- 1. Temperature Data Logger (2D Array)
- Problem Statement: Design a program to log temperature readings from multiple sensors for 24 hours, sampled every hour.
- Requirements:
 - Use a 2D array of size [N][24] to store temperature data, where N is the number of sensors (defined as a const variable).
 - Use static variables to calculate and store the daily average temperature for each sensor.
 - Use nested for loops to populate and analyze the array.
 - Use if statements to identify sensors exceeding a critical threshold temperature.

```
#include <stdio.h>
#include <stdlib.h>
#include <time.h>
#define N 5
#define CT 80

int main()
{
   const int h = 24;
   float t[N][h], s;
   static float a[N];
   int i, j;
   srand(time(0));
   for ( i = 0; i < N; i++)</pre>
```

```
{
  s=0.0;
  for (j = 0; j < h; j++)
     t[i][j] = (rand() \% 500) / 10.0;
     s += t[i][j];
   }
  a[i] = s / h;
printf("Temperature readings (°C):\n");
for (i = 0; i < N; i++)
{
  printf("Sensor %d: ", i + 1);
  for (j = 0; j < h; j++)
     printf("%.2f", t[i][j]);
  printf("\n");
printf("\nDaily average temperatures (°C):\n");
for (i = 0; i < N; i++)
{
  printf("Sensor %d: %.2f", i + 1, a[i]);
  if (a[i] > CT)
     printf(" Exceeds critical threshold\n");
  printf("\n");
return 0;
```

}

Temperature readings (°C):

Sensor 1: 33.20 32.60 48.60 43.30 36.50 7.90 48.90 12.30 46.70 6.40 32.80 7.10 21.20 37.50 24.70 29.60 38.30 26.10 17.20 4.20 38.40 32.70 11.30 23.50

Sensor 2: 39.30 31.90 13.20 45.70 0.00 24.20 45.50 42.40 20.70 28.10 27.40 11.00 39.00 30.20 23.70 42.60 1.50 33.20 15.80 15.90 12.60 11.40 31.50 18.50

Sensor 3: 18.00 10.70 0.00 5.60 35.80 28.60 40.00 44.30 11.80 45.60 25.60 28.20 37.70 33.40 8.40 20.00 30.10 44.10 38.90 27.50 23.20 21.50 38.60 46.50

Sensor 4: 3.40 22.40 30.70 38.80 13.20 49.70 47.10 7.30 32.50 29.10 32.00 43.80 14.10 24.30 2.90 35.10 21.20 6.90 31.10 39.30 4.40 37.80 0.80 36.60

Sensor 5: 9.00 7.10 0.00 31.20 7.50 29.90 29.60 12.20 0.10 33.20 49.30 5.90 5.50 16.00 33.70 38.80 15.30 15.70 9.70 13.10 43.30 45.10 47.00 36.10

Daily average temperatures (°C):

Sensor 1: 27.54

Sensor 2: 25.22

Sensor 3: 27.67

Sensor 4: 25.19

Sensor 5: 22.26

2. LED Matrix Control (2D Array)

- Problem Statement: Simulate the control of an LED matrix of size 8x8. Each cell in the matrix can be ON (1) or OFF (0).
- Requirements:
 - $_{\circ}$ Use a 2D array to represent the LED matrix.

- Use static variables to count the number of ON LEDs.
- Use nested for loops to toggle the state of specific LEDs based on input commands.
- Use if statements to validate commands (e.g., row and column indices).

```
#include <stdio.h>
#define S 8
int main()
  int 1[S][S];
  static int count = 0;
  int r, c, i, j;
  char ch;
  for (i = 0; i < S; i++)
  {
     for (j = 0; j < S; j++)
        1[i][j] = 0;
   }
  while (1)
     printf("State of LED matrix:\n");
     for (i = 0; i < S; i++)
     {
        for (j = 0; j < S; j++)
          printf("%d", 1[i][j]);
        printf("\n");
```

```
}
  printf("Current ON LEDs: %d\n", count);
  printf("Enter command - t to toggle, q to quit: ");
  scanf(" %c", &ch);
  if (ch == 'q')
     break;
  else if (ch == 't')
  {
     printf("Enter row and column to toggle (0-7): ");
     scanf("%d %d", &r, &c);
     if (r \ge 0 \&\& r \le S \&\& c \ge 0 \&\& c \le S)
     {
       l[r][c] = !l[r][c];
       count += (1[r][c] == 1) ? 1 : -1;
     }
     else
       printf("Invalid row or column\n");
  }
  else
     printf("Invalid command\n");
}
printf("Final state of the matrix:\n");
for (i = 0; i < S; i++)
{
  for (j = 0; j < S; j++)
     printf("%d ", 1[i][j]);
```

```
printf("\n");
                 printf("Final ON LEDs: %d\n", count);
                 return 0;
               }
O/P:
       State of LED matrix:
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       Current ON LEDs: 0
       Enter command - t to toggle, q to quit: t
       Enter row and column to toggle (0-7): 4 6
       State of LED matrix:
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 1\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
       0\ 0\ 0\ 0\ 0\ 0\ 0
```

```
0\ 0\ 0\ 0\ 0\ 0\ 0
```

Current ON LEDs: 1

Enter command - t to toggle, q to quit: t

Enter row and column to toggle (0-7): 8 2

Invalid row or column

State of LED matrix:

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

0000010

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

Current ON LEDs: 1

Enter command - t to toggle, q to quit: t

Enter row and column to toggle (0-7): 2 3

State of LED matrix:

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

00010000

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 1\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

Current ON LEDs: 2

Enter command - t to toggle, q to quit: q

Final state of the matrix:

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

00010000

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 1\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

 $0\ 0\ 0\ 0\ 0\ 0\ 0$

Final ON LEDs: 2

3. Robot Path Mapping (2D Array)

- Problem Statement: Track the movement of a robot on a grid of size M x N.
- Requirements:
 - Use a 2D array to store visited positions (1 for visited, 0 otherwise).
 - Declare grid dimensions using const variables.
 - Use a while loop to update the robot's position based on input directions (e.g., UP, DOWN, LEFT, RIGHT).
 - o Use if statements to ensure the robot stays within bounds.

#include <stdio.h>

#define M 3

#define N 3

```
int main()
  int g[M][N];
  int x = 0, y = 0, i, j;
  char d;
  for (i = 0; i < M; i++)
  {
     for (j = 0; j < N; j++)
       g[i][j] = 0;
  }
  g[x][y] = 1;
  printf("Initial Position: (%d, %d)\n", x, y);
  while (1)
  {
     printf("Grid State:\n");
     for (i = 0; i < M; i++)
       for (j = 0; j < N; j++)
          printf("%d ", g[i][j]);
       printf("\n");
         printf("Enter direction - U=UP, D=DOWN, L=LEFT,
R=RIGHT, Q=QUIT): ");
     scanf(" %c", &d);
     if (d == 'Q' \parallel d == 'q')
       break;
     if (d == 'U' || d == 'u')
     {
```

```
if (x > 0)
     X--;
  else
     printf("Cannot move UP\n");
}
else if (d == 'D' \parallel d == 'd')
{
  if (x \le M - 1)
     x++;
  else
     printf("Cannot move DOWN\n");
}
else if (d == 'L' \parallel d == 'l')
{
  if (y > 0)
     y--;
  else
     printf("Cannot move LEFT\n");
}
else if (d == 'R' \parallel d == 'r')
  if (y < N - 1)
     y++;
  else
     printf("Cannot move RIGHT\n");
}
else
```

```
printf("Invalid direction\n");
                 g[x][y] = 1;
                 printf("Robot moved to position: (%d, %d)\n", x, y);
               }
               printf("Final state of the grid:\n");
               printf("Grid State:\n");
               for (i = 0; i < M; i++)
               {
                 for (j = 0; j < N; j++)
                    printf("%d ", g[i][j]);
                 printf("\n");
               }
               return 0;
             }
O/P:
      Initial Position: (0, 0)
      Grid State:
      100
      000
      000
      Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): u
      Cannot move UP
      Robot moved to position: (0, 0)
      Grid State:
      100
      000
```

```
000
Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): d
Robot moved to position: (1, 0)
Grid State:
100
100
000
Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): r
Robot moved to position: (1, 1)
Grid State:
100
1 1 0
000
Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): d
Robot moved to position: (2, 1)
Grid State:
100
1 1 0
0 1 0
Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): 1
Robot moved to position: (2, 0)
Grid State:
100
1 1 0
1 1 0
Enter direction - U=UP, D=DOWN, L=LEFT, R=RIGHT, Q=QUIT): q
Final state of the grid:
```

```
Grid State:
```

100

1 1 0

1 1 0

- 4. Sensor Data Aggregation (3D Array)
- Problem Statement: Store and analyze data from multiple sensors placed in a 3D grid (e.g., environmental sensors in a greenhouse).
- Requirements:
 - Use a 3D array of size [X][Y][Z] to store data, where dimensions are defined using const variables.
 - o Use nested for loops to populate the array with sensor readings.
 - Use if statements to find and count sensors reporting critical values (e.g., temperature > 50°C).
 - Use static variables to store aggregated results (e.g., average readings per layer).

```
#include <stdio.h>

#define X 3

#define Y 3

#define Z 2

#define CT 70.0

int main()
{
    float s[X][Y][Z], s1=0.0, r;
    static float a[Z];
```

```
int i, j, k, c=0, sc=0;
  printf("Sensor data\n");
  for (i = 0; i < X; i++)
  {
     for (j = 0; j < Y; j++)
     {
       for (k = 0; k < Z; k++)
        {
          s[i][j][k] = 20.0 + i * 10.0 + j * 5.0 + k * 2.0;
          printf("Sensor[%d][%d][%d] = \%.2f\n", i, j, k, s[i][j][k]);
        }
     }
  for (k = 0; k < Z; k++)
   {
     for (i = 0; i < X; i++)
       for (j = 0; j < Y; j++)
          r = s[i][j][k];
          s1 += r;
          sc++;
          if (r > CT)
             c++;
               printf("Critical sensor at [%d][%d][%d] with value:
%.2f\n'', i, j, k, r);
           }
```

```
}
           a[k] = s1 / sc;
           printf("Layer %d - Average Reading: %.2f\n", k, a[k]);
         }
        printf("\nTotal critical sensors: %d\n", c);
        return 0;
      }
Sensor data
Sensor[0][0][0] = 20.00
Sensor[0][0][1] = 22.00
Sensor[0][1][0] = 25.00
Sensor[0][1][1] = 27.00
Sensor[0][2][0] = 30.00
Sensor[0][2][1] = 32.00
Sensor[1][0][0] = 30.00
Sensor[1][0][1] = 32.00
Sensor[1][1][0] = 35.00
Sensor[1][1][1] = 37.00
Sensor[1][2][0] = 40.00
Sensor[1][2][1] = 42.00
Sensor[2][0][0] = 40.00
Sensor[2][0][1] = 42.00
Sensor[2][1][0] = 45.00
Sensor[2][1][1] = 47.00
```

```
Sensor[2][2][0] = 50.00
```

Sensor[2][2][1] = 52.00

Layer 0 - Average Reading: 35.00

Layer 1 - Average Reading: 36.00

Total critical sensors: 0

- 5. Image Processing (2D Array)
- Problem Statement: Perform edge detection on a grayscale image represented as a 2D array.
- Requirements:
 - Use a 2D array of size [H][W] to store pixel intensity values (defined using const variables).
 - Use nested for loops to apply a basic filter (e.g., Sobel filter) on the matrix.
 - Use decision-making statements to identify and highlight edge pixels (threshold-based).
 - o Store the output image in a static 2D array.

```
#include <stdio.h>
#include <math.h>

#define H 5

#define W 5

#define ET 100

void main()
{
```

```
int inp[H][W] = \{ \{10, 10, 10, 10, 10\}, \}
              \{10, 50, 50, 50, 10\},\
              \{10, 50, 100, 50, 10\},\
              \{10, 50, 50, 50, 10\},\
              {10, 10, 10, 10, 10} };
int Gx[3][3] = \{ \{-1, 0, 1\}, \}
              \{-2, 0, 2\},\
             \{-1, 0, 1\} };
int Gy[3][3] = \{ \{-1, -2, -1\}, \}
             \{0, 0, 0\},\
             { 1, 2, 1} };
static int out[H][W];
int i, j, x, y, m;
printf("Input Image:\n");
for (i = 0; i < H; i++)
  for (j = 0; j < W; j++)
     printf("%4d", inp[i][j]);
  printf("\n");
}
for (i = 1; i < H - 1; i++)
{
  for (j = 1; j < W - 1; j++)
     int gX = 0, gY = 0;
     for (x = -1; x \le 1; x++)
     {
```

```
for (y = -1; y \le 1; y++)
             gX += inp[i + x][j + y] * Gx[x + 1][y + 1];
             gY += inp[i + x][j + y] * Gy[x + 1][y + 1];
          }
       m = (int) \operatorname{sqrt}(gX * gX + gY * gY);
       out[i][j] = (m > ET) ? 255 : 0;
  }
  printf("\nEdge Detected Image:\n");
  for (i = 0; i < H; i++)
  {
     for (j = 0; j < W; j++)
       printf("%4d", out[i][j]);
    printf("\n");
}
```

Input Image:

```
10 10 10 10 10
10 50 50 50 10
10 50 100 50 10
10 50 50 50 10
10 10 10 10 10
```

Edge Detected Image:

0

0

0

- 6. Traffic Light Controller (State Management with 2D Array)
- Problem Statement: Manage the states of traffic lights at an intersection with four roads, each having three lights (red, yellow, green).
- Requirements:

 $0 \quad 0$

- Use a 2D array of size [4][3] to store the state of each light (1 for ON, 0 for OFF).
- o Use nested for loops to toggle light states based on time intervals.
- o Use static variables to keep track of the current state cycle.
- Use if statements to validate light transitions (e.g., green should not overlap with red).

```
#include <stdio.h>
#include <unistd.h>
#define R 0
#define Y 1
#define G 2
#define R1 4
#define L 3
```

```
void fun(int t[R1][L], int *c)
  int k;
  k=*c \% R1;
  t[k][G] = 0;
  t[k][Y] = 1;
  sleep(1);
  t[k][Y] = 0;
  t[k][R] = 1;
  sleep(1);
  t[k][R] = 0;
  t[k][G] = 1;
  (*c)++;
}
void main()
  int t[R1][L], i, j, t1;
  static int c = 0;
  for (i = 0; i < R1; i++)
  {
     t[i][R] = 1;
     t[i][Y] = 0;
     t[i][G] = 0;
  while(1)
   {
```

```
printf("\nCycle %d:\n", c);
                 printf("State of Traffic Lights (RED, YELLOW, GREEN):\n");
                 for (i = 0; i < R1; i++)
                 {
                    printf("Road %d: ", i + 1);
                    for (j = 0; j < L; j++)
                      printf("%d ", t[i][j]);
                    printf("\n");
                 fun(t, &c);
               }
            }
O/P:
      Cycle 0:
      State of Traffic Lights (RED, YELLOW, GREEN):
      Road 1: 1 0 0
      Road 2: 1 0 0
      Road 3: 1 0 0
      Road 4: 1 0 0
      Cycle 1:
      State of Traffic Lights (RED, YELLOW, GREEN):
      Road 1: 0 0 1
      Road 2: 1 0 0
      Road 3: 1 0 0
      Road 4: 1 0 0
```

Cycle 2:

State of Traffic Lights (RED, YELLOW, GREEN):

Road 1: 0 0 1

Road 2: 0 0 1

Road 3: 1 0 0

Road 4: 100

Cycle 3:

State of Traffic Lights (RED, YELLOW, GREEN):

Road 1: 0 0 1

Road 2: 0 0 1

Road 3: 0 0 1

Road 4: 1 0 0

Cycle 4:

State of Traffic Lights (RED, YELLOW, GREEN):

Road 1: 0 0 1

Road 2: 0 0 1

Road 3: 0 0 1

Road 4: 0 0 1

7. 3D LED Cube Animation (3D Array)

- Problem Statement: Simulate an animation on an LED cube of size 4x4x4.
- Requirements:
 - Use a 3D array to represent the LED cube's state.

- o Use nested for loops to turn ON/OFF LEDs in a predefined pattern.
- o Use static variables to store animation progress and frame counters.
- Use if-else statements to create transitions between animation frames.

```
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#define S 4
#define D 500
int main()
{
  printf("Animation on a 4x4x4 LED cube\n");
  static int c[S][S][S];
  static int f = 0;
  int x, y, z, i;
  while (f < 10)
     for (z = 0; z < S; z++)
       for (y = 0; y < S; y++)
        {
          for (x = 0; x < S; x++)
          c[z][y][x] = 0;
```

```
if (f \% 3 == 0)
  for (i = 0; i < S; i++)
     c[i][i][i] = 1;
}
else if (f \% 3 == 1)
{
  for (y = 0; y < S; y++)
     for (x = 0; x < S; x++)
        c[S / 2][y][x] = 1;
   }
else
  for (z = 0; z < S; z++)
     for (x = 0; x < S; x++)
        c[z][x][(x + f) \% S] = 1;
   }
for (z = 0; z < S; z++)
  printf("Layer %d:\n", z);
  for (y = 0; y < S; y++)
     for (x = 0; x < S; x++)
```

```
printf("%d ", c[z][y][x]);
              printf("\n");
            printf("\n");
          }
          printf("-----\n");
          usleep(D);
          f++;
        return 0;
     }
Animation on a 4x4x4 LED cube
Layer 0:
1000
0\ 0\ 0\ 0
0000
0000
Layer 1:
0000
0 1 0 0
0\ 0\ 0\ 0
0000
```

Layer 2:

0 0 0 0
0 0 0 0
0 0 1 0
0 0 0 0
Layer 3:
0 0 0 0
0 0 0 0
0 0 0 0
0 0 0 1
Layer 0:
0 0 0 0
0 0 0 0
0 0 0 0
0.000
0 0 0 0
0 0 0 0
0 0 0 0 Layer 1:
Layer 1:
Layer 1: 0 0 0 0
Layer 1: 0 0 0 0 0 0 0 0
Layer 1: 0 0 0 0 0 0 0 0 0 0 0 0
Layer 1: 0 0 0 0 0 0 0 0 0 0 0 0
Layer 1: 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Layer 1: 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 Layer 2:

```
1111
1 1 1 1
Layer 3:
0\ 0\ 0\ 0
0000
0\ 0\ 0\ 0
0\ 0\ 0\ 0
Layer 0:
0010
0\ 0\ 0\ 1
1000
0 1 0 0
Layer 1:
0010
0001
1000
0 1 0 0
Layer 2:
0010
0001
1000
0 1 0 0
```

- 8. Warehouse Inventory Tracking (3D Array)
- Problem Statement: Track inventory levels for multiple products stored in a 3D warehouse (e.g., rows, columns, and levels).
- Requirements:
 - Use a 3D array of size [P][R][C] to represent the inventory of P products in a grid.
 - o Use nested for loops to update inventory levels based on shipments.
 - o Use if statements to detect low-stock levels in any location.
 - o Use a static variable to store total inventory counts for each product.

```
#include <stdio.h>

#define P 3

#define R 4

#define C 5

#define T 10

void update(int inv[P][R][C], int p, int r, int c, int s)
{
    static int t[P] = {0};
```

```
if (p < P \&\& r < R \&\& c < C)
     inv[p][r][c] += s;
     t[p] += s;
      printf("Updated inventory for Product %d at (%d, %d): %d
units (Total: %d units)\n", p, r, c, inv[p][r][c], t[p]);
  }
  else
     printf("Invalid product or location\n");
}
int main()
{
  int inv[P][R][C] = \{0\}, p, r, c;
  update(inv, 0, 2, 1, 40);
  update(inv, 1, 0, 3, 60);
  update(inv, 2, 2, 3, 8);
  printf("\nCurrent Inventory Levels:\n");
  for (p = 0; p < P; p++)
  {
     printf("Product %d:\n", p);
     for (r = 0; r < R; r++)
     {
       for (c = 0; c < C; c++)
          printf("%4d", inv[p][r][c]);
       printf("\n");
     printf("\n");
```

```
}
         printf("\nChecking for low stock levels:\n");
         for (p = 0; p < P; p++)
         {
           for (r = 0; r < R; r++)
            {
              for (c = 0; c < C; c++)
                if (inv[p][r][c] > 0 && inv[p][r][c] < T)
                      printf("Low stock for product %d at (%d, %d): %d
      units\n", p, r, c, inv[p][r][c]);
            }
         }
         return 0;
      }
Updated inventory for Product 0 at (2, 1): 40 units (Total: 40 units)
```

Updated inventory for Product 1 at (0, 3): 60 units (Total: 60 units) Updated inventory for Product 2 at (2, 3): 8 units (Total: 8 units)

Current Inventory Levels:

Product 0:

```
0
      0
              0
   0
         0
  0 0 0 0
0
0 40
      0 \quad 0
             0
  0 \quad 0 \quad 0
            0
```

Product 1:

- 0 0 0 60 0
- 0 0 0 0 0
- 0 0 0 0 0
- 0 0 0 0 0

Product 2:

- 0 0 0 0 0
- 0 0 0 0 0
- 0 0 0 8 0
- 0 0 0 0 0

Checking for low stock levels:

Low stock for product 2 at (2, 3): 8 units

9. Signal Processing on a 3D Matrix

- Problem Statement: Apply a basic signal filter to a 3D matrix representing sampled signals over time.
- Requirements:
 - o Use a 3D array of size [X][Y][Z] to store signal data.
 - Use nested for loops to apply a filter that smoothens the signal values.
 - Use if statements to handle boundary conditions while processing the matrix.
 - o Store the filtered results in a static 3D array.

```
#include <stdio.h>
#define X 4
#define Y 4
#define Z 4
// Function to print a 3D matrix
void printMatrix(int matrix[X][Y][Z]) {
            for (int i = 0; i < X; i++) {
                         printf("Layer %d:\n", i+1);
                         for (int j = 0; j < Y; j++) {
                                      for (int k = 0; k < Z; k++) {
                                                   printf("%d ", matrix[i][j][k]);
                                        }
                                      printf("\n");
                         printf("\n");
             }
 }
int main()
 {
            int s[X][Y][Z] = {
                           \{\{1, 2, 3, 4\}, \{5, 6, 7, 8\}, \{9, 10, 11, 12\}, \{13, 14, 15, 16\}\},\
                            \{\{17, 18, 19, 20\}, \{21, 22, 23, 24\}, \{25, 26, 27, 28\}, \{29, 30, 20\}, \{21, 22, 23, 24\}, \{21, 22, 23, 24\}, \{22, 23, 24\}, \{23, 26, 27, 28\}, \{23, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\}, \{24, 26, 27, 28\},
31, 32}},
                            {{33, 34, 35, 36}, {37, 38, 39, 40}, {41, 42, 43, 44}, {45, 46,
47, 48}},
```

```
\{\{49, 50, 51, 52\}, \{53, 54, 55, 56\}, \{57, 58, 59, 60\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 61\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{61, 62, 62\}, \{
63, 64}}
                };
               int f[X][Y][Z] = \{0\}, i, j, k, sum, c, di, dj, dk, ni, nj, nk;
               for (i = 0; i < X; i++)
                 {
                               for (j = 0; j < Y; j++)
                                              for (k = 0; k < Z; k++)
                                                 {
                                                              sum = 0;
                                                               c = 0;
                                                              for (di = -1; di \le 1; di++)
                                                                             for (dj = -1; dj \le 1; dj++)
                                                                                {
                                                                                             for (dk = -1; dk \le 1; dk++)
                                                                                                            ni = i + di;
                                                                                                            nj = j + dj;
                                                                                                            nk = k + dk;
                                                                                                              if (ni \ge 0 \&\& ni < X \&\& nj \ge 0 \&\& nj < Y \&\&
nk >= 0 \&\& nk < Z
                                                                                                               {
                                                                                                                             sum += s[ni][nj][nk];
                                                                                                                             c++;
                                                                                                               }
                                                                                                }
```

```
}
        f[i][j][k] = sum / c;
     }
   }
printf("Original Signal:\n");
for (i = 0; i < X; i++)
  printf("Layer %d:\n", i+1);
  for (j = 0; j < Y; j++)
     for (k = 0; k < Z; k++)
        printf("%d ", s[i][j][k]);
     printf("\n");
  printf("\n");
printf("Filtered Signal:\n");
for (i = 0; i < X; i++)
{
  printf("Layer \%d:\n", i+1);
  for (j = 0; j < Y; j++)
     for (k = 0; k < Z; k++)
        printf("%d ", f[i][j][k]);
     printf("\n");
```

```
}
                 printf("\n");
               }
              return 0;
            }
O/P:
      Original Signal:
      Layer 1:
      1 2 3 4
      5 6 7 8
      9 10 11 12
      13 14 15 16
      Layer 2:
      17 18 19 20
      21 22 23 24
      25 26 27 28
      29 30 31 32
      Layer 3:
      33 34 35 36
      37 38 39 40
      41 42 43 44
      45 46 47 48
```

Layer 4:

- 49 50 51 52
- 53 54 55 56
- 57 58 59 60
- 61 62 63 64

Filtered Signal:

Layer 1:

- 11 12 13 13
- 13 14 15 15
- 17 18 19 19
- 19 20 21 21

Layer 2:

- 19 20 21 21
- 21 22 23 23
- 25 26 27 27
- 27 28 29 29

Layer 3:

- 35 36 37 37
- 37 38 39 39
- 41 42 43 43
- 43 44 45 45

Layer 4:

- 43 44 45 45
- 45 46 47 47

10. Weather Data Analysis (3D Array)

- Problem Statement: Analyze weather data recorded over multiple locations and days, with hourly samples for each day.
- Requirements:
 - Use a 3D array of size [D][L][H] to store temperature readings (D days, L locations, H hours per day).
 - Use nested for loops to calculate the average daily temperature for each location.
 - Use if statements to find the location and day with the highest temperature.
 - Use static variables to store results for each location.

```
#include <stdio.h>

#define D 3

#define L 4

#define H 24

void temp(int w[D][L][H], int *mT, int *mTDay, float *max)

{
    *max = -1000;
    int d, l, h;
    for (d = 0; d < D; d++)
    {
        for (l = 0; l < L; l++)
```

```
{
       for (h = 0; h < H; h++)
          if (w[d][l][h] > *max)
          {
             *max = w[d][1][h];
             mT = 1;
             *mTDay = d;
}
void average(int w[D][L][H], float avg[L])
{
  int d, l, h;
  for (1 = 0; 1 < L; 1++)
  {
     float t = 0;
     for (d = 0; d < D; d++)
     {
       for (h = 0; h < H; h++)
          t += w[d][1][h];
     avg[1] = t / (D * H);
  }
```

```
}
int main()
{
  int w[D][L][H] = {
     {
        {20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35,
36, 37, 38, 39, 40, 41, 42, 43},
        {25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40,
41, 42, 43, 44, 45, 46, 47, 48},
        {30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45,
46, 47, 48, 49, 50, 51, 52, 53},
        {22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37,
38, 39, 40, 41, 42, 43, 44, 45}
     },
        {21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36,
37, 38, 39, 40, 41, 42, 43, 44},
        {26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41,
42, 43, 44, 45, 46, 47, 48, 49},
        {31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46,
47, 48, 49, 50, 51, 52, 53, 54},
        {23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38,
39, 40, 41, 42, 43, 44, 45, 46}
     },
        {22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37,
38, 39, 40, 41, 42, 43, 44, 45},
        {27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42,
43, 44, 45, 46, 47, 48, 49, 50},
```

```
{32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47,
48, 49, 50, 51, 52, 53, 54, 55},
        {24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39,
40, 41, 42, 43, 44, 45, 46, 47}
     }
  };
  float avg[L] = \{0\};
  int mT = 0, mTDay = 0, d, l, h;
  float max = 0;
  printf("Weather Data:\n");
  for (d = 0; d < D; d++)
  {
     printf("Day %d:\n", d + 1);
     for (1 = 0; 1 < L; 1++)
       printf("Location %d: ", 1 + 1);
       for (h = 0; h < H; h++)
          printf("%d", w[d][1][h]);
       printf("\n");
     }
     printf("\n");
  average(w, avg);
  printf("Average Daily Temperatures for Each Location:\n");
  for (1 = 0; 1 < L; 1++)
     printf("Location %d: %.2f\n", 1 + 1, avg[1]);
  temp(w, &mT, &mTDay, &max);
```

```
printf("\nLocation %d on day %d had the highest temperature:
%.2f\n", mT + 1, mTDay + 1, max);
return 0;
}
```

Weather Data:

Day 1:

Location 1: 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43

Location 2: 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48

Location 3: 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53

Location 4: 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45

Day 2:

Location 1: 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44

Location 2: 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49

Location 3: 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54

Location 4: 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46

Day 3:

Location 1: 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45

Location 2: 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50

Location 3: 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55

Location 4: 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47

Average Daily Temperatures for Each Location:

Location 1: 32.50

Location 2: 37.50

Location 3: 42.50

Location 4: 34.50

Location 3 on day 3 had the highest temperature: 55.00