

# 第16讲 大规模无约束优化

- 非精确Newton-CG方法
- 信赖域Newton-CG方法
- 有限记忆BFGS方法

大规模无约束优化问题： $\min_{x \in R^n} f(x)$

古典Newton法的迭代公式： $x_{k+1} = x_k + d_k$

其中 $x_k$ 处的Newton方向

$$d_k = -\nabla^2 f(x_k)^{-1} \nabla f(x_k)$$

等价于求解方程组

$$\nabla^2 f(x_k) d + \nabla f(x_k) = 0$$

如果方程组没有精确计算到解，牛顿方法是否还有类似的收敛性和收敛速度？

## 局部收敛的非精确牛顿法

迭代格式:  $x_{k+1} = x_k + p_k$

其中  $p_k$  满足:  $\|\nabla^2 f(x_k) p + \nabla f(x_k)\| \leq \eta_k \|\nabla f(x_k)\|$ , (7.3)

且  $0 < \eta_k < 1$

### Theorem 7.1.

Suppose that  $\nabla^2 f(x)$  exists and is continuous in a neighborhood of a minimizer  $x^*$ , with  $\nabla^2 f(x^*)$  is positive definite. Consider the iteration  $x_{k+1} = x_k + p_k$  where  $p_k$  satisfies (7.3), and assume that  $\eta_k \leq \eta$  for some constant  $\eta \in [0, 1)$ . Then, if the starting point  $x_0$  is sufficiently near  $x^*$ , the sequence  $\{x_k\}$  converges to  $x^*$  and satisfies

$$\|\nabla^2 f(x^*)(x_{k+1} - x^*)\| \leq \hat{\eta} \|\nabla^2 f(x^*)(x_k - x^*)\|, \quad (7.4)$$

for some constant  $\hat{\eta}$  with  $\eta < \hat{\eta} < 1$ .

**Theorem 7.2.**

*Suppose that the conditions of Theorem 7.1 hold, and assume that the iterates  $\{x_k\}$  generated by the inexact Newton method converge to  $x^*$ . Then the rate of convergence is superlinear if  $\eta_k \rightarrow 0$ . If in addition,  $\nabla^2 f(x)$  is Lipschitz continuous for  $x$  near  $x^*$  and if  $\eta_k = O(\|\nabla f_k\|)$ , then the convergence is quadratic.*

To obtain superlinear convergence, we can set, for example,  $\eta_k = \min(0.5, \sqrt{\|\nabla f_k\|})$ ; the choice  $\eta_k = \min(0.5, \|\nabla f_k\|)$  would yield quadratic convergence.

**Algorithm 7.1** (Line Search Newton–CG).

Given initial point  $x_0$ ;

for  $k = 0, 1, 2, \dots$

    Define tolerance  $\epsilon_k = \min(0.5, \sqrt{\|\nabla f_k\|}) \|\nabla f_k\|$ ;

    Set  $z_0 = 0, r_0 = \nabla f_k, d_0 = -r_0 = -\nabla f_k$ ;

    for  $j = 0, 1, 2, \dots$

        if  $d_j^T B_k d_j \leq 0$

            if  $j = 0$

                return  $p_k = -\nabla f_k$ ;

        else

            return  $p_k = z_j$ ;

        Set  $\alpha_j = r_j^T r_j / d_j^T B_k d_j$ ;

        Set  $z_{j+1} = z_j + \alpha_j d_j$ ;

        Set  $r_{j+1} = r_j + \alpha_j B_k d_j$ ;

        if  $\|r_{j+1}\| < \epsilon_k$

            return  $p_k = z_{j+1}$ ;

        Set  $\beta_{j+1} = r_{j+1}^T r_{j+1} / r_j^T r_j$ ;

        Set  $d_{j+1} = -r_{j+1} + \beta_{j+1} d_j$ ;

    end (for)

    Set  $x_{k+1} = x_k + \alpha_k p_k$ , where  $\alpha_k$  satisfies the Wolfe, Goldstein, or Armijo backtracking conditions (using  $\alpha_k = 1$  if possible);

end

$$\nabla^2 f_k d \approx \frac{\nabla f(x_k + hd) - \nabla f(x_k)}{h},$$

# 信赖域Newton-CG方法

**Algorithm 4.1** (Trust Region).

Given  $\hat{\Delta} > 0$ ,  $\Delta_0 \in (0, \hat{\Delta})$ , and  $\eta \in [0, \frac{1}{4})$ :

for  $k = 0, 1, 2, \dots$

    Obtain  $p_k$  by (approximately) solving (4.3);

    Evaluate  $\rho_k$  from (4.4);

    if  $\rho_k < \frac{1}{4}$

$$\Delta_{k+1} = \frac{1}{4} \Delta_k$$

    else

        if  $\rho_k > \frac{3}{4}$  and  $\|p_k\| = \Delta_k$

$$\Delta_{k+1} = \min(2\Delta_k, \hat{\Delta})$$

        else

$$\Delta_{k+1} = \Delta_k;$$

    if  $\rho_k > \eta$

$$x_{k+1} = x_k + p_k$$

    else

$$x_{k+1} = x_k;$$

end (for).

# 信赖域子问题的求解

**Algorithm 7.2** (CG–Steihaug).

Given tolerance  $\epsilon_k > 0$ ;

Set  $z_0 = 0, r_0 = \nabla f_k, d_0 = -r_0 = -\nabla f_k$ ;

if  $\|r_0\| < \epsilon_k$

    return  $p_k = z_0 = 0$ ;

for  $j = 0, 1, 2, \dots$

    if  $d_j^T B_k d_j \leq 0$

        Find  $\tau$  such that  $p_k = z_j + \tau d_j$  minimizes  $m_k(p_k)$  in (4.5)

        and satisfies  $\|p_k\| = \Delta_k$ ;

        return  $p_k$ ;

    Set  $\alpha_j = r_j^T r_j / d_j^T B_k d_j$ ;

    Set  $z_{j+1} = z_j + \alpha_j d_j$ ;

    if  $\|z_{j+1}\| \geq \Delta_k$

        Find  $\tau \geq 0$  such that  $p_k = z_j + \tau d_j$  satisfies  $\|p_k\| = \Delta_k$ ;

        return  $p_k$ ;

    Set  $r_{j+1} = r_j + \alpha_j B_k d_j$ ;

    if  $\|r_{j+1}\| < \epsilon_k$

        return  $p_k = z_{j+1}$ ;

    Set  $\beta_{j+1} = r_{j+1}^T r_{j+1} / r_j^T r_j$ ;

    Set  $d_{j+1} = -r_{j+1} + \beta_{j+1} d_j$ ;

end (for).

# 有限记忆BFGDS

**Algorithm 7.5** (L-BFGS).

Choose starting point  $x_0$ , integer  $m > 0$ ;

$k \leftarrow 0$ ;

**repeat**

    Choose  $H_k^0$  (for example, by using (7.20));

    Compute  $p_k \leftarrow -H_k \nabla f_k$  from Algorithm 7.4;

    Compute  $x_{k+1} \leftarrow x_k + \alpha_k p_k$ , where  $\alpha_k$  is chosen to  
        satisfy the Wolfe conditions;

**if**  $k > m$

        Discard the vector pair  $\{s_{k-m}, y_{k-m}\}$  from storage;

    Compute and save  $s_k \leftarrow x_{k+1} - x_k$ ,  $y_k = \nabla f_{k+1} - \nabla f_k$ ;

$k \leftarrow k + 1$ ;

**until convergence.**



$$x_{k+1} = x_k - \alpha_k H_k \nabla f_k,$$

$$H_{k+1} = V_k^T H_k V_k + \rho_k s_k s_k^T$$

$$(\text{BFGS}) \quad H_{k+1} = (I - \rho_k s_k y_k^T) H_k (I - \rho_k y_k s_k^T) + \rho_k s_k s_k^T, \quad (6.17)$$

$$\rho_k = \frac{1}{y_k^T s_k}, \quad V_k = I - \rho_k y_k s_k^T, \quad s_k = x_{k+1} - x_k, \quad y_k = \nabla f_{k+1} - \nabla f_k.$$

$$\begin{aligned} H_k &= (V_{k-1}^T \cdots V_{k-m}^T) H_k^0 (V_{k-m} \cdots V_{k-1}) \\ &\quad + \rho_{k-m} (V_{k-1}^T \cdots V_{k-m+1}^T) s_{k-m} s_{k-m}^T (V_{k-m+1} \cdots V_{k-1}) \\ &\quad + \rho_{k-m+1} (V_{k-1}^T \cdots V_{k-m+2}^T) s_{k-m+1} s_{k-m+1}^T (V_{k-m+2} \cdots V_{k-1}) \\ &\quad + \cdots \\ &\quad + \rho_{k-1} s_{k-1} s_{k-1}^T. \end{aligned} \quad (7.19)$$

**Algorithm 7.4** (L-BFGS two-loop recursion).

$q \leftarrow \nabla f_k;$

**for**  $i = k - 1, k - 2, \dots, k - m$

$\alpha_i \leftarrow \rho_i s_i^T q;$

$q \leftarrow q - \alpha_i y_i;$

**end (for)**

$r \leftarrow H_k^0 q;$

**for**  $i = k - m, k - m + 1, \dots, k - 1$

$\beta \leftarrow \rho_i y_i^T r;$

$r \leftarrow r + s_i(\alpha_i - \beta)$

**end (for)**

**stop** with result  $H_k \nabla f_k = r.$

# 练习: 习题6

4. 用信赖域算法 6.1 和子问题的截断共轭梯度算法 6.4 编程计算如下最优化问题 (取  $n = 10$ ) 的解.

$$\min f(x) = \sum_{i=1}^n [(1 - x_{2i-1})^2 + 10(x_{2i} - x_{2i-1}^2)^2].$$

实现非精确牛顿法Algorithm 7.1 和信赖域Newton-CG法 (Algorithm 7.2), 对上面的问题计算  $n=500, 1000, 3000$ , 与牛顿法、拟牛顿法、最速下降法, 非线性共轭梯度法进行比较。信息班的同学每人都必须交实验报告。

# 微分计算

- 有限差分
- 自动差分
- 符号差分

# 有限差分导数逼近

- 主要工具: Taylor 展式

$$f(x + p) = f(x) + \nabla f(x)^T p + \frac{1}{2} p^T \nabla^2 f(x + tp) p, \quad \text{some } t \in (0, 1)$$

- 向前差分:

$$\frac{\partial f}{\partial x_i}(x) \approx \frac{f(x + \epsilon e_i) - f(x)}{\epsilon}.$$

# 有限差分导数逼近

- 取  $p = \epsilon e_i$

$$\nabla f(x)^T p = \nabla f(x)^T e_i = \partial f / \partial x_i,$$

$$\frac{\partial f}{\partial x_i}(x) = \frac{f(x + \epsilon e_i) - f(x)}{\epsilon} + \delta_\epsilon, \quad \text{where } |\delta_\epsilon| \leq (L/2)\epsilon.$$

$$\frac{\partial f}{\partial x_i}(x) = \frac{f(x + \epsilon e_i) - f(x - \epsilon e_i)}{2\epsilon} + O(\epsilon^2).$$

By setting  $p = \epsilon e_i$  and  $p = -\epsilon e_i$ , respectively, we obtain

$$f(x + \epsilon e_i) = f(x) + \epsilon \frac{\partial f}{\partial x_i} + \frac{1}{2} \epsilon^2 \frac{\partial^2 f}{\partial x_i^2} + O(\epsilon^3),$$

$$f(x - \epsilon e_i) = f(x) - \epsilon \frac{\partial f}{\partial x_i} + \frac{1}{2} \epsilon^2 \frac{\partial^2 f}{\partial x_i^2} + O(\epsilon^3).$$

$$\frac{\partial f}{\partial x_i}(x) = \frac{f(x + \epsilon e_i) - f(x - \epsilon e_i)}{2\epsilon} + O(\epsilon^2).$$

$\mathbf{u}$  known as *unit roundoff*

$$|\text{comp}(f(x)) - f(x)| \leq \mathbf{u}L_f,$$

$$|\text{comp}(f(x + \epsilon e_i)) - f(x + \epsilon e_i)| \leq \mathbf{u}L_f,$$

$$\frac{\partial f}{\partial x_i}(x) = \frac{f(x + \epsilon e_i) - f(x)}{\epsilon} + \delta_\epsilon, \quad \text{where } |\delta_\epsilon| \leq (L/2)\epsilon. \quad (8.4)$$

an error that is bounded by

$$(L/2)\epsilon + 2\mathbf{u}L_f/\epsilon.$$

the minimizing value is

$$\epsilon = \sqrt{\mathbf{u}}.$$

$$\epsilon^2 = \frac{4L_f\mathbf{u}}{L}.$$



$$\frac{\partial f}{\partial x_i}(x) = \frac{f(x + \epsilon e_i) - f(x - \epsilon e_i)}{2\epsilon} + O(\epsilon^2).$$

最优取值  $\epsilon = u^{\frac{1}{3}}$

误差界  $u^{\frac{2}{3}}$

$$\nabla f(x + \epsilon p) = \nabla f(x) + \epsilon \nabla^2 f(x) p + O(\epsilon^2), \quad (8.19)$$

so that

$$\nabla^2 f(x) p \approx \frac{\nabla f(x + \epsilon p) - \nabla f(x)}{\epsilon} \quad (8.20)$$

$$\frac{\partial^2 f}{\partial x_i \partial x_j}(x) = \frac{f(x + \epsilon e_i + \epsilon e_j) - f(x + \epsilon e_i) - f(x + \epsilon e_j) + f(x)}{\epsilon^2} + O(\epsilon). \quad (8.21)$$