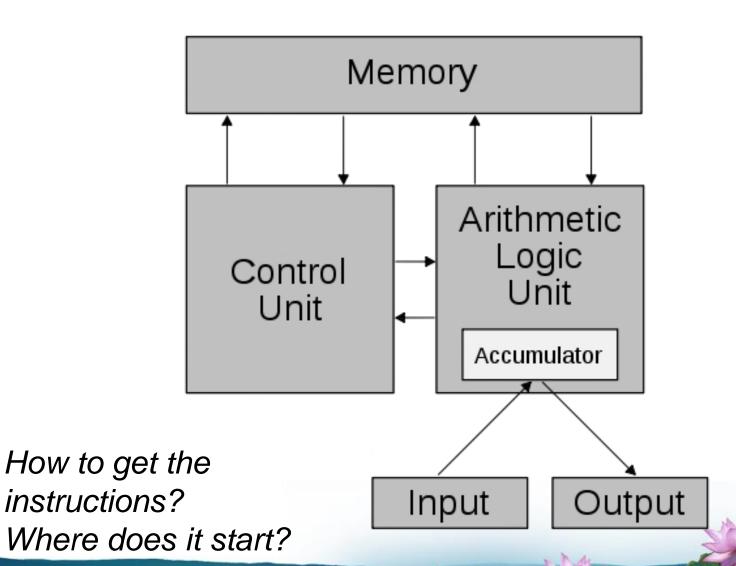


How system boot-up

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System Architecture





Memory vs Storage





Memory vs Storage





A specialized Storage device



- Can keep the data without battery
- Can be read as RAM
- Set to reset address
- Our option:
 - ROM
 - Eeprom
 - Nor Flash

However.....



Nor flash are expensive and

difficult to deploy.



| | U10 | |
|-----------|--|---------------|
| LADDR1 25 | A0 D0 | 29 LDATA0 |
| LADDR2 24 | Al DI | 31 LDATA1 |
| LADDR3 23 | | 33 LDATA2 |
| LADDR4 22 | (C.75) (C.75) | 35 LDATA3 |
| LADDR5 21 | A3 D3 D4 | 38 LDATA4 |
| LADDR6 20 | 120 Billion (120 Billion 120 Billion 1 | 40 LDATA5 |
| LADDR7 19 | A5 D5 | 42 LDATA6 |
| LADDR8 18 | A6 D6 | 44 LDATA7 |
| LADDR9 8 | A7 D7 | 30 LDATA8 |
| LADDR10 7 | A8 D8 | 32 LDATA9 |
| LADDR11 6 | A9 D9 | 34 LDATA10 |
| LADDR12 5 | A10 D10 | 36 LDATA11 |
| LADDR13 4 | A11 D11 | 39 LDATA12 |
| LADDR143 | A12 D12 | 41 LDATA13 |
| LADDR15 2 | A13 D13 | 43 LDATA14 |
| LADDR16 1 | A14 D14 | 45 LDATA15 |
| LADDR1748 | A15 D15 | |
| LADDR187 | A16 | 37 Irmnaari |
| LADDR196 | A17 VDD | VDD33V |
| LADDR20 9 | A18 | 28 LnOE |
| LADDR2110 | A19 nOE | 11 LnWE |
| LADDR223 | A20/NC nWE | 26 nGCS0 |
| LIDDIGE | A21/NC nCE | 12 nRESET |
| 15 | nRST/NC | 14 |
| . 17 | NC nWP | *** |
| VDD33V 27 | NC | 46 |
| | VSS VSS | 10 |
| GND | AM29LV160DB | GNT |

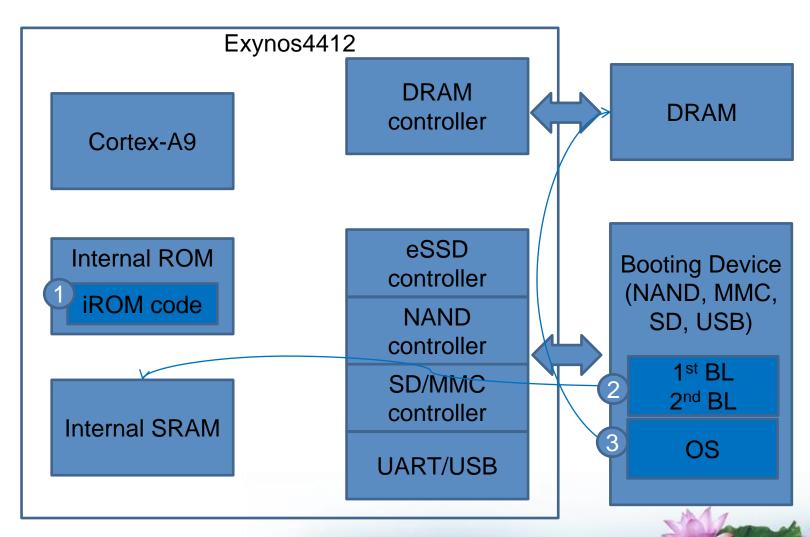
New solutions



- spi flash, nand flash, sdcard, USB storage.....
- We need a Stepstone.
- We need some helper program.

U-boot loading process





What we do when boot up



- Disable watchdog
- Initialize LED and/or UART
- Initialize DRAM
- Copy to DRAM (Optional)
- Initialize stack
- ■Get into stage-2

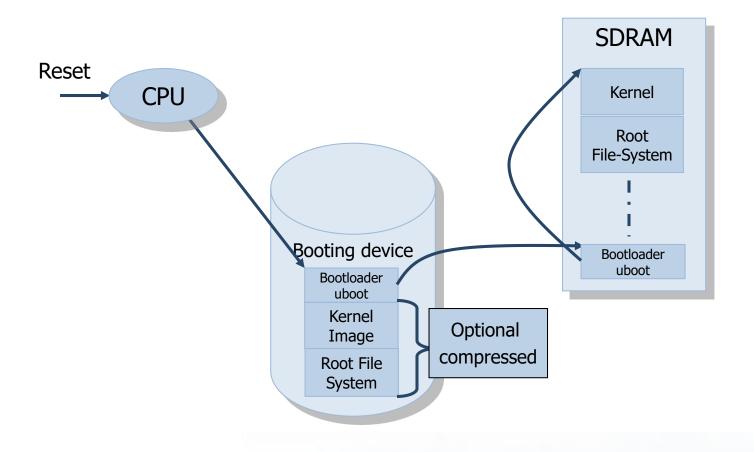


Boot-up program of Tizen



Loading through bootloader

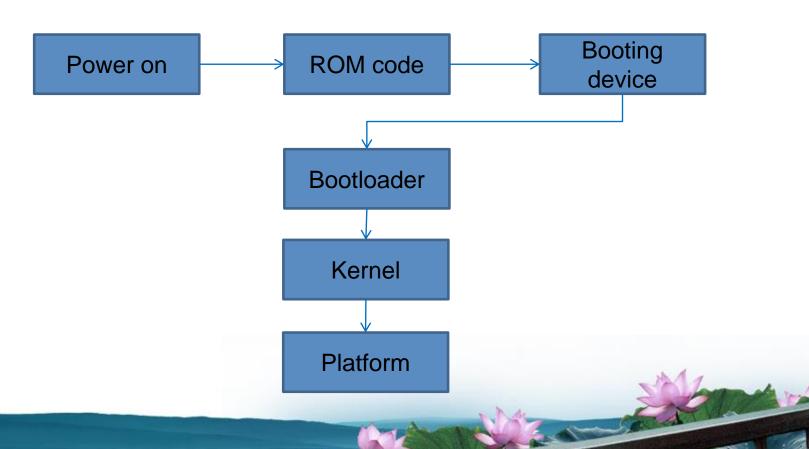




System bootup overview



- Bootloader
 - Memory Init
 - Pass Machine ID and the boot arguments to kernel



What is bootloader

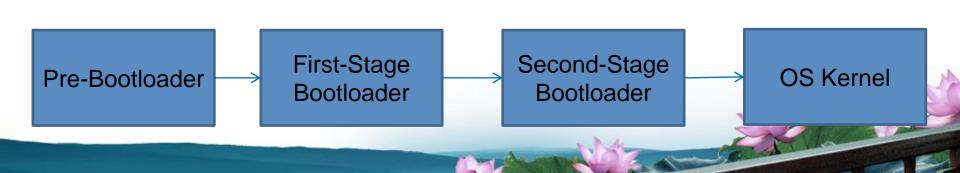


- What is boot loader?
 - A boot loader is the first program which executes (before the main program i.e. kernel) whenever a system is initialized
 - A boot loader is a computer program that loads the main program (i.e. operating system, kernel) for the board after completion of the self-tests
- Why boot loader is needed?
 - Gives a development environment
 - Saves cost of flash writers
 - Setup the basic running environment for operating system
 - Give flexibility to load any operating system

Steps of bootloader

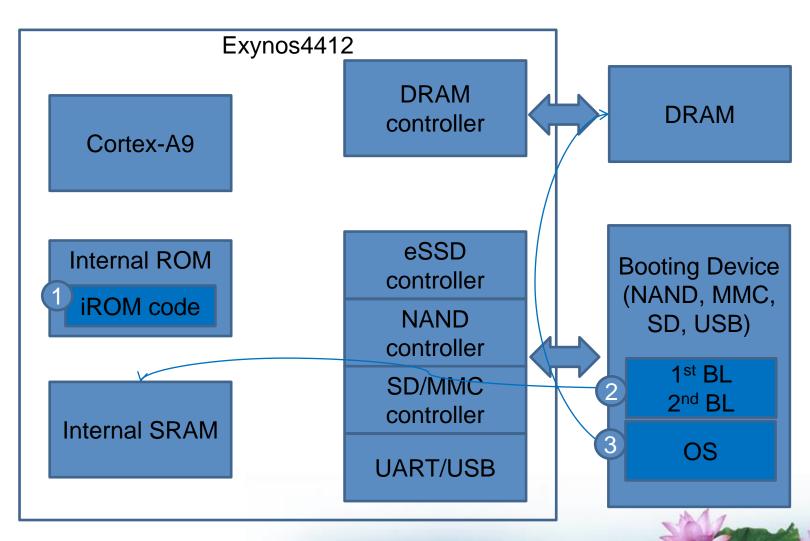


- What are different types of boot loaders?
 - Boot-ROM (or Pre-Boot Loader)
 - Small code which loads First stage boot loader
 - First Stage Boot Loader
 - Small Piece of code that initialize the NAND/MMC & DRAM controller.
 - Second Stage Boot Loader
 - Primary function of the second-stage boot loader is to Loading the kernel into RAM or jumping directly to the start of the kernel.



U-boot loading process





U-boot loading process



- BL0; iRom code (boot-rom or pre-boot loader)
 - Simple platform independent code, stored in internal ROM
 - Initialize basic functions (clock, stack, heap, etc)
 - Load first stage boot loader (from booting device to internal SRAM)
- BL1; first boot loader
 - Simple platform independent code, stored in external memory(booting device)
 - Load second boot loader
 - Initialize NAND/MMC and DRAM controller
- BL2; second boot loader
 - Platform dependent complex code, stored in external memory
 - Initialize clock, UART
 - Load OS image from booting device to DRAM
 - Jump to operating system

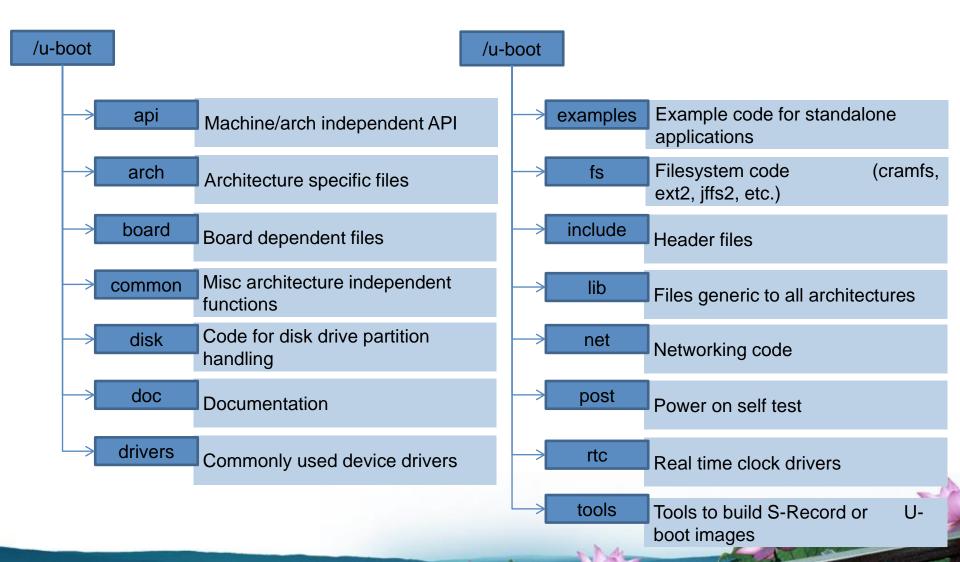
Uboot source code



- \$ git clone ssh://your_id@review.tizen.org:29418/platform/kernel/uboot.git u-boot-tizen
- \$ cd u-boot-tizen
- \$ git checkout -b tizen origin/tizen

U-boot directory structure



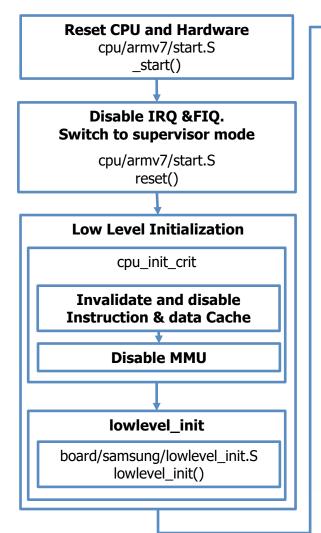


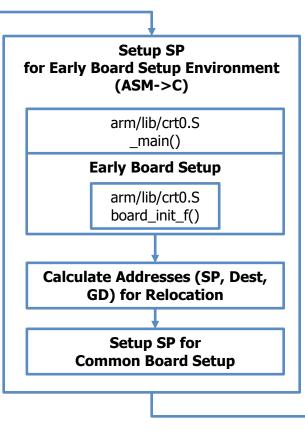


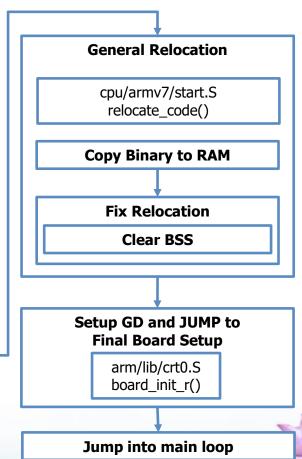
- 1. Disable all interrupts
- 2. Copy any initialized data from ROM to RAM
- 3. Zero the uninitialized data area
- 4. Allocate space for and initialize the stack
- 5. Initialize the processor's stack pointer
- 6. Create and initialize the heap
- 7. Execute the initializers for all global data
- 8. Enable interrupts
- 9. Call main loop













- _start() /* Entry point function */
- reset() /* Reset CPU configurations */
 - save_boot_params() /* Save boot parameters */
 - Disable the FIQ & IRQ
 - Switch to supervisor mode
 - cpu_init_crit()
 - Invalidate I, D Cache
 - Disable I cache if CONFIG_SYS_ICACHE_OFF
 - Disable MMU
 - lowlevel_init()
- _main() /* setup initial stack & global data.
 And jump to C routine for board initialization */



board_init_f()

arm pci init

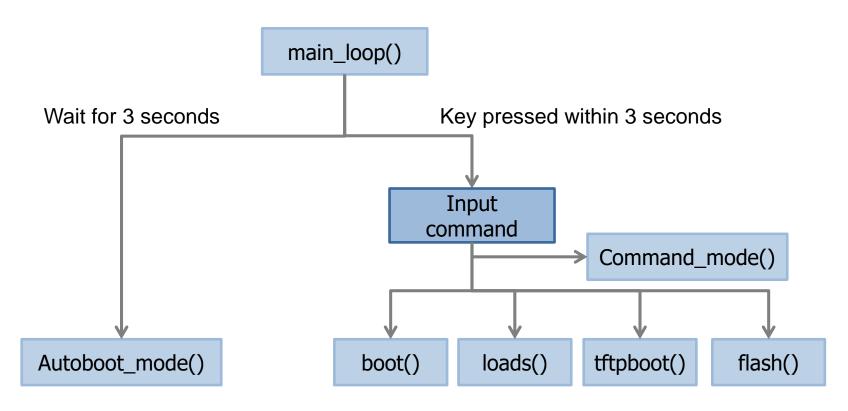
```
arch_cpu_init
                                   // basic arch cpu dependent setup
board_early_init_f
                        // early board initialization, UART pin setting
timer init
                        // initialize timer
env init
                        // initialize mmc/sdcard environment
init baudrate
                                   // initialize baudrate settings
                        // serial communication setup
serial init
console init f
                                   // stage 1 init of console, configure console from
console.c
display_banner
                        // say that we are here, print u-boot banner
print_cpuinfo
                                   // display cpu info
checkboard
                        // display board info
init_func_i2c
                        // initialize I2C
dram_init
                        // configure available RAM backs
```



board_init_r()

```
board init
                        // setup chipselects specific configuration
logbuff_init_ptrs
                        // initialize default log level
mem_malloc_init
                        // configure malloc area
                        // initialize flash/mmc
nand init mmc init
env relocate
                        // relocate environment or set NULL
stdio init
                        // setup stdio ready for use
api init
                        // initialize API
console init r
                        // fully init console as a device
arch misc init
                        // miscellaneous arch dependent initialization
misc init r
                        // miscellaneous platform dependent initialization
interrupt_init
                                   // set up exceptions
enable_interrupts
                        // enable exceptions
                        // board late initialization
board late init
eth initialize
                        // setup ethernet
                        // jump to main loop & waiting for commands from console
main loop
```





Jump to kernel image address

Experiment: Create a bootable TF card



Boot images layout

| Binary name | SD (blk) | eMMC boot* (blk) |
|----------------|----------|---------------------|
| bl1 | 1 | 0 |
| bl2 | 31 | 30 |
| u-boot-mmc.bin | 63 | 62 |
| tzsw | 2111 | 2110 |

■B11, b12, tzsw are provided by hardware vendor.

https://github.com/hardkernel/U-Boot/tree/odroid-v2010.12/sd_fuse

Compile your own u-boot



- DTC build from u-boot-tizen directory:
 - \$ cd ./tools/dtc \$ make install
 - \$ dtc -v #Check DTC version
 - Version: DTC 1.4.0-dirty
- Build the U-Boot Tizen
- Now you can build the U-Boot image using the following commands:
 - \$ CROSS_COMPILE="arm-linux-gnueabihf-" make tizen_config
 - \$ CROSS_COMPILE="arm-linux-gnueabihf-" make

Prepare your file



- First, a multiple dtbs should be appended to it (this is the one of differences with mainline U-Boot):
 - \$./tools/mkimage_multidtb.sh u-boot.bin
- The script output is: u-boot-multi.bin And then make a compatible platform signature:
 - \$./tools/mkimage_signed.sh u-boot-multi.bin tizen_config
- The script output is: u-boot-mmc.bin

Prepare your SD card



- Please follow this steps:
 - \$ cd u-boot-tizen
 - \$ mv u-boot-mmc.bin u-boot.bin #The script sd_fusing.sh uses u-boot.bin
 - \$ mkdir fuse \$ cd fuse
 - \$ wget -q https://github.com/hardkernel/U-Boot/raw/odroid-v2010.12/sd_fuse/bl1.HardKernel
 - \$ wget -q https://github.com/hardkernel/U-Boot/raw/odroid-v2010.12/sd_fuse/bl2.HardKernel
 - \$ wget -q https://github.com/hardkernel/U-Boot/raw/odroidv2010.12/sd_fuse/tzsw.HardKernel
 - \$ wget -q https://github.com/hardkernel/U-Boot/raw/odroid-v2010.12/sd_fuse/sd_fusing.sh
 - \$ chmod u+x sd_fusing.sh
- Please choose the steps suitable for your case (SD or eMMC):
- SD Card
 - Connect the SD Card Reader and insert your card.
 - Check the mass storage device (/dev/sd*) using 'dmesg | tail' commands.
- go into u-boot-tizen/fuse directory
- run:
 - \$ sudo ./sd_fusing.sh /dev/sd*

Homework



- U-boot source code analysis report
- Add a new u-boot command to print your personalized information.



Acknowledgement



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