

NANDA KISHORE VASUDEVAN

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EDUCATION

National Institute of Technology, Tiruchirappalli (NIT, Trichy)

August '14 - June '18

B. Tech. (Electrical and Electronics Engineering), 7th semester

CGPA: **9.75/10** (till date)

1st rank in class.

TI Matriculation Higher Secondary school

June '12 - May '14

Class XII (Higher Secondary Course Certificate)

Percentage: **98.67%**

1st rank in school.

RESEARCH INTERESTS

- Multi-Robot Systems
- Artificial Intelligence
- Perception and Navigation

INTERSHIPS AND RESEARCH

Light Writing with Crazyswarm

May '17 - July '17

Viterbi-India Summer Research Program

Mentor: Prof. Nora Ayanian, Assistant Professor, University of Southern California

- Developed an algorithm to autonomously perform light painting of text¹ by a swarm of Crazyflie 2.0 quadcopters.
- Generated trajectories for the **swarm of quadcopters** for any font and text using the Crazyswarm codebase with VICON motion capture system for localization.

Exploring Unmapped Terrain with a Multi-Robot System

December '16 - Ongoing

Mentor: Prof. V Sankaranarayanan, Associate Professor, NIT, Trichy

- Implemented **optimized random algorithm** on a ROS platform for LEGO EV3 differential drive robots to disperse them in the terrain.
- Planned paths for the other robots to reach the goal after one of the robots identifies the goal.

Strategy for Evader in Pursuit Evasion using Reinforcement Learning

May '16 - July '16

Science Academies' Summer Research Fellowship

Mentor: Prof. Aparajita Ojha, Professor, IIITDM Jabalpur

- Implemented **Q-learning coupled with neural network** in keras for the evader in grid-based pursuit evasion games.
- Obtained a success rate of 92.4%² for the evader in simulations.

¹Text written using light captured by long exposure photograph

²Report submitted to Indian Academy of Sciences.

PROJECTS

Soccer Robots

July '16 - Ongoing

- Designed and fabricated four omnidirectional soccer playing robots in compliance with the **RoboCup Small Size League (SSL)** rules.
- Controlled the robots from a central master incorporating feedback from overhead cameras.

Mobile Robotics Development Platform

Nov '15 - Feb '16

- Developed a robotics research and development platform based on ROS with low-cost sensors like Kinect, Rotary Encoders and IMU (Inertial Measurement Unit).
- Endowed with the ability to map the environment (2-D mapping), localize itself in the map and navigate in the environment (**Simultaneous Localization and Mapping**).

Sound Source Localizing All Terrain Hexapod

Oct '15 - Feb '16

- Developed a **six-legged, all-terrain, disaster management robot** inspired from R-HEX developed by Boston Dynamics.
- Developed algorithms to enable the robot to perform walking, stair and ramp climbing, inverted operation (ability to operate even when inverted) and **sound source localization** for locating the victims.

TECHNICAL SKILLS

Programming Languages	C, C++, Python, MATLAB, JavaScript, PHP, Shell scripting, L ^A T _E X
Libraries	ROS, OpenCV, Keras, TensorFlow
Softwares	Gazebo, Git, Simulink, TINA, PSpice
Hardware	Crazyflie 2.0, VICON, LEGO EV3 and NXT, Arduino and TI boards

ACADEMIC ACHIEVEMENTS

- One of the 19 students selected from India for **Viterbi-India Summer Research Program**³ 2017 sponsored by USC Viterbi School of Engineering and Indo-US Science and Technology Forum.
- **DAAD-WISE scholarship**⁴ 2017 for internship in Germany (deferred).
- Recipient of **Science Academies' Summer Research Fellowship**⁵ 2016.
- Awarded **S J Chainulu Medal of Excellence** for securing **1st rank** in the department in the first year.

CO-CURRICULAR AND EXTRACURRICULAR ACTIVITIES

- **Vice-President, RMI (Robotics and Machine Intelligence)**, the official robotics club of NIT, Trichy.
- **Treasurer, Electrical and Electronics Engineering Association** affiliated to the department of Electrical and Electronics Engineering, NIT, Trichy.
- Awarded the **3rd position** in Sangam, the prestigious **innovation challenge**, during Pragyan '16 - the ISO certified Annual International Techno-Managerial Festival of NIT, Trichy for the project "Sound Source Localizing All Terrain Hexapod".
- Conducted 5 different **hands-on workshops** on the basics of robotics, image processing, and machine learning.

³Homepage of Viterbi-India Summer Research Program

⁴Homepage of DAAD-WISE scholarship

⁵Homepage of Science Academies Summer Research Fellowship Programme 2016