

BACKGROUND:

→ Who is NanoView?

They make a machine capable of measuring markers on exosomes and extracellular vesicles using silicon chips.

→ What do we provide them?

NanoView manually moves its chips from a container called a "traveler" to a container called a "clamshell".

We automate this process by providing:

- High throughput
- Error Checking

→ How do we do it?

Object detection finds the traveler and clamshells' general locations.

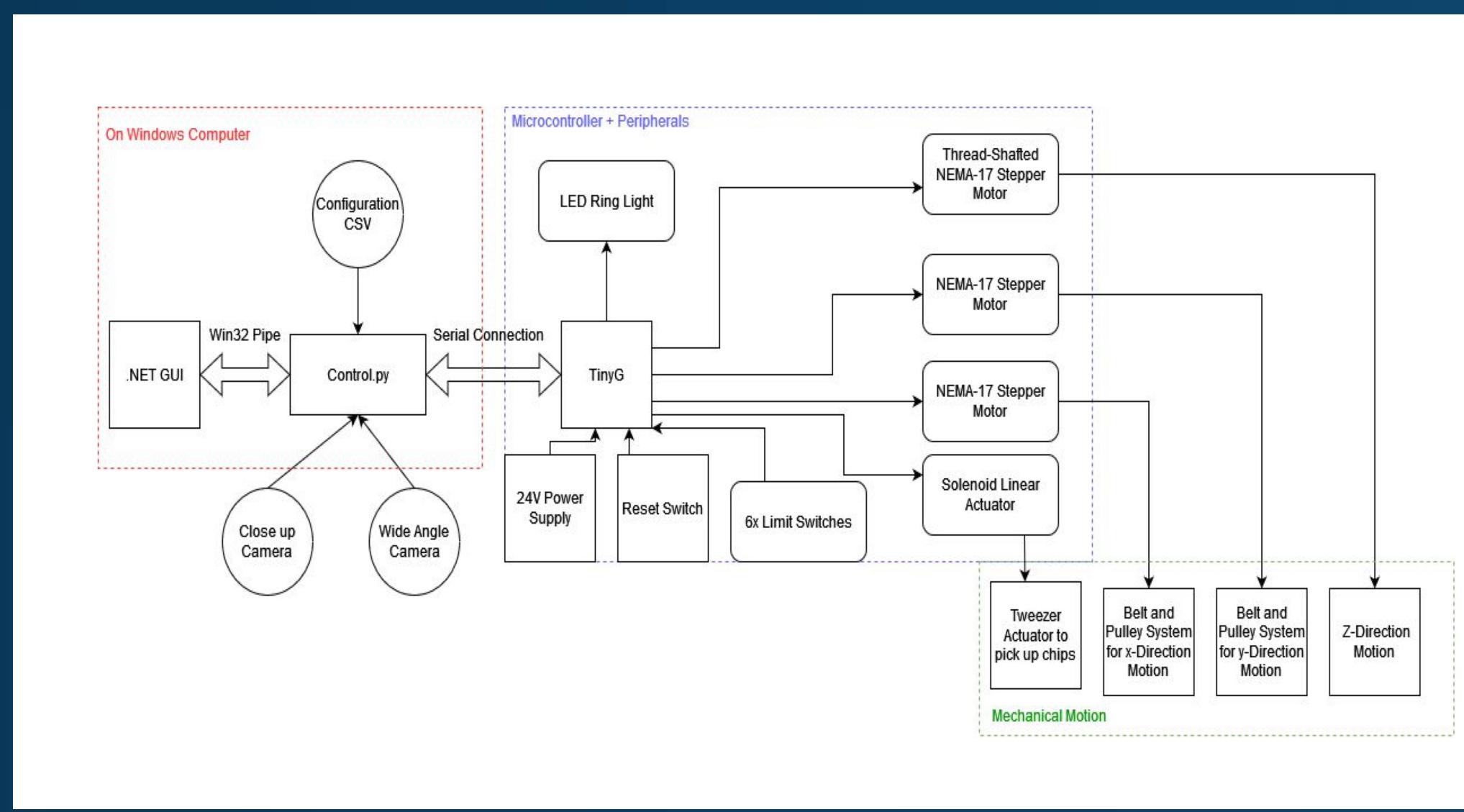
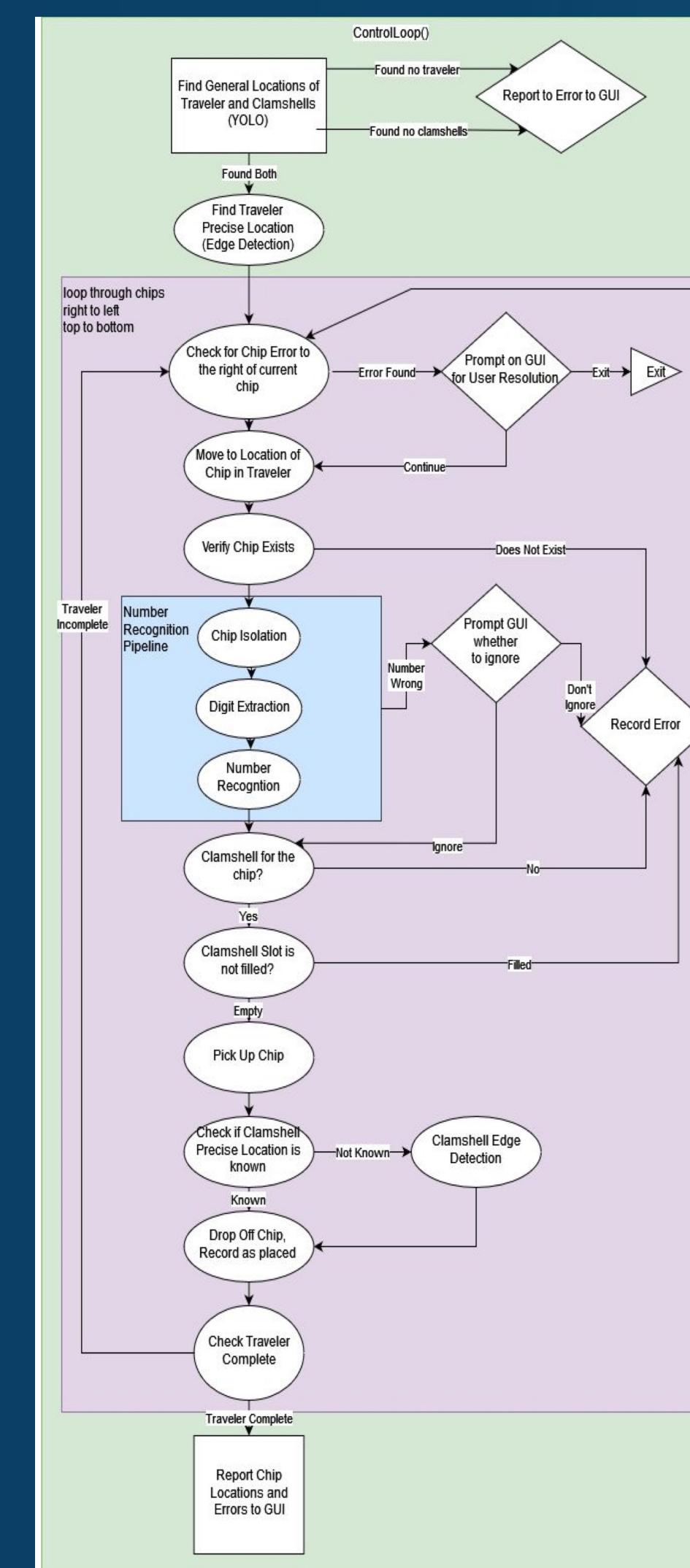
Number recognition is used to check for errors in the traveler packing process.

Chips are picked up using either a vacuum tweezers or a mechanical tweezers.

Controlled by a user from a .NET GUI

THE MACHINE:

- CNC-style machine using parts from the Liteplacer Pick&Place
- Control Loop in python orchestrates everything.
- TinyG control board used to receive G-Code commands and translate those to movement in mm based on configuration.

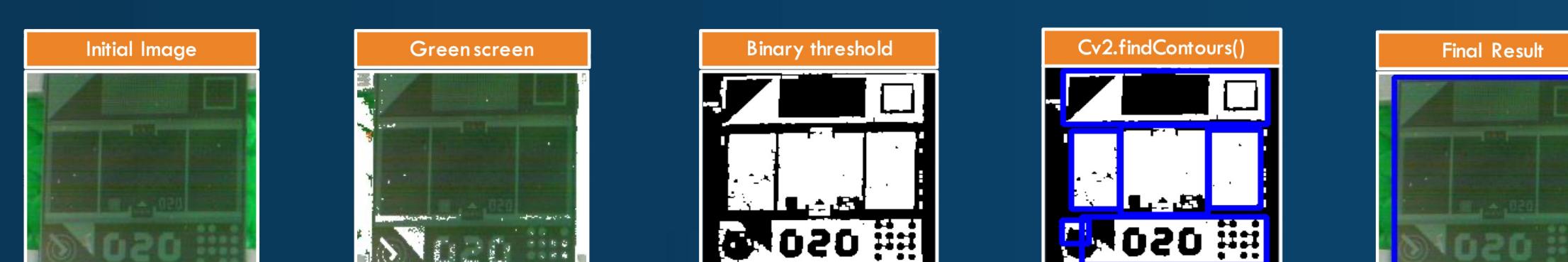


NUMBER RECOGNITION:

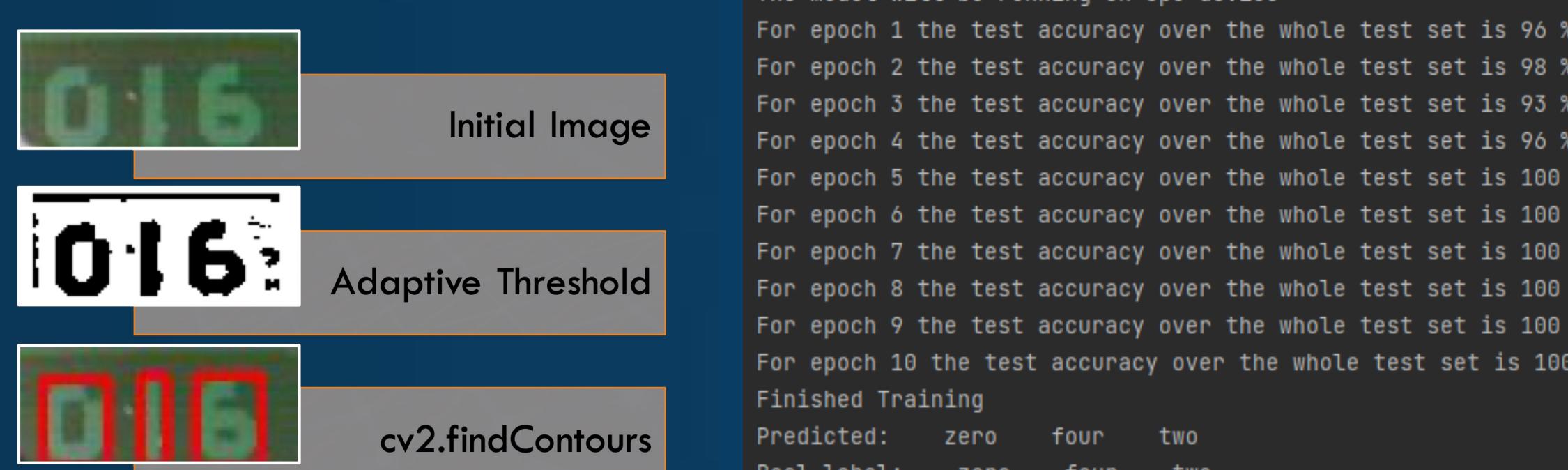
→ Number recognition is used to verify that chip locations match the position file



Chip Contouring:



Digit Extraction:



OBJECT DETECTION:

What it does:

The object detection locates the clamshell and traveler it then allows the machine to move to where they are located.

How it works:

→ Data Augmentation:

Added to the dataset by taking existing images and labels and altering images to increase datasets.

→ Retraining Weights:

We re-trained the YoloV5 model on our data using the existing model weights.

→ Scaling images:

Translated image position to machine bed position based on camera location

→ YoloV5:

An open-source object detection model based on a CNN.



GRAPHICAL USER INTERFACE:

