

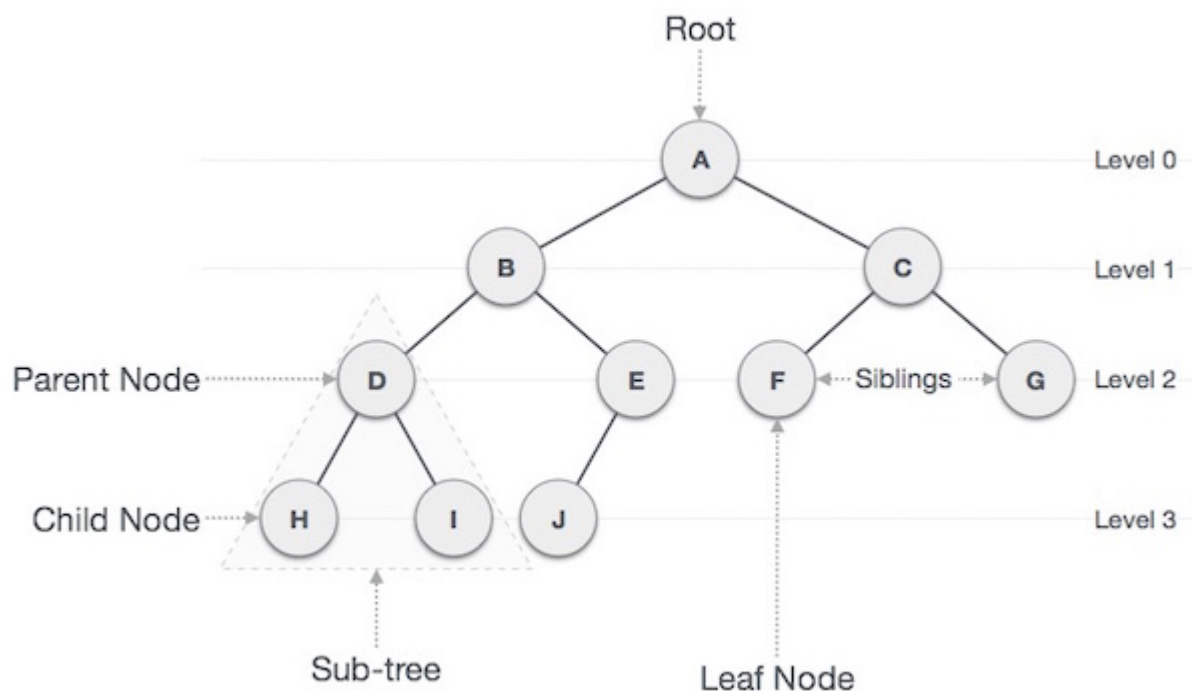
DATA STRUCTURE - TREE

http://www.tutorialspoint.com/data_structures_algorithms/tree_data_structure.htm

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Tree represents nodes connected by edges. We'll going to discuss binary tree or binary search tree specifically.

Binary Tree is a special datastructure used for data storage purposes. A binary tree has a special condition that each node can have two children at maximum. A binary tree have benefits of both an ordered array and a linked list as search is as quick as in sorted array and insertion or deletion operation are as fast as in linked list.



Terms

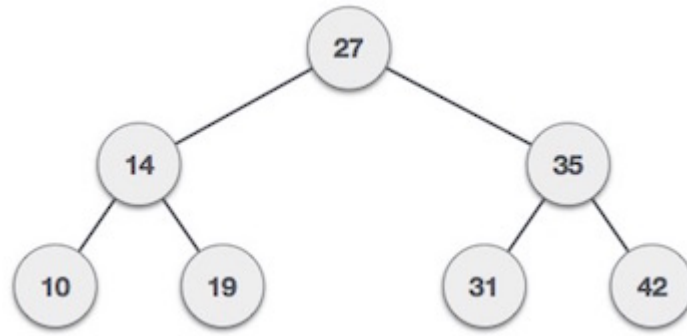
Following are important terms with respect to tree.

- **Path** – Path refers to sequence of nodes along the edges of a tree.
- **Root** – Node at the top of the tree is called root. There is only one root per tree and one path from root node to any node.
- **Parent** – Any node except root node has one edge upward to a node called parent.
- **Child** – Node below a given node connected by its edge downward is called its child node.
- **Leaf** – Node which does not have any child node is called leaf node.
- **Subtree** – Subtree represents descendents of a node.
- **Visiting** – Visiting refers to checking value of a node when control is on the node.
- **Traversing** – Traversing means passing through nodes in a specific order.
- **Levels** – Level of a node represents the generation of a node. If root node is at level 0, then its next child node is at level 1, its grandchild is at level 2 and so on.
- **keys** – Key represents a value of a node based on which a search operation is to be carried out for a node.

Binary Search Tree Representation

Binary Search tree exhibits a special behaviour. A node's left child must have value less than its

parent's value and node's right child must have value greater than its parent value.



We're going to implement tree using node object and connecting them through references.

Node

A tree node should look like the below structure. It has data part and references to its left and right child nodes.

```
struct node {  
    int data;  
    struct node *leftChild;  
    struct node *rightChild;  
};
```

In a tree, all nodes share common construct.

BST Basic Operations

The basic operations that can be performed on binary search tree data structure, are following –

- **Insert** – insert an element in a tree / create a tree.
- **Search** – search an element in a tree.
- **Preorder Traversal** – traverse a tree in a preorder manner.
- **Inorder Traversal** – traverse a tree in an inorder manner.
- **Postorder Traversal** – traverse a tree in a postorder manner.

We shall learn creating *inserting into* tree structure and searching a data-item in a tree in this chapter. We shall learn about tree traversing methods in the coming one.

Insert Operation

The very first insertion creates the tree. Afterwards, whenever an element is to be inserted. First locate its proper location. Start search from root node then if data is less than key value, search empty location in left subtree and insert the data. Otherwise search empty location in right subtree and insert the data.

Algorithm

```
If root is NULL  
    then create root node  
return  
  
If root exists then  
    compare the data with node.data  
  
    while until insertion position is located  
        If data is greater than node.data  
            goto right subtree  
        else
```

```

        goto left subtree

    endwhile

    insert data

end If

```

Implementation

The implementation of insert function should look like this –

```

void insert(int data) {
    struct node *tempNode = (struct node*) malloc(sizeof(struct node));
    struct node *current;
    struct node *parent;

    tempNode->data = data;
    tempNode->leftChild = NULL;
    tempNode->rightChild = NULL;

    //if tree is empty, create root node
    if(root == NULL) {
        root = tempNode;
    }else {
        current = root;
        parent = NULL;

        while(1) {
            parent = current;

            //go to left of the tree
            if(data < parent->data) {
                current = current->leftChild;

                //insert to the left
                if(current == NULL) {
                    parent->leftChild = tempNode;
                    return;
                }
            }

            //go to right of the tree
            else {
                current = current->rightChild;

                //insert to the right
                if(current == NULL) {
                    parent->rightChild = tempNode;
                    return;
                }
            }
        }
    }
}

```

Search Operation

Whenever an element is to be search. Start search from root node then if data is less than key value, search element in left subtree otherwise search element in right subtree. Follow the same algorithm for each node.

Algorithm

```

If root.data is equal to search.data
    return root
else

```

```

while data not found

    If data is greater than node.data
        goto right subtree
    else
        goto left subtree

    If data found
        return node

endwhile

return data not found

end if

```

The implementation of this algorithm should look like this.

```

struct node* search(int data) {
    struct node *current = root;
    printf("Visiting elements: ");

    while(current->data != data) {
        if(current != NULL)
            printf("%d ", current->data);

        //go to left tree

        if(current->data > data) {
            current = current->leftChild;
        }
        //else go to right tree
        else {
            current = current->rightChild;
        }

        //not found
        if(current == NULL) {
            return NULL;
        }

        return current;
    }
}

```

To see the implementation of binary search tree data structure, please [click here](#).

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