camera "Real Sense and Kinect), Image processing
- **Machine learning Using Python**
- IOT using Raspberry pi and ESP8266

Miscellaneous

Google Local guide: Level 6 Contributor

References

- 1. Prof. Dr. Vanita Jain, Vice-Principal BVOCE New Delhi
- 2. Deepika Thapar Singh, CEO-Principal Credence High School Dubai