CS528

End to End Delay Minimization for Scientific Workflow in cloud under Budget Constraints

Robust Scheduling of Scientific Workflows with Deadline and Budget Constraints in Clouds

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Reference:

Wu et.al, End to End Delay Minimization for Scientific Workflow in cloud under Budget Constraints, IEEE Trans. On Cloud Computing. 2015.

Introduction

- With emergence of cloud computing and rapid deployment of cloud infrastructures
 - Number of scientific workflows have been shifted to cloud environments.
- Challenges:
 - Reducing financial cost in addition
 - to meeting the traditional goal : performance
- Quick evaluation of scientific workflow
 - to minimize the workflow end-to-end delay under a user-specified financial constraint

Scientific Workflow: SWF

- Large-scale scientific computing tasks
 - for data generation, processing, and analysis are
 - often assembled and constructed as Workflows
 - comprised of many interdependent modules
- Workflow (WF) module communicates
 - with others through the sharing of data sets,
 - which are either stored in shared file system or
 - transferred from node to node by WF management system
- Scientific Workflows are
 - typically executed in a distributed manner
 - in heterogeneous network environments

WF in Clouds System

- It is essential construct analytical models
 - to quantify the network performance of scientific workflows
 - in IaaS cloud environments,
 - and formulate a task scheduling problem
- Scheduling Problems: WF on Cloud
 - to minimize the workflow end-to-end delay
 - under a user-specified financial cost constraint,
- Referred to as Minimum End-to-end Delay under Cost Constraint (MED-CC)

Workflow Execution in Cloud

- Workflow is represented as
 - a directed acyclic graph (DAG),
- Submitted to the workflow engine
 - for executing, scheduling, tracking and reporting
- Workflow (WF) have independent tasks (Work/W), and
 - Execution model with inter-module dependencies
 - Identify and quantify the key financial and time cost

Cost Model: time and financial

 Time Cost or simply Time: overall time to execute Work W_i on VM_j

$$T_{i,j}=T(I_j)+T(E_{i,j})+T(R_i)$$

- T_{i,j}= overall time to execute Work W_i on VM_j
- $-T(I_i)$ = Startup Time for VM_i
- $-T(E_{i,j})$ = time to execute W_i on VM_j
- $-T(R_i)$ = time of upload/download data from/to VM_j

Cost Model: time and financial

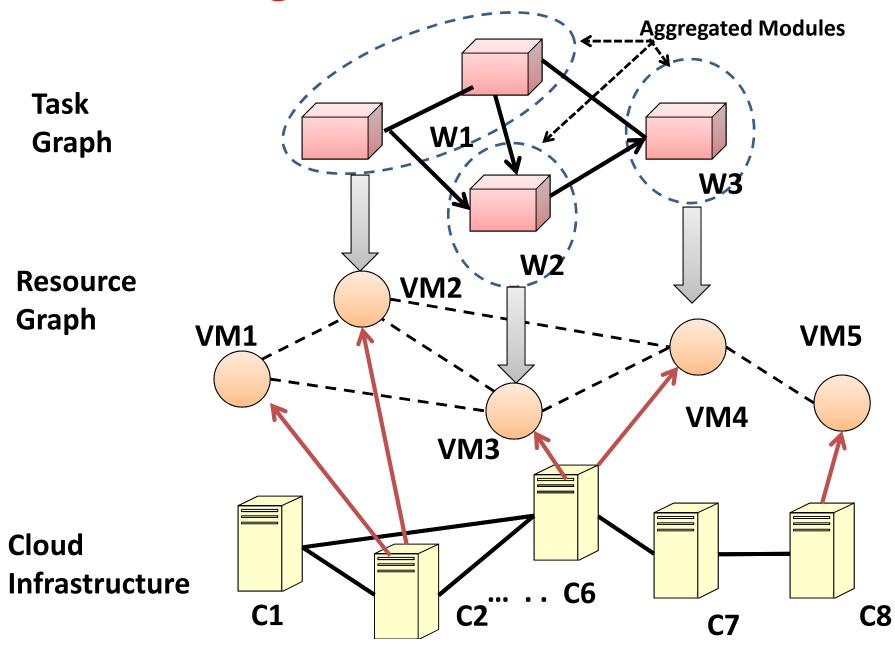
 Financial Cost (or simply Cost): Overall time to execute Work W_i on VM_i

$$C_{i,j}=C(I_j)+C(E_{i,j})+C(R_i)+C(S_i)$$

- $-C(S_i)$ = data storage cost of W_i
- C(I_j), C(E_{i,j}), C(R_i) cost of Init VMj, execution of Wi on VMj and download/upload data to/from VM_i for W_i
- Set of Available VM type VT={vt₀,vt₁,...vt_{n-1}}
 - vt_j have processing power p_j and cost c_j
- Cost of executing W_i on VM_j

$$C(E_{i,j})=T(E_{i,j})*c_j$$

Modeling Workflow Exe in Cloud



3 Layer Models of WF Exeⁿ in Cloud

- Three layers in the work-flow scheduling problem in cloud environments
 - Task graph layer comprised of interdependent workflow modules,
 - Resource graph layer representing a network of VMs,
 - Cloud infrastructure layer consisting of physical computer nodes connected by network links

Work mapping to VM

- Task graph layer: scientific work- flows
 - preprocessed by an appropriate clustering technique
 - based on the inter-module dependencies
 - and the volumes of inter-module data transfer
- A group of modules in the original workflow are
 - bundled together as one aggregate module in the resulted task graph
- Simple mapping: one-to-one mapping scheme
 - Each aggregate module in the task graph is
 - Assigned to a different VM for execution.

Layer1: Workflow Model

Task graph/workflow modeled as DAG

$$G_w(V_w, E_w)$$

- Consisting of V_w modules
- -with E_w directed edges $I_{i,j}$ representing the data dependency between module w_i and w_j
- -Each module $w_i \in V_w$ carries a certain amount of workload WL_i
- Each edge $I_{i,j}$ transfers a certain data size $DS_{i,j}$.

VM Cost and Perf. Model

A set of available VM types

$$VT = \{ vt_0, vt_1, \dots vt_n \}$$

- where each type vt_j is associated with both cost- and performance-related attributes vt_i as : vt_i (vp_i , Cv_i)
- vp_j: Processing power of VM type vt_j
 - including its processor, speed, disk volume and memory space
- Cv_i: Financial cost for using this VM
 - Per time unit including all cost components such as
 - VM initialization, module execution, and data transfer

Layer3: Cloud Infrastructure Model

- cloud infrastructure is model as arbitrary weighted graph $G_c = \{V_c, E_c\}$
 - consisting of a set of physical computer nodes.
 - Each computer node $c_i \in V_c$ has a processing power PP_i
- Cost of a data transfer R_{ij} of size DS_{ij} from module \mathbf{w}_i to \mathbf{w}_i is calculated as:

$$C(R_{i,j}) = C_R . DS_{i,j}$$

Layer 2: Virtual Resource Model

- Virtual Resource : Modeled as fully connected weighted graph $G'_{c}(V'_{c}, E'_{c})$
 - consisting of $|V'_c|$ VMs connected by $|E'_c|$ virtual links.
 - Each virtual link $l'_{p,q}$ has a bandwidth $BW'_{p,q}$,
 - which is a function of physical bandwidth between two physical machines provisioning VMs c'_p and c'_q .
 - Each VM $\mathbf{c'} \in \mathbf{V'_c}$ is an instance of a certain VM type.
- Time of data transfer R_{ij} of size DS_{ij} from module w_i to w_i is calculated as

$$T(R_{i,j}) = DS_{i,j}/BW'_{pq} + d'_{pq}$$

– where d'_{pq} is delay of the virtual link

Time and Cost Execution W_i on VM_J

Time of Execution E_{ij} of module w_i on a VM of type vt_j

$$T(E_{ij}) = WI_i / vp_j$$

- Wl_i is workload of w_i and
- $-\mathbf{vp_j}$ is performance of $\mathbf{vt_j}$ of VM_j
- Module execution cost is calculated as:

$$C(E_{ij}) = T(E_{ij}) C_{Vj}$$

Min End2End Exe Cost Constraints

- MED-CC Problem : Given DAG $G_w(V_w, E_w)$, VT set $VT = \{vt_0, vt_1, \dots vt_n\}$ and budget B
- Find a Schedule S, such that
 - minimum end-to-end delay of the one-to-one mapped workflow is achieved

$$MED = \min_{all\ possible\ S} (T_{total}) = \min_{all\ possible\ S} (\sum_{all\ w_i \in \mathit{CP}} T_{i,j})$$

- Subjected Cost Constraints $C_{total} = \sum_{i=0}^{m-1} C_{i,i} \leq B$
- Proved to be NPC
 - Using Multiple Choice Knapsack Problem (MCKP)

Critical Greedy Heuristics

```
CriticalGreedy(G, VT, B){
```

- 1. For all w_i , for all vt_j calculate C_{ij} and T_{ij}
- 2. Find Minimal Cost C_{min}
- 3. if $(B < C_{min})$ No Solution, return;
- 4. Find Maximal Cost C_{max},
- 5. if (B>C_{max}) Map all w_i to best vt_{max} return;
- 6. AllcateVM using global budget level();
- 7. Do local adjustment ();

Allocate VM using Global Budget Level

Try to allocate good VT based on Budget

$$GBL = (B-C_{min})/(C_{max}-C_{min})$$

For all **w**_i map to **vt**_i with GBL

Target cost for w_i , $tc_i = C_{i,min} + (C_{i,max} - C_{i,min}) * GBL$

Target VT for w_i, for min(tc_i-C_{i,k}) and C_{i,k}<tc_i

Do local adjustment ();

```
While cost2Spend > 0 {
Calculate Current Critical path CP;
For all w<sub>i</sub> in CP for all vt<sub>i</sub>
  find max benefit with \Delta T_{i,j} > 0 and \max \frac{\Delta T_{i,j}}{\Delta C_{i,i}}
  //Putting small money but max time reduction
  if such wi found change mapping of wi to new vti
  cost2Spend -= ExtraCostSpendonThis;
```

Reference:

Poola et.al, *Robust Scheduling of Scientific Workflows with Deadline and Budget Constraints in Clouds*, IEEE Int. Conf. on Adv. Info.

Networking & Applications,. 2014.

Introduction

- Scientific workflows Scheduling in Cloud
 - Cost and Deadline common criteria
- Reliability and Robustness is also Important
- Robust scheduling
 - that handles performance variations of Cloud resources and
 - failures in the environment is essential in the context of Clouds
- Robust and fault-tolerant schedule
 - while minimizing makespan.

Failure in Cloud

- Failures also affect the overall workflow execution and increase the makespan.
- Failures in a workflow application are types
 - Task failures, VM failures, WF level failures
- Task failures may occur due to
 - dynamic execution environment configurations,
 - missing input data, or
 - system errors.
- VM failures are caused by
 - hardware failures and load in the datacenter

Failure in Cloud

- Workflow level failures can occur due to
 - server failures, Cloud outages,
- Prominent fault tolerant techniques that handle such failures are
 - retry, alternate resource, check-pointing, and replication
- Workflow management systems
 - should handle performance variations and
 - failures while scheduling workflows

Robust Scheduler

- A schedule is said to be robust if
 - it is able to absorb some degree of uncertainty
 - in the task execution time
- Robust schedules are much needed in
 - mission-critical applications and
 - time-critical applications
- Robust and fault-tolerant scheduling algorithms
 - identify these aspects and provide a schedule
 - that is insensitive to these uncertainties
 - by tolerating variations and failures
 - in the environment up to a certain degree.

Robust Scheduler

- Robustness of a schedule is always
 - measured with respect to another parameter such as makespan, schedule length
- Robustness is usually achieved
 - with redundancy in time or space
 - Adding slack time or replication of nodes.
- Robust Scheduling Approach
 - efficiently maps tasks on resources
 - judiciously adds slack time based on the deadline and budget constraints

System Model

- Cloud environment in system model has a single datacenter
 - that provides heterogeneous VM/resource types

$$VT = \{vt_1, vt_2, ..., vt_m\}$$

- Each VM type has: config. and price
- Configuration of VM type differs
 - with respect to memory, CPU measured in (MIPS) and OS.
- Each vt_i has a Price(vt_i) associated with it
 - charged on an unit time basis
 - (e.g. 1 hour, 10 minutes, etc.)

Kind of Failure/Uncertainty

- Two kinds of uncertainties
 - task failures and performance variations of VMs.
- Performance variations in the system arise due to
 - factors like load, network delays, VM consolidation, etc.
- Due to the performance variation of a VM
 - Execution time of task increase/decrease by y
- y is a random variable with a mean value of zero.
- Actual execution time (AET) of a task is

$$AET(t_i) = e_i (1 + y),$$

– where e_i is the expected execution time of task t_i .

Workflow representation

- Workflow as DAG, G = (T, E),
 - where T is a set of nodes, $T = \{t_1, t_2, ..., t_n\}$, each node represents a task
 - E represents a set of edges between tasks, which can be control and/or data dependencies.
- Each workflow: bounded by user defined
 - deadline D, money budget B constraints.
- Each task t_i has a task length (Payload/work) of
 - len_i given in Million Instructions.
- Task length and MIPS value of VM are used
 - Estimate the execution time on a particular VM type