Department of Computer Engineering

T.E. (Computer Sem VI) Assignment -1 Artificial Intelligence (CSC604)

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CO Addressed:— CSC604.1 -To conceptualize the basic ideas and techniques underlying the design of intelligent systems.

Assignment 1:

- 1. Explain the concept of rationality in the context of intelligent agents. How does rationality relate to the behavior of agents in their environments? Provide examples to illustrate your explanation.
- 2. Discuss the nature of environments in which intelligent agents operate. What are the key characteristics that define an environment, and how do they influence the design and behavior of agents? Provide examples of different types of environments and the challenges they present to agents.
- 3. Describe the structure of intelligent agents and the types of agents commonly used in artificial intelligence. What are the components of an agent, and how do they interact to achieve intelligent behavior? Provide examples of different types of agents and their applications in real-world scenarios.
- 4. Outline the process of problem-solving by searching, including the role of problem-solving agents and the formulation of problems. How do problem-solving agents analyze and approach problems, and what methods do they use to search for solutions? Illustrate your explanation with examples of problem-solving tasks and the strategies employed by agents to solve them.

Rubrics for the First Assignments:

Indicator	Average	Good	Excellent	Marks
Organization (2)	Readable with some missing points and structured (1)	Readable with improved points coverage and structured (1)	Very well written and fully structured	
Level of content(4)	All major topics are covered, the information is accurate (2)	Most major and some minor criteria are included. Information is accurate (3)	All major and minor criteria are covered and are accurate (4)	
Depth and breadth of discussion and representation(4)	Minor points/information may be missing and representation is minimal (1)	Discussion focused on some points and covers them adequately (2)	Information is presented in depth and is accurate (4)	
Total				

Signature of the Teacher

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ASSIGNMENT-1

(QI) Explain the concept of rationality in context of intelligent agents. How does rationality relate to the behaviour of agents in their environments? Provide examples of to #Hillustrate your explanation Ball Rationality refers to the ability of an agent to make decisions that maximize its expected utility or achieve its goals given the available information and resources Rationality is about making the best possible decisions given the circumstances ever if those decisions are not always perfect 3) Rationality relates to the behaviour of agents in the environments by guiding them to select actions that lead to desirable outcomes or goals WAn agent is considered rational if it consistently chooses actions that are expected to maximize its utility or achieve its objectives 5) Examples: - A chess-playing agent A rational chess playing agent would choose mowes that are expected to lead to victory or at least avoid defeat. It evaluates potential moves based on its understanding of the game state and selects the one that maximizes its chances of winning 2) In a self-driving car rationality involves making decisions that prioritize safety and efficiency. The car must havigate through traffic, obey traffic laws and avoid accidents all while reaching its

destination in a timely manner. A rational self-driving con would choose routes and driving behaviours that minimize the risk of accidents and optimize travel time

- (2) Discuss the nature of environments in which intelligent agents operate. What are key characteristics that define an environment and how do they influence the design and behaviour of agents? Provide examples of different types of environment and challenges they present to agents. Other nature of environments in which intelligent agents operated diverse and can vary greatly depending on factors such as complexity, dynamics, observability, determinicism and experisodicity.
 - 1) complexity: Environments can runge from simple deterministing environments with a few states and actions to complex stochastic environments with countries possible states and actions
 - 2) Dynamics Environments may be static, where the gents actions do not change the state or dynamic, where the environment evolves when even with out the agent's intervention
 - 3 Observability: Environments can be tully observable where the agents has access to complete information about the current state or partially observable where the agent has limited or incomplete information
 - Determinism: Environments may be deterministic, where the outcome of an action is fully determined by current state and the action takes or stochastic where there is uncertainty in outcome

(5) Episodicity: - Environments may be episodic where each action leads to an immediate reward and resets the menvironment to an initial state or sequential where actions taken now can affect future states Examples: - Stock Market: A stochastic partially observable sequential environment with high complexity. Agents may analyze historical data, predict future market movements and adapt their strategies in real-time to changing conditions 2) Robot Navigation: - A dynamic observable sequential environment with moderate complexity. Agents need to perceive their surroundings through sensors plan trajectorie to ravigate obstacles and updates their plans as new information becomes available (B) Describe the structure of intelligent agents and the types of agents commonly used in artificial intelligence What are the components of an agent and how do they Interact to achieve intelligent behaviour? Provide examples of different types of agents and their applications in real world seen anos 1) Intelligent agents in artificial intelligence typically the consist of five main components (i) Perception: This component involves sensing the environment using sensors to gather information its

- about how an agent perceives its sumoundings
- 2) Reasoning: Agente use reasoning mechanism tato make decisions and plan actions based on information they have gathered. This involves processing and an alyzing data to come up with solutions or responses
 - 3) Actuation: once a decision is made the agent must exact upon it. Advators are mechanisms through which the agent interacts with environment to carry out actions
 - Throw ledge: Agents posess knowledges or information about the environment, themselves and the tooks they need to perform. This knowledge can be pre-defined, learned or inferred from past experiences
 - Dearning:- Intelligent agents can improve their performance over time through learning mechanisms. This could invove acquiring good knowledge adapting strategies or optimize behaviour based on feedback

Types of ioteligent agents include

- O simple reflex agents: These agents take autions based solely on a current percept without considering the history of past percepts. An example is a thermostat that adjusts the temperature based on whent readings
- Donodel Based Reflex Agents. They maintain an internal It model of an environment and use it to make decisions for example, a vacuum dearing robot that uses a map of room to decide where to dear next
- 3 Goal Based Any Agents: These agents have goals or objectives that they aim to achieve and take actions to move towards these goals. An example is a delivery drone that navigates to deliver packages to specific locations

(2) Oblity Based agents: They evaluate the desirability of various actions based on a utility function and choose the action that maximizes expected utility A personal assistant app that schedules tasks based or user preferences and priorities is an example (5) Learning Agenta: These agents improve their performan over time through learning from experience. Examples lodude recommendation systems that learn ween preferences from interactions and adapt their recommendations accordingly ey) outline the process of problem-solving by searching, including the role of problem-solving egents and the formulation of problems. How do problem-solving agents analyze and approach problems and what methods do they use to search for solitions Illustrate your explanation with examples of problem-solving tasks

A Role of problem-solving agents

O Problem-solving agents operate independently making decisions and taking actions to achieve desired goals

without human intervention

2) These agents are designed to efficiently explore and navigate problem spaces to find optimal or satisfactory problems solutions

3) Problem-solving agents can adapt to changes in

- their environment or problem domain adout soing their strategies to accommodate peco information or new constaints
- They can handle a wide range of problem types and complexities from simple puzzles to complex red-world scenarios
- (2) Formulation of problems
 - O Problem formulation involves abstracting real-world scenarios into a formal representation that can be understood arand processed by problem-solving agents
 - 2 Problems are represented in a way that captures essential elements such as initial states, goal states action and constraints
 - B formulating problems provides a structured approach to problem-solving, breaking down complex issues into smaller, more manageable components
 - (3) Methods used for securching solutions:
 - O uninformed exarch: Agents explore the problem space systematically without consideration of domain specific knowledge
 - eg Breadth first search, depth- first search
 - 2 Informed search Agents use domain specific knowledge or heunistics to guide the search towards promising solutions Eg Ak ocard, gready best-first search
 - 3) Local search agents Agents iteratively improve condidates
- (4) Examples
 - O Routing Planning! In navigation systems, problem-solving agents search for the shortest path between two locations and they analyze the road network consider traffic conditions and employ algorithms like Ark to find optional routes

12) Puzzle solving : In games Likes Sudoku or Rubik's whe
agents taim to find solutions satisfying contain
constraints. They analyze the puzzles witial state
explore possible moves and use strategies like constact
* propagation or backtracking to solve the puzzle.
(3) Automated planning: In robotics or automated
Systems problem solving agents plan sequences of
actions to achieve desired outcomes They analyze
the environment consider constaints and employ
planning algorithms like POSL to generate action
Seguences