# Foundations of Reinforcement Learning with Applications in Finance

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# A bit about me and about my book

- Co-Founder CXScore Al to improve Customer Experience on Apps
- Adjunct Professor, Applied Mathematics (ICME), Stanford University
- Past: MD at Morgan Stanley, Trading Strategist at Goldman Sachs
- Wall Street career mostly in Rates and Mortgage Derivatives
- Educational background: Algorithms Theory and Abstract Algebra
- I direct Stanford's Mathematical & Computational Finance program
- Research & Teaching in: RL and it's applications in Finance & Retail
- Book: Foundations of RL with Applications in Finance
- Lived in Mumbai, LA, NYC, London, now settled in Palo Alto

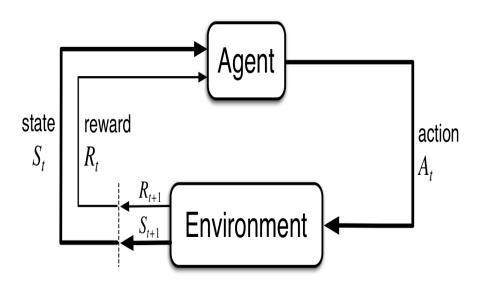
# Key features of my book

- Book blends Theory, Modeling, Algorithms, Python, Trading problems
- Emphasis on broader principles in Applied Math & Software Design
- Focus on foundations and core understanding of concepts
- Tutorial-styled coverage, sometimes compromising rigor for intuition
- Significant emphasis on learning by coding the details
- 5 important financial applications covered in the book

# Al for Dynamic Decisioning under Uncertainty

- Let's browse some terms used to characterize this branch of AI
- Stochastic: Uncertainty in key quantities, evolving over time
- Optimization: A well-defined metric to be maximized ("The Goal")
- *Dynamic*: Decisions need to be a function of the changing situations
- Control: Overpower uncertainty by persistent steering towards goal
- Jargon overload due to confluence of Control Theory, OR and AI
- For language clarity, let's just refer to this area as Stochastic Control
- The core framework is called Markov Decision Processes (MDP)
- Reinforcement Learning is a class of algorithms to solve MDPs

#### The MDP Framework

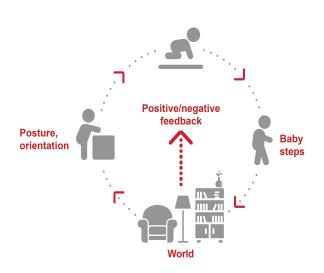


# Components of the MDP Framework

- The Agent and the Environment interact in a time-sequenced loop
- Agent responds to [State, Reward] by taking an Action
- Environment responds by producing next step's (random) State
- Environment also produces a (random) scalar denoted as Reward
- Each State is assumed to have the Markov Property
- Goal of Agent is to maximize Expected Sum of all future Rewards
- ullet By controlling the (*Policy* : *State* o *Action*) function
- This is a dynamic (time-sequenced control) system under uncertainty

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# How a baby learns to walk



# Many real-world problems fit this MDP framework

- Self-driving vehicle (speed/steering to optimize safety/time)
- Game of Chess (Boolean Reward at end of game)
- Complex Logistical Operations (eg: movements in a Warehouse)
- Make a humanoid robot walk/run on difficult terrains
- Manage an investment portfolio
- Control a power station
- Optimal decisions during a football game
- Strategy to win an election (high-complexity MDP)

# Self-Driving Vehicle



# Why are these problems hard?

- State space can be large or complex (involving many variables)
- Sometimes, Action space is also large or complex
- No direct feedback on "correct" Actions (only feedback is Reward)
- Time-sequenced complexity (Actions influence future States/Actions)
- Actions can have delayed consequences (late Rewards)
- Agent often doesn't know the Model of the Environment
- "Model" refers to probabilities of state-transitions and rewards
- So, Agent has to learn the Model AND solve for the Optimal Policy
- Agent Actions need to tradeoff between "explore" and "exploit"

# Dynamic Programming

- When Probabilities Model is known ⇒ *Dynamic Programming* (DP)
- DP Algorithms take advantage of knowledge of probabilities
- So, DP Algorithms do not require interaction with the environment
- In the Language of AI, DP is a type of Planning Algorithm
- Why is DP not effective in practice?
  - Curse of Dimensionality
  - Curse of Modeling
- Curse of Dimensionality can be partially cured with Approximate DP
- To resolve both curses effectively, we need RL

# Reinforcement Learning

- Typically in real-world, we don't have access to a Probabilities Model
- All we have is access to an environment serving individual transitions
- Even if MDP model is available, model updates can be challenging
- Often real-world models end up being too large or too complex
- Sometimes estimating a sampling model is much more feasible
- RL interacts with either actual or simulated environment
- Either way, we receive individual transitions to next state and reward
- RL is a "trial-and-error" approach linking *Actions* to *Rewards*
- Try different actions & learn what works, what doesn't
- This is hard because actions have overlapping reward sequences
- Also, sometimes Actions result in delayed Rewards

# RL: Learning Value Function Approximation from Samples

- RL incrementally learns and improves from transitions data
- Deep Neural Networks used to estimate expected reward sums
- Big Picture: Sampling and Deep Learning estimates come together
- RL algorithms are clever about balancing "explore" versus "exploit"
- Promise of modern A.I. is based on success of RL algorithms
- Potential for automated decision-making in many industries
- In 10-20 years: Bots that act or behave more optimal than humans
- RL already solves various low-complexity real-world problems
- Possibilities in Finance are endless (book covers 5 key problems)

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# P1: Dynamic Asset-Allocation and Consumption

- The broad topic is Investment Management
- Applies to Corporations as well as Individuals
- The two considerations are:
  - How to allocate money across assets in one's investment portfolio
  - How much to consume for one's needs/operations/pleasures
- We consider the dynamic version of these dual considerations
- Asset-Allocation and Consumption decisions at each time step
- Asset-Allocation decisions typically deal with Risk-Reward tradeoffs
- Consumption decisions are about spending now or later
- Objective: Horizon-Aggregated Expected Utility of Consumption

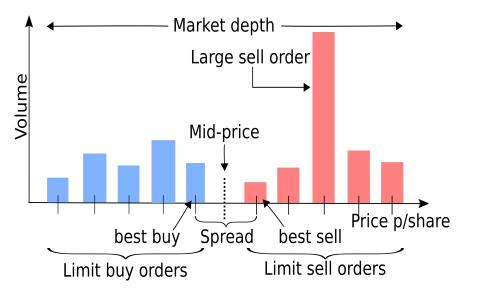
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# P1: Consider the simple example of Personal Finance

- Broadly speaking, Personal Finance involves the following aspects:
  - Receiving Money: Salary, Bonus, Rental income, Asset Liquidation etc.
  - Consuming Money: Food, Clothes, Rent/Mortgage, Car, Vacations etc.
    - Investing Money: Savings account, Stocks, Real-estate, Gold etc.
- Goal: Maximize lifetime-aggregated Expected Utility of Consumption
- This can be modeled as a Markov Decision Process
- State: Age, Asset Holdings, Asset Valuation, Career situation etc.
- Action: Changes in Asset Holdings, Optional Consumption
- Reward: Utility of Consumption of Money
- Model: Career uncertainties, Asset market uncertainties

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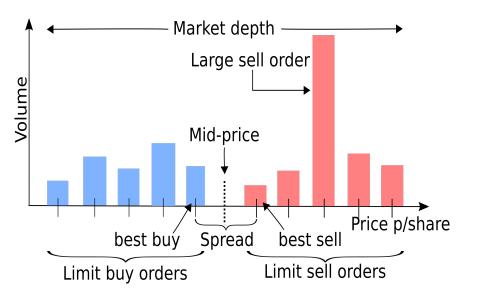
# P2: Trading Order Book (abbrev. OB)



# P2: Basics of Order Book (OB)

- Buyers/Sellers express their intent to trade by submitting bids/asks
- These are Limit Orders (LO) with a price P and size N
- Buy LO (P, N) states willingness to buy N shares at a price  $\leq P$
- Sell LO (P, N) states willingness to sell N shares at a price  $\geq P$
- Order Book aggregates order sizes for each unique price
- So we can represent with two sorted lists of (Price, Size) pairs
- We call best bid as simply Bid, best ask as Ask, their average as Mid
- We call Ask Bid as Spread, Worst Ask Worst Bid as Market Depth
- A Market Order (MO) states intent to buy/sell N shares at the best possible price(s) available on the OB at the time of MO submission

# P2: Trading Order Book



# P2: Price Impact and Order Book Dynamics

- A new Sell LO (P, N) potentially removes best bid prices on the OB
- After this removal, it adds to the asks side of the OB
- A new Buy LO operates analogously (on the other side of the OB)
- A Sell Market Order N will remove the best bid prices on the OB
- A Buy Market Order N will remove the best ask prices on the OB
- A large-sized MO can result in a big Big-Ask Spread we call this the Temporary Price Impact
- Spread typically replenished by new LOs, potentially from either side
- Subsequent Replenishment moves Bid/Ask/Mid we call this the Permanent Price Impact
- Price Impact Models with OB Dynamics can be quite complex

# P2: Optimal Trade Order Execution Problem

- The task is to sell a large number *N* of shares
- ullet We are allowed to trade in  ${\mathcal T}$  discrete time steps
- We are only allowed to submit Market Orders
- Need to consider both Temporary and Permanent Price Impact
- For simplicity, consider a model of just the Bid Price Dynamics
- Goal is to maximize Expected Total Utility of Sales Proceeds
- ullet By breaking N into appropriate chunks (timed appropriately)
- If we sell too fast, we are likely to get poor prices
- If we sell too slow, we risk running out of time
- Selling slowly also leads to more uncertain proceeds (lower Utility)
- This is a Dynamic Optimization problem
- We can model this problem as a Markov Decision Process (MDP)