A Guided Tour of Chapter 6: Dynamic Asset-Allocation and Consumption

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- Objective: Horizon-Aggregated Expected Utility of Consumption

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- Model: Career uncertainties, Asset market uncertainties

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- Consumption Utility assumed to have Constant Relative Risk-Aversion

Problem Notation

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- $\gamma =$ (Constant) Relative Risk-Aversion $\frac{-x \cdot U''(x)}{U'(x)}$



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- Note: $c_t \ge 0$, but π_t is unconstrained

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Use Ito's Lemma on dV^* , remove the dz_t term since it's a martingale, and divide throughout by dt to produce the HJB Equation in PDE form:

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Let us write the above equation more succinctly as:

$$\max_{\pi_t, c_t} \Phi(t, W_t; \pi_t, c_t) = \rho \cdot V^*(t, W_t)$$

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$$egin{aligned} \max_{\pi_t, c_t} \mathbb{E}_t [d(e^{-
ho t} \cdot V^*(t, W_t)) + rac{e^{-
ho t} \cdot c_t^{1-\gamma}}{1-\gamma} \cdot dt] &= 0 \end{aligned} \ \Rightarrow \max_{\pi_t, c_t} \mathbb{E}_t [dV^*(t, W_t) + rac{c_t^{1-\gamma}}{1-\gamma} \cdot dt] &=
ho \cdot V^*(t, W_t) \cdot dt \end{aligned}$$

Use Ito's Lemma on dV^* , remove the dz_t term since it's a martingale, and divide throughout by dt to produce the HJB Equation in PDE form:

$$\max_{\pi_t, c_t} \left[\frac{\partial V^*}{\partial t} + \frac{\partial V^*}{\partial W} ((\pi_t(\mu - r) + r)W_t - c_t) + \frac{\partial^2 V^*}{\partial W^2} \cdot \frac{\pi_t^2 \sigma^2 W_t^2}{2} + \frac{c_t^{1-\gamma}}{1-\gamma} \right]$$

$$= \rho \cdot V^*(t, W_t)$$

Let us write the above equation more succinctly as:

$$\max_{\pi_t, c_t} \Phi(t, W_t; \pi_t, c_t) = \rho \cdot V^*(t, W_t)$$

Note: we are working with the constraints $W_t > 0$, $c_t \ge 0$ for $0 \le t \le T_{0.9}$

Optimal Allocation and Consumption

Find optimal π_t^* , c_t^* by taking partial derivatives of $\Phi(t, W_t; \pi_t, c_t)$ with respect to π_t and c_t , and equate to 0 (first-order conditions for Φ).

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$$(\mu - r) \cdot \frac{\partial V^*}{\partial W_t} + \frac{\partial^2 V^*}{\partial W_t^2} \cdot \pi_t \cdot \sigma^2 \cdot W_t = 0$$

$$\Rightarrow \pi_t^* = \frac{-\frac{\partial V^*}{\partial W_t} \cdot (\mu - r)}{\frac{\partial^2 V^*}{\partial W_t^2} \cdot \sigma^2 \cdot W_t}$$

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• Partial derivative of Φ with respect to c_t :

$$-\frac{\partial V^*}{\partial W_t} + (c_t^*)^{-\gamma} = 0$$
$$\Rightarrow c_t^* = (\frac{\partial V^*}{\partial W_t})^{\frac{-1}{\gamma}}$$

Now substitute π_t^* and c_t^* in $\Phi(t, W_t; \pi_t, c_t)$ and equate to $\rho V^*(t, W_t)$, which gets us the Optimal Value Function PDE:

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The second-order conditions for Φ are satisfied **under the assumptions** $c_t^*>0,\,W_t>0,\,\frac{\partial^2 V^*}{\partial W_t^2}<0$ for all $0\leq t< T$ (we will later show that these are all satisfied in the solution we derive), and for concave $U(\cdot)$, i.e., $\gamma>0$

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The solution to this ODE is:

$$f(t) = \begin{cases} \frac{1 + (\nu \epsilon - 1) \cdot e^{-\nu(T - t)}}{\nu} & \text{for } \nu \neq 0 \\ T - t + \epsilon & \text{for } \nu = 0 \end{cases}$$

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Putting it all together (substituting the solution for f(t)), we get:

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• f(t) > 0 for all $0 \le t < T$ (for all ν) ensures $W_t, c_t^* > 0, \frac{\partial^2 V^*}{\partial W_t^2} < 0$. This ensures the constraints $W_t > 0$ and $c_t \ge 0$ are satisfied and the second-order conditions for Φ are also satisfied.

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- The HJB Formulation was key and this solution approach provides a template for similar continuous-time stochastic control problems.

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- With Optimal Allocation & Consumption, the Wealth process is:

$$\frac{dW_t^*}{W_t^*} = \left(r + \frac{(\mu - r)^2}{\sigma^2 \gamma} - \frac{1}{f(t)}\right) \cdot dt + \frac{\mu - r}{\sigma \gamma} \cdot dz_t$$

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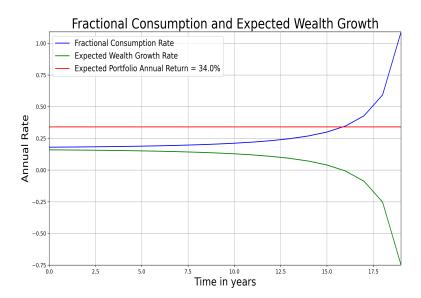
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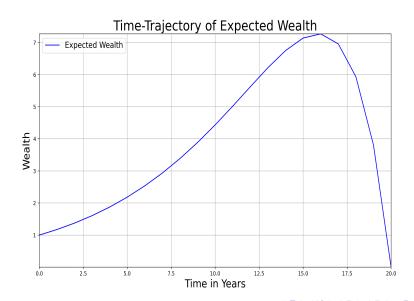
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Fractional Consumption and Expected Wealth Growth



Time-Trajectory of Expected Wealth



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• So we maximize, for each $t = 0, 1, \dots, T - 1$, over choices of $x_t \in \mathbb{R}$:

$$\mathbb{E}[\frac{-e^{-aW_T}}{a}|(t,W_t)]$$



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- MDP discount factor $\gamma = 1$



• Denote Value Function at time t for policy $\pi = (\pi_0, \pi_1, \dots, \pi_{T-1})$ as:

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• Make an educated guess for the functional form of the $V_t^*(W_t)$:

$$V_t^*(W_t) = -b_t \cdot e^{-c_t \cdot W_t}$$

where b_t, c_t are independent of the wealth W_t

We express Bellman Optimality Equation using this functional form:

$$\begin{split} V_t^*(W_t) &= \max_{x_t} \{ \mathbb{E}_{Y_t \sim \mathcal{N}(\mu, \sigma^2)}[-b_{t+1} \cdot e^{-c_{t+1} \cdot W_{t+1}}] \} \\ &= \max_{x_t} \{ \mathbb{E}_{Y_t \sim \mathcal{N}(\mu, \sigma^2)}[-b_{t+1} \cdot e^{-c_{t+1} \cdot (x_t \cdot (Y_t - r) + W_t \cdot (1 + r))}] \} \\ &= \max_{x_t} \{ -b_{t+1} \cdot e^{-c_{t+1} \cdot (1 + r) \cdot W_t - c_{t+1} \cdot (\mu - r) \cdot x_t + c_{t+1}^2 \cdot \frac{\sigma^2}{2} \cdot x_t^2} \} \end{split}$$

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• The partial derivative of term inside the max with respect to x_t is 0:

$$-c_{t+1} \cdot (\mu - r) + \sigma^2 \cdot c_{t+1}^2 \cdot x_t^* = 0$$

$$\Rightarrow x_t^* = \frac{\mu - r}{\sigma^2 \cdot c_{t+1}}$$

$$\tag{1}$$

• Next we substitute maximizing x_t^* in Bellman Optimality Equation:

$$V_t^*(W_t) = -b_{t+1} \cdot e^{-c_{t+1} \cdot (1+r) \cdot W_t - \frac{(\mu-r)^2}{2\sigma^2}}$$

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• Substituting for W_T , we get:

$$V_{T-1}^*(W_{T-1}) = \max_{x_{T-1}} \{ \mathbb{E}_{Y_{T-1} \sim \mathcal{N}(\mu, \sigma^2)} [\frac{-e^{-a(x_{T-1} \cdot (Y_{T-1} - r) + W_{T-1} \cdot (1 + r))}}{a}] \}$$

January 26, 2022

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• Now we can unroll recursions for b_t and c_t :

$$b_t = \frac{e^{-\frac{(\mu-r)^2 \cdot (T-t)}{2\sigma^2}}}{a}$$

$$c_t = a \cdot (1+r)^{T-t}$$

• Substituting the solution for c_{t+1} in (1) gives the Optimal Policy:

$$\pi_t^*(W_t) = x_t^* = \frac{\mu - r}{\sigma^2 \cdot a \cdot (1 + r)^{T - t - 1}}$$

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Code for Discrete-time Dynamic Asset-Allocation

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```
@dataclass(frozen=True)
class AssetAllocDiscrete:
    risky_return_distributions: \
        Sequence [Distribution [float]]
    riskless_returns: Sequence[float]
    utility_func: Callable[[float], float]
    risky_alloc_choices: Sequence[float]
    feature_functions: \
        Sequence [Callable [[Tuple [float, float]], float
    dnn_spec: DNNSpec
    initial_wealth_distribution: Distribution[float]
```

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- In real-world, we need to model this problem as an MDP (capturing various frictions/constraints), and solve with ADP/RL