**LATEX** Refsheet Haoli Yin p. 1 of 1

# **Trig Identities**

$$tan(x) = \frac{\sin(x)}{\cos(x)}, \csc(x) = \frac{1}{\sin(x)}, \sec(x) = \frac{1}{\cos(x)}$$

$$sin^{2}(x) + cos^{2}(x) = 1, tan^{2}(x) + 1 = sec^{2}(x)$$

$$cot^{2}(x) + 1 = csc^{2}(x), \sin(2\theta) = 2\sin(\theta)\cos(\theta)$$

$$cos(2\theta) = cos^{2}(\theta) - sin^{2}(\theta)$$

$$tan(2\theta) = \frac{2tan(\theta)}{1 - tan^{2}(\theta)}, \sin^{2}(x) = \frac{1 - cos(2x)}{2}$$

$$cos^{2}(x) = \frac{1 + cos(2x)}{2}$$

### **Derivatives**

$$\begin{array}{l} d(sinx) = cosx \ , \ d(cosx) = -sinx \ , \ d(tanx) = \\ sec^2x \\ d(secx) = secxtanx \ , \ d(cscx) = -cscxcotx \\ d(cotx) = -csc^2x \\ d(sin^{-1}x) = \frac{1}{\sqrt{1-x^2}}, \ d(cos^{-1}x) = \frac{-1}{\sqrt{1-x^2}} \\ d(tan^{-1}x) = \frac{1}{1+x^2}, \ d(sec^{-1}x) = \frac{1}{|x|\sqrt{x^2-1}} \\ d(csc^{-1}x) = \frac{-1}{|x|\sqrt{x^2-1}}, \ d(cot^{-1}x) = \frac{-1}{1+x^2} \end{array}$$

## **Ch1: Basic Definitions**

**Partial**: multiple independent variables. Order: highest derivative. Linear dif**feq**: additive combination of first powers:  $a_n(x)\frac{d^ny}{dx^n} + a_{n-1}\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y =$ 

Example of linear:  $t^3 \frac{dx}{dt} - x = t^3$ . Nonli**near**:  $\frac{d^2y}{dx^2} + y^3 = 0$  bc of  $y^3$  term. Another: **li**: 1.  $\frac{dy}{dx} + P(x)y = Q(x)y^n$ ,  $y = y^{1-n}$  $\frac{d^2y}{dx^2} - y\frac{dy}{dx} = \cos x$  bc of ydy term. **Explicit Soln**: function  $\phi(x)$  when sub for y

in eqn satisfies for  $\forall x$  in interval. **Implicit Soln**: Verify by differentiate implicit soln wrt ind. var on both sides to check if same as original.

**Note**: Diff of y wrt x becomes  $\frac{dy}{dx}$ Existence & Uniqueness: 1. Find the form of the differential equation  $\frac{dy}{dx} = f(x,y)$ . 2. Identify the function f(x,y) and the partial derivative  $\frac{\partial y}{\partial x}$  such that both are continuous in the rectangle (x, f(x)). **Autonomous eqns**: y' = f(y), rhs is fxn of dependent var only. **Method of Isoclines:** y' = f(x, y) = c, solve for y to make isoclines (dotted lines), slope same along isocline. **Euler's Method**:  $y_{n+1} = y_n + hf(x_n, y_n)$ , where h is step size  $(\frac{dist}{numstep})$ .

# Ch2: Solving Linear 1st Order

**Separable:** y' = f(x)g(y), sep. into  $\frac{dy}{g(y)} =$ f(x)dx, integrate both sides.

**Linear**  $a_1(x)\frac{dy}{dx} + a_0(x)y = b(x)$ . Special cases:  $a_0(x) = 0$ (no y term) then  $y(x) = \int \frac{b(x)}{a_1(x)} dx + C$  $a_0(x) = a'_1(x)$  product rule y(x) = $\frac{1}{a_1(x)}(\int b(x)dx + C)$ , Standard Form:  $\frac{dy}{dx} + P(x)y = Q(x)$ , Integrating Factor:  $\mu(x) =$  $exp(\int P(x)dx)$ , Solve:  $\mu(x)\psi(x) = \int \mu(x)Q(x)dx +$ C, Exact: Form M(x,y)dx + N(x,y)dy = 0check  $M_v = N_x$  for exactness, Solving: 1. Text exactness, 2.  $F(x,y) = \int M(x,y)dx + g(y)$ , 3.  $\frac{\partial F}{\partial y} = N(x, y)$  to get g'(y), 4.  $g(y) = \int g'(y) dy$ , 5. sub g(y) into F(x,y) = C, Exactness pends on x or  $\frac{1}{M}(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y})$  only depends on y, then  $\mu(\cdot) = exp((\cdot)d(\cdot))$ , plug in **Ordinary**: single independent variable.  $\mu(x,y)M(x,y)dx + \mu(x,y)N(x,y)dy = 0$ , solve with exact. Homogenous: 1. Express dy/dx in terms of y/x, 2. Sub v = y/x = f(x, v), 3. x(dv/dx) + v = f(x, v) solve with separable, 4. Resub v = y/x. Solving dy/dx = G(ax + by): 1. sub z = ax + by, 2. diff dz/dx = a + b(dy/dx)then sub dy/dx = (dz/dx - a)/b, 3. solve separable 4. resub ax + by = z. Bernoul-2. 1/(1-n)dv/dx + P(x)v = Q(x), 3. solve linear w/  $\mu(x)$ . Linear Coeff: Special cases: 1.  $a_1b_2 = a_2b_1$  then z = ax + by, 2.  $b_1 = a_2$  then exact, 3.  $c_1 = c_2 = 0$  then homogenous. Coeff Solve: 1. solve system  $a_1h + b_1k = -c$  and  $a_2h + b_2k = -c$  for h, k, 2. sub in x = u + h and y = v + k for form

M(u,v)du + N(u,v)dv = 0, 3. Rearr for dv/du, sub z = v/u, 4. dv/du = u(dz/du) + z, 5. solve separable (partial frac) 6. resub z, u, v.

# Ch3: 1st Order Applications

**Mixing Problems**:  $dx/dt = r_{in} - r_{out}$ , where r(t) can also be salt concentration, if so, then  $dx/dt = r_{in}c_{in} - r_{out}x(t)/V$ , where x(t) is [salt] Malthusian/Exponential Model:  $dP/dt = kp, p(0) = p_0, p(t) = p_0 * exp(kt)$  **Logistic Model**:  $dP/dt = k_1 p - k_2 \frac{p(p-1)}{2}$ , p(t) = $\frac{p_0p_1}{p_0+(p_1-p_0)exp(-Ap_1t)}$  Newton's Law of Coo**ling**:  $T(t) = exp(-kt) \int exp(kt)(kM+H+U)dt +$ C\*exp(-kt), where M is initial temp, H is heat  $(\geq 0)$ , U is heating(+)/cooling rate(-). Oscillating M Problem: Given time constant (1/k)and M varies as sine wave w/ min/max time/temp given, find min/max time/temp of building.