Naive Bays & Support Vector Machines

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Outline

- 1. Introduction
- 2. Bayesian Classifier
- 3. Support Vector Machines

Bayesian Classifiers

- There are three different types of Bayesian Classifiers.
- 1. Maximum Likelihood Classifier
- 2. Minimum Distance Classifier
- 3. Minimum Risk Classifier

Maximum likelihood classifier is the most popular classifier.

It requires the following information

- 1. P(i)- Prior Probability of the class
- 2. P(x/i)-Conditional Probability that class i has x. This can be calculated from the training data table.
- 3. P(x)-Sum of P(x/i) over the entire dataset. This information is not the probability information, but serves as a normalization factor.

Bayesian Classifiers

- There are three types of Naive Bayes Model, which are given below:
- ❖ Gaussian: The Gaussian model assumes that features follow a normal distribution. This means if predictors take continuous values instead of discrete, then the model assumes that these values are sampled from the Gaussian distribution.
- Multinomial: The Multinomial Naïve Bayes classifier is used when the data is multinomial distributed. It is primarily used for document classification problems, it means a particular document belongs to which category such as Sports, Politics, education, etc. The classifier uses the frequency of words for the predictors.
- ❖ Bernoulli: The Bernoulli classifier works similar to the Multinomial classifier, but the predictor variables are the independent Booleans variables. Such as if a particular word is present or not in a document. This model is also famous for document classification tasks.

Bayesian Classifiers

What is Bayesian Principle?

As per the Bayesian Principle, one can find the inverse probability P(i/x) from P(x/i) and P(i). The Bayes theorem can be given as

The Prior Probability of the class can be obtained from the training set.

The Prior Probability can be estimated by plotting a histogram of the image.

Maximum likelihood Classifier

- Arr The **Bayesian rule** can be applied as the only term that is unknown is P(i/x).
- ❖ The Bayesian optimality rule states that any instance assigned to a wrong class is worse and all types of misclassifications are equally worse.
- ❖ Therefore, according to the Bayesian maximum likelihood classifier, the instance is assigned to class i for which P(i/x) is maximum.

Advantages

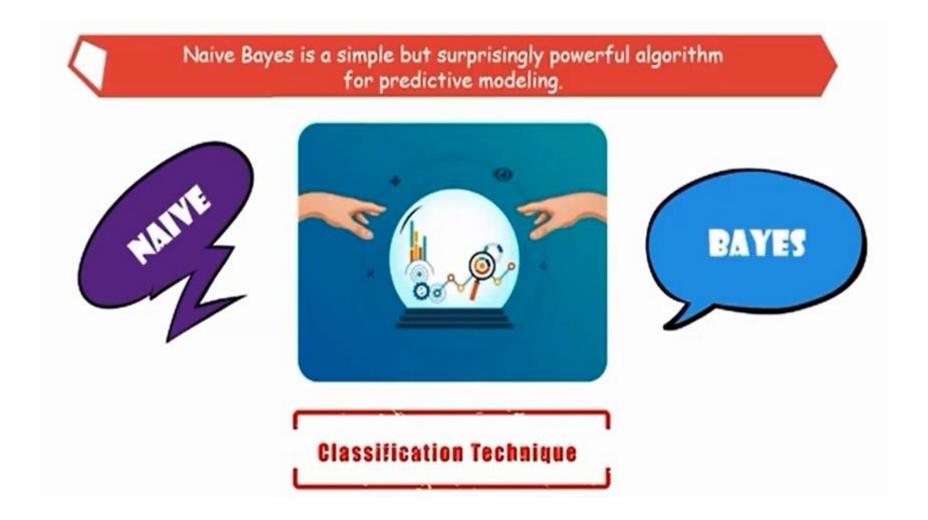
Easy to use, It requires only one scan of the training set, & not affected much by missing values.

It produces good results for datasets with simple relationships.

Naïve Bayes

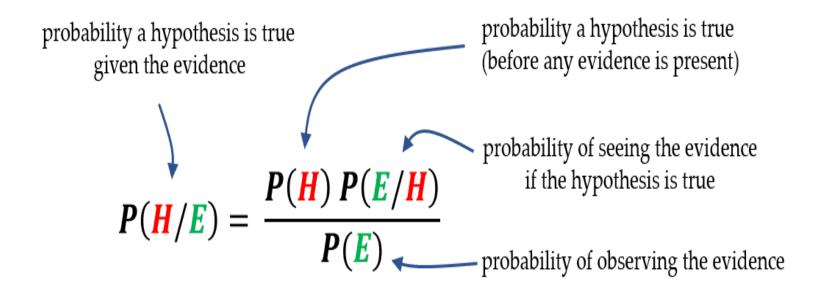
- What is Naïve Bayes
- Bayes Theorem and Its use
- Mathematical working of Naïve Bayes
- Step by step programming Naïve Bayes
- Prediction using Naïve Bayes
- Predictive Analytics

Naïve Bayes



Bayes Theorem

Given a hypothesis H and Evidence E, Bayes theorem states that the relationship between The probability of the hypothesis before getting the evidence P(H) and the probability of the Hypothesis after getting the evidence P(H/E) is



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Naïve Bayes

Classification technique based on Bayes theorem Assumes that the presence of a particular feature in a class is unrelated to the presence of any other feature.

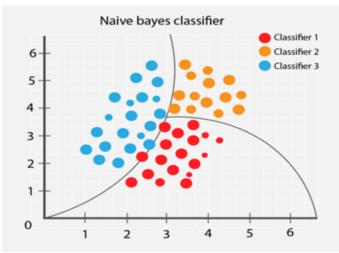
Naive Bayes

In machine learning, naive Bayes classifiers are a family of simple "probabilistic classifiers" based on applying Bayes' theorem with strong (naive) independence assumptions between the features.

$$P(A|B) = \frac{P(B|A) P(A)}{P(B)}$$

using Bayesian probability terminology, the above equation can be written as

$$Posterior = \frac{prior \times likelihood}{evidence}$$



Bayes Theorem Proof

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

$$P(B|A) = \frac{P(B \cap A)}{P(A)}$$

$$P(A \cap B) = P(A|B).P(A) = P(B|A).P(B)$$
$$= P(A|B) = P(B|A).P(B)$$
$$P(A)$$

Bayes Theorem Proof

Likelihood

How probable is the evidence Given that our hypothesis is true?

Prior

How probable was our hypothesis Before observing the evidence?

$$P(H|E) = P(E|H).P(H)$$
 $P(E)$

Posterior

How probable is our Hypothesis Given the observed evidence? (Not directly computable)

Marginal

How probable is the new evidence Under all possible hypothesis?

Naïve Bayesian Classifier

❖ If the features or attributes are assumed to be implemented, the resulting classifier is called Naïve Bayesian Classifier.

Algorithm

- 1. Train the classifier with the training images or labelled featured data.
- 2. Compute the probability P(i) using intuition, based on experts' opinion, or using Histogram-based estimation.
- 3. Compute P(i/x)
- 4. Find the maximum P(i/x) and assign the unknown instances to that class.

Naïve Bayesian classifier does not work for real time datasets as it Naïve to assume that the features are independent of each other and also naïve Bayesian classification does not work for continuous data.

Naïve Bayes Working

Classification Steps

- Handling Data
- Summarizing Data
- Making a Prediction
- Making all the Prediction
- Evaluate the Accuracy
- Tying all together

1. Let us assume a simple dataset, as shown in Table. Let us apply the Bayesian classifier to predict (2,2).

a1	a2	class(i)
2	0	c1
0	2	c1
2	4	c2
0	2	c2
_3	2	c2

Soln-Here c1=2 and c2=3 from the training set. Therefore the prior probabilities are P(c1) = 2/5 and P(c2) = 3/5. The conditional probability is estimated.

$$P(a1=2/c1)=1/2$$
; $P(a1=2/c2)=1/3$
 $P(a2=2/c1)=1/2$; $P(a2=2/c2)=2/3$

Therefore,
$$P(x/c1) = P(a1=2/c1) \times P(a2=2/c1) = 1/2 \times 1/2 = 1/4$$

Soln-

$$P(x/c2) = P(a1=2/c2) \times P(a2=2/c2)$$

= 1/3 x 2/3 = 2/9

$$p(x)=1$$

This is used to evaluate

$$P(c1/x) = P(c1) \times P(x/c1)/p(x)$$

$$= 2/5 \times 1/4 = 2/20=0.1$$

$$P(c2/x)=P(c2) \times P(x/c2)/p(x)$$

$$= 3/5 \times 2/9=6/45=0.13$$

Since P(c2/x) > P(c1/x), the sample is predicted to be in class c2.

1. Let us consider a classification problem that involves classification of an image pixel using a single feature colour into two classes-forest and non-forest. Let the prior probability of the forest class be 0.6, the feature i of colour green belonging to the forest image in the training set be 0.2, and the probability of the green pixel feature belonging to the forest in the overall population be 0.4. What is the probability that an image is a forest image given that the image contains the green colour feature?

Soln-For the two given classes, the only feature commonly available is colour. Let the feature be x. So the available information is

- (a) Prior probability of the class P(i) is 0.6
- (b) Conditional Probability that the class i has x=P(x/i)=0.2
- (c) P(x)=0.4

So as per the Bayesian theorem,
$$P(i/x) = \frac{P(x/i) P(i)}{P(x)} = \frac{0.2 \times 0.6}{0.4}$$

Fruit	Yellow	Sweet	Long	Total	P(Fruit Orange) = (-53 × 0.69 × 0 = 0) P(Fruit Banana) = 1 × 0.75 × 0.87 = (0.65)
Orange	350	450	0	650	
Banana	400	300	350	400	P(Fruit Others) = 0.33 x 0.66 x 0.33 = 0.072
Others	50	100	50	150	
Total	800	850	400	1200	
P(Ale	3) = P((B/A).	P(A)		
P(B) 350 , 800					
P(Yellow Orange) = P(orange Yellow). P(Yellow) = 800 1200					
l len	P(orange) 1200				

Example 13.6 Use Naïve Bayes classifier and classify the unknown pixel X. There are two classes of pixels # and * present in the image as shown:

$$\begin{pmatrix} \# & \# & \# & * \\ \# & X & \# & * \\ \# & \# & * & * \\ \# & \# & * & * \end{pmatrix}$$

Consider the 8-neighbourhood of X and determine the class of X.

Solution The prior probabilities are
$$P(\text{Pixel} = \text{`#'}) = \frac{\text{Number of # pixels}}{\text{Total number of pixels}} = \frac{9}{16} \approx 0.56$$

$$P(\text{Pixel} = \text{`*'}) = \frac{\text{Number of * pixels}}{\text{Total number of pixels}} = \frac{6}{16} \approx 0.38$$

Given the 8-neighbourhood of X, it is possible to calculate the likelihood of X. Likelihood of X given '#' in the 8-neighbourhood

Number of # pixels in neighbourhood of
$$X = \frac{7}{9} \approx 0.78$$

Likelihood of X given '*' in the 8-neighbourhood

$$= \frac{\text{Number of * pixels in neighbourhood of } X}{\text{Total number of '*' pixels}} = \frac{1}{6} \cong 0.17$$

Now posterior probability can be calculated as

[Prior probability
$$P(\text{pixel} = \text{`#'})] \times [\text{Likelihood of } X \text{ given '#'} \text{ in the 8-neighbourhood}]$$

= $0.56 \times 0.78 = 0.4368$

[Prior probability
$$P(\text{pixel} = `*`)] \times [\text{Likelihood of } X \text{ given '*'} \text{ in the 8-neighbourhood}]$$

= $0.38 \times 0.17 = 0.0646$

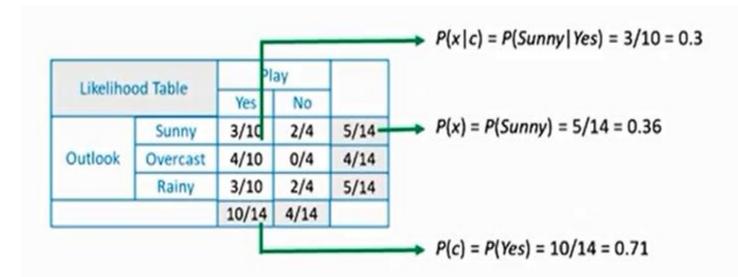
Since 0.4368 is greater than 0.0646, the pixel X must be #.

Day	Outlook	Humidity	Wind	Play
D1	Sunny	High	Weak	Yes
D2	Sunny	High	Strong	No
D3	Overcast	High	Weak	Yes
D4	Rain	High	Weak	Yes
D5	Rain	Normal	Weak	Yes
D6	Rain	Normal	Strong	No
D7	Overcast	Normal	Strong	Yes
D8	Sunny	High	Weak	No
D9	Sunny	Normal	Weak	Yes
D10	Rain	Normal	Weak	Yes
D11	Sunny	Normal	Strong	Yes
D12	Overcast	High	Strong	Yes
D13	Overcast	Normal	Weak	Yes
D14	Rain	High	Strong	No

		Play Game		
		Yes	No	
Outlook	Sunny	3	2	
	Overcast	4	0	
	Rain	3	2	

			Play Game		
		Yes	No		
Humidity	High	4	3		
	Normal	6	1		

		Play Game		
		Yes	No	
Wind	Strong	3	3	
	Week	7	1	



Likelihood of 'Yes' given Sunny is

$$P(c|x) = P(Yes|Sunny) = P(Sunny|Yes)^* P(Yes) / P(Sunny) = (0.3 x 0.71) / 0.36 = 0.591$$

Similarly Likelihood of 'No' given Sunny is

$$P(c/x) = P(No|Sunny) = P(Sunny|No)* P(No) / P(Sunny) = (0.4 x 0.36) / 0.36 = 0.40$$

Suppose we have a day with the following values

Outlook = Rain Humidity = High Wind = Weak

Play =

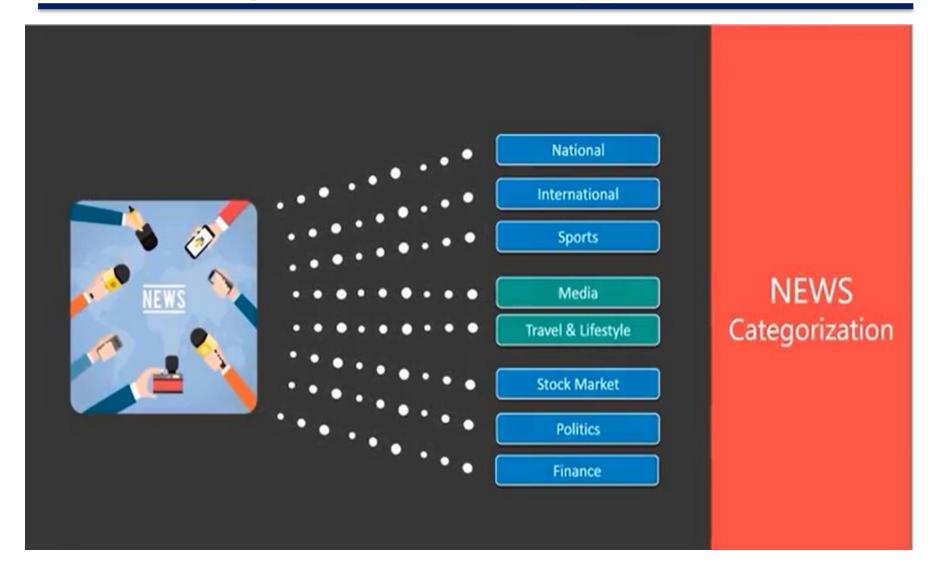
Likelihood of 'Yes' on that Day = P(Outlook = Rain|Yes)*P(Humidity= High|Yes)*P(Wind= Weak|Yes)*P(Yes)= 2/9*3/9*6/9*9/14=0.0199

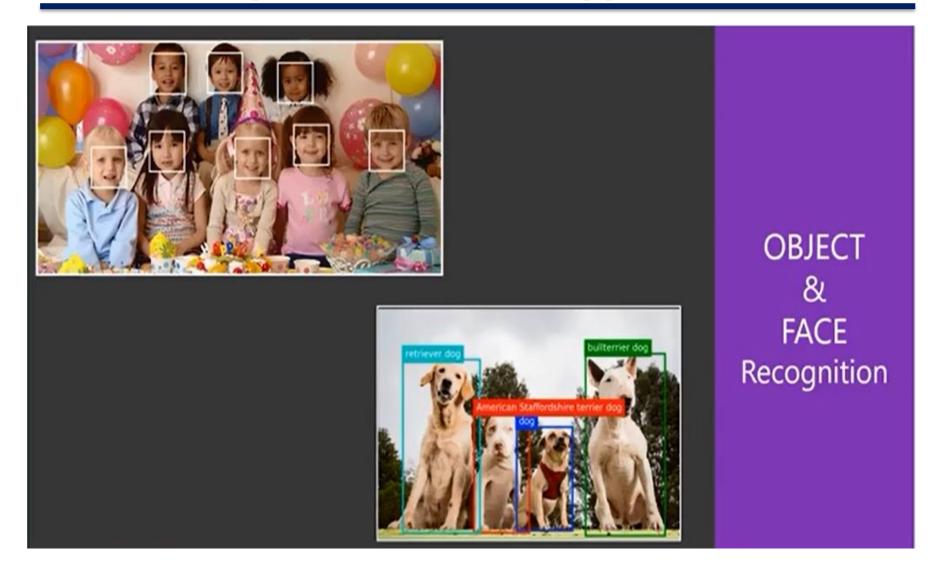
Likelihood of 'No' on that Day = P(Outlook = Rain|No)*P(Humidity= High|No)* P(Wind= Weak|No)*P(No) = 2/5 * 4/5 * 2/5 * 5/14 = 0.0166

$$P(Yes) = 0.0199 / (0.0199 + 0.0166) = 0.55$$

$$P(No) = 0.0166 / (0.0199 + 0.0166) = 0.45$$

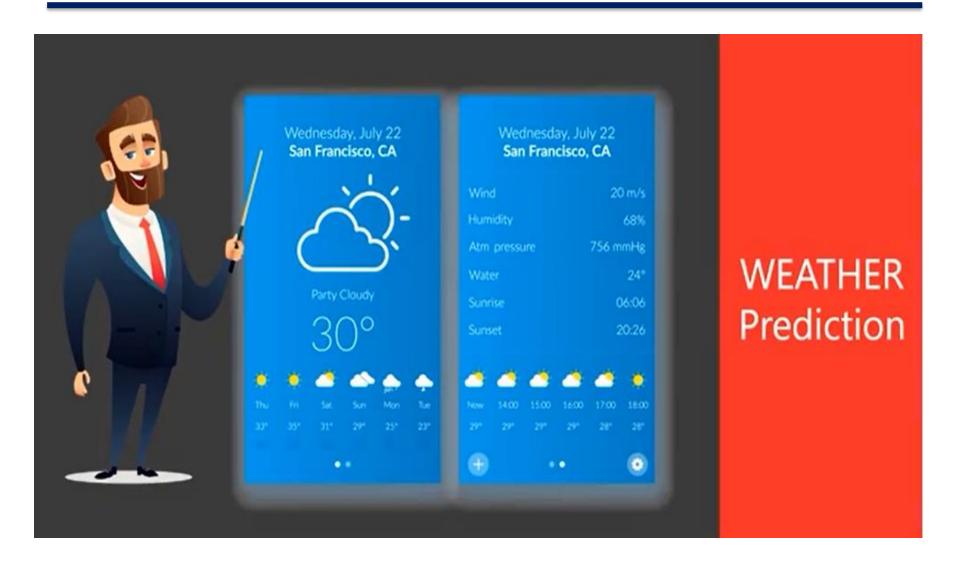
Our model predicts that there is a 55% chance there will be game tomorrow







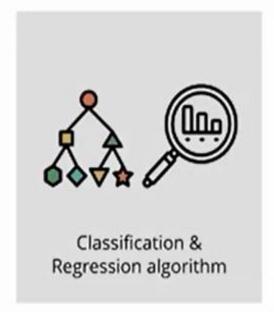


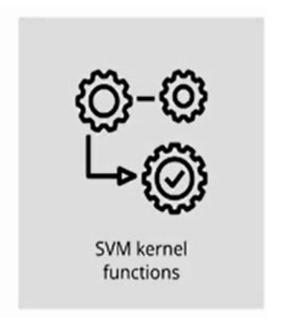


What is SVM

Support Vector Machine is a supervised Classification method that separates data using Hyperplanes.







- Support Vectors
- **♦** Hyperplanes
- Marginal Distance
- Linear Separable
- * Non Linear Separable

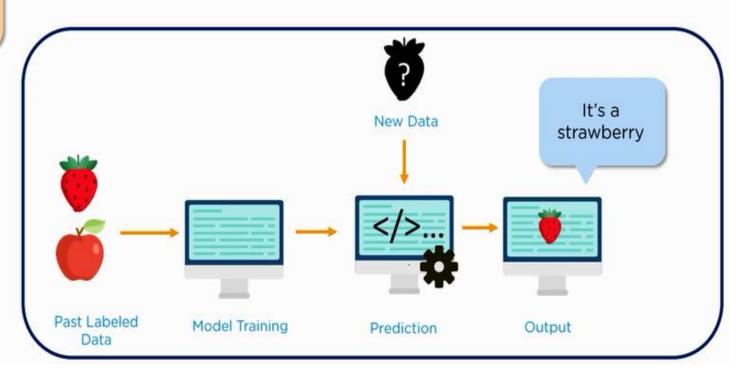


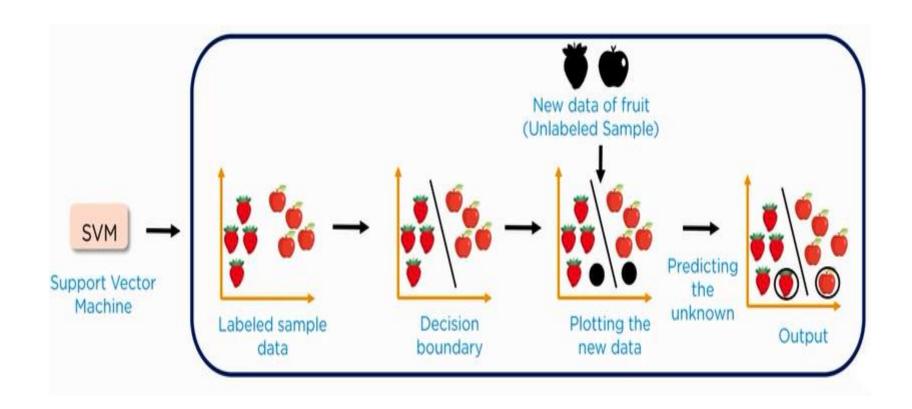


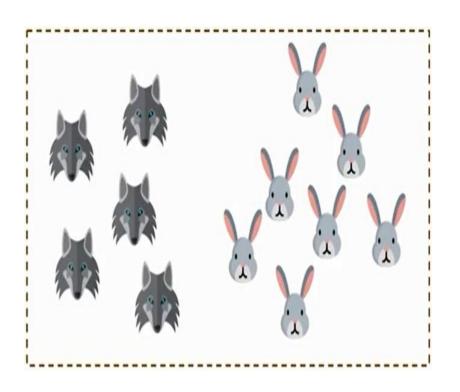


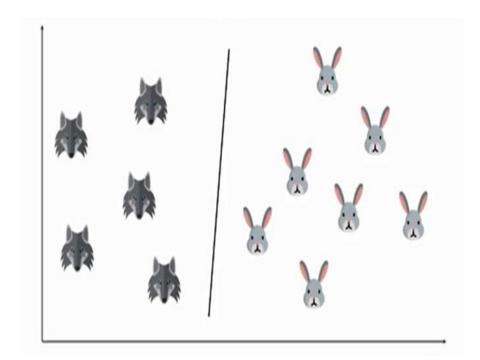
Why not build a model which can predict an unknown data??

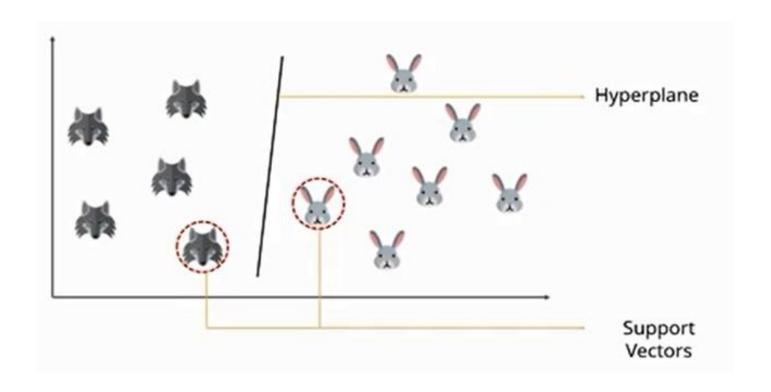


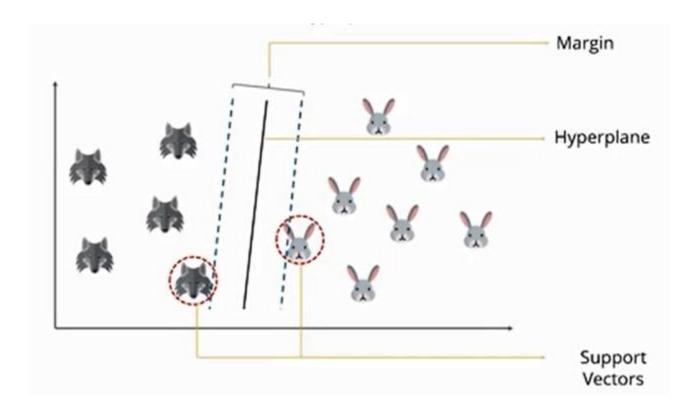


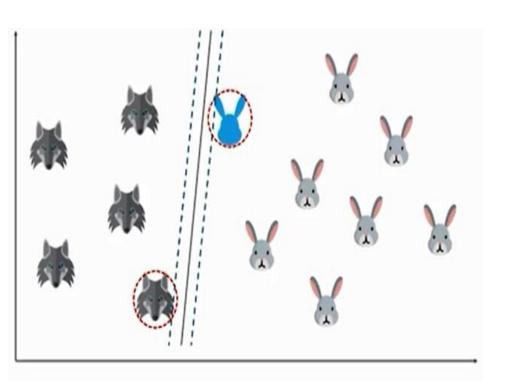


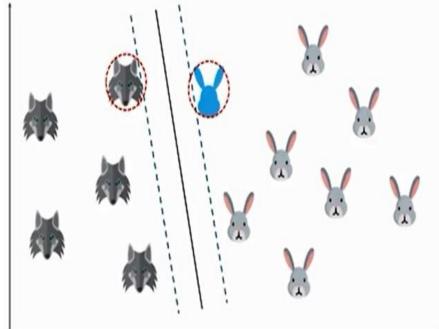


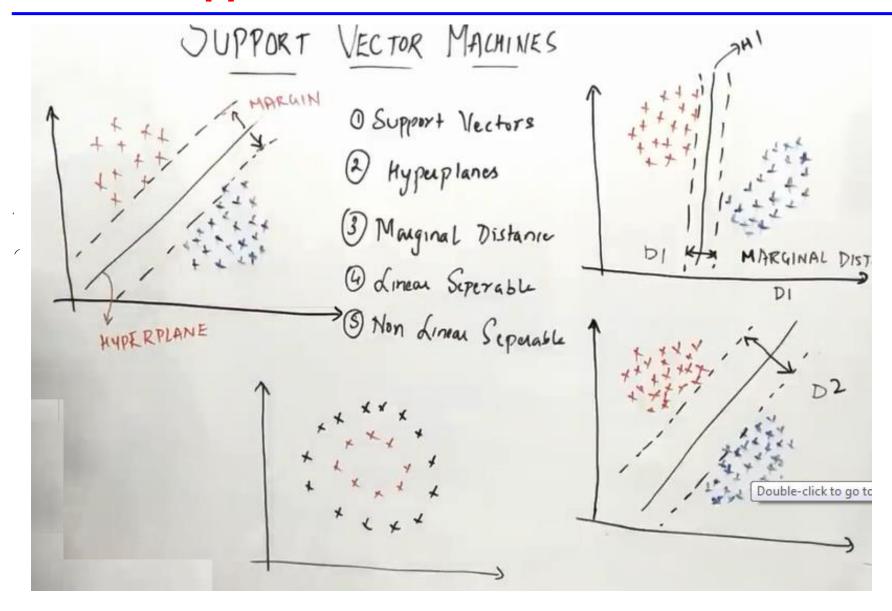












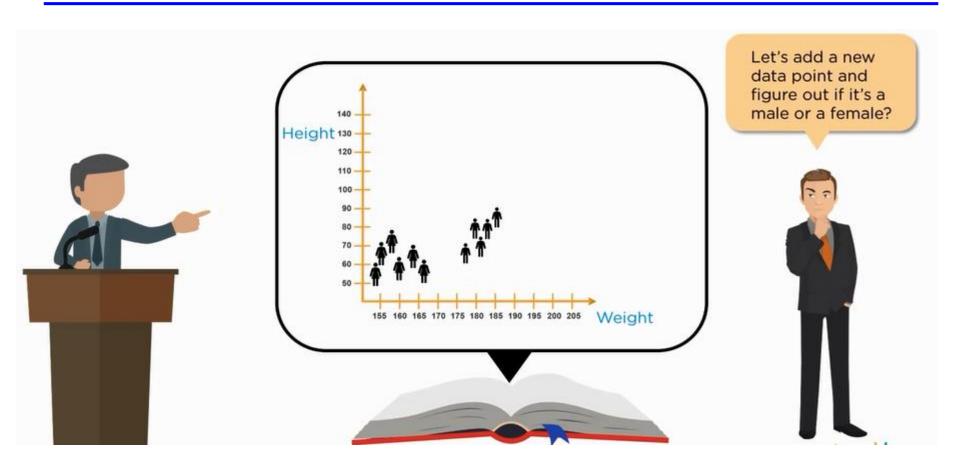
Problem Statement-We have the people of different heights and widths

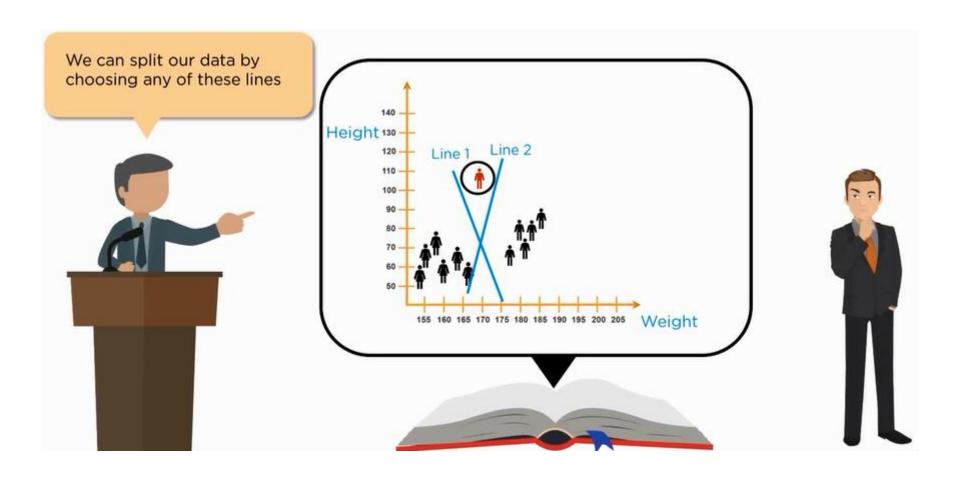
Female

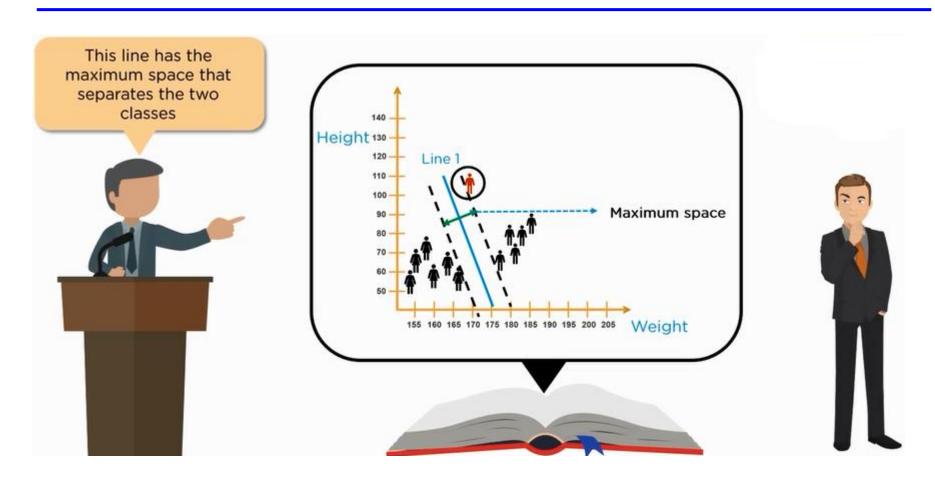
Height	Weight
174	65
174	88
175	75
180	65
185	80

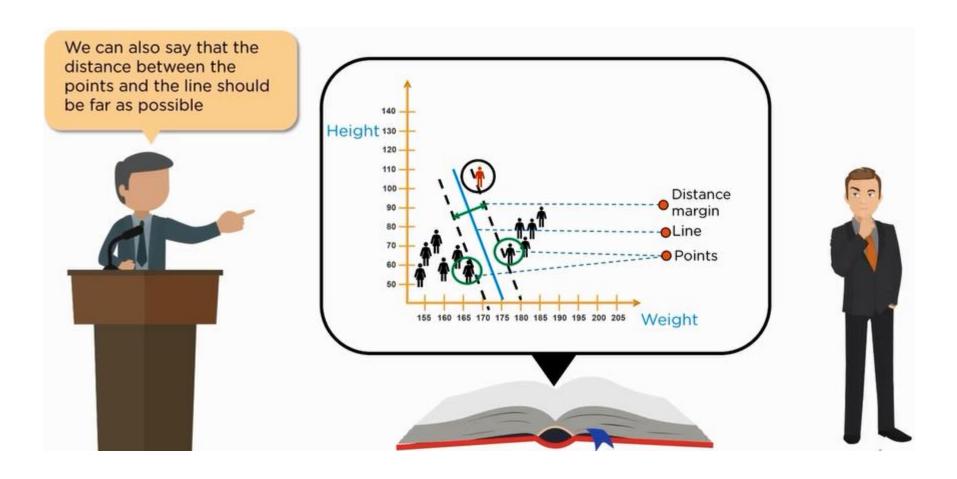
male

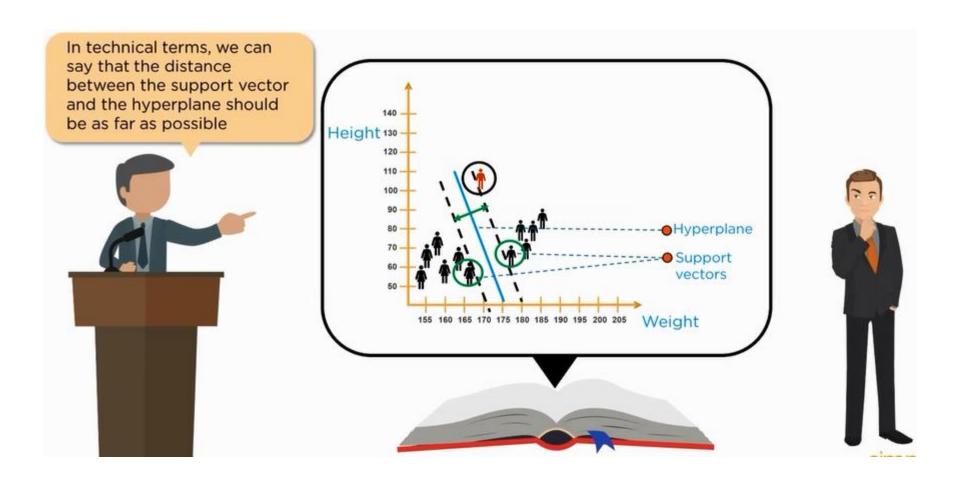
Height	Weight
179	90
180	80
183	80
187	85
182	72

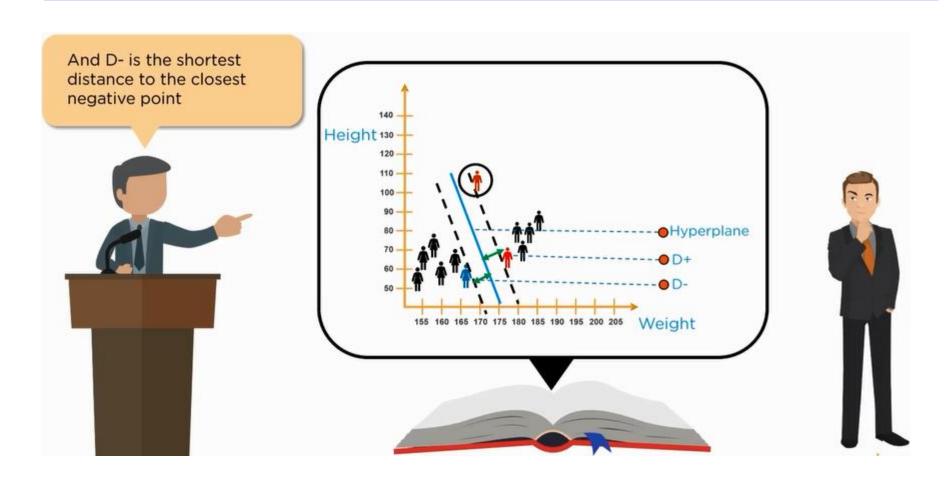


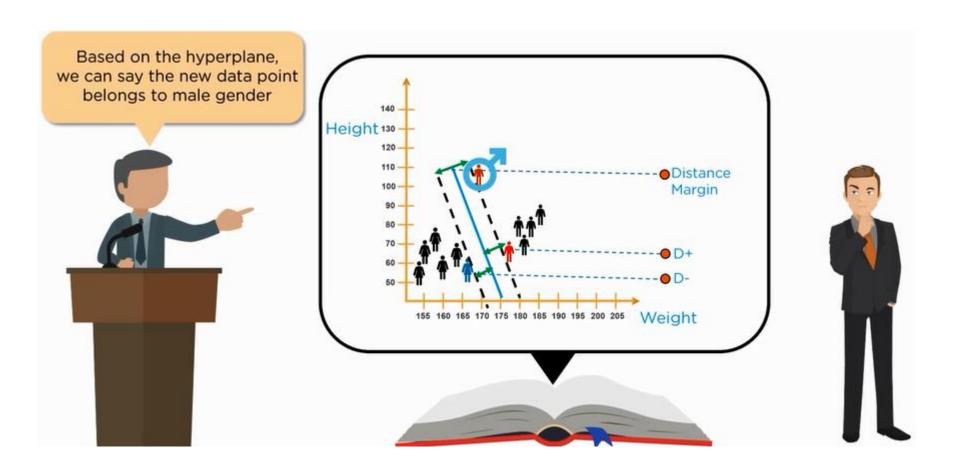


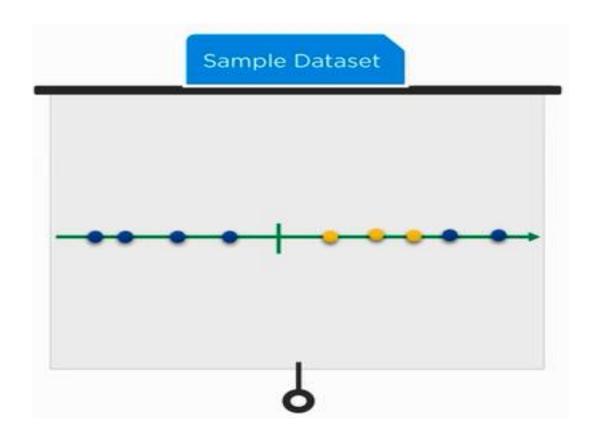


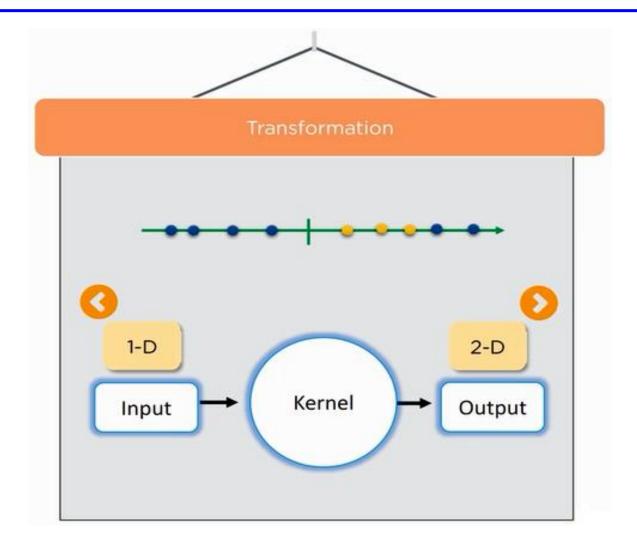


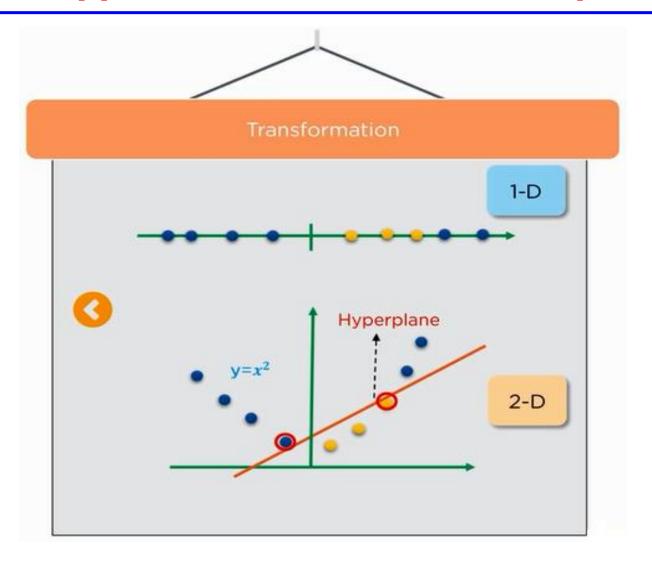




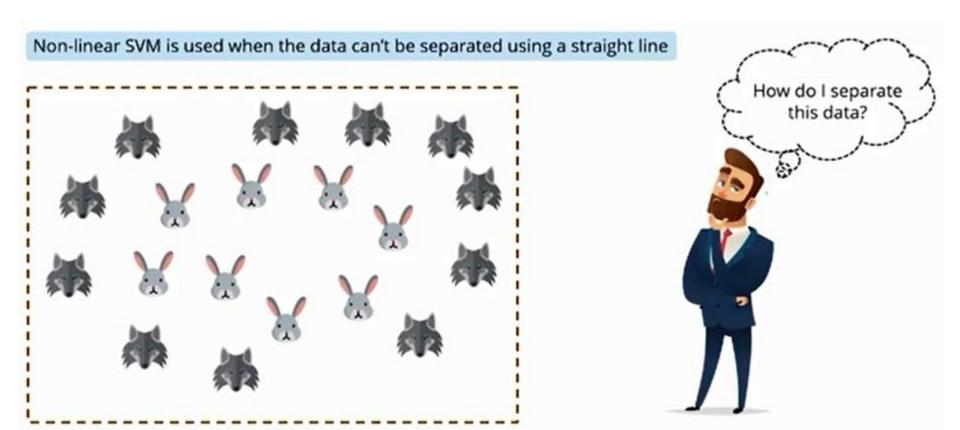




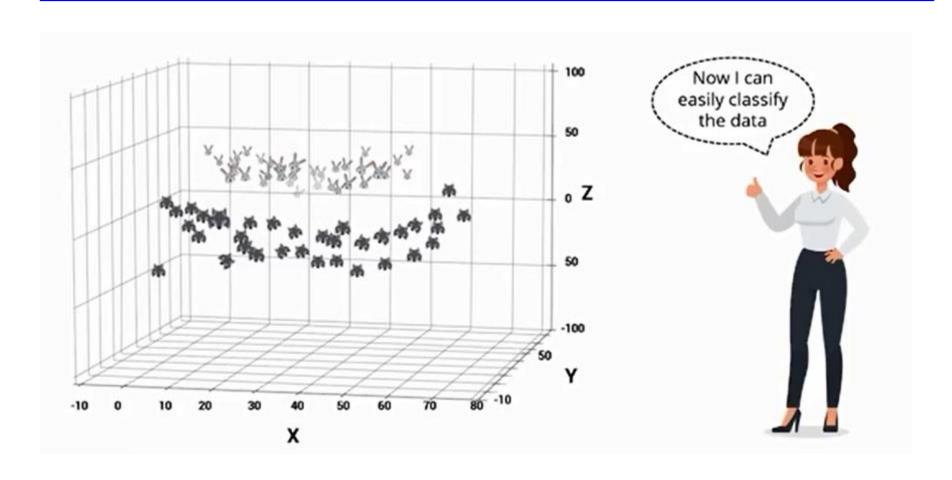


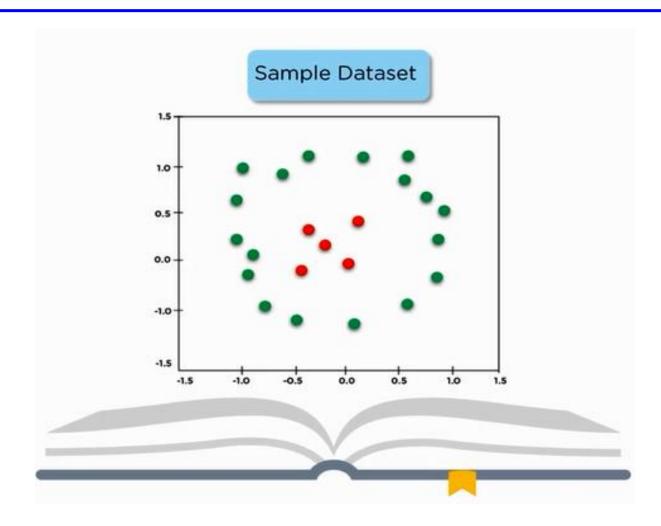


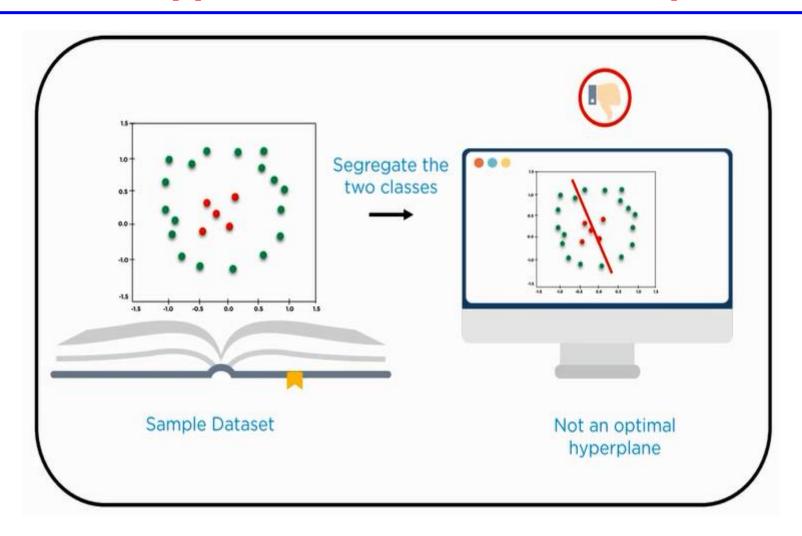
Non Linear Support Vector Machine

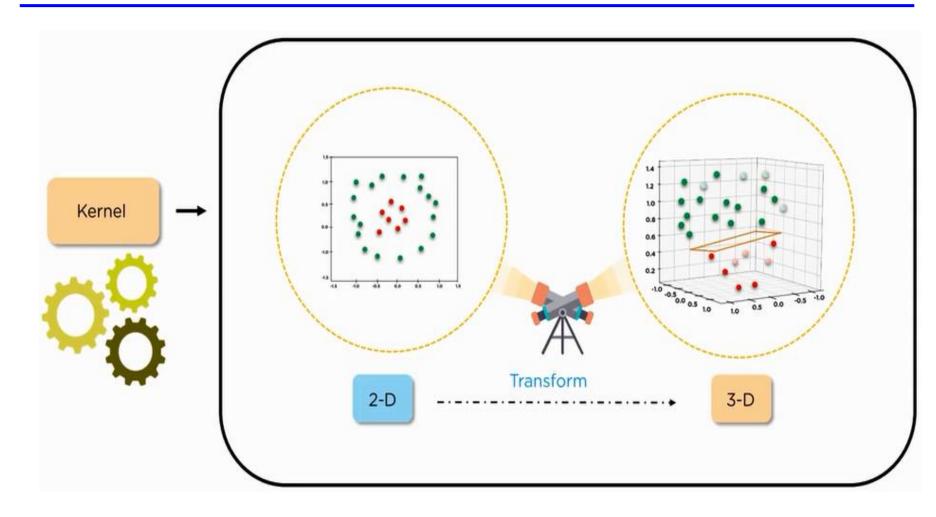


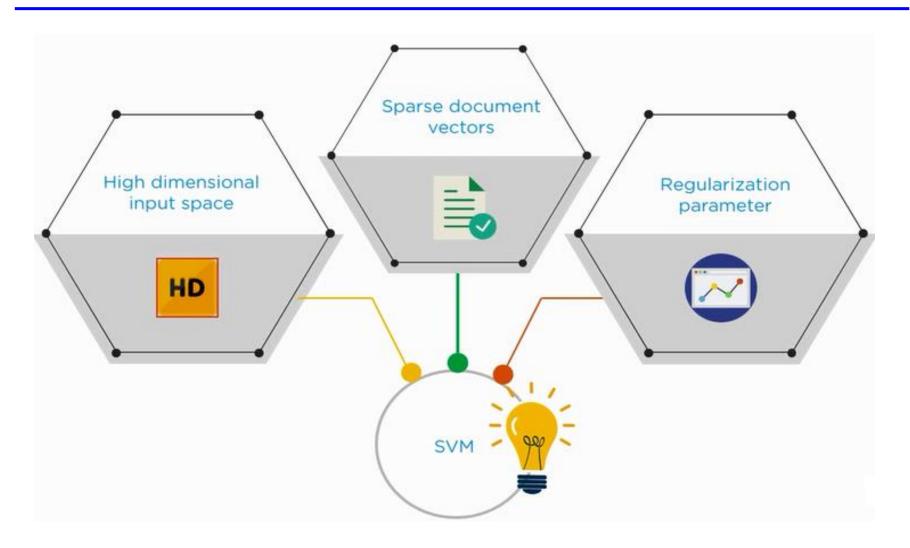
Non Linear Support Vector Machine



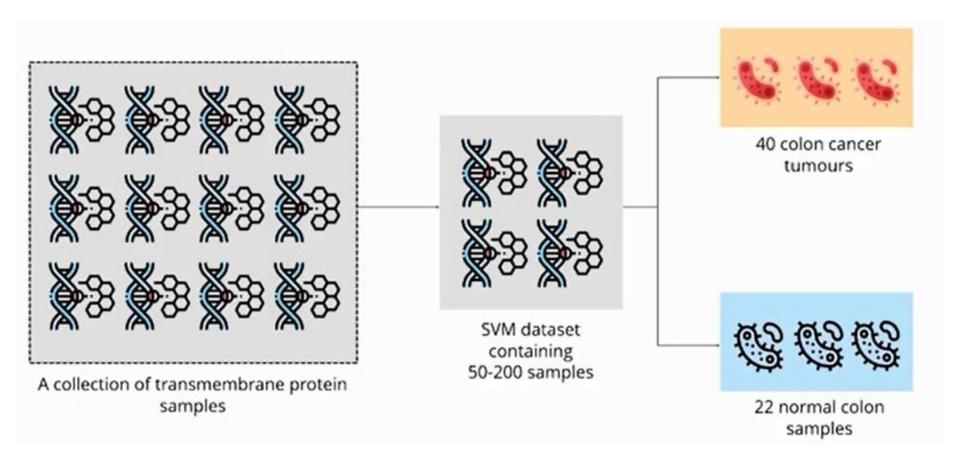




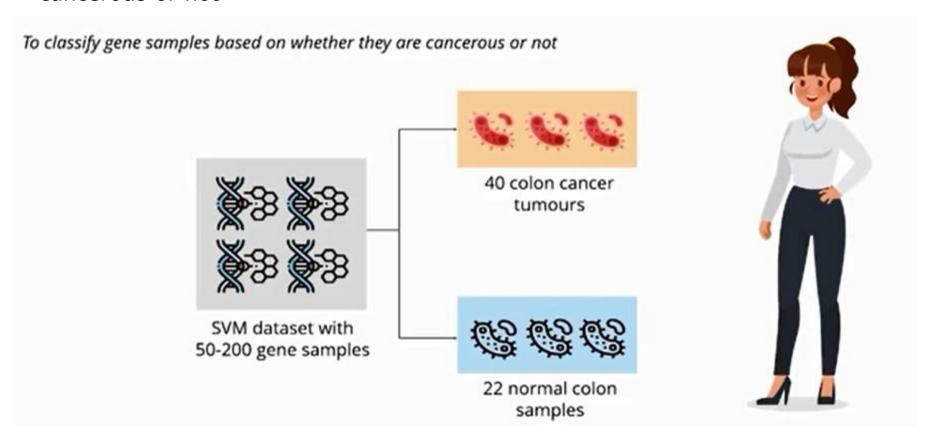




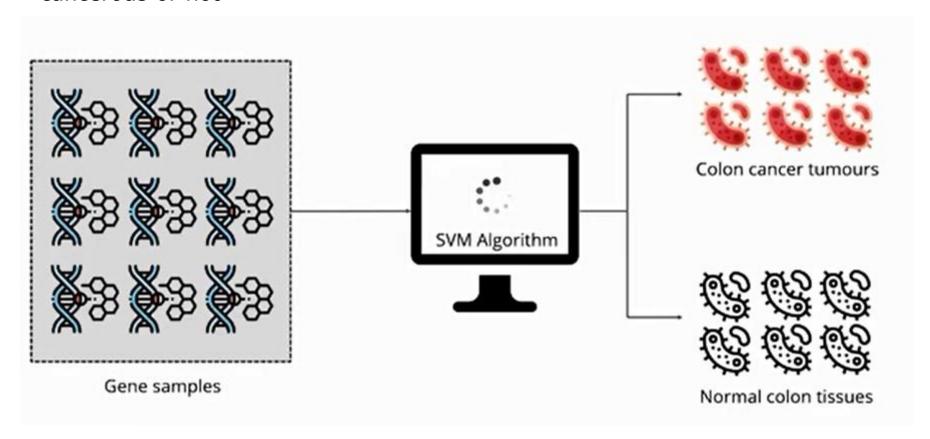
Colon Cancer Classification



Problem Statement-To Classify gene samples based on whether they are cancerous or not



Problem Statement-To Classify gene samples based on whether they are cancerous or not



Support Vector Machine-Applications

