

Semiparametric Scale Mixture of Skew Normal Distributions

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OUTLINE

1. Mixture model & Skew Normal Distribution.
 2. Scale Mixture of Skew Normal Distribution
 3. Semiparametric Scale Mixture of Skew Normal
 4. Simulation
 5. Real Data Analysis : Estimation
 6. Conclusion

MIXTURE MODELS

Finite Mixture Models

- We can manage numerous data structure using Mixture Models.
 - From Lindsay (1995), finite mixture models can be written as

$$f(x; \boldsymbol{\pi}, \boldsymbol{\theta}) = \sum_{j=1}^k \pi_j f(x; \theta_j) \quad (1)$$

where $\boldsymbol{\pi} = (\pi_1, \dots, \pi_k)^T$ is a mixing probabilities, constrained to be non-negative and $\sum_{j=1}^k \pi_j = 1$, and $\boldsymbol{\theta} = (\theta_1, \dots, \theta_k)^T$ is a vector of mixing parameters.



MIXTURE MODELS

Latent Distributions

- ▶ Consider θ_j in (1) as a random variable that describes the specific attributes of the j -th component population.
 - ▶ Let Q be a latent distribution of the component parameter θ_j .
 - ▶ Then, estimation of unknown parameter π, θ is equivalent to estimate the unknown distribution Q .



MIXTURE MODELS

Discrete Latent Distribution

- The discrete probability measure Q puts mass π_j at the component parameter θ_j . That is,

$$f(x; \boldsymbol{\pi}, \boldsymbol{\theta}) = \sum_{j=1}^k \pi_j f(x; \theta_j) = \mathbb{E}_x[f(x; \Theta)]. \quad (2)$$

Continuous Latent Distribution

- We can extend (2) to a continuous density, say $dQ(\theta) = q(\theta)d\theta$. Then the mixture model becomes

$$f(x; Q) := \int f(x; \theta) dQ(\theta) = \int f(x; \theta) q(\theta) d\theta.$$

NONPARAMETRIC MIXTURE

Nonparametric Mixture Model (Lindsay (1995))

- If the latent distribution Q is treated as completely unspecified, this will be called the *nonparametric mixture model*.
 - Since we do not assume anything on Q , we can expect to obtain more flexible distribution family.
 - If there exists another parameter η which is differ from mixing parameter θ , this will be called *semiparametric mixture model*.

ESTIMATION OF MIXTURE MODELS

Case1 : Fixed Support Size

- ▶ The number of components k is assumed to be known.
 - ▶ In order to estimate appropriately, we should choose a proper k .
 - ▶ \hat{Q} that maximizes the likelihood can be estimated by EM-type algorithm.

ESTIMATION OF MIXTURE MODELS

Case2 : Flexible Support Size

- ▶ There is no assumption about the number of components k .
 - ▶ It is a reasonable approach since, in general, we do not know how many components the data has.
 - ▶ \hat{Q} that maximizes the likelihood cannot be estimated by EM-type algorithm.
 - ▶ Algorithms for the flexible support size case leads to the mixture NPMLE theorem (Bohning (1982), Lindsay et al. (1983)).

DIRECTIONAL DERIVATIVE

Estimation

- NPMLE for mixture models can be characterized in terms of *directional derivative*.

Directional Derivative

The directional derivative is given by

$$D_Q(\sigma) = \sum_{i=1}^n \frac{f(x_i, \sigma)}{f(x_i, Q)} - n$$

$$= \sum_{i=1}^n \frac{f(x_i, \sigma)}{\sum_{l=1}^k \pi_l f(x_i, \sigma_l)} - n$$

where Q is a probability measure with finite support and σ is a support point of mixture model.

NONPARAMETRIC MIXTURE

Idea for Computing NPMLE

- If $D_Q(\sigma^+) > 0$ for some σ^+ , then the likelihood can be increased over $\ell(Q)$ by using a distribution with additional mass at σ^+ .
 - If \hat{Q} is NPMLE, $\ell(\hat{Q}) > \ell(Q)$ for all Q .
 - There exists an π such that

$$\ell((1-\pi)Q + \pi Q_{\sigma}^+) > \ell(Q),$$

where Q_σ^+ is a distribution with mass 1 at σ^+ .

NONPARAMETRIC MIXTURE

Mixture NPMLE theorem in Lindsay (1995)

1. \hat{Q} is the NPMLE if and only if $D_Q(\sigma) \leq 0 \ \forall \sigma$.
 2. \hat{Q} is discrete and has at most n support points σ .
 3. $D_Q(\sigma) = 0$ for all support points of \hat{Q} .

SKEW NORMAL DISTRIBUTION

Skew Normal Distribution

- As developed by Azzalini (1985), a random variable Y follows a univariate skew normal distribution with location parameter ξ , scale parameter σ , and skewness parameter $\lambda \in \mathbb{R}$ if it has the density

$$\psi(y|\xi, \sigma^2, \lambda) = \frac{2}{\sigma} \phi\left(\frac{y-\xi}{\sigma}\right) \Phi\left(\lambda \frac{y-\xi}{\sigma}\right),$$

where $\phi(\cdot)$, $\Phi(\cdot)$ denote the standard normal density and cumulative distribution function, respectively.

SKEW NORMAL DISTRIBUTION

Moments of Skew Normal Distribution

- Suppose $Y \sim SN(\xi, \sigma^2, \lambda)$, then

$$\mathbb{E}(Y) = \xi + \sqrt{\frac{2}{\pi}}\delta(\lambda)\sigma, \quad \mathbb{V}(Y) = \left\{1 - \frac{2}{\pi}\delta^2(\lambda)\right\}\sigma^2.$$

$$\gamma_Y = \frac{\sqrt{2}(4-\pi)\lambda^3}{\{\pi + (\pi-2)\lambda^2\}^{3/2}}, \quad \kappa_Y = 3 + \frac{8(\pi-3)\lambda^4}{\pi + (\pi-2)\lambda^2}^2.$$

where $\delta(\lambda) = \lambda/\sqrt{1+\lambda^2}$ and γ_Y, κ_Y are the measures of skewness and kurtosis, respectively.

- Range : $-0.9953 < \gamma\gamma < 0.9953$,

$$3 < \kappa_Y < 3.8692$$

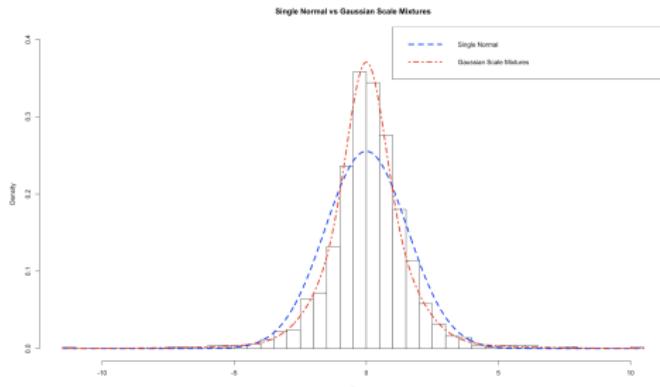
SCALE MIXTURES OF SKEW NORMAL

Gaussian Scale Mixtures

- ▶ Gaussian scale mixtures can manage the symmetric heavy tail family.

Examples: $X \sim t_3$ with $n = 1000$.

Single normal (blue) and gaussian scale mixture (red).



SCALE MIXTURES OF SKEW NORMAL

Scale Mixture of Skew Normal

- ▶ Branco and Dey (2001) suggested a continuous scale mixture of skew normal (SMSN) distribution.

Continuous Scale Mixture of Skew Normal (da Silva Ferreira et al., 2011)

A random variable Y follows a distribution between the SMSN class with location parameter $\xi \in \mathbb{R}$, scale factor σ^2 and skewness parameter $\lambda \in \mathbb{R}$, if its pdf is given by

$$f(y) = 2 \int_0^{+\infty} \phi(y|\xi, \sigma^2 \kappa(u)) \Phi_1(\lambda \frac{y-\xi}{\sigma}) dQ(u), \quad (3)$$

where U is a positive random variable with cdf $Q(u; \nu)$.

SCALE MIXTURES OF SKEW NORMAL

Example : Continuous SMSN ((da Silva Ferreira et al., 2011))

- Skew-Student- t normal distribution with d.f. ν .

$$-\kappa(u) = 1/u$$

- $U \sim Gamma(\nu, \nu)$, $\nu > 0$

- #### ► Skew-Slash distribution.

$$- \quad \kappa(u) = 1/u, \quad 0 < u < 1$$

$$- U \sim Beta(\nu, 1), \quad \nu > 0$$

SEMIPARAMETRIC SMSN

Semiparametric Scale Mixture of Skew Normal

- ▶ Do not make any parametric assumptions on Q .
That is, consider *nonparametric mixture*.
 - ▶ In this case, scale parameter σ is the only mixing parameter, and location parameter ξ and skewness parameter λ is unknown with fixed value.
 - ▶ *Semiparametric Mixture Model.*

SEMIPARAMETRIC SMSN

Semiparametric Scale Mixture of Skew Normal

A random variable Y follows a distribution between the *Semiparametric SMSN* class with location parameter $\xi \in \mathbb{R}$, scale parameter $\sigma \in \mathbb{R}^+$ and skewness parameter $\lambda \in \mathbb{R}$, if its pdf is given by

$$f_Y(y; \mathbf{Q}) = \int f(y|\xi, \sigma, \lambda) d\mathbf{Q}(\sigma), \quad (4)$$

where $f(y|\xi, \sigma, \lambda)$ is a density of $SN(\xi, \sigma, \lambda)$ and Q is unspecified.

SEMIPARAMETRIC SMSN

Semiparametric Scale Mixture of Skew Normal

- ▶ Does “Semiparametric SMSN” has wider range of skewness and kurtosis than single Skew Normal has?
 - ▶ Suppose that

$$f_Y(y; \boldsymbol{\pi}, \boldsymbol{\xi}, \boldsymbol{\sigma}, \lambda) = \sum_{j=1}^m \pi_j f_j(y)$$

where $f_j(y)$ is a density of $SN(\xi, \sigma_j, \lambda)$, $\boldsymbol{\pi} = (\pi_1, \dots, \pi_m)^T$, and $\boldsymbol{\sigma} = (\sigma_1, \dots, \sigma_m)^T$.

SEMIPARAMETRIC SMSN

Moments of Finite Scale Mixture of Skew Normal

- Then, the moments of the random variable that has j -th component density are

$$\mu_j = \xi + \sqrt{\frac{2}{\pi}} \delta(\lambda) \sigma_j, \quad \nu_j^2 = \left\{ 1 - \frac{2}{\pi} \delta^2(\lambda) \right\} \sigma_j^2.$$

$$\gamma = \frac{\sqrt{2}(4-\pi)\lambda^3}{\{\pi + (\pi-2)\lambda^2\}^{3/2}}, \quad \kappa = 3 + \frac{8(\pi-3)\lambda^4}{\{\pi + (\pi-2)\lambda^2\}^2}.$$

where $\delta(\lambda) = \lambda/\sqrt{1 + \lambda^2}$ and γ, κ are the measures of skewness and kurtosis, respectively.

SEMIPARAMETRIC SMSN

Moments of Finite Scale Mixture of Skew Normal

- Then, the moments of the random variable Y are

$$\mathbb{E}(Y) = \sum_{j=1}^m \pi_j \mu_j, \quad V(Y) = \sum_{j=1}^m \pi_j \nu_j^2 + \sum_{j=1}^m \pi_j (\mu_j - \mu)^2,$$

$$\gamma_Y = \frac{1}{\nu^3} \sum_{j=1}^m \pi_j \{ \gamma \nu_j^3 + (\mu_j - \mu)^3 + 3(\mu_j - \mu) \nu_j^2 \}$$

$$\kappa_Y = \frac{1}{\nu^4} \sum_{j=1}^m \pi_j \{ \kappa \nu_j^4 + (\mu_j - \mu)^4 + 4(\mu_j - \mu)\gamma \nu_j^3 + 6(\mu_j - \mu)^2 \nu_j^2 \}.$$

SEMIPARAMETRIC SMSN

Moments of Finite Scale Mixture of Skew Normal

- Consider 2-component scale mixture of skew normal. That is,

$$Y \sim 0.6SN(0, 1, 5) + 0.4SN(0, 3, 5)$$

- ▶ Then, $\gamma_Y = 1.82502$, $\kappa_Y = 7.03653$, which is outside the range of skewness and kurtosis of single skew normal.
 - ▶ Since semiparametric mixtures include finite mixtures, we can make wider distribution family that contains the asymmetric, heavy tail distributions.

SEMIPARAMETRIC SMSN

Estimation of Semiparametric SMSN

- Sometimes, σ that is closed to 0 makes likelihood unbounded.
 - That is, likelihood is maximized when the scale parameter becomes 0.
 - Then, 0 is included in the set of support point, but we do not want this kind of estimate.
 - Support point σ near to 0 is called *spurious support*.

SEMIPARAMETRIC SMSN

Estimation of Semiparametric SMSN

- The *spurious support* problem can be solved by estimating the model after adding some constant $c > 0$ to σ (Seo et al., 2017). That is, consider our model (4) as

$$f_Y(y; \mathbf{Q}) = \int f(y|\xi, \sigma + c, \lambda) d\mathbf{Q}(\sigma).$$

with constant $c > 0$.

- Then, directional derivatives become

$$D_Q(\sigma) = \sum_{i=1}^n \frac{f(x_i, \sigma + c)}{f(x_i, Q)} - n$$

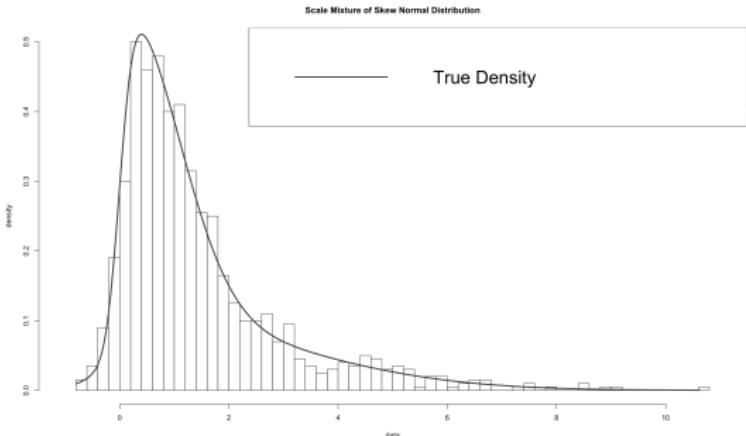
$$= \sum_{i=1}^n \frac{f(x_i, \sigma + c)}{\sum_{l=1}^k \pi_l f(x_i, \sigma_l + c)} - n$$

SIMULATION

Simulation Setting

- We fixed the location parameter ($\xi = 0$) and the skewness parameter ($\lambda = 5$). The data follows

$$X \sim 0.6 \text{ } SN(\xi, \sigma = 1, \lambda) + 0.4 \text{ } SN(\xi, \sigma = 3, \lambda), n = 1000.$$



ISDM ALGORITHM

Intra Simplex Direction Method

- ▶ Lesperance and Kalbfleisch (1992) suggested *Intra Simplex Direction Method*(ISDM) as a faster algorithm than VDM.
 - ▶ Instead of taking the only global maxima as support points, add all local maxima.
 - ▶ Find an appropriate convex combination of the selected support points.

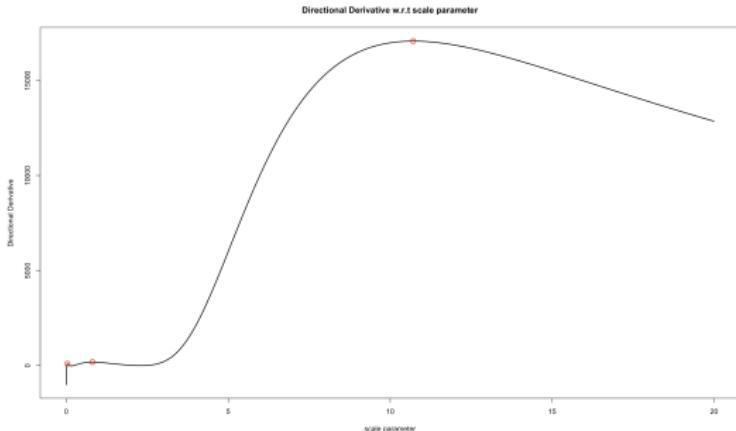
ISDM ALGORITHM

Intra Simplex Direction Method

- **Step 1** : Assign the initial values, say $\xi_0, \sigma_0, \lambda_0$, to the parameter ξ, σ , and λ , respectively.
 - **Step 2** : With fixed $\xi^{(t)}, \lambda^{(t)}$, find all local maxima and add them to the set of current support points, $Q^{(t)}$.
 - **Step 3** : Find proper mixing probabilities corresponding to each support points and set this as $Q^{(t+1)}$.
 - **Step 4** : With fixed $Q^{(t+1)}$, find $\xi^{(t+1)}, \lambda^{(t+1)}$ that maximize the likelihood.
 - **Step 5** : Go back to **Step 2**.

SIMULATION

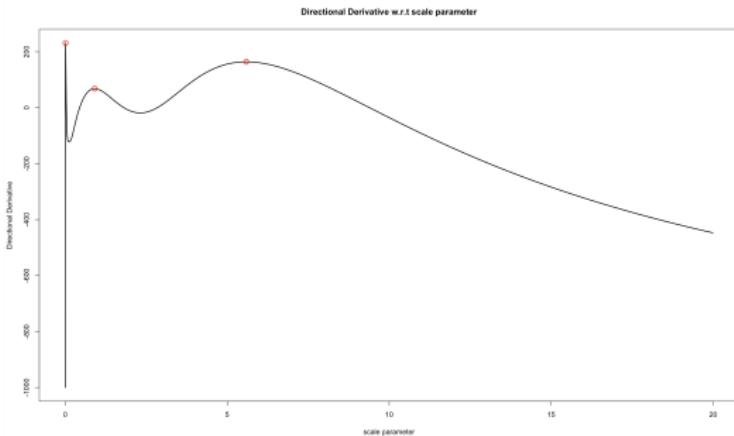
ISDM Algorithm : 1st Iteration



Support	$\sigma_0 = 2.2997$	$\sigma_{11} = 0.1384$	$\sigma_{12} = 0.9087$	$\sigma_{13} = 10.8099$
Mixing Probability	$\pi_0 = 0.7459$	$\pi_{11} = 2.23e-14$	$\pi_{12} = 0.2331$	$\pi_{13} = 0.0210$

SIMULATION

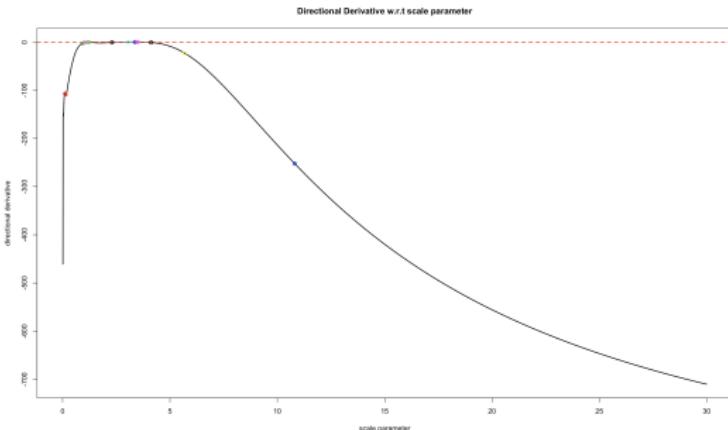
ISDM Algorithm : 2nd Iteration



σ	2.2997	0.1384	0.9087	10.8099	0.11	1.0071	5.6891
π	0.5296	7.73e-232	2.24e-07	7.23e-308	8.46e-231	0.4061	0.0643

SIMULATION

ISDM : Directional Derivative Plot



- If \hat{Q} is NPMLE, then, $D_{\hat{Q}}(\sigma) \leq 0$ for all scale parameter σ .

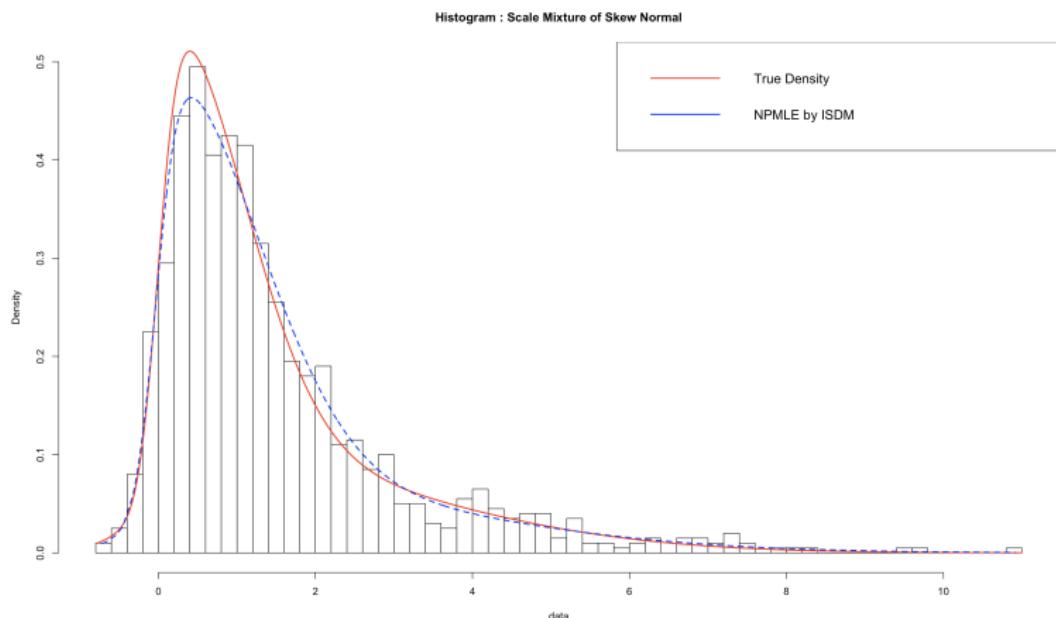
NONPARAMETRIC MIXTURE

Mixture NPMLE theorem in Lindsay (1995)

1. \hat{Q} is the NPMLE if and only if $D_Q(\sigma) \leq 0 \ \forall \sigma$.
 2. \hat{Q} is discrete and has at most n support points σ .
 3. $D_Q(\sigma) = 0$ for all support points of \hat{Q} .

SIMULATION

ISDM Algorithm : Result



SIMULATION

ISDM Algorithm

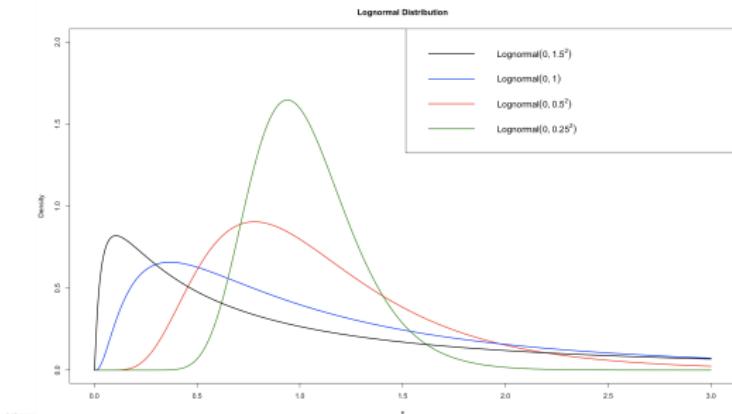
Type	Iteration(Support)	Location(ξ)	Skewness(λ)
ISDM	6(14)	-0.0293	5.7306

- ▶ We can check that NPMLE is similar to the true density.
 - ▶ That is, we can estimate finite scale mixture of skew normal by using *Semiparametric Scale Mixture of Skew Normal*.

SIMULATION

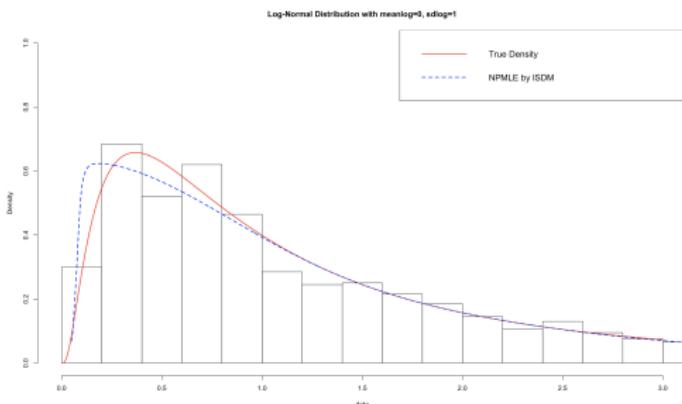
Log normal distribution

- Log-normal distribution is well-known for its asymmetry and heavy tail.



SIMULATION

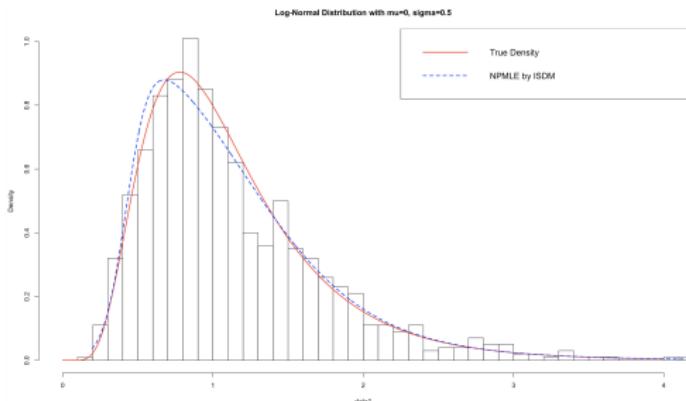
Case 1: Log normal with $\mu = 0, \sigma = 1$



- ▶ With $\mu = 0, \sigma = 1$, log-normal density becomes highly asymmetric and heavy tailed distribution
 - ▶ We can check that NPMLE is similar to the true density.

SIMULATION

Case 2: Log normal with $\mu = 0, \sigma = 0.5$

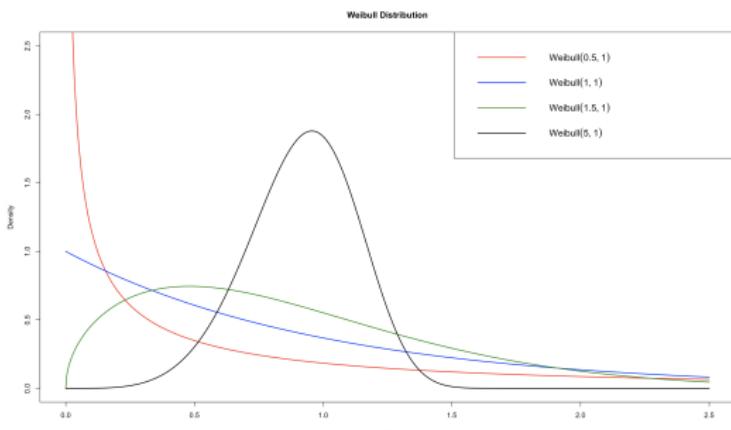


- With $\mu = 0, \sigma = 0.5$, log-normal density becomes quite asymmetric.
 - We can check that NPMLE is similar to the true density.

SIMULATION

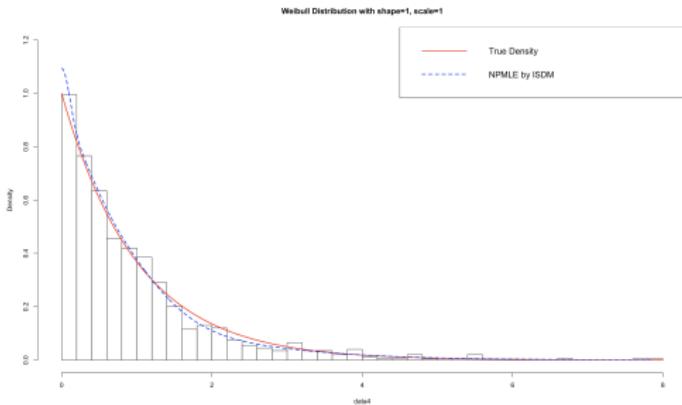
Weibull distribution

- Weibull distribution is also well-known for its asymmetry and mainly used in Survival Analysis.



SIMULATION

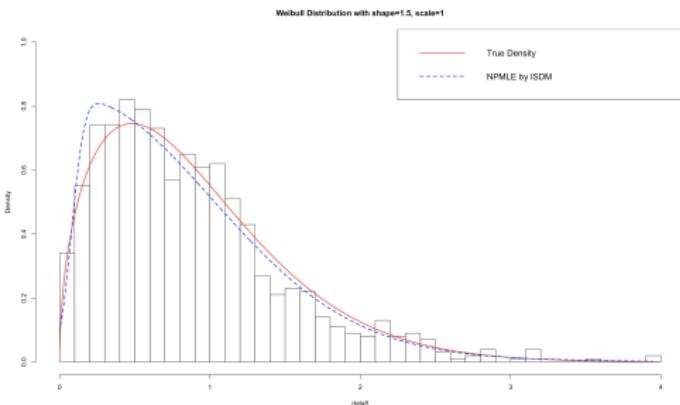
Case 1: Weibull(1, 1)



- ▶ With shape parameter $k = 1$, and scale parameter $\lambda = 1$, weibull density becomes exponential distribution with mean 1.
 - ▶ We can check that NPMLE is similar to the true density.

SIMULATION

Case 2: Weibull(1.5, 1)



- With shape parameter $k = 1.5$, and scale parameter $\lambda = 1$, weibull density becomes highly asymmetric and heavy tailed distribution.
 - We can check that NPMLE is similar to the true density.

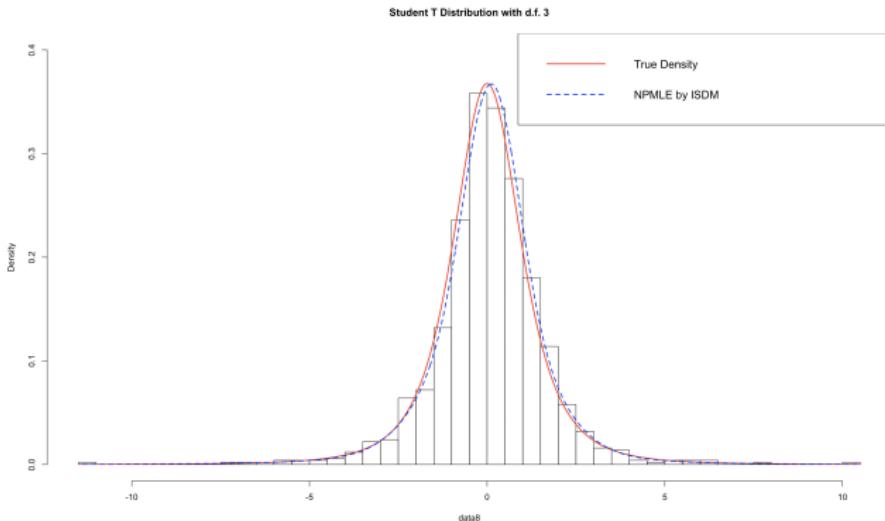
SIMULATION

Symmetric Distribution

- ▶ *Semiparametric Scale Mixture of Normal(SMN)* class contains almost all of unimodal and symmetric distributions.
 - ▶ *t* distribution with d.f. 3 and laplace distribution are included in *semiparametric SMN*.
 - ▶ *Semiparametric SMSN* class contains *semiparametric SMN*.

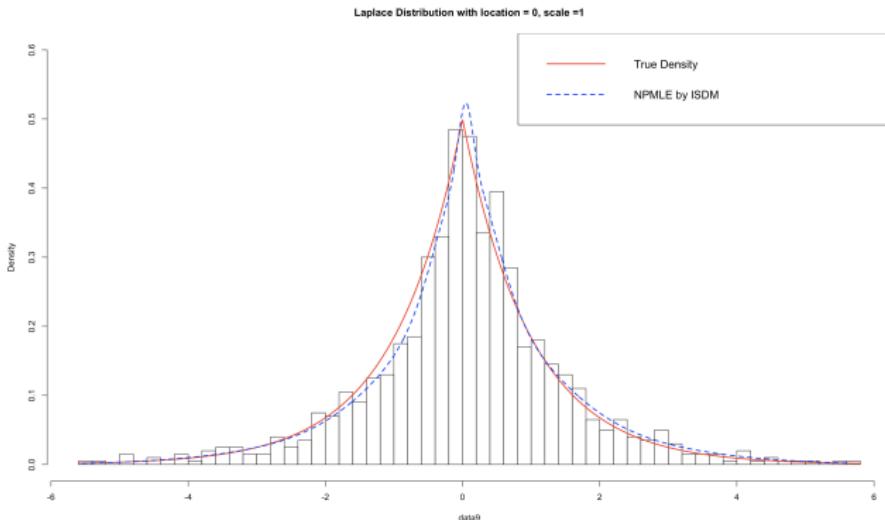
SIMULATION

Symmetric Distribution



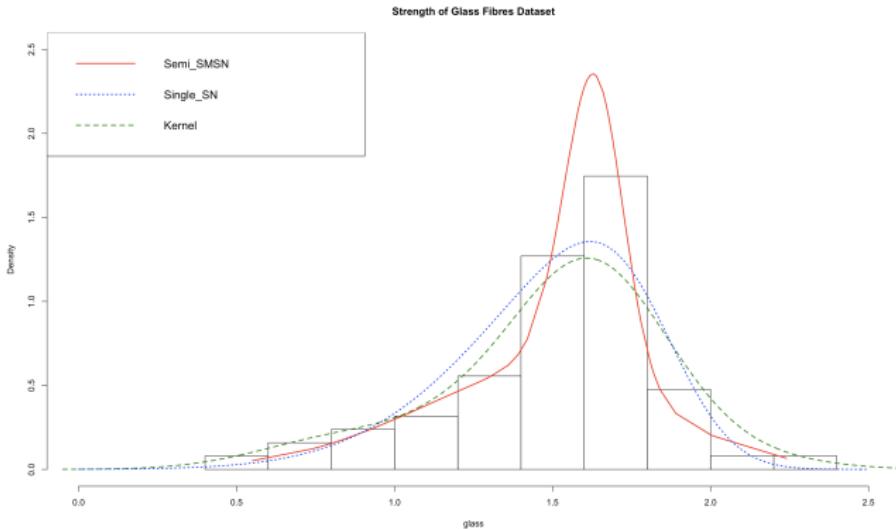
SIMULATION

Symmetric Distribution



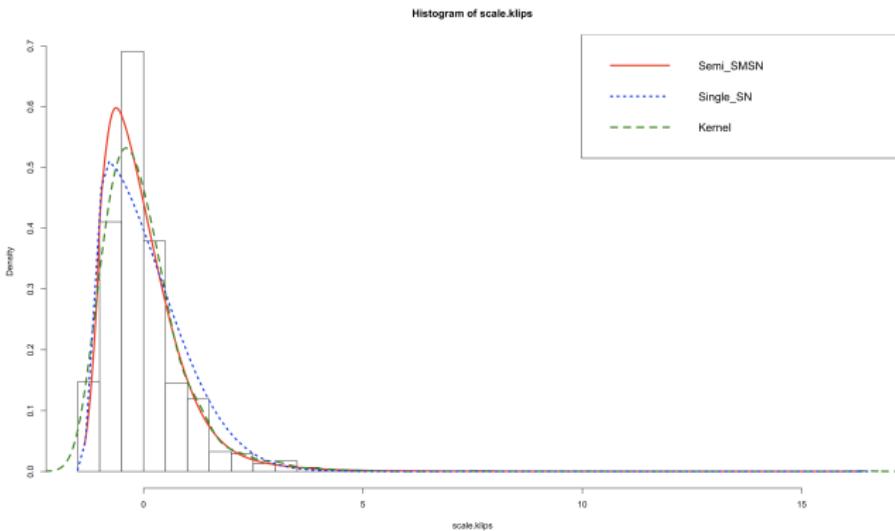
REAL DATA ANALYSIS

Density Estimation : Strength of Glass Fibres Data



REAL DATA ANALYSIS

Density Estimation : KLIPS Data



CONCLUSION

Conclusion

- We suggested *Semiparametric Scale Mixture of Skew Normal* distribution class which is wider than Semiparametric Scale Mixture of Normal class.
 - We can manage asymmetric and heavy tailed data, using *Semiparametric SMSN*.
 - Now, we are identifying the theoretical coverage of *Semiparametric SMSN* by cheking the range of skewness and kurtosis.
 - In the future, we plan to apply *Semiparametric SMSN* to the *Modal Regression*.

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APPENDIX

Directional Derivative

- Let P and Q are probability measures with finite support. For $\alpha \in [0, 1]$, define

$$\begin{aligned}\ell^*(\alpha) &:= \ell((1-\alpha)Q + \alpha P) = \sum_{i=1}^n \log f(x_i, (1-\alpha)Q + \alpha P) \\ &= \sum_{i=1}^n \log((1-\alpha)f(x_i, Q) + \alpha f(x_i, P))).\end{aligned}$$

- Taking the derivative of $\ell^*(\alpha)$ at $\alpha = 0$ gives

$$\frac{\partial}{\partial \alpha} \ell^*(\alpha) = \Phi(Q, P) = \lim_{\alpha \rightarrow 0} \frac{\ell((1-\alpha)Q + \alpha P) - \ell(Q)}{\alpha}. \quad (5)$$

APPENDIX

Directional Derivative

- Applying l'Hôpital's rule to (4) leads to

$$\Phi(Q, P) = \sum_{i=1}^n \frac{f(x_i, P) - f(x_i, Q)}{f(x_i, Q)}.$$

- ▶ In particular, for the one point mass P_σ at σ the directional derivative is given by

$$D_Q(\sigma) = \sum_{i=1}^n \frac{f(x_i, \sigma)}{f(x_i, Q)} - n$$

$$= \sum_{i=1}^n \frac{f(x_i, \sigma)}{\sum_{l=1}^k \pi_l f(x_i, \sigma_l)} - n$$

APPENDIX

ISDM : Pseudocode

From an initial estimate, G_1 and $j = 1$,

Step 1: Compute all local maxima $\theta_{j1}^*, \dots, \theta_{jm_j}^*$ of $g(\theta, G_j)$, $\theta \in \Omega$, such that $g(\theta_{js}^*, G_j) \geq 0$ ($s = 1, \dots, m_j < k$). If $\max_{\theta \in \Omega} g(\theta_{js}^*, G_j) = 0$, stop.

Step 2 : Compute $\epsilon_{j0}, \dots, \epsilon_{jm_j}$, the values that maximize

$$\ell \left\{ \epsilon_0 G_j + \sum_{s=1}^{m_j} \epsilon_s \delta_{\theta_{js}^*} \right\} = \sum_r n_r \log \left\{ \epsilon_0 L_r(G_j) + \sum_{s=1}^{m_j} \epsilon_s L_r(\theta_{js}^*) \right\}$$

subject to $\sum_{s=0}^{m_j} \epsilon_s = 1$ and $\epsilon_s \geq 0 (s = 0, \dots, m_j)$.

Step 3 : $G_{j+1} = \epsilon_{j0}G_j + \sum_{s=1}^{m_j} \epsilon_{js}\delta_{\theta_{js}^*}$. Set $j = j + 1$ and go to **Step 1**.