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1.C Code for Sensor module
#include <stdio.h>
#include <stdlib.h>
#include <wiringPi.h>
#include <softPwm.h>
// Define sensor pins and other parameters
#define CAMERA_PIN 2
#define MOTION_PIN 3
#define TEMPERATURE_PIN 4
void setup() {
  wiringPiSetup();
  pinMode(CAMERA_PIN, INPUT);
  pinMode(MOTION_PIN, INPUT);
  pinMode(TEMPERATURE_PIN, INPUT);
}
void loop() {
  // Read sensor data
  int camera_data = digitalRead(CAMERA_PIN);
  int motion_data = digitalRead(MOTION_PIN);
  int temperature_data = analogRead(TEMPERATURE_PIN);
  // Process data (e.g., filter noise, extract features)
  // ...
  // Transmit data to server (e.g., using MQTT, HTTP)
  // ...
  delay(1000); // Adjust delay as needed
}
2. Python Code for Central Server
       import paho.mqtt.client as mqtt
       import time
```

import cv2

import tensorflow as tf

```
# MQTT client setup
def on_connect(client, userdata, flags, rc):
  print("Connected with result code " + str(rc))
  client.subscribe("sensor_data")
def on_message(client, userdata, msg):
  data = msg.payload.decode()
  # Process received data (e.g., parse JSON, extract features)
  # ...
  # Use machine learning models for analysis
  model = tf.keras.models.load_model('wildlife_detection_model.h5')
  predictions = model.predict(preprocessed_data)
  # ...
  # Generate alerts and notifications
  # ...
# MQTT client initialization
client = mqtt.Client()
client.on_connect = on_connect
client.on_message = on_message
client.connect("broker.hivemq.com", 1883, 60)
# Start the MQTT client
client.loop_start()
# Main loop
while True:
  # Other tasks (e.g., user interface, data visualization)
  time.sleep(1)
```