MA 322: Scientific Computing Lecture - 4



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• It is called forward difference operator **because** evaluation of $\Delta f(x)$ depends on the value of f(x+h).

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Proof.

- $\bullet \Delta f(x)$ is called first order forward difference.
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 - Similarly, other higher order forward difference operators, denoted by $\Delta^3 f(x), \ \Delta^4 f(x), \dots$ etc. can be defined. In general, $\Delta^{r+1} = \Delta^r(\Delta)$
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(Take other relations as Home Work.)



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X	f(x)	$\Delta f(x)$
<i>x</i> ₀	$f(x_0)$	
	\longrightarrow	$\Delta f(x_0) = f(x_1) - f(x_0)$
x_1	$f(x_1)$	
	\longrightarrow	$\Delta f(x_1) = f(x_2) - f(x_1)$
x_2	$f(x_2)$	
:	:	<u>:</u>
x_{n-1}	$f(x_{n-1})$	
		$\Delta f(x_{n-1}) = f(x_n) - f(x_{n-1})$
X _n	$f(x_n)$	

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• Using the fact $\Delta^2 f(x_i) = \Delta f(x_{i+1}) - \Delta f(x_i)$, we have following tabular representation for first and second order finite differences

X	f(x)	$\Delta f(x)$	$\Delta^2 f(x)$
<i>x</i> ₀	$f(x_0)$		
	\longrightarrow	$\Delta f(x_0)$	
x_1	$f(x_1)$	\longrightarrow	$\Delta^2 f(x_0) = \Delta f(x_1) - \Delta f(x_0)$
	\longrightarrow	$\Delta f(x_1)$	
<i>x</i> ₂	$f(x_2)$	\longrightarrow	$\Delta^2 f(x_1) = \Delta f(x_2) - \Delta f(x_1)$
:	:	:	:
x_{n-1}	$f(x_{n-1})$	\longrightarrow	$\Delta^2 f(x_{n-2}) = \Delta f(x_{n-1}) - \Delta f(x_{n-2})$
	\longrightarrow	$\Delta f(x_{n-1})$	
Xn	$f(x_n)$		

Tabular Representation of Forward Differences Contd..

Example If f(0) = 3, f(1) = 12, f(2) = 81, f(3) = 200 and f(4) = 100, find $\Delta^4 f(0)$.

X	f(x)	$\Delta f(x)$	$\Delta^2 f(x)$	$\Delta^3 f(x)$	$\Delta^4 f(x)$
0	3				
	\longrightarrow	9			
1	12	\longrightarrow	60	-10	
				-10	-259
2	81	69 <i>→</i>	50		
				-269	
3	→ 200 →	$\begin{array}{c} 119 \\ \longrightarrow \\ -100 \end{array}$	-219		
4	100	100			

• Now, we wish to discuss finite differences for the polynomial function. For polynomials, we observe following patterns

 $\Delta x =$

$$\Delta x = (x+h) - x =$$

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$$\Delta^2 x^2 =$$

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The answer is given by



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The answer is given by Fundamental Theorem of Finite Difference.



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$$= \Delta^{k+1}(a_0x^{k+1}) + \Delta\{\Delta^k(a_1x^k + a_2x^{k-1} + \dots + a_kx + a_{k+1})\}. (2)$$

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Hence, the result is true for n = k + 1. This completes the rest of the proof.

Important Applications:

Important Applications: Missing Values

- Important Applications: Missing Values
 - Estimate f(4) from the following data

X	1	2	3	4	5
,,		_	_		_

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Х	1	2	3	4	5
y = f(x)	2	5	7	×	32

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- In the above question, we are asked to 'Estimate' f(4) not to find f(4). What does it mean?
- In practice, we may not able to find f(4) exactly from the given data.

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- Interpolation is a technique of fitting a continuous function.