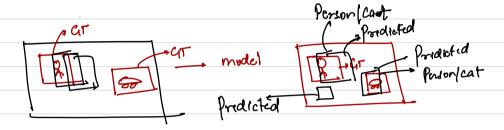
"How to measure the object detection model's accuracy mean average Precision and Intersection over Union.

Pricogion = TP/ all detections Recall: TP/ Ground Truths

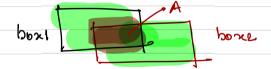


- Whenever we are evaluating object detection models.

 O Class of the object wedsteet

 O hocation of the bounding bon companion

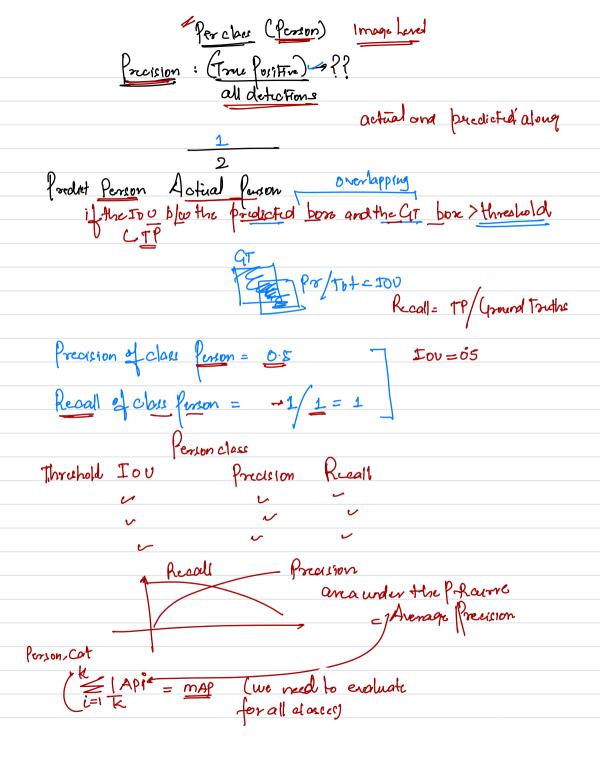
Intersection over Union



Red Part (intersection area) = A Green Part (Total area) = B

Producted box (detecting the coordinates)

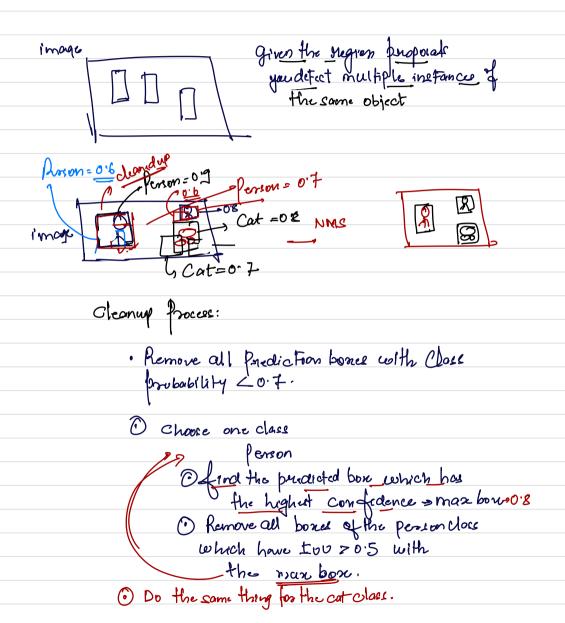
Person detecting the class.



for multiple images Class - Person Precision TP / detections (Person does) Recall= TP/Ground touther (forson class)

map = X Api

Non-more Sugression



У	loLo	Cyan	u only	hook	once)			
			•					