

MA 322: Scientific Computing

Lecture - 6



Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the monomial basis $1, x, \dots, x^n$, which corresponds to the choice $\phi_j(x) = x^j$ for $j = 0 : n$.

Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the monomial basis $1, x, \dots, x^n$, which corresponds to the choice $\phi_j(x) = x^j$ for $j = 0 : n$. Then $p(x) = a_0 + a_1x + \dots + a_nx^n$ is obtained by solving the Vandermonde system

$$\begin{bmatrix} 1 & x_0 & \cdots & x_0^n \\ 1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \cdots & \vdots \\ 1 & x_n & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}.$$

Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the monomial basis $1, x, \dots, x^n$, which corresponds to the choice $\phi_j(x) = x^j$ for $j = 0 : n$. Then $p(x) = a_0 + a_1x + \dots + a_nx^n$ is obtained by solving the Vandermonde system

$$\begin{bmatrix} 1 & x_0 & \cdots & x_0^n \\ 1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \cdots & \vdots \\ 1 & x_n & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}.$$

Drawbacks:

- The Vandermonde matrix is extremely ill-conditioned.

Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the monomial basis $1, x, \dots, x^n$, which corresponds to the choice $\phi_j(x) = x^j$ for $j = 0 : n$. Then $p(x) = a_0 + a_1x + \dots + a_nx^n$ is obtained by solving the Vandermonde system

$$\begin{bmatrix} 1 & x_0 & \cdots & x_0^n \\ 1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \cdots & \vdots \\ 1 & x_n & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}.$$

Drawbacks:

- The Vandermonde matrix is extremely ill-conditioned.
- The solution of the system requires large numbers of operations.

Interpolating polynomial in monomial basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the monomial basis $1, x, \dots, x^n$, which corresponds to the choice $\phi_j(x) = x^j$ for $j = 0 : n$. Then $p(x) = a_0 + a_1x + \dots + a_nx^n$ is obtained by solving the Vandermonde system

$$\begin{bmatrix} 1 & x_0 & \cdots & x_0^n \\ 1 & x_1 & \cdots & x_1^n \\ \vdots & \vdots & \cdots & \vdots \\ 1 & x_n & \cdots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{bmatrix}.$$

Drawbacks:

- The Vandermonde matrix is extremely ill-conditioned.
- The solution of the system requires large numbers of operations.
- Any additional new data (x_{n+1}, f_{n+1}) requires re-computation.

Example

Consider the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$. Then there is a unique interpolating polynomial $p(x) = a_0 + a_1x + a_2x^2$ of degree ≤ 2 .

Example

Consider the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$. Then there is a unique interpolating polynomial $p(x) = a_0 + a_1x + a_2x^2$ of degree ≤ 2 .

The Vandermonde system is given by

$$\begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

Example

Consider the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$. Then there is a unique interpolating polynomial $p(x) = a_0 + a_1x + a_2x^2$ of degree ≤ 2 .

The Vandermonde system is given by

$$\begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix}.$$

Example

Consider the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$. Then there is a unique interpolating polynomial $p(x) = a_0 + a_1x + a_2x^2$ of degree ≤ 2 .

The Vandermonde system is given by

$$\begin{bmatrix} 1 & x_0 & x_0^2 \\ 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & -2 & 4 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix}.$$

Solving the system, we have $[a_0, a_1, a_2] = [-1, 5, -4]$ so that the interpolating polynomial is given by

$$p(x) = -1 + 5x - 4x^2.$$

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

$$\phi_0(x) := (x - x_1)(x - x_2) \cdots (x - x_n) \text{ and } \ell_0(x) = \frac{\phi_0(x)}{\phi_0(x_0)}$$

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

$$\phi_0(x) := (x - x_1)(x - x_2) \cdots (x - x_n) \text{ and } \ell_0(x) = \frac{\phi_0(x)}{\phi_0(x_0)}$$

$$\phi_1(x) := (x - x_0)(x - x_2) \cdots (x - x_n) \text{ and } \ell_1(x) := \frac{\phi_1(x)}{\phi_1(x_1)}$$

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

$$\phi_0(x) := (x - x_1)(x - x_2) \cdots (x - x_n) \text{ and } \ell_0(x) = \frac{\phi_0(x)}{\phi_0(x_0)}$$

$$\phi_1(x) := (x - x_0)(x - x_2) \cdots (x - x_n) \text{ and } \ell_1(x) := \frac{\phi_1(x)}{\phi_1(x_1)}$$

$$\vdots$$

$$\phi_n(x) := (x - x_0)(x - x_1) \cdots (x - x_{n-1}) \text{ and } \ell_n(x) := \frac{\phi_n(x)}{\phi_n(x_n)}$$

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

$$\phi_0(x) := (x - x_1)(x - x_2) \cdots (x - x_n) \text{ and } \ell_0(x) = \frac{\phi_0(x)}{\phi_0(x_0)}$$

$$\phi_1(x) := (x - x_0)(x - x_2) \cdots (x - x_n) \text{ and } \ell_1(x) := \frac{\phi_1(x)}{\phi_1(x_1)}$$

$$\vdots$$

$$\phi_n(x) := (x - x_0)(x - x_1) \cdots (x - x_{n-1}) \text{ and } \ell_n(x) := \frac{\phi_n(x)}{\phi_n(x_n)}$$

- The basis $\ell_0(x), \dots, \ell_n(x)$ is called the **Lagrange basis** of \mathcal{P}_n .

Interpolating polynomial in Lagrange basis

- Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.
- Consider the bases $\phi_0(x), \dots, \phi_n(x)$ and $\ell_0(x), \dots, \ell_n(x)$ given by

$$\phi_0(x) := (x - x_1)(x - x_2) \cdots (x - x_n) \text{ and } \ell_0(x) = \frac{\phi_0(x)}{\phi_0(x_0)}$$

$$\phi_1(x) := (x - x_0)(x - x_2) \cdots (x - x_n) \text{ and } \ell_1(x) := \frac{\phi_1(x)}{\phi_1(x_1)}$$

\vdots

$$\phi_n(x) := (x - x_0)(x - x_1) \cdots (x - x_{n-1}) \text{ and } \ell_n(x) := \frac{\phi_n(x)}{\phi_n(x_n)}$$

- The basis $\ell_0(x), \dots, \ell_n(x)$ is called the **Lagrange basis** of \mathcal{P}_n .
- Then it follows that

$$\ell_j(x) = \prod_{i \neq j} \frac{(x - x_i)}{(x_j - x_i)}, \quad j = 0 : n.$$

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .
- Any additional new data requires re-computation.

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .
- Any additional new data requires re-computation.

Example: For the data set $(-2, -27), (0, -1), (1, 0)$, we have

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .
- Any additional new data requires re-computation.

Example: For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$p(x) = -27 \frac{(x-0)(x-1)}{(-2-0)(-2-1)} - 1 \frac{(x+2)(x-1)}{(0+2)(0-1)} + 0 \frac{(x+2)(x-0)}{(1+2)(1-0)}$$

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .
- Any additional new data requires re-computation.

Example: For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{aligned} p(x) &= -27 \frac{(x-0)(x-1)}{(-2-0)(-2-1)} - 1 \frac{(x+2)(x-1)}{(0+2)(0-1)} + 0 \frac{(x+2)(x-0)}{(1+2)(1-0)} \\ &= -\frac{9}{2}x(x-1) + \frac{1}{2}(x+2)(x-1) \end{aligned}$$

Interpolating polynomial in Lagrange basis (cont.)

Note that $\ell_j(x_i) = \delta_{ij}$, where δ_{ij} is the Dirac delta function. Hence it follows that the polynomial

$$p(x) := f_0\ell_0(x) + \cdots + f_n\ell_n(x)$$

interpolates the data set $(x_0, f_0), \dots, (x_n, f_n)$ and is called the **Lagrange interpolating** polynomial.

Drawbacks:

- Cannot accommodate new data (x_{n+1}, f_{n+1}) .
- Any additional new data requires re-computation.

Example: For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{aligned} p(x) &= -27 \frac{(x-0)(x-1)}{(-2-0)(-2-1)} - 1 \frac{(x+2)(x-1)}{(0+2)(0-1)} + 0 \frac{(x+2)(x-0)}{(1+2)(1-0)} \\ &= -\frac{9}{2}x(x-1) + \frac{1}{2}(x+2)(x-1) = -1 + 5x - 4x^2 \end{aligned}$$

Interpolating polynomial in Newton basis

Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Interpolating polynomial in Newton basis

Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Define $N_0(x) := 1$ and $N_j(x) := (x - x_0) \cdots (x - x_{j-1})$ for $j = 1 : n$.

Interpolating polynomial in Newton basis

Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Define $N_0(x) := 1$ and $N_j(x) := (x - x_0) \cdots (x - x_{j-1})$ for $j = 1 : n$.

Fact: The Newton polynomials $N_0(x), \dots, N_n(x)$ form a basis of \mathcal{P}_n which is referred to as **Newton basis**.

Interpolating polynomial in Newton basis

Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Define $N_0(x) := 1$ and $N_j(x) := (x - x_0) \cdots (x - x_{j-1})$ for $j = 1 : n$.

Fact: The Newton polynomials $N_0(x), \dots, N_n(x)$ form a basis of \mathcal{P}_n which is referred to as **Newton basis**.

Let $p(x) := a_0 N_0(x) + \cdots + a_n N_n(x)$. The interpolation conditions $p(x_j) = f_j$ for $j = 0 : n$ yield the **lower triangular system**

Interpolating polynomial in Newton basis

Consider the nodes $[x_0, \dots, x_n]$ and the values $[f_0, \dots, f_n]$.

Define $N_0(x) := 1$ and $N_j(x) := (x - x_0) \cdots (x - x_{j-1})$ for $j = 1 : n$.

Fact: The Newton polynomials $N_0(x), \dots, N_n(x)$ form a basis of \mathcal{P}_n which is referred to as **Newton basis**.

Let $p(x) := a_0 N_0(x) + \cdots + a_n N_n(x)$. The interpolation conditions $p(x_j) = f_j$ for $j = 0 : n$ yield the **lower triangular system**

$$\begin{bmatrix} N_0(x_0) & 0 & 0 & \cdots & 0 \\ N_0(x_1) & N_1(x_1) & 0 & \cdots & 0 \\ N_0(x_2) & N_1(x_2) & N_2(x_2) & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ N_0(x_n) & N_1(x_n) & N_2(x_n) & \cdots & N_n(x_n) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}.$$

Interpolating polynomial in Newton basis

Consider the **nodes** $[x_0, \dots, x_n]$ and the **values** $[f_0, \dots, f_n]$.

Define $N_0(x) := 1$ and $N_j(x) := (x - x_0) \cdots (x - x_{j-1})$ for $j = 1 : n$.

Fact: The Newton polynomials $N_0(x), \dots, N_n(x)$ form a basis of \mathcal{P}_n which is referred to as **Newton basis**.

Let $p(x) := a_0 N_0(x) + \cdots + a_n N_n(x)$. The interpolation conditions $p(x_j) = f_j$ for $j = 0 : n$ yield the **lower triangular system**

$$\begin{bmatrix} N_0(x_0) & 0 & 0 & \cdots & 0 \\ N_0(x_1) & N_1(x_1) & 0 & \cdots & 0 \\ N_0(x_2) & N_1(x_2) & N_2(x_2) & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ N_0(x_n) & N_1(x_n) & N_2(x_n) & \cdots & N_n(x_n) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}.$$

Solving the triangular system for $a_j, j = 0 : n$, we obtain the interpolating polynomial $p(x) = a_0 N_0(x) + \cdots + a_n N_n(x)$ in **Newton's form**.

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix}$$

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix} \implies [a_0, a_1, a_2] = [-27, 13, -4].$$

Hence

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix} \implies [a_0, a_1, a_2] = [-27, 13, -4].$$

Hence $p(x) = -27 + 13(x + 2) - 4(x + 2)x$

Interpolating polynomial in Newton basis (cont.)

Advantage: Can accommodate new data (x_{n+1}, f_{n+1}) with additional computational cost.

Example: For the data set $(x_0, f_0), (x_1, f_1), (x_2, f_2)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & (x_1 - x_0) & 0 \\ 1 & (x_2 - x_0) & (x_2 - x_0)(x_2 - x_1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} f_0 \\ f_1 \\ f_2 \end{bmatrix}.$$

For the data set $(-2, -27), (0, -1), (1, 0)$, we have

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 2 & 0 \\ 1 & 3 & 3 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} -27 \\ -1 \\ 0 \end{bmatrix} \implies [a_0, a_1, a_2] = [-27, 13, -4].$$

Hence $p(x) = -27 + 13(x + 2) - 4(x + 2)x = -1 + 5x - 4x^2$.