

# Three-dimensional Dam Break

## 1 Introduction

This case provides a description for three-dimensional dam break use case in which a volume of fluid formulation is used in the presence of air and water mixing.

## 2 Domain

The three-dimensional geometry for this tutorial is captured in Figure 1. A tank of dimension  $3.22 \times 1 \times 1$  m in the streamwise (x-), vertical (y-), and spanwise direction (z-direction), respectively, includes a rectangular obstruction (0.161 meter in height, 0.403 m in width, and 0.16 m in length) 0.6635 m from the end of the domain. An initial block of water 0.55 m in height and 1.228 m in length (spanning the full width of the tank) is released, [1].

The top boundary is an open boundary in which a static pressure is supplied. All other boundary surfaces are specified to be a no-slip wall boundary condition.

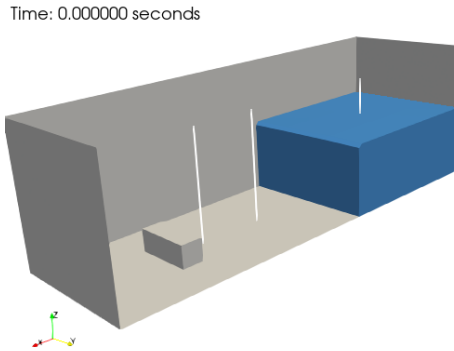


Figure 1: Three-dimensional dam break geometry. Also shown are the experimental height probes that are ordered from the obstruction backward, H1, H2, and H3.

### 3 Theory

The air/water configuration is represented by the following set of transport equations,

Continuity:

$$\frac{\partial u_j}{\partial x_j} = 0. \quad (1)$$

Momentum:

$$\frac{\partial \rho u_i}{\partial t} + \frac{\partial \rho u_j u_i}{\partial x_j} - \frac{\partial \sigma_{ij}}{\partial x_j} = F_i. \quad (2)$$

Volume of Fluid:

$$\frac{\partial \alpha}{\partial t} + u_j \frac{\partial \alpha}{\partial x_j} = 0. \quad (3)$$

In the above equation,  $\rho$  is the fluid density,  $\alpha$  is the volume of fluid, and  $u_j$  is the fluid velocity. The stress tensor is provided by

$$\sigma_{ij} = 2\mu S_{ij}^* - P\delta_{ij}, \quad (4)$$

where the traceless rate-of-strain tensor is defined as

$$S_{ij}^* = S_{ij} - \frac{1}{3}\delta_{ij}S_{kk} = S_{ij} - \frac{1}{3}\frac{\partial u_k}{\partial x_k}\delta_{ij}.$$

The momentum equation includes the general source term  $F_i$ , which contains both gravitational,  $\rho g_i$ , and surface tension effects,  $\sigma \kappa \frac{\partial \alpha}{\partial x_i}$ . Here,  $\sigma$  is the surface tension of the liquid and  $\kappa$  is the curvature,  $\kappa = -\frac{\partial n_j}{\partial x_j}$ , with the surface normal,  $n_j$ , defined as,

$$n_j = \frac{\frac{\partial \alpha}{\partial x_j}}{\left\| \frac{\partial \alpha}{\partial x_j} \right\|}, \quad (5)$$

In a low-Mach flow, the above pressure,  $P$ , is the perturbation about the thermodynamic pressure,  $P^{th}$ . Surface tension can also be applied in this configuration.

Properties as a function of the volume of fluid via a linear relationship,

$$\phi = \phi^L \alpha^L + \phi^G (1 - \alpha), \quad (6)$$

where  $\phi^L$  and  $\phi^G$  are the properties at a pure liquid and gas state, respectively. Therefore,  $\alpha$  is interpreted at the volume fraction of liquid, where a value of unity implies pure liquid. The isosurface of 1/2 represents the diffuse interface between liquid and air.

The underlying methodology exercises a balanced-force method for pressure stabilization in the presence of multi-phase flow, see Francois *et al.* [2] and the more recent unstructured control-volume finite element method work of Domino and Horne [3].

## 4 Results

We follow the numerical validation approach of Kleefsman *et al.* [1] where prediction of water level heights at various stations and time are provided. These data files are available in the postP directory.

### 4.1 Simulation Specification and Results

The density of air and water are specified to be 1 and  $1000 \text{ kg/m}^3$ , respectively, while the viscosity for air and water are  $1.98\text{e-}5$  and  $1.0\text{e-}3 \text{ Pa-s}$ , respectively. The coarse mesh simulation exercises a Hex8 linear element.

In Figure 2, results are provided for the specifications provided above.

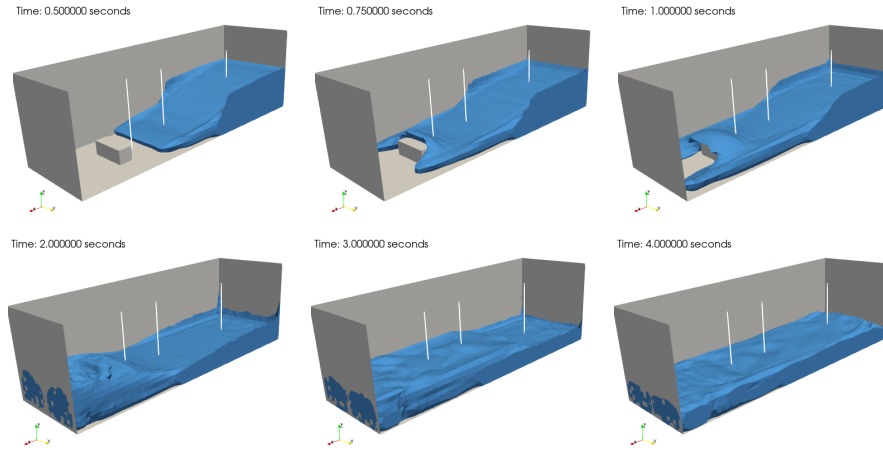


Figure 2: Volume of fluid evolution at 0.5, 0.75, 1.0, 2.0, 3.0, and 4.0 seconds.

## 5 Discussion Points

There are several interesting activities associated with this sample case including the following:

- Explore the mesh and input file specifications associated with this case.
- Replicate Figure 2 using Paraview. Here, load the data set and perform a “clip” based on the scalar value of volume of fluid to be one-half.
- Probe all degree-of-freedom results, i.e., velocity and pressure. What is of interest?
- Set the line command “activate\_buoyancy\_pressure\_stabilization: no”, and add an additional source term to the momentum system by the name *buoyancy*. Re-run and report and differences.

## References

- [1] Kleefsman, K., Fekken, G., Veldman, A., Iwanowski, B., and Buchner, B., *A balanced-force algorithm for continuous and sharp interfacial surface tension models within a volume tracking framework*, Journal of Computational Physics, Vol. 1, pp.141-173, 2006.
- [2] Francois, M. M., Cummins, S. J., Dendy, E. D., Kothe, D. B., Sicilian, J. M., Williams, M. W., *A Volume-of-Fluid based simulation method for wave impact problems*, Journal of Computational Physics, Vol. 1, pp.363-393, 2005.
- [3] Domino, S. P., Horne, W., *Development and deployment of a credible unstructured, six-DOF, implicit low-Mach overset high-fidelity simulation tool for wave energy applications*, Renewable Energy, under review, 2022.