

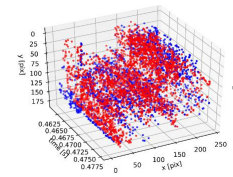
Frame



gray,  
resize

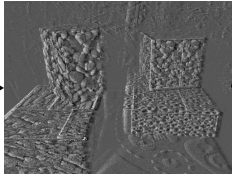


Events  $\{\mathbf{e}_k\}$

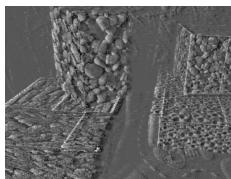
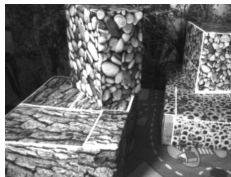


Integration

$$\int_{\Delta t} dt$$

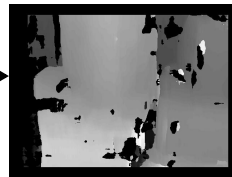


stereo  
rectification



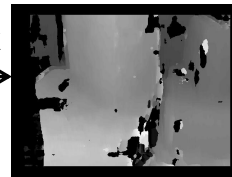
cross-  
correlation

disparity map



coarse-  
to-fine  
framework

finer and smoother



warp &  
compare

