# NANDA KISHORE VASUDEVAN

No.6, Ramalingam 4th cross street, Gandhi Nagar, Avadi, Chennai - 600054, India  $(+91)\cdot 98\cdot 416\cdot 31475 \diamond$  nandakishore12111996@gmail.com

#### **EDUCATION**

#### National Institute of Technology, Trichy

May '14 - July '18

Bachelor of Technology (Electrical and Electronics Engineering), 7<sup>th</sup> semester

CGPA: 9.74/10 (till date), 1<sup>st</sup> rank in class.

## TI Matriculation Higher Secondary school

June '12 - May'14

Class XII (Physics, Chemistry, Mathematics, Computer Science, English, and French)

Percentage: 98.67%, 1st rank in school.

#### RESEARCH INTERESTS

• Mobile Robotics

• Perception and Navigation

• Robot Control

• Multi-Robot Systems

• Artificial Intelligence

#### **INTERNSHIPS**

#### LightWriting with Crazyswarm

May '17 - July '17

Viterbi-India Summer Research Program

Mentor: **Dr. Nora Ayanian**, Assistant Professor, University of Southern California Institute: Viterbi School of Engineering, University of Southern California, Los Angeles

- Developed an algorithm to autonomously perform **light painting of text** (text written using light captured by long exposure photograph) by a swarm of Crazyflie 2.0 quadcopters.
- Generated trajectories for the swarm of quadcopters using the **Crazyswarm** codebase with *VICON* motion capture system for localization.

Strategy for Evader in Pursuit Evasion using Reinforcement Learning May '16 - July '16 Science Academies' Summer Research Fellowship

Mentor: **Prof. Aparajita Ojha**, Former Director, IIITDM Jabalpur

Institute: Indian Institute of Information Technology D&M, Jabalpur

- Implemented **Q-learning coupled with neural network** in keras for the evader in grid-based pursuit evasion games.
- Obtained a success rate of  $92.4\%^{1}$  for the evader in simulations.

#### RESEARCH

## Exploring Unmapped Terrain with a Multi-Robot System

July '17 - Ongoing

 $Under graduate\ Researcher$ 

Mentor: Prof. Sankaranarayanan V, Associate Professor, NIT-Trichy

Institute: National Institute of Technology, Trichy

- Implemented **optimized random algorithm** on a ROS platform for LEGO EV3 differential drive robots to disperse them in the terrain.
- Planned paths for the other robots to reach the goal after one of the robots identifies the goal.

<sup>&</sup>lt;sup>1</sup>Link to the report submitted to Indian Academy of Sciences.

Soccer robots

July '16 - Ongoing

- Designed and fabricated four soccer playing robots in compliance with the **RoboCup Small Size**League rules.
- Controlled the omnidirectional robots from a **central master** incorporating feedback from **overhead** cameras.

#### Sound source Localizing All Terrain Hexapod

Nov '15 - Feb '16

- Developed a **six-legged**, **all-terrain**, **disaster management robot** inspired from R-HEX developed by Boston Dynamics.
- Developed algorithms to enable the robot to perform sound source localization, walking, stair climbing, ramp climbing and inverted operation (ability to operate even when inverted).

### Mobile Robotics Development Platform

Sept '15 - Feb '16

- Developed a robotics research and development platform based on ROS, Kinect, Rotary Encoders and IMU (Inertial Measurement Unit).
- Endowed with the ability to map the environment (2-D mapping), localize itself in the map and navigate in the environment (Simultaneous Localization and Mapping).

#### TECHNICAL STRENGTHS

Programming Languages C, C++, Python, MATLAB, JavaScript, PHP, Shell scripting, LATEX

Libraries ROS, OpenCV, Keras

Softwares Gazebo, Git, Simulink, TINA, PSpice

Hardware Crazyflie 2.0, VICON, LEGO EV3 and NXT, Arduino and TI boards

#### ACADEMIC ACHIEVEMENTS

- One of the 20 students selected from India for Viterbi-India Summer Research Program 2017<sup>2</sup> sponsored by USC Viterbi School of Engineering and Indo-US Science and Technology Forum.
- Selected for **DAAD-WISE**<sup>3</sup> scholarship 2017.
- Recipient of Science Academies Summer Research Fellowship<sup>4</sup>, 2016.
- Recipient of S J Chainulu Medal of Excellence during institute day 2016 for securing 1<sup>st</sup> rank in the department in the first year.
- Felicitated for securing overall 3<sup>rd</sup> rank across departments in the first year during institute day 2016.

#### CO-CURRICULAR AND EXTRACURRICULAR ACTIVITIES

- Core member of RMI (Robotics and Machine Intelligence), the official robotics club of NIT-Trichy.
- Treasurer, Electrical and Electronics Engineering Association affiliated to the department of Electrical and Electronics Engineering, NIT-Trichy
- Awarded the **3<sup>rd</sup> position** in Sangam, the prestigious **innovation challenge**, organized during Pragyan 16 the ISO certified Annual International Techno-Management Festival of NIT Trichy for the project "Sound source Localizing All Terrain Hexapod".
- Conducted **5** hands-on workshops on the basics of robotics, image processing, and machine learning.

<sup>&</sup>lt;sup>2</sup>Homepage of Viterbi-India Summer Research Program

<sup>&</sup>lt;sup>3</sup>Homepage of DAAD-WISE scholarship

<sup>&</sup>lt;sup>4</sup>Homepage of Science Academies Summer Research Fellowship Programme 2016