EXPERIMENT 5

Postlab

- 1. Explain the Time Complexity of the A^{*} Algorithm.
- 2. What are the limitations of A* Algorithm?
- 3. Discuss A^* , BFS, DFS and Dijkstra's algorithm in detail with examples.

Name = Namrota G. Joshi ROLL NO: 9545 TE COMPS A EXPT-5 (1) Explain the time complexity of At algorithms? The time complexity of A+ algorithm depends on the hearistic accuracy and search spaces size. In the worst-case scenario, it can be exponential. Mowever with an admissible and consistent heuristic A* quarantees finding the optimal solution efficiently (2) What are the limitations of A* algorithm? D'Ax can consume significantly memory searchis especially in large spaces e worst care time complexity can be exponential particularly with ineffective heuristics or large search spaces (3) The quality of heuristic heavily influence AR efficiency and optimality (4) At may encounter scenarios where itexplose scenarios of search space intentionally (3) Discuss A* , BFS, DFS, dijkstra's algorithmin detail with example A* algorithm Ax is a widey used informed search algorit that finds the shortest path from a short nod to a goal node in graph, It combines the advantages of Dijkstra's algorithm and greedy best first search by ving both the cost to reach a node Algorithm Initialize on open list and add the start node While the open list is not empty select the bode with towest total cost If the selected node is goal, terminale with

If the open list becomes empty without reach the goal, tominates the fullire Example: - And the shortest path from A box (2) Bread to first Search Search DIES an uninformed search algorithm that systematically explores all neighbours modes at present depth before moving on to sodes at the next depth level. I' 2 Argonithmir (Start with an withal node and enqueue itip a equeue While the quare is not empty beque a node from the queue If the dequented node is the good, terminal with successes Enqueue all visited neighbour modes of depor node If the queue becomes empty without reaching the good, terminale the gode 3) Depth first search DES is an uninformed search algorithm that explores as far as possible along each breach before brack back tracking It does not guarantee finding the shortest path and can get state in deep branches Start with the initial node and push it into a stack, While the stack is not empty Pap a node from stack If popped node is good terminale surecess Puch all unisited neighbour moder of papped node of the stack Dijkstra's Algorithm