

# NanoPack

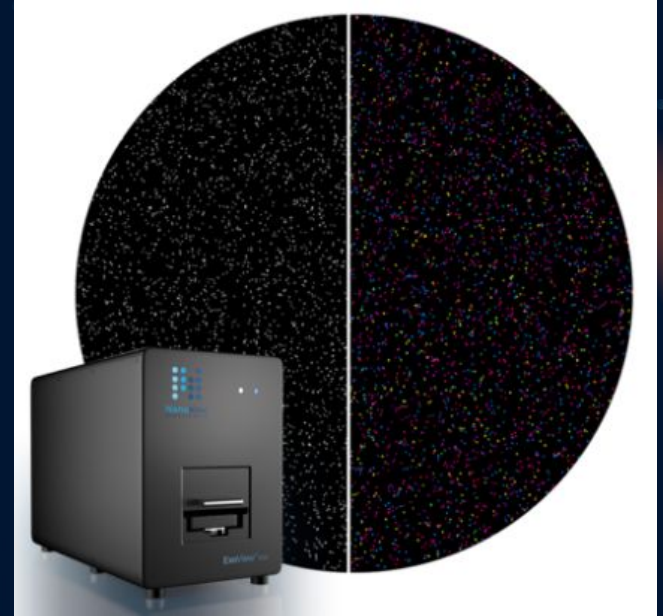
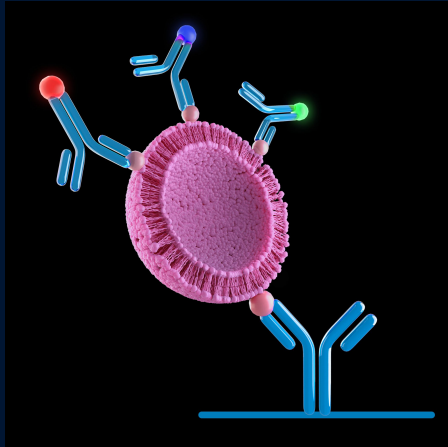
For NanoView Biosciences

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# Background

## Nanoview Biosciences:

Makers of a machine and technology which is capable of measuring markers on single exosomes and other extracellular vesicles.



## Problem Statement

- NanoView currently uses a person with tweezers when they transfer silicon chips from their lab container, “the traveler” into user cases, “clamshells.”
- Our job is to automate the process of transferring the chips from the traveler to clamshell
- This will speed up the process, prevent human error, and reduce risk of contamination.

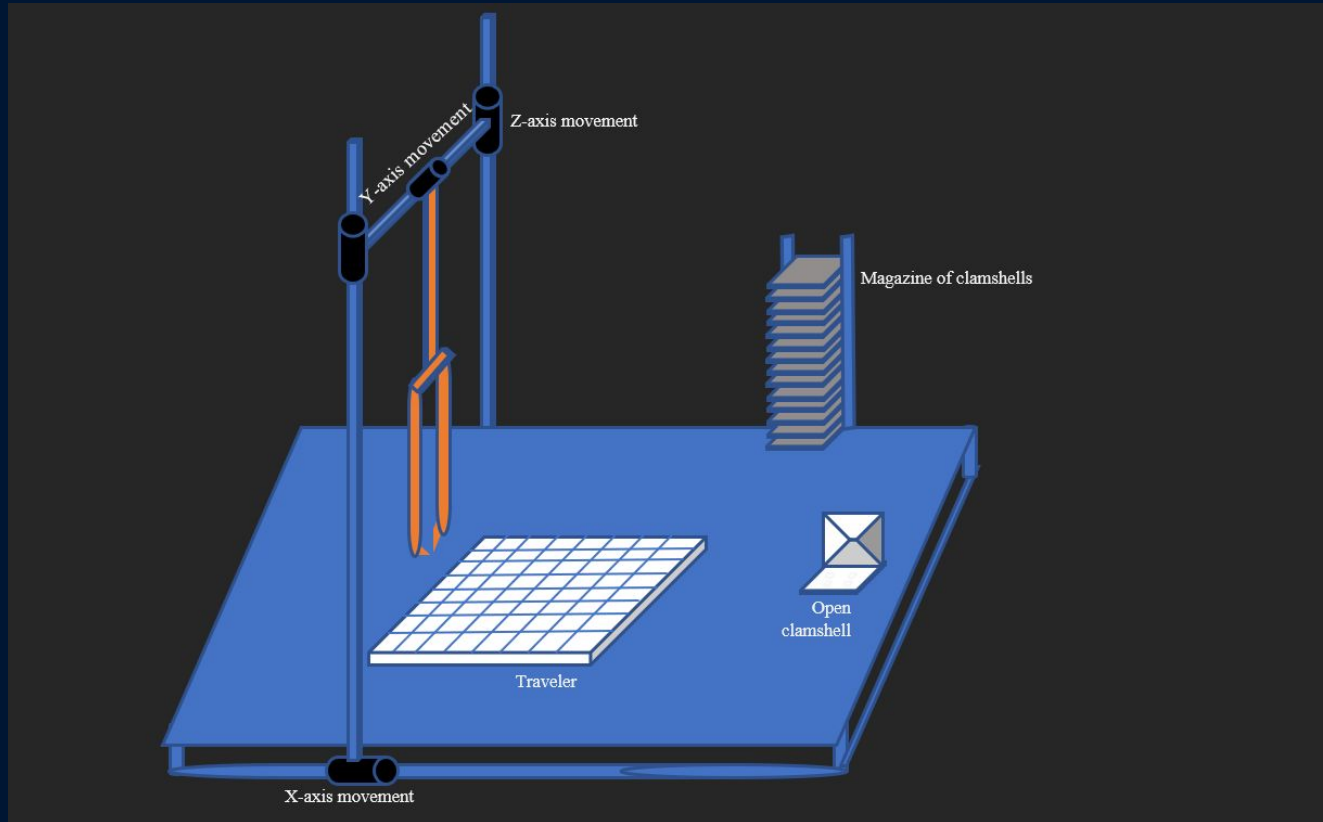
## Proposed Solution

- A packing machine that can fully automate the process of chip transfer.
- A robot will pick up and deposit the chips.
  - Robotic arm or CNC-style robot
  - Soft robotic claw to pick up chips
- Machine vision will be used to detect the location and orientation of the clamshell.

# Visualization - Robotic Arm



# Visualization - CNC machine (numerical control)



# Deliverables

A packing machine with:

- A robot with the ability to transfer chips from traveler to clamshell
- A computer vision system that can:
  - Read chip codes to decipher plate maps
  - Detect clamshell placement to guide arm
- A software application to control the machine and document the chips

# Functions + Objectives

1. Read chip identifiers
2. Detect exact clamshell locations
3. Open clamshell
4. Pick up chips from traveler w/o damage
5. Decide where to place chip based on input data file
6. Drop chip into correct spot in clamshell
7. Close clamshell



# Constraints

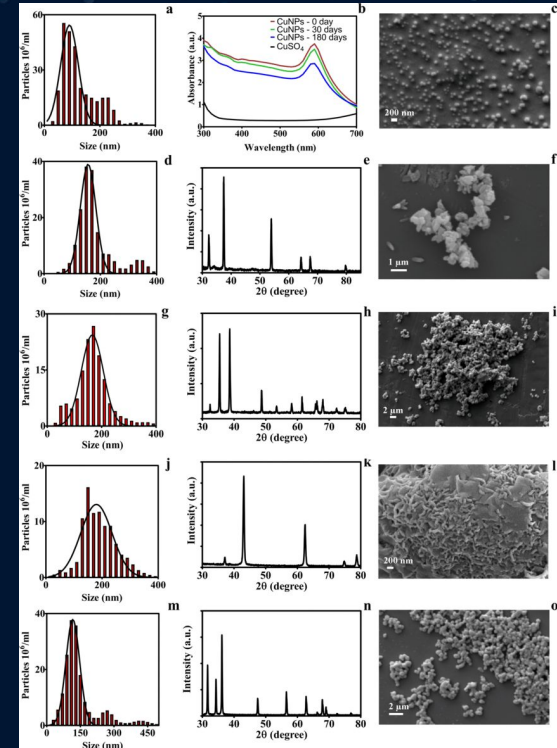
1. Packer must cover a 200x100mm area
2. Precision capture and release of a chip
3. High throughput - 1000 clamshells/day
4. Low or zero error rate



# Competing Technologies (NanoView)

Nanoparticle Tracking Analysis (NTA)  
Microscope:

- utilizes the properties of both light scattering and Brownian motion in order to obtain the nanoparticle size distribution of samples in liquid suspension
- manufactured by various companies such as Malvern Panalytical or ZetaView
- NanoView is able to measure details with greater accuracy at smaller sizes



# Competing Manufacturing Processes

Because of the dimensions of the chip and the fragile nature of the coating only custom manufacturing solutions would be suitable.

- Kuka - Custom Robotics Solutions
  - Mobile robot, battery operated
  - Custom patented “grippers”
  - High Cost
- Isel Wafer Handling robot
  - “Scoops” chips
  - Not very scalable
  - High Cost



Questions?

