

CS201 DISCRETE MATHEMATICS FOR COMPUTER SCIENCE

Dr. QI WANG

Department of Computer Science and Engineering

Office: Room903, Nanshan iPark A7 Building

Email: wangqi@sustech.edu.cn

■ Recall: the cardinality of a finite set is defined by the number of the elements in the set.



Recall: the cardinality of a finite set is defined by the number of the elements in the set.

■ The sets A and B have the same cardinality if there is a one-to-one correspondence between elements in A and B.



- Recall: the cardinality of a finite set is defined by the number of the elements in the set.
- The sets A and B have the same cardinality if there is a one-to-one correspondence between elements in A and B.
- A set that is <u>either finite</u> or <u>has the same cardinality</u> as the set of positive integers Z⁺ is called *countable*. A set that is <u>not countable</u> is called *uncountable*.



- Recall: the cardinality of a finite set is defined by the number of the elements in the set.
- The sets A and B have the same cardinality if there is a one-to-one correspondence between elements in A and B.
- A set that is either finite or has the same cardinality as the set of positive integers Z⁺ is called *countable*. A set that is **not countable** is called *uncountable*.
 - Why are these called **countable**?
 - ♦ The elements of the set can be **enumerated and listed**.



Theorem

The set of real numbers \mathbf{R} is uncountable.



Theorem

The set of real numbers \mathbf{R} is uncountable.

Proof by contradiction:

Assume that **R** is countable. Then every subset of **R** is countable (why?), in particular, the interval from 0 to 1 is countable. This implies that the elements of this set can be listed as r_1, r_2, r_3, \ldots , where

```
-r_1 = 0.d_{11}d_{12}d_{13}d_{14}\cdots
-r_2 = 0.d_{21}d_{22}d_{23}d_{24}\cdots
-r_3 = 0.d_{31}d_{32}d_{33}d_{34}\cdots
all d_{ii} \in \{0, 1, 2, \dots, 9\}.
```



Theorem

The set of real numbers \mathbf{R} is uncountable.

Proof by contradiction:

We want to show that not all real numbers in the interval between 0 and 1 are in this list.

Form a new number called $r = 0.d_1d_2d_3d_4\cdots$, where $d_i = 2$ if $d_{ii} \neq 2$, and $d_i = 3$ if $d_{ii} = 2$.



Theorem

The set of real numbers \mathbf{R} is uncountable.

Proof by contradiction:

We want to show that not all real numbers in the interval between 0 and 1 are in this list.

Form a new number called $r = 0.d_1d_2d_3d_4\cdots$, where $d_i = 2$ if $d_{ii} \neq 2$, and $d_i = 3$ if $d_{ii} = 2$.

Example: suppose	r1 = 0.75243	d1 = 2
	r2 = 0.524310	d2 = 3
	r3 = 0.131257	d3 = 2
	r4 = 0.9363633	d4 = 2
	rt = 0.23222222	dt = 3



Theorem

The set of real numbers \mathbf{R} is uncountable.

Proof by contradiction:

We claim that r is different from each number in the list.

Each expansion is unique, if we exclude an infinite string of 9's. r and r_i differ in the i-th decimal place for all i.



Algorithms

An algorithm is a finite sequence of precise instructions for performing a computation or for solving a problem.



Abu Ja'far Mohammed ibn Musa al-Khowarizmi



Which function is "bigger"?

$$\frac{1}{10}n^2$$
 or $100n + 10000$



Which function is "bigger"?

$$\frac{1}{10}n^2$$
 or $100n + 10000$

It depends on the value of n.



Which function is "bigger"?

$$\frac{1}{10}n^2$$
 or $100n + 10000$

It depends on the value of n.

In Computer Science, we are usually interested in what happens when our problem input size gets large.



Which function is "bigger"?

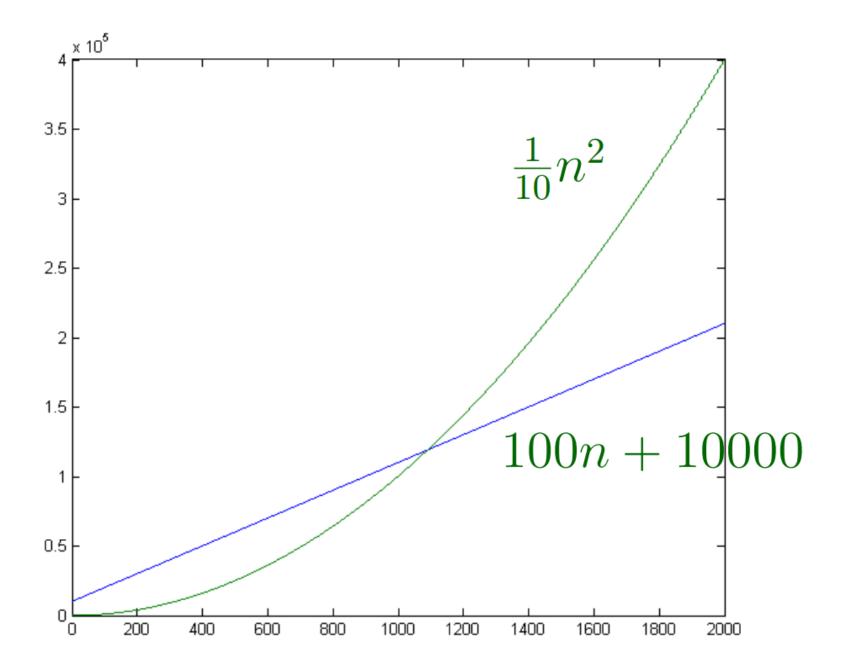
$$\frac{1}{10}n^2$$
 or $100n + 10000$

It depends on the value of n.

In Computer Science, we are usually interested in what happens when our problem input size gets large.

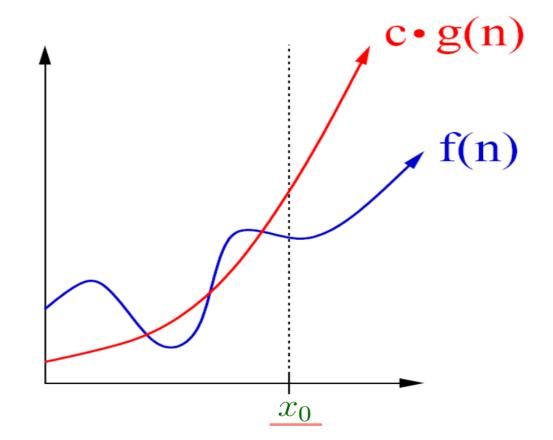
Notice that when n is "large enough", $\frac{1}{10}n^2$ gets much bigger than 100n + 10000 and stays larger.







Let f and g be functions from the set of integers or the set of real numbers to the set of real numbers. We say that f(n) = O(g(n)) (reads: f(n) is O of g(n)), if there exist some positive constants C and x_0 such that $|f(n)| \le C|g(n)|$, whenever $n > x_0$.





 $\frac{1}{10}n^2$ and 100n + 10000



 $\frac{1}{10}n^2$ and 100n + 10000

```
Let k = 1091
Can verify that \forall n \ge k, 100n + 10000 \le \frac{1}{10}n^2
Thus, 100n + 10000 = O(\frac{1}{10}n^2)
```



 $\frac{1}{10}n^2$ and 100n + 10000

```
Let k = 1091
Can verify that \forall n \ge k, 100n + 10000 \le \frac{1}{10}n^2
Thus, 100n + 10000 = O(\frac{1}{10}n^2)
```

Note that the opposite is **not** true! (Why?)



 $\frac{1}{10}n^2$ and 100n + 10000

```
Let k = 1091
Can verify that \forall n \ge k, 100n + 10000 \le \frac{1}{10}n^2
Thus, 100n + 10000 = O(\frac{1}{10}n^2)
```

Note that the opposite is **not** true! (Why?) (Proof by contradiction)



 $\frac{1}{10}n^2$ and 100n + 10000

```
Let k = 1091
Can verify that \forall n \ge k, 100n + 10000 \le \frac{1}{10}n^2
Thus, 100n + 10000 = O(\frac{1}{10}n^2)
```

Note that the opposite is **not** true! (Why?)

(Proof by contradiction)

Examples

$$4n^{2}$$

 $8n^{2} + 2n - 3$ are all $O(n^{2})$
 $n^{2}/5 + \sqrt{n} - 10 \log n$
 $n(n-3)$



Big-O Estimates for Polynomials

Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$, where $a_0, a_1, \ldots, a_{n-1}$ are real numbers. Then $f(x) = O(x^n)$.



Big-O Estimates for Polynomials

Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$, where $a_0, a_1, \ldots, a_{n-1}$ are real numbers. Then $f(x) = O(x^n)$.

Proof:

Assuming x > 1, we have

$$|f(x)| = |a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0|$$

$$\leq |a_n| x^n + |a_{n-1}| x^{n-1} + \dots + |a_1| x + |a_0|$$

$$= x^n (|a_n| + |a_{n-1}| / x + \dots + |a_1| / x^{n-1} + |a_0| / x^n)$$

$$< x^n (|a_n| + |a_{n-1}| + \dots + |a_1| + |a_0|).$$



Big-O Estimates for Polynomials

Let $f(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0$, where $a_0, a_1, \ldots, a_{n-1}$ are real numbers. Then $f(x) = O(x^n)$.

Proof:

Assuming x > 1, we have

$$|f(x)| = |a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0|$$

$$\leq |a_n| x^n + |a_{n-1}| x^{n-1} + \dots + |a_1| x + |a_0|$$

$$= x^n (|a_n| + |a_{n-1}|/x + \dots + |a_1|/x^{n-1} + |a_0|/x^n)$$

$$\leq x^n (|a_n| + |a_{n-1}| + \dots + |a_1| + |a_0|).$$

The leading term $a_n x^n$ of a polynomial dominates its growth.



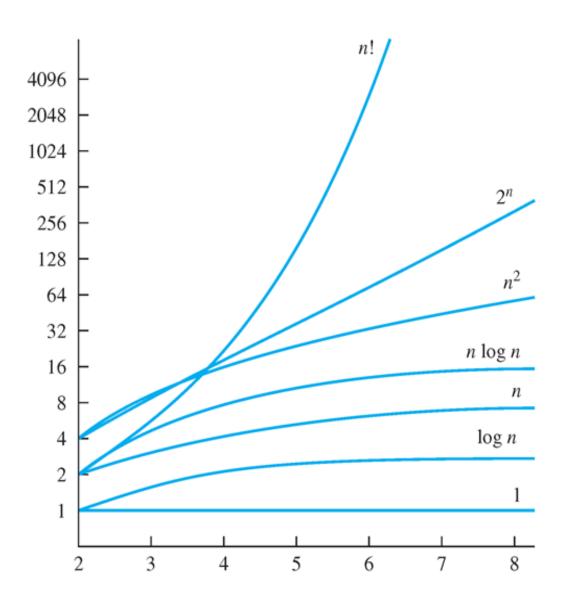
Big-O Estimates for Some Functions

■
$$1 + 2 + \cdots + n = O(n^2)$$

 $n! = O(n^n)$
 $\log n! = O(n \log n)$
 $\log_a n = O(n)$ for an integer $a \ge 2$
 $n^a = O(n^b)$ for integers $a \le b$
 $n^a = O(2^n)$ for an integer a



Display of Growth of Functions





Combinations of Functions

■ If $f_1(x)$ is $O(g_1(x))$ and $f_2(x)$ is $O(g_2(x))$ then $(f_1 + f_2)(x) = O(\max(|g_1(x)|, |g_2(x)|))$

Proof:

By definition, there exist constants C_1 , C_2 , k_1 , k_2 such that $|f_1(x)| \le C_1 |g_1(x)|$ when $x > k_1$ and $|f_2(x)| \le C_2 |g_2(x)|$ when $x > k_2$. Then $|(f_1 + f_2)(x)| = |f_1(x) + f_2(x)|$ $\leq |f_1(x)| + |f_2(x)|$ $\leq C_1|g_1(x)| + C_2|g_2(x)|$ $\leq C_1|g(x)|+C_2|g(x)|$ $= (C_1 + C_2)|g(x)|$ = C|g(x)|,

SOUTHERN

Combinations of Functions

If $f_1(x)$ is $O(g_1(x))$ and $f_2(x)$ is $O(g_2(x))$ then $(f_1f_2)(x) = O(g_1(x)g_2(x))$

Proof:

When
$$x > \max(k_1, k_2)$$
,
$$|(f_1 f_2)(x)| = |f_1(x)||f_2(x)|$$

$$\leq C_1 |g_1(x)|C_2|g_2(x)|$$

$$\leq C_1 C_2 |(g_1 g_2)(x)|$$

$$\leq C|(g_1 g_2)(x)|,$$

where $C = C_1 C_2$.



Ordering Functions by Order of Growth

•
$$f_1(n) = (1.5)^n$$

 $f_2(n) = 8n^3 + 17n^2 + 111$
 $f_3(n) = (\log n)^2$
 $f_4(n) = 2^n$
 $f_5(n) = \log(\log n)$
 $f_6(n) = n^2(\log n)^3$
 $f_7(n) = 2^n(n^2 + 1)$
 $f_8(n) = n^3 + n(\log n)^2$
 $f_9(n) = 100000$
 $f_{10}(n) = n!$



Big-Omega Notation

Let f and g be functions from the set of integers or the set of real numbers to the set of real numbers. We say that $f(n) = \Omega(g(n))$ (reads: f(n) is Ω of g(n)), if there exist some positive constants C and x_0 such that $|f(n)| \ge C|g(n)|$, whenever $n > x_0$.



Big-Omega Notation

Let f and g be functions from the set of integers or the set of real numbers to the set of real numbers. We say that $f(n) = \Omega(g(n))$ (reads: f(n) is Ω of g(n)), if there exist some positive constants C and x_0 such that $|f(n)| \ge C|g(n)|$, whenever $n > x_0$.

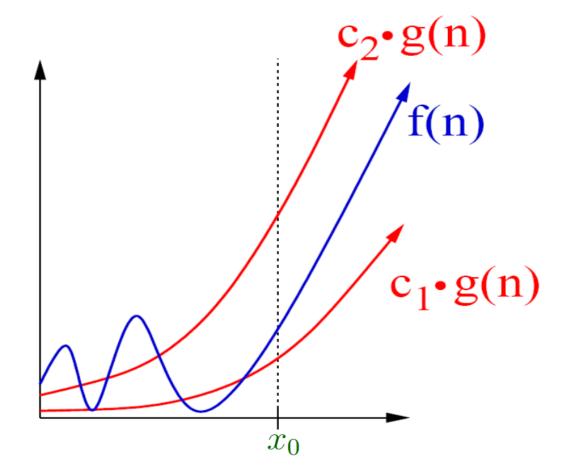
Big-O gives an upper bound on the growth of a function, while Big- Ω gives a lower bound. Big- Ω tells us that a function grows at least as fast as another.

Note: f(x) is $\Omega(g(x))$ if and only if g(x) is O(f(x)).



Big-Theta Notation (Big-O & Big-Omega)

Two functions f(n), g(n) have the same order growth if f(n) = O(g(n)) and g(n) = O(f(n)). In this case, we say that $f(n) = \Theta(g(n))$, which is the same as $g(n) = \Theta(f(n))$.





Examples $(f(n) = \Theta(g(n)))$

```
■ 3n^2 + 4n = \Theta(n)?

3n^2 + 4n = \Theta(n^2)?

3n^2 + 4n = \Theta(n^3)?

n/5 + 10n \log n = \Theta(n^2)?

n^2/5 + 10n \log n = \Theta(n \log n)?

n^2/5 + 10n \log n = \Theta(n^2)?
```



Examples $(f(n) = \Theta(g(n)))$

■
$$3n^2 + 4n = \Theta(n)$$
?
 $3n^2 + 4n = \Theta(n^2)$?
 $3n^2 + 4n = \Theta(n^3)$?
 $n/5 + 10n \log n = \Theta(n^2)$?
 $n^2/5 + 10n \log n = \Theta(n \log n)$?
 $n^2/5 + 10n \log n = \Theta(n^2)$?





Examples $(f(n) = \Theta(g(n)))$

$$3n^{2} + 4n = \Theta(n) ?$$

$$3n^{2} + 4n = \Theta(n^{2}) ?$$

$$3n^{2} + 4n = \Theta(n^{3}) ?$$

$$n/5 + 10n \log n = \Theta(n^{2}) ?$$

$$n^{2}/5 + 10n \log n = \Theta(n \log n) ?$$

$$n^{2}/5 + 10n \log n = \Theta(n^{2}) ?$$

No

Yes



■
$$3n^2 + 4n = \Theta(n)$$
?
 $3n^2 + 4n = \Theta(n^2)$?
 $3n^2 + 4n = \Theta(n^3)$?
 $n/5 + 10n \log n = \Theta(n^2)$?
 $n^2/5 + 10n \log n = \Theta(n \log n)$?
 $n^2/5 + 10n \log n = \Theta(n^2)$?

No

Yes

No, but $O(n^3)$



■
$$3n^2 + 4n = \Theta(n)$$
?
 $3n^2 + 4n = \Theta(n^2)$?
 $3n^2 + 4n = \Theta(n^3)$?
 $n/5 + 10n \log n = \Theta(n^2)$?
 $n^2/5 + 10n \log n = \Theta(n \log n)$?
 $n^2/5 + 10n \log n = \Theta(n^2)$?

No Yes

No, but $O(n^3)$

No, but $O(n^2)$



$$3n^{2} + 4n = \Theta(n) ?$$

$$3n^{2} + 4n = \Theta(n^{2}) ?$$

$$3n^{2} + 4n = \Theta(n^{3}) ?$$

$$n/5 + 10n \log n = \Theta(n^{2}) ?$$

$$n^{2}/5 + 10n \log n = \Theta(n \log n) ?$$

$$n^{2}/5 + 10n \log n = \Theta(n^{2}) ?$$

No Yes

No, but $O(n^3)$

No, but $O(n^2)$

No



■
$$3n^2 + 4n = \Theta(n)$$
 ? No $3n^2 + 4n = \Theta(n^2)$? Yes $3n^2 + 4n = \Theta(n^3)$? No, but $O(n^3)$ No, but $O(n^3)$ $n/5 + 10n \log n = \Theta(n^2)$? No, but $O(n^2)$ $n^2/5 + 10n \log n = \Theta(n \log n)$? No $n^2/5 + 10n \log n = \Theta(n^2)$? Yes



Algorithms

An algorithm is a finite sequence of precise instructions for performing a computation or for solving a problem.

A *computational problem* is a specification of the desired input-output relationship.

Example (Computational Problem and Algorithm)

The following procedure is an algorithm for calculating the sum of n given numbers a_1, a_2, \ldots, a_n .

```
Step 1: set S = 0
```

Step 2: for
$$i = 1$$
 to n , replace S by $S + a_i$



Instance

An instance of a problem is all the inputs needed to compute a solution to the problem.

Example (Instance of Problem)

■ A correct algorithm halts with the correct output for every input instance. We can then say that the algorithm solves the problem.



Time and Space Complexity

The number of <u>machine operations</u> (addition, multiplication, comparison, replacement, etc) needed in an algorithm is the <u>time complexity</u> of the algorithm, and <u>amount of memory</u> needed is the <u>space</u> <u>complexity</u> of the algorithm.



Time and Space Complexity

The number of machine operations (addition, multiplication, comparison, replacement, etc) needed in an algorithm is the time complexity of the algorithm, and amount of memory needed is the space complexity of the algorithm.

Example (Algorithm)

```
Step 1: set S = 0
```

```
Step 2: for i = 1 to n, replace S by S + a_i
```

Step 3: output *S*



Time and Space Complexity

The number of machine operations (addition, multiplication, comparison, replacement, etc) needed in an algorithm is the time complexity of the algorithm, and amount of memory needed is the space complexity of the algorithm.

Example (Algorithm)

```
Step 1: set S = 0
```

Step 2: for i = 1 to n, replace S by $S + a_i$

Step 3: output *S*

Step 1 and Step 3 take one operation. Step 2 takes 2n operations. Therefore, altogether this algorithm takes 2n + 2 operations. The time complexity is O(n).

Example

Consider the evaluation of $f(x) = 1 + 2x + 3x^2 + 4x^3$. Direct computation takes 3 additions and 6 multiplications. Can we do better?



Example

Consider the evaluation of $f(x) = 1 + 2x + 3x^2 + 4x^3$. Direct computation takes 3 additions and 6 multiplications. Can we do better?

Another way is f(x) = 1 + x(2 + x(3 + 4x)), which takes 3 additions and 3 multiplications.



Example

Consider the evaluation of $f(x) = 1 + 2x + 3x^2 + 4x^3$. Direct computation takes 3 additions and 6 multiplications. Can we do better?

Another way is f(x) = 1 + x(2 + x(3 + 4x)), which takes 3 additions and 3 multiplications.

```
Step 1: set S = a_n
```

Step 2: for
$$i = 1$$
 to n , replace S by $a_{n-i} + Sx$



Step 1: set $S = a_n$ Step 2: for i = 1 to n, replace S by $a_{n-i} + Sx$ Step 3: output S



Step 1: set $S = a_n$ Step 2: for i = 1 to n, replace S by $a_{n-i} + Sx$ Step 3: output S

The final value of S output at Step 3 is the desired value of $a_0 + a_1x + \cdots + a_nx^n$. The number of operations needed in this algorithm is 1 + 3n + 1 = 3n + 2. So the time complexity of this algorithm is O(n).



Determine the time complexity of the following algorithm:

```
for i := 1 to n

for j := 1 to n

a := 2 * n + i * j;

end for

end for
```



Determine the time complexity of the following algorithm:

```
for i := 1 to n

for j := 1 to n

a := 2 * n + i * j;

end for

end for
```

In the second loop, computing a takes 4 operations (two multiplications, one addition, and one replacement). For each i, it takes 4n operations to complete the second loop. So it takes $n \times 4n = 4n^2$ operations to complete the two loops. The time complexity of this algorithm is $O(n^2)$.

Determine the time complexity of the following algorithm:

```
S := 0
for i := 1 to n
for j := 1 to i
S := S + i * j;
end for
end for
```

Determine the time complexity of the following algorithm:

```
S := 0
for i := 1 to n
for j := 1 to i
S := S + i * j;
end for
end for
```

Computing S takes 3 operations. For each i, completing the second loop takes 3i operations. So altogether it takes

$$1 + \sum_{i=1}^{n} 3i = 1 + 3 \frac{n(n+1)}{2}$$

operations. So the complexity of this algorithm is $O(n^2)$.

More on Time Complexity

Example: (Insertion Sort) **Input**: A[1...n] is an array of numbers for j := 2 to nkey = A[j];i = j - 1;while $i \ge 1$ and A[i] > key do A[i+1] = A[i];i--;end while A[i+1] = key;end for



More on Time Complexity

Example: (Insertion Sort) **Input**: A[1...n] is an array of numbers for j := 2 to nkey = A[j];i = i - 1; while $i \ge 1$ and A[i] > key do A[i+1] = A[i];i--;end while A[i+1] = key; end for

key

Sorted

Unsorted

Where in the sorted part to put "key"?



Three Cases of Analysis: I

Best Case: constraints on the input, other than size, resulting in the fastest possible running time for the given size.



Three Cases of Analysis: I

Best Case: constraints on the input, other than size, resulting in the fastest possible running time for the given size.

Example: (Insertion Sort)

$$A[1] \leq A[2] \leq A[3] \leq \cdots \leq A[n]$$

The number of comparisons needed is

$$\underbrace{1 + 1 + 1 + \dots + 1}_{n-1} = n - 1 = \Theta(n)$$

key

Sorted Unsorted "key" is compared to only the element right before it.



Three Cases of Analysis: II

Worst Case: constraints on the input, other than size, resulting in the slowest possible running time for the given size.



Three Cases of Analysis: II

Worst Case: constraints on the input, other than size, resulting in the slowest possible running time for the given size.

Example: (Insertion Sort)

$$A[1] \ge A[2] \ge A[3] \ge \cdots \ge A[n]$$

The number of comparisons needed is

$$1+2+3+\cdots+(n-1)=\frac{n(n-1)}{2}=\Theta(n^2)$$

	key	
--	-----	--

Sorted Unsorted

"key" is compared to everything element before it.



Three Cases of Analysis: III

 Average Case: average running time over every possible type of input for the given size (usually involve probabilities of different types of input)



Three Cases of Analysis: III

 Average Case: average running time over every possible type of input for the given size (usually involve probabilities of different types of input)

Example: (Insertion Sort)

 $\Theta(n^2)$ assuming that each of the n! instances are equally likely

key

Sorted

On average, "key" is compared to half of the elements before it.



• Algorithm Design, is mainly about designing algorithms that have small Big-O running time.



• Algorithm Design, is mainly about designing algorithms that have small Big-O running time.

Being able to do good algorithm design lets you identify the hard parts of your problem and deal with them effectively.



- Algorithm Design, is mainly about designing algorithms that have small Big-O running time.
- Being able to do good algorithm design lets you identify the hard parts of your problem and deal with them effectively.
- Too often, programmers try to slove problems using brute force techniques and end up with slow complicated code!



- Algorithm Design, is mainly about designing algorithms that have small Big-O running time.
- Being able to do good algorithm design lets you identify the hard parts of your problem and deal with them effectively.
- Too often, programmers try to slove problems using brute force techniques and end up with slow complicated code!
- A few hours of abstract thought devoted to algorithm design could have speeded up the solution substantially and simplified it!

What happens if you can't find an efficient algorithm for a given problem?



What happens if you can't find an efficient algorithm for a given problem?

Blame yourself.



I couldn't find a polynomial-time algorithm. I guess I am too dumb.



What happens if you can't find an efficient algorithm for a given problem?

Show that no-efficient algorithm exists.



I couldn't find a polynomial-time algorithm, because no such algorithm exists.



Showing that a problem has an efficient algorithm is, relatively easy:



Showing that a problem has an efficient algorithm is, relatively easy:

"All" that is needed is to demonstrate an algorithm.



Showing that a problem has an efficient algorithm is, relatively easy:

"All" that is needed is to demonstrate an algorithm.

Proving that no efficient algorithm exists for a particular problem is difficult:



Dealing with Hard Problems

Showing that a problem has an efficient algorithm is, relatively easy:

"All" that is needed is to demonstrate an algorithm.

Proving that no efficient algorithm exists for a particular problem is difficult:

How can we prove the non-existence of something?



Dealing with Hard Problems

Showing that a problem has an efficient algorithm is, relatively easy:

"All" that is needed is to demonstrate an algorithm.

Proving that no efficient algorithm exists for a particular problem is difficult:

How can we prove the non-existence of something?

We will now learn about NP-Complete problems, which provide us with a way to approach this question.



A very large class of thousands of practical problems for which it is not known if the problems have "efficient" solutions.



- A very large class of thousands of practical problems for which it is not known if the problems have "efficient" solutions.
- It is known that if any one of the NP-Complete problems has an efficient solution then all of the NP-Complete problems have efficient solutions.



- A very large class of thousands of practical problems for which it is not known if the problems have "efficient" solutions.
- It is known that if any one of the NP-Complete problems has an efficient solution then all of the NP-Complete problems have efficient solutions.
- Researchers have spent innumberable man-years trying to find efficient solutions to these problems but failed.



- A very large class of thousands of practical problems for which it is not known if the problems have "efficient" solutions.
- It is known that if any one of the NP-Complete problems has an efficient solution then all of the NP-Complete problems have efficient solutions.
- Researchers have spent innumberable man-years trying to find efficient solutions to these problems but failed.
- So, NP-Complete problems are very likely to be hard.



- A very large class of thousands of practical problems for which it is not known if the problems have "efficient" solutions.
- It is known that if any one of the NP-Complete problems has an efficient solution then all of the NP-Complete problems have efficient solutions.
- Researchers have spent innumberable man-years trying to find efficient solutions to these problems but failed.
- So, NP-Complete problems are very likely to be hard.
- What do you do: prove that your problem is NP-Complete.



What do you actually do:



I couldn't find a polynomial-time algorithm, but neither could all these other smart people!



Encoding the Inputs of Problems

Complexity of a problem is measure w.r.t the size of input.



Encoding the Inputs of Problems

Complexity of a problem is measure w.r.t the size of input.

In order to formally discuss how hard a problem is, we need to be much more formal than before about the input size of a problem.



■ The input size of a problem might be defined in a number of ways.



The input size of a problem might be defined in a number of ways.

Definition The *input size* of a problem is the minimum number of bits $(\{0,1\})$ needed to encode the input of the problem.



The input size of a problem might be defined in a number of ways.

Definition The *input size* of a problem is the minimum number of bits $(\{0,1\})$ needed to encode the input of the problem.

■ The exact input size s, determined by an optimal encoding method, is hard to compute in most cases.



The input size of a problem might be defined in a number of ways.

Definition The *input size* of a problem is the minimum number of bits $(\{0,1\})$ needed to encode the input of the problem.

■ The exact input size s, determined by an optimal encoding method, is hard to compute in most cases.

However, we do not need to determine s exactly.

For most problems, it is sufficient to choose some natural, and (usually) simple, encoding and use the size *s* of this encoding.

Input Size Example: Composite

Example:

Given a positive integer n, are there integers j, k > 1 such that n = jk? (i.e., is n a composite number?)



Input Size Example: Composite

Example:

Given a positive integer n, are there integers j, k > 1 such that n = jk? (i.e., is n a composite number?)

Question:

What is the input size of this problem?



Input Size Example: Composite

Example:

Given a positive integer n, are there integers j, k > 1 such that n = jk? (i.e., is n a composite number?)

Question:

What is the input size of this problem?

Any integer n > 0 can be represented in the binary number system as a string $a_0 a_1 \cdots a_k$ of length $\lceil \log_2(n+1) \rceil$.

Thus, a natural measure of input size is $\lceil \log_2(n+1) \rceil$ (or just $\log_2 n$)



Input Size Example: Sorting

Example:

Sort n integers a_1, \ldots, a_n



Input Size Example: Sorting

Example:

Sort n integers a_1, \ldots, a_n

Question:

What is the input size of this problem?



Input Size Example: Sorting

Example:

Sort n integers a_1, \ldots, a_n

Question:

What is the input size of this problem?

Using fixed length encoding, we write a_i as a binary string of length $m = \lceil \log_2 \max(|a_i| + 1) \rceil$.

This coding gives an input size *nm*.



Complexity in terms of Input Size

Example: (Composite)

The naive algorithm for determining whether n is composite compares n with the first n-1 numbers to see if any of them divides n



Complexity in terms of Input Size

Example: (Composite)

The naive algorithm for determining whether n is composite compares n with the first n-1 numbers to see if any of them divides n

This makes $\Theta(n)$ comparisons, so it might seem linear and very efficient.



Complexity in terms of Input Size

Example: (Composite)

The naive algorithm for determining whether n is composite compares n with the first n-1 numbers to see if any of them divides n

This makes $\Theta(n)$ comparisons, so it might seem linear and very efficient.

But, note that the input size of this problem is $size(n) = \log_2 n$, so the number of comparisons performed is actually $\Theta(n) = \Theta(2^{size(n)})$, which is exponential.



■ **Definition** Two positive functions f(n) and g(n) are of the same type if

$$c_1g(n^{a_1})^{b_1} \leq f(n) \leq c_2g(n^{a_2})^{b_2}$$

for all large n, where $a_1, b_1, c_1, a_2, b_2, c_2$ are some positive constants.



■ **Definition** Two positive functions f(n) and g(n) are of the same type if

$$c_1g(n^{a_1})^{b_1} \leq f(n) \leq c_2g(n^{a_2})^{b_2}$$

for all large n, where $a_1, b_1, c_1, a_2, b_2, c_2$ are some positive constants.

Example:

All polynomials are of the same type, but *polynomials* and *exponentials* are of different types.



Input Size Example: Integer Multiplication

Example: (Integer Multiplication problem) Compute $a \times b$.



Input Size Example: Integer Multiplication

Example: (Integer Multiplication problem) Compute $a \times b$.

Question:

What is the input size of this problem?



Input Size Example: Integer Multiplication

Example: (Integer Multiplication problem) Compute $a \times b$.

Question:

What is the input size of this problem?

The minimum inpute size is

$$s = \lceil \log_2(a+1) \rceil + \lceil \log_2(b+1) \rceil.$$

A natural choice is to use $t = \log_2 \max(a, b)$ since $\frac{s}{2} \le t \le s$.



Decision Problems

■ **Definition** A *decision problem* is a question that has two possible answers: yes and no.



Decision Problems

■ **Definition** A *decision problem* is a question that has two possible answers: yes and no.

If L is the problem, and x is the input, we will oftern write $x \in L$ to denote a yes answer and $x \notin L$ to denote a no answer.



Optimization Problems

■ **Definition** An *optimization problem* requires an answer that is an optimal configuration.



Optimization Problems

■ **Definition** An *optimization problem* requires an answer that is an optimal configuration.

An optimization problem usually has a corresponding decision problem.



Optimization Problems

■ **Definition** An *optimization problem* requires an answer that is an optimal configuration.

An optimization problem usually has a corresponding decision problem.

Examples:

Knapsack vs. Decision Knapsack (DKnapsack)



Knapsack vs. DKnapsack

• We have a knapsack of capacity W (a positive integer) and n objects with weights w_1, \ldots, w_n and values v_1, \ldots, v_n , where v_i and w_i are positive integers.



Knapsack vs. DKnapsack

• We have a knapsack of capacity W (a positive integer) and n objects with weights w_1, \ldots, w_n and values v_1, \ldots, v_n , where v_i and w_i are positive integers.

Optimization problem: (Knapsack)

Find the largest value $\sum_{i \in T} v_i$ of any subset T that fits in the knapsack, i.e., $\sum_{i \in T} w_i \leq W$.

Decision problem: (DKnapsack)

Given k, is there a subset of the objects that fits in the knapsack and has total value at least k?



Optimization and Decision Problems

Given a subroutine for solving the optimization problem, solving the corresponding decision problem is usually trivial.



Optimization and Decision Problems

Given a subroutine for solving the optimization problem, solving the corresponding decision problem is usually trivial.

First solve the optimization problem, then check the decision problem. If it does, answer yes, otherwise no.



Optimization and Decision Problems

Given a subroutine for solving the optimization problem, solving the corresponding decision problem is usually trivial.

First solve the optimization problem, then check the decision problem. If it does, answer yes, otherwise no.

Thus, if we prove that a given decision problem is hard to solve efficiently, then it is obvious that the optimization problem must be (at least as) hard.



- The Theory of Complexity deals with
 - the classification of certain "decision problems" into several classes:
 - the class of "easy" problems
 - the class of "hard" problems
 - the class of "hardest" problems



- The Theory of Complexity deals with
 - the classification of certain "decision problems" into several classes:
 - ♦ the class of "easy" problems
 - the class of "hard" problems
 - the class of "hardest" problems
 - relations among the three classes



- The Theory of Complexity deals with
 - the classification of certain "decision problems" into several classes:
 - ♦ the class of "easy" problems
 - ♦ the class of "hard" problems
 - the class of "hardest" problems
 - relations among the three classes
 - properties of problems in the three classes



- The Theory of Complexity deals with
 - the classification of certain "decision problems" into several classes:
 - ♦ the class of "easy" problems
 - ♦ the class of "hard" problems
 - the class of "hardest" problems
 - relations among the three classes
 - properties of problems in the three classes

Question:

How to classify decision problems?



- The Theory of Complexity deals with
 - the classification of certain "decision problems" into several classes:
 - ♦ the class of "easy" problems
 - the class of "hard" problems
 - the class of "hardest" problems
 - relations among the three classes
 - properties of problems in the three classes

Question:

How to classify decision problems?

A. Use polynomial-time algorithms.



Definition An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n, and n is the input size of the problem that the algorithm solves.



Definition An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n, and n is the input size of the problem that the algorithm solves.

Whether we use n or n^a (for a fixed a > 0) as the input size, it will not affect the conclusion of whether an algorithm is polynomial-time.



Definition An algorithm is *polynomial-time* if its running time is $O(n^k)$, where k is a constant independent of n, and n is the input size of the problem that the algorithm solves.

Whether we use n or n^a (for a fixed a > 0) as the input size, it will not affect the conclusion of whether an algorithm is polynomial-time.

Example:

The standard multiplication algorithm has time $O(m_1m_2)$, where m_1, m_2 denote the number of digits in the two integers, respectively.



■ **Definition** An algorithm is *nonpolynomial-time* if the running time is not $O(n^k)$ for any fixed $k \ge 0$.



■ **Definition** An algorithm is *nonpolynomial-time* if the running time is not $O(n^k)$ for any fixed $k \ge 0$.

Let's return to the Composite problem.

- \diamond it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \le K \le N 1$.
- \diamond The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.



■ **Definition** An algorithm is *nonpolynomial-time* if the running time is not $O(n^k)$ for any fixed $k \ge 0$.

Let's return to the Composite problem.

- \diamond it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \le K \le N 1$.
- \diamond The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is nonpolynomial!



■ **Definition** An algorithm is *nonpolynomial-time* if the running time is not $O(n^k)$ for any fixed $k \ge 0$.

Let's return to the Composite problem.

- \diamond it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \le K \le N 1$.
- \diamond The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is nonpolynomial!

Question:

Why?



■ **Definition** An algorithm is *nonpolynomial-time* if the running time is not $O(n^k)$ for any fixed $k \ge 0$.

Let's return to the Composite problem.

- \diamond it checks, in time $\Theta((\log N)^2)$, whether K divides N for each K with $2 \le K \le N 1$.
- \diamond The complete algorithm therefore uses $\Theta(N(\log N)^2)$ time.

Conclusion: The algorithm is nonpolynomial!

Question:

Why?

In terms of the input size, the complexity is $\Theta(2^n n^2)$.



Polynomial- vs. Nonpolynomial-Time

Nonpolynomial-time algorithms are impractical.

 2^n for n = 100: it takes billions of years!!!



Polynomial- vs. Nonpolynomial-Time

Nonpolynomial-time algorithms are impractical.

 2^n for n = 100: it takes billions of years!!!

In reality, an $O(n^{20})$ algorithm is not really practical.



Polynomial-Time Solvable Problems

■ **Definition** A problem is *solvable in polynomial time* (or more simply, the problem is *in polynomial time*) if there exists an algorithm which solves the problem in polynomial time (a.k.a. *tractable*).



Polynomial-Time Solvable Problems

■ **Definition** A problem is *solvable in polynomial time* (or more simply, the problem is *in polynomial time*) if there exists an algorithm which solves the problem in polynomial time (a.k.a. *tractable*).

Definition (The Class P) The class P consists of all decision problems that are solvable in polynomial time. That is, there exists an algorithm that will decide in polynomial time if any given input is a yes-input or a no-input.



• Question:

How to prove that a decision problem is in P?



• Question:

How to prove that a decision problem is in P?

A. Find a polynomial-time algorithm.



• Question:

How to prove that a decision problem is in P?

A. Find a polynomial-time algorithm.

Question:

How to prove that a decision problem is not in P?



Question:

How to prove that a decision problem is in P?

A. Find a polynomial-time algorithm.

Question:

How to prove that a decision problem is not in P?

A. You need to prove that there is no polynomial-time algorithm for this problem. (much much harder)



■ **Observation:** A decision problem is usually formulated as:

Is there an object satisfying some conditions?



■ **Observation:** A decision problem is usually formulated as:

Is there an object satisfying some conditions?





A certificate is a specific object corresponding to a yes-input, such that it can be used to show that the input is indeed a yes-input.



A certificate is a specific object corresponding to a yes-input, such that it can be used to show that the input is indeed a yes-input.

Verifying a certificate: Given a presumed yes-input and its corresponding certificate, by making use of the given certificate, we verify that the input is actually a yes-input.



■ **Definition** The class NP consists of all decision problems such that, for each yes-input, there exists a *certificate* which allows one to verify in polynomial time that the input is indeed a yes-input.



■ **Definition** The class NP consists of all decision problems such that, for each yes-input, there exists a *certificate* which allows one to verify in polynomial time that the input is indeed a yes-input.

NP – "nondeterministic polynomial-time"



■ For Composite, a yes-input is just the integer *n* that is composite.



■ For Composite, a yes-input is just the integer *n* that is composite.

Question: (Certificate) What is needed to show n is actually a yes-input?



■ For Composite, a yes-input is just the integer *n* that is composite.

Question: (Certificate) What is needed to show *n* is actually a yes-input?

A. An integer a (1 < a < n) with the property that $a \mid n$.



■ For Composite, a yes-input is just the integer *n* that is composite.

Question: (Certificate) What is needed to show n is actually a yes-input?

- **A.** An integer a (1 < a < n) with the property that $a \mid n$.
 - \diamond Given a certificate a, check whether a divides n.
 - \diamond This can be done in $O((\log n)^2)$.
 - \diamond Composite \in NP



For Composite, a yes-input is just the integer n that is composite.

```
Question: (Certificate) What is needed to show n is actually a yes-input?
```

- **A.** An integer a (1 < a < n) with the property that $a \mid n$.
 - \diamond Given a certificate a, check whether a divides n.
 - \diamond This can be done in $O((\log n)^2)$.
 - \diamond Composite \in NP

```
\mathsf{DKnapsack} \in \mathsf{NP}
```



■ One of the most important problems in CS is whether P = NP or $P \neq NP$?



- One of the most important problems in CS is whether P = NP or $P \neq NP$?
- Observe that $P \subseteq NP$.



- One of the most important problems in CS is whether P = NP or $P \neq NP$?
- Observe that $P \subseteq NP$.
- Intuitively, NP ⊆ P is doubtful.



- One of the most important problems in CS is whether P = NP or $P \neq NP$?
- Observe that P ⊂ NP.
- Intuitively, NP ⊆ P is doubtful.

Just being able to verify a certificate in polynomial time does not necessarily mean we can tell whether an input is a yes-input or a no-input in polynomial time.



- One of the most important problems in CS is whether P = NP or $P \neq NP$?
- Observe that P ⊂ NP.
- Intuitively, NP ⊆ P is doubtful.

Just being able to verify a certificate in polynomial time does not necessarily mean we can tell whether an input is a yes-input or a no-input in polynomial time.

However, we are still no closer to solving it and do not know the answer. The search for a solution, though, has provided us with deep insights into what distinguishes an "easy" problem from a "hard" one.



Next Lecture

number theory ...

