

# Automatic RFIC Synthesis for Passive Downconversion Mixers

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- ▶ In this project, I have automated the schematic design of Passive Downconversion Voltage mode and Current mode Mixers.
- ▶ The automation uses the popular **Gradient Descent** algorithm.



## Why ML in circuit design?

- ▶ The complexity and density of integrated circuits continue to grow exponentially in the VLSI industry. Today a processor chip can have over a **billion** transistors..
- ▶ AI and ML offer innovative solutions to optimize various processes and improve efficiency.

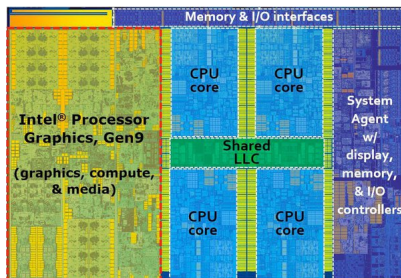


Figure 1: microprocessor chip with over  $10^9$  transistors



## Active ML applications today

- ▶ **Performance Optimization** ML-driven optimization techniques enhance circuit performance by fine-tuning design parameters.
- ▶ **Design Automation** ML algorithms assist in automating layout generation and optimizing power, performance, and area.
- ▶ **Fault Detection and Testing** ML algorithms increase the accuracy of fault detection checks in designs where manual checking is near impossible.



## Downconversion Mixers

- ▶ In a direct conversion RF receiver, a mixer translates the received signal from RF to baseband.
- ▶ Passive mixers are a class of mixers in which the transistors do not operate as amplifying devices. Instead, they function as switches.

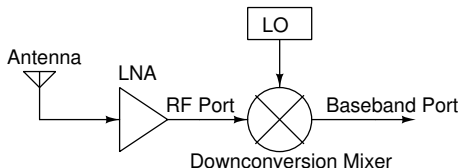


Figure 2: Downconversion mixer in receiver path



Passive mixers are a suitable option for applications requiring low noise figures and good impedance matching over a wide range of frequencies, such as,

- ▶ Wireless communication - cellular base station transceivers
- ▶ AM/FM and two-way radio systems
- ▶ RADARs used in defence



# Introduction (cont.)

## Types of Passive Mixers

1) Based on whether the input is an RF voltage or RF current:

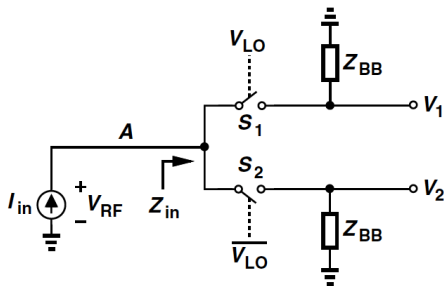
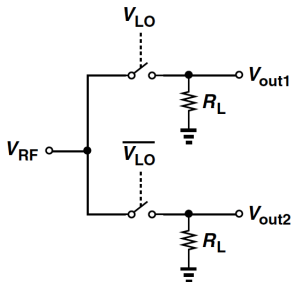


Figure 3: Voltage mode passive mixer      Figure 4: Current mode passive mixer



# Introduction (cont.)

2) Based on whether the load used is a resistor or capacitor:

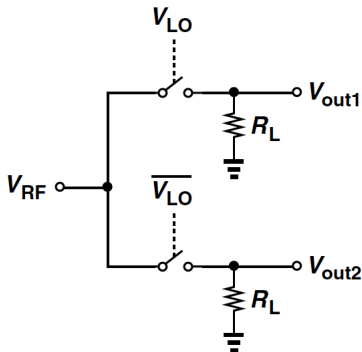


Figure 5: Return-to-zero mixer

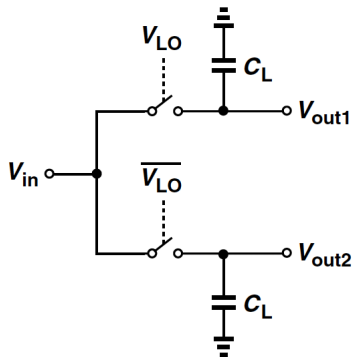


Figure 6: Non-return-to-zero/sampling mixer





# Introduction (cont.)

3) Based on whether the input is single-ended or differential:

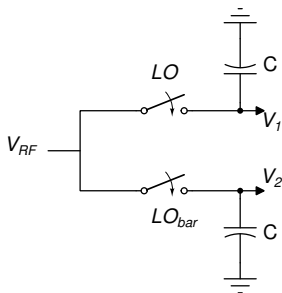


Figure 7: Single-balanced mixer

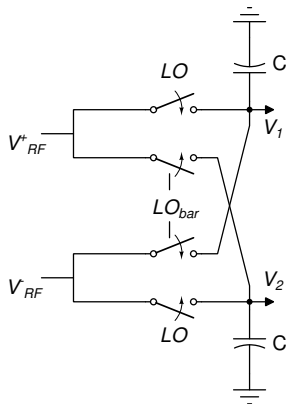


Figure 8: Double-balanced mixer



# Optimisation Algorithm - Gradient Descent

## Principle

The **loss function** is minimised by iteratively adjusting the model parameters in the opposite direction of the *gradient* of the loss function with respect to those parameters.

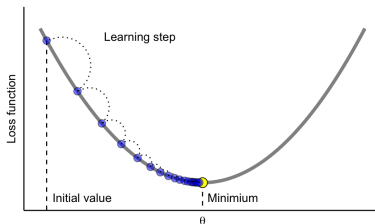


Figure 9: 1-D gradient descent

Key parameters in gradient descent: Loss function, loss weights, gradient of the loss function, learning rate ( $\alpha$ ), model parameter update.



# Gradient Descent - Optimising Schematic design

The specifications of the passive mixer that are of importance are input impedance matching  $S_{11}$ , conversion gain, integrated single sideband (SSB) noise figure,  $IIP_3$  and power consumption.

The automation routine implements gradient descent on the mixer netlist

- ▶ starting with hand-calculated circuit parameters
- ▶ The loss function and its gradient with respect to the circuit parameters used in optimisation are evaluated in every iteration.
- ▶ Every iteration, the circuit parameters are updated using the gradient.



# Gradient Descent - Loss Function

Mixer specifications used to define the Loss-input impedance matching  $S_{11}$ , conversion gain, integrated single sideband (SSB) noise figure,  $IIP_3$  and power consumption.

The Rectified Linear Unit function  $ReLU(x)$  is used to define loss.

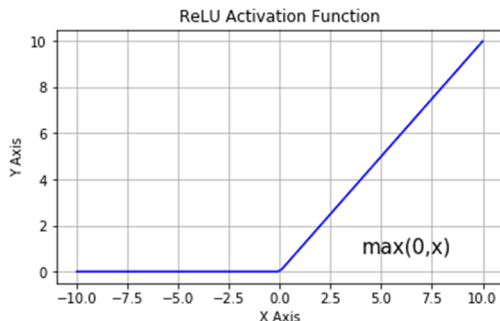


Figure 10: Rectified Linear Unit



# Gradient Descent - Loss Function (cont.)

$$\text{Loss } S_{11} = \text{ReLU}(\text{Simulation } S_{11} - \text{Reference } S_{11}) \quad (1)$$

$$\text{Loss gain} = \text{ReLU}(\text{Reference gain} - \text{Simulation gain}) \quad (2)$$

$$\text{Loss } NF = \text{ReLU}(\text{Simulation } NF - \text{Reference } NF) \quad (3)$$

$$\text{Loss } IIP_3 = \text{ReLU}(\text{Reference } IIP_3 - \text{Simulation } IIP_3) \quad (4)$$

$$\text{Loss ldd} = \text{ldd} \quad (5)$$

Total Loss function:

$$\text{Loss} = A_1 \cdot \text{Loss } S_{11} + A_2 \cdot \text{Loss gain} + A_3 \cdot \text{Loss } NF + \\ A_4 \cdot \text{Loss } IIP_3 + A_5 \cdot \text{Loss ldd} \quad (6)$$



# Gradient Descent - Updating Circuit Parameters

In the  $k^{th}$  iteration,  $x_j(k)$  indicates the  $j^{th}$  circuit parameter

$$\frac{\partial Loss}{\partial x_j} \approx \frac{\Delta Loss}{\Delta x_j} \quad (7)$$

$$x_j(k+1) = x_j(k) - \alpha_j \frac{\partial Loss}{\partial x_j} x_j^2(k) \quad (8)$$

Equation (7) - computation of gradient with respect to  $x_j$

Equation (8) - Updating  $x_j$





# Voltage Mode Passive Mixer

- ▶ Quadrature LO signalling with 25% duty cycle (figure 23)
- ▶ LO Range of operation - 100 MHz to 1 GHz
- ▶ Input impedance looking in from the differential RF inputs matched to  $50\Omega$
- ▶ LO input is fed to the gate of the switching nMOSFET through buffers built with inverters (figure 24)

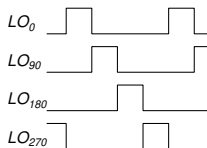


Figure 12: quadrature LO with 25% duty cycle

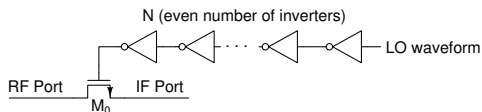


Figure 13: Buffer connecting LO to switching transistor





# Voltage Mode Passive Mixer - Small signal

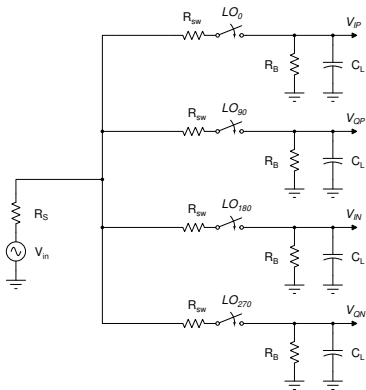


Figure 14: single-balanced mixer, small signal LPTV model

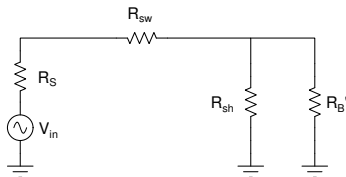


Figure 15: LTI model for input impedance matching



# Voltage Mode Passive Mixer - Equations

Equations based on figures 14 and 15 are used to set up the netlist before optimisation

$$R_{sw} \cdot C_L \ll T_{on} , \text{ during the on-time of the switch} \quad (9)$$

$$R_B \cdot C_L \gg T_{off} , \text{ during the off-time of the switch} \quad (10)$$

$$R_{sh} = (R_{sw} + R_s) \cdot \frac{4\gamma}{1 - 4\gamma} \quad (11)$$

$$Z_{in} = R_{sw} + (\gamma R_B) \parallel R_{sh} \quad (12)$$

$$\text{Number of Inverters} = N = \log_{\rho} \left( \frac{2C_{sw}}{C_i} \right) \quad (13)$$

$$R_s = 50\Omega \text{ and } \gamma = \frac{2}{\pi^2} = 0.203$$



# Voltage Mode Passive Mixer

Updating the circuit parameters in each iteration

$$W_r \leftarrow W_r - \alpha \frac{\partial \text{Loss}}{\partial W_r} W_r^2 \quad (14)$$

$$W_c \leftarrow W_c - \alpha \frac{\partial \text{Loss}}{\partial W_c} W_c^2 \quad (15)$$

$$W_{sw} \leftarrow W_{sw} - \alpha \frac{\partial \text{Loss}}{\partial W_{sw}} W_{sw}^2 \quad (16)$$

$$\rho \leftarrow \rho - \alpha \frac{\partial \text{Loss}}{\partial \rho} \rho^2 \quad (17)$$

$W_r$  = width of resistance  $R_B$

$W_c$  = width of capacitance  $C_L$

$W_{sw}$  = width of nMOSFET

$\rho$  = inverter size ratio



# Voltage Mode Passive Mixer - Optimisation Results

	Pre-optimisation	Specification	Post-optimisation
$S_{11}$	-23.98 dB	$< -15$ dB	-16.05 dB
Gain	2.61 dB	$> 4$ dB	4.27 dB
SSB NF	6.86 dB	$< 7$ dB	6.01 dB
$IIP_3$	24.78 dBm	$> 15$ dBm	26.42 dBm
Power	3.692 mW	Minimise	3.529 mW

Table 1: Specifications at  $f_{LO} = 550$  MHz before and after optimisation

Loss	Starting value	Post-optimisation
$S_{11}$	0	0
Gain	0.421	0
SSB NF	0	0
$IIP_3$	0	0
Power	$9.23 \times 10^{-4}$	$8.82 \times 10^{-4}$
Total loss	0.422	$8.82 \times 10^{-4}$

Table 2: Loss values before and after optimisation



# Voltage Mode Passive Mixer - Optimisation Results (cont.)

## Loss vs iterations

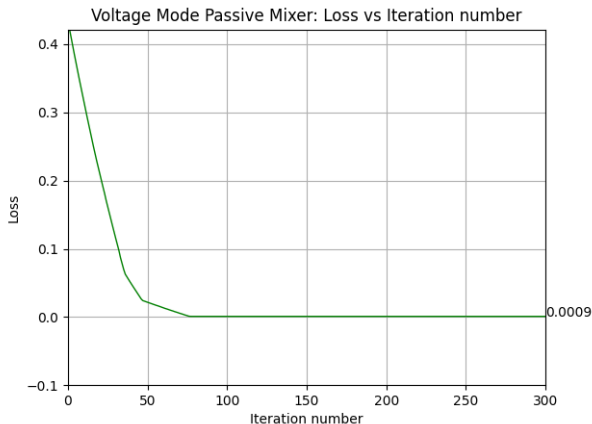


Figure 16: Loss vs iterations for voltage mode mixer



# Voltage Mode Passive Mixer - Optimisation Results (cont.)

## $S_{11}$ process and temperature variations

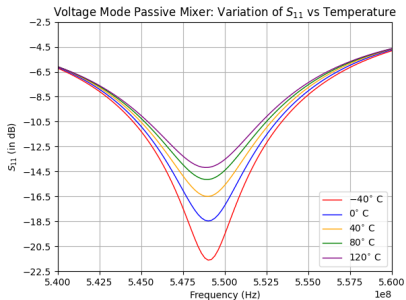


Figure 17: Temperature

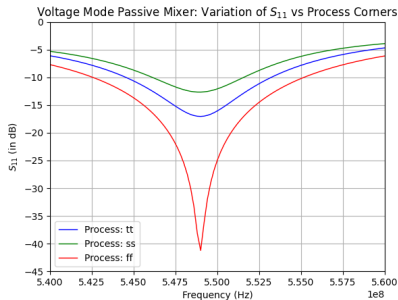


Figure 18: Process variations at 27°C



# Voltage Mode Passive Mixer - Optimisation Results (cont.)

## Gain process and temperature variations

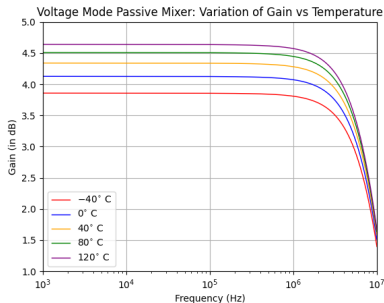


Figure 19: Temperature

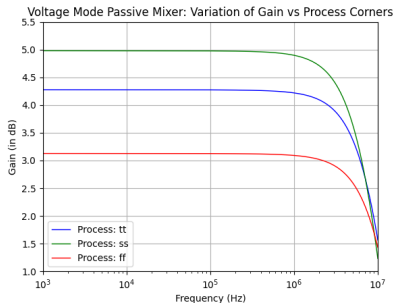
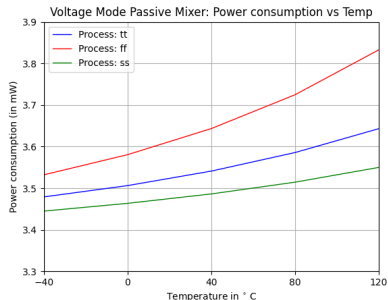
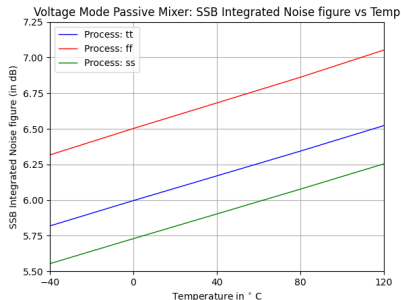


Figure 20: Process variations at 27°C



# Voltage Mode Passive Mixer - Optimisation Results (cont.)





# Current Mode Passive Mixer

## Circuit diagram

The schematic chosen for optimisation is the double-balanced, fully differential current mode downconversion mixer.

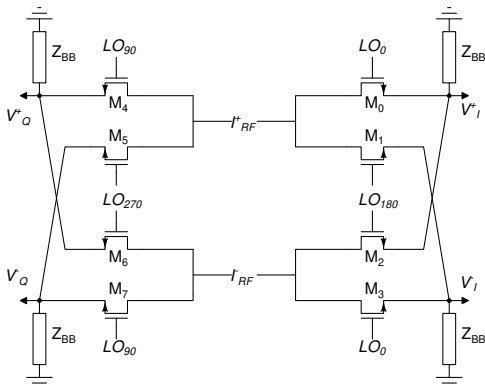


Figure 21: Double-balanced fully differential Current mode mixer



# Current Mode Passive Mixer

$Z_{BB}$  is a **trans-impedance amplifier (TIA)**. The trans-impedance amplifier (figure 22) translates the switching current from the RF side to a baseband output voltage. The trans-impedance,  $Z_{BB}(j2\pi f)$  (or current to voltage gain) of the amplifier is given by (the OPAMP is assumed to be ideal)

$$Z_{BB}(j2\pi f) = \frac{V_{out}}{I_{in}} = \frac{R_L}{1 + j2\pi f C_L R_L} \quad (18)$$

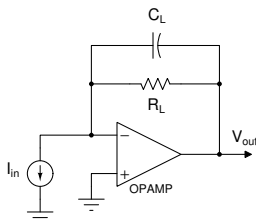


Figure 22: Trans-impedance amplifier



# Current Mode Passive Mixer

- ▶ Quadrature LO signalling with 25% duty cycle (figure 23)
- ▶ LO Range of operation - 100 MHz to 1 GHz
- ▶ Input impedance looking in from the differential RF inputs matched to  $0\Omega$
- ▶ LO input is fed to the gate of the switching nMOSFET through buffers built with inverters (figure 24)
- ▶ The input impedance looking into the mixer from the differential RF port resembles a frequency-translated version of  $Z_{BB}(j2\pi f)$

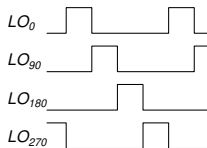


Figure 23: quadrature LO with 25% duty cycle

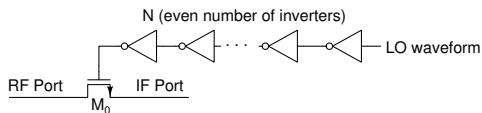


Figure 24: Buffer connecting LO to switching transistor



Updating the circuit parameters in each iteration

$$W_r \leftarrow W_r - \alpha \frac{\partial \text{Loss}}{\partial W_r} W_r^2 \quad (19)$$

$$W_c \leftarrow W_c - \alpha \frac{\partial \text{Loss}}{\partial W_c} W_c^2 \quad (20)$$

$$W_{sw} \leftarrow W_{sw} - \alpha \frac{\partial \text{Loss}}{\partial W_{sw}} W_{sw}^2 \quad (21)$$

$$\rho \leftarrow \rho - \alpha \frac{\partial \text{Loss}}{\partial \rho} \rho^2 \quad (22)$$

$W_r$  = width of resistance  $R_B$

$W_c$  = width of capacitance  $C_L$

$W_{sw}$  = width of nMOSFET

$\rho$  = inverter size ratio



# Current Mode Passive Mixer - Optimisation Results

	Pre-optimisation	Specification	Post-optimisation
$S_{11}$	-5.66 dB	$ S_{11}  < 5$ dB	-4.953 dB
Gain	61.847 dB	$> 60$ dB	60.532 dB
SSB NF	7.28 dB	$< 8$ dB	7.3 dB
$IIP_3$	25.63 dBm	$> 15$ dBm	27.46 dBm
Power	12.431 mW	Minimise	10.09 mW

Table 3: Specifications at  $f_{LO} = 550$  MHz before and after optimisation

Loss	Starting value	Post-optimisation
$S_{11}$	0.098	0
Gain	0	0
SSB NF	0	0
$IIP_3$	0	0
Power	$3.1 \times 10^{-3}$	$2.523 \times 10^{-3}$
Total loss	0.101	$2.523 \times 10^{-3}$

Table 4: Loss values before and after optimisation



# Current Mode Passive Mixer - Optimisation Results (cont.)

## Loss vs iterations

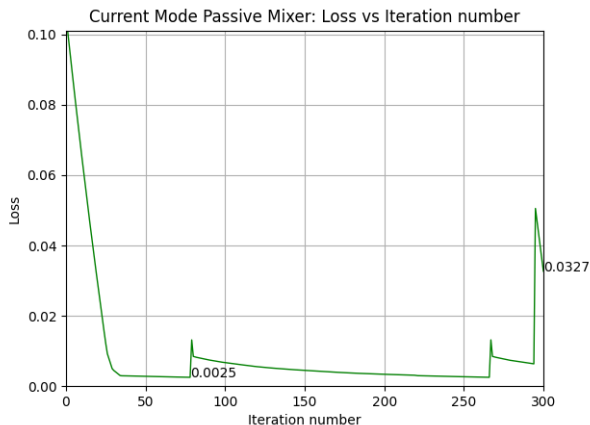


Figure 25: Loss vs iterations for current mode mixer



# Current Mode Passive Mixer - Optimisation Results (cont.)

## $S_{11}$ process and temperature variations

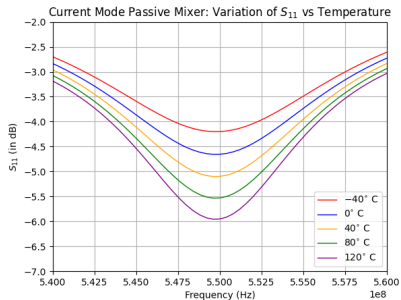


Figure 26: Temperature

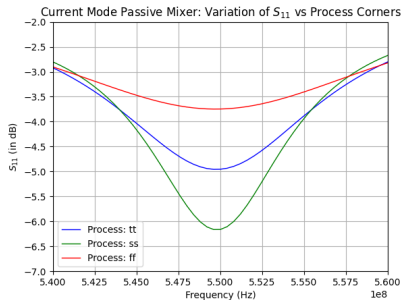


Figure 27: Process variations at 27°C



# Current Mode Passive Mixer - Optimisation Results (cont.)

## Gain process and temperature variations

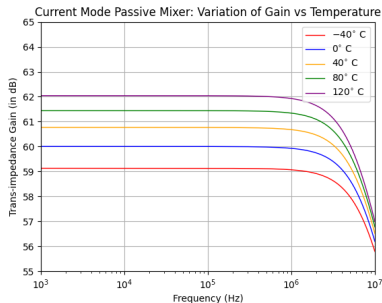


Figure 28: Temperature

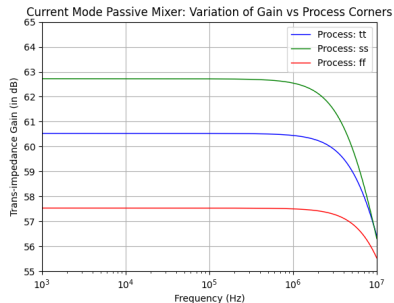
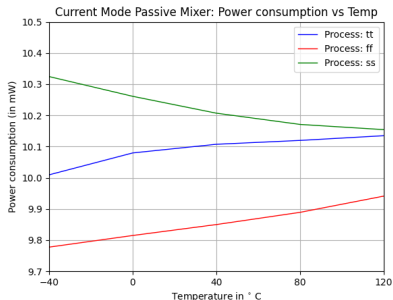
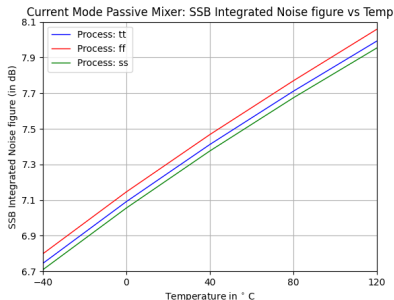


Figure 29: Process variations at  $27^{\circ}\text{C}$





# Current Mode Passive Mixer - Optimisation Results (cont.)



# Conclusion

In this project,

- ▶ I have automated the schematic design of double-balanced fully differential **voltage** and **current mode** passive downconversion mixers
- ▶ Optimisation algorithm used - Gradient Descent
- ▶ Quadrature LO waveforms with 25% duty cycle are used to drive both mixers
- ▶ Specifications optimised are - input impedance matching  $S_{11}$ , conversion gain, integrated single sideband (SSB) noise figure,  $IIP_3$  and power consumption
- ▶ Temperature and process variations are analysed post-optimisation using Python code



# Further Improvements

- ▶ Expand Automatic RFIC synthesis for more mixer circuit topologies
- ▶ Automation for Layout design
- ▶ The local minimum achieved in gradient descent depends on the choice of initial circuit parameters in the netlist. Hence the **role of a circuit designer is very important** in converging to the optimum solution faster.



END

Thank You

