

Nandu Krishna Raji Mol

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EDUCATION

California State University, Northridge
Master of Science in Computer Engineering

Northridge, CA
Aug. 2024 – May 2026 (Expected)

APJ Abdul Kalam Technological University
Bachelor of Technology in Electronics and Communication Engineering

Thiruvananthapuram, Kerala
Aug. 2017 – Mar. 2021

EXPERIENCE

California State University, Northridge
Graduate Research Associate, CSUN ARCS

Jan. 2025 – Present
Northridge, CA

- Collaborating on a NASA-backed research project to improve drone processor fault tolerance for Mars missions.
- Designing a buffer system to store critical flight data for auxiliary-processor handoff during primary processor failure.
- Addressing power constraints by enabling failover without running dual processors simultaneously.

Rajadhani Institute of Engineering and Technology
Co-Founder, WELKIN AVES

Oct. 2019 – Jan. 2024
Thiruvananthapuram, Kerala

- Developed a drone prototype with a battery-swapping feature.
- Raised \$12,000 for prototyping through government grants; incubated at AICTE IDEA Lab and Cisco ThingQbator.

PROJECTS

Risk-X Real-Time Risk Intelligence Pipeline | *Azure (Event Hubs, Container Apps, SQL), Python, Streamlit, Drift Detection (ADWIN/Page-Hinkley)*

- Built a cloud-native Azure pipeline to replay IEEE-CIS fraud transactions into Event Hubs and score streams via a containerized Python microservice (Azure Container Apps).
- Implemented online anomaly scoring with drift detection (ADWIN, Page-Hinkley) and an auto-adaptation policy to recalibrate alert thresholds and reset the anomaly model upon drift to maintain stable alert quality.
- Persisted scoring and drift events in Azure SQL and developed a Streamlit dashboard for monitoring and auditability; *in progress*: offline evaluation and reliability/performance benchmarking.

Camera-Guided Humanoid Navigation (Ainex) | *ROS Noetic, Python, OpenCV, OpenAI Vision-Language Model*

- Conducting research under **Prof. Michael Cho** on closed-loop camera-guided navigation for an Ainex humanoid using ROS Noetic, integrating perception, decision-making, and actuation for real-time autonomous motion.
- Implemented a vision-language decision module to map live frames into safe actions (forward/left/right/stop/ask-user) and execute motion via ROS services/scripts; *in progress*: expanding trials, strengthening safety logic, and optimizing end-to-end latency.

TECHNICAL SKILLS

Languages: Python, SQL, Embedded C, VHDL, SystemVerilog

ML / Data: Anomaly Detection, Drift Detection (ADWIN, Page-Hinkley), Feature Engineering, Model Evaluation, Cross-Validation, Hyperparameter Tuning

Cloud / DevOps: Microsoft Azure (Event Hubs, Container Apps, Azure SQL), Docker, Git

Robotics / Tools: ROS Noetic, OpenCV, VS Code, Keil uVision, AMD Vivado, Libero SoC Design Suite

Libraries: pandas, NumPy, Matplotlib, Scikit-learn, TensorFlow, XGBoost