

class Topology:

```
def init(self, array):
```

```
    self.nodes = array.
```

```
    self.edges = []
```

```
def connect(self, point1, point2, weight):
```

```
    self.edges.append(point1, point2, weight)
```

```
    self.edges.append(point2, point1, weight)
```

```
def distanceVectorRouting(self):
```

```
    import collections
```

```
    for point in self.nodes:
```

```
        distance = collections.defaultdict(int)
```

```
        next_hop = {pointnode: node}
```

```
        for points in self.nodes:
```

```
            if points != point:
```

```
                distance[points] = 99999
```

```
    for i in range(self.nodes.__len__ - 1):
```

```
        for edge in self.edges:
```

```
            source, destination, weight = edge.
```

```
            if distancedestination[source] + weight
```

```
                < distancedestination[destination]:
```

N. Agarwal

distance [destination] = distance [destination] + weight

if source == point:

next_hop [destination] = destination.

else if source in next_hop:

next_hop [destination] = next_hop[source]

self.print_table (node, distance, next_hop)

def print_table (self, node, dist, next_hop)

for dest, cost in dist.items():

print (f' {dest} \t {cost} \t {next_hop
[dest]}')

nodes = ['A', 'B', 'C', 'D', 'E', 'F', 'G']

t = Topology (nodes).

t.~~add~~ connect ('A', 'B', 4)

t. connect ('A', 'C', 5)

" ('A', 'D', 3)

" ('B', 'C', 2)

" ('B', 'F', 3)

" ('B', 'G', 4)

" ('C', 'D', 6)

" ('C', 'E', 4)

" ('C', 'F', 4)

" ('D', 'E', 3)

" ('E', 'F', 2)

" ('F', 'G', 5)

t.distance Vector
Routing()