Assignment I	Optimization Techniques in Engineering
Department of Mechanical Engineering	ME 6003/2004

1. Match the following terms and descriptions.

(a) Free feasible point	$g_j(X)=0$
(b) Free infeasible point	Some $g_j(X) = 0$ and other $g_j(X) < 0$
(c) Bound feasible point	Some $g_j(X) = 0$ and other $g_j(X) > 0$
(d) Bound infeasible point	Some $g_j(X) > 0$ and other $g_j(X) < 0$
(e) Active constraints	All $g_i(X) < 0$

- 2. Define the following terms with example.
 - (a) Design Variable, (b) Side Constraint, (c) Behavior constraint
 - (d) Objective Function (e) Inequality and Equality constraints
 - (f) Graphical method of solving the two variables non-linear problem.
- 3. Define an Optimization Constrained problem and give an engineering example.
- 4. What is the difference between linear and nonlinear programming problems?
- 5. What is the difference between design variables and preassigned parameters?
- 6. What is a design space? What is the difference between a bound point and a free point in the design space? What are objective function contours?
- 7. State five engineering applications of optimization.
- 8. Give detail of the classifications of the optimization problems.

9.

Consider the slider-crank mechanism shown in Fig. 1.16 with the crank rotating at a constant angular velocity ω . Use a graphical procedure to find the lengths of the crank and the connecting rod to maximize the velocity of the slider at a crank angle of $\theta = 30^{\circ}$ for $\omega = 100$ rad/s. The mechanism has to satisfy Groshof's criterion $l \ge 2.5r$ to ensure 360° rotation of the crank. Additional constraints on the mechanism are given by $0.5 \le r \le 10$, $2.5 \le l \le 25$, and $10 \le x \le 20$.

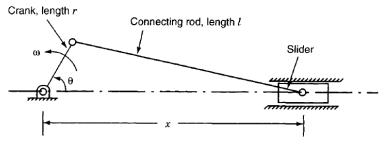


Figure 1.16 Slider-crank mechanism.

- 10. What is single variable unconstrained optimization problem.
- 11. Provide the list of different optimization methods that are available to solve the single variable optimization problem.
- 12. Explain the Direct search method for solving the OUC problem with its algorithm.
- 13. What are the methods available to eliminate the region of the uncertainty interval. Write down their algorithms for eliminating the region.
- 14. Write down the necessary and sufficient conditions to find the maximum and minimum of the objective function.
- 15. Explain the concept of local maxima, local minima, global maxima and global minima.
- 16. Solve the problem for minimization using exhaustive search method. $F(x)= x^2 + 54 / x$ in the interval [0,5].
- 17. Solve the above objective function with bounding phase method and dichotomous method.