

* UNIT - 3 *

* COMPUTER NETWORKS *

Introduction to computer networks: Computer network consists of two or more computers that are interconnected with each other and share resources such as printers, servers, hardware and exchange the data in the form of files and facilitating electronic communication. Computers on a network can be connected through twisted pair cables, telephone lines, radio waves, electromagnetic waves, satellite and optical fibre cables.

Advantages of computer network:

1. File sharing: It facilitates the user to share and access files stored on a remote computer thus saves time and gives more flexibility. It allows multiple users to collaborate on the same project through network.
2. Resource sharing: It facilitates the user to share limited and expensive resources among number of computing devices.
3. Increased storage capacity: A standalone computer has limited storage capacity but when computers are connected together, the storage memory of all these computers can be made available for each computer.
4. Increased cost efficiency: Commercial software packages are costly and take time for installation. Networks allow software stored (or) installed on one computer can be shared among other computers.
5. Load sharing: A single computer will take more time to carry out all the tasks and will slow down. Networks allow transferring extra jobs to other machines connected in the same network for faster processing.

execution. This will improve the performance of a system.

6. Facilitating communication: A network facilitates the users to communicate easily and efficiently through electronic mail and instant messaging thereby allowing the exchange of important messages in a speedy manner without wasting paper.

7. Types of connection: A network of is two (or) more devices connected through links. A link is a communication pathway that transfers data from one device to another.

(i) Point to point (uni casting): A point to point connection provides a dedicated link between two devices.

The entire capacity of the link is reserved for transmission between those two devices.

(ii) Point to multipoint: A multipoint connection is one in which more than two specific devices share a single link, it has broad casting (or) multi casting.

(i) Broadcasting: One node can send data to the all connected system over a sharing link.

(ii) Multi casting: One node can send data to the subscribed nodes belong to all connected nodes.

8. Transmission modes: The direction in which data can be transmitted between any two linked devices is of 3 types

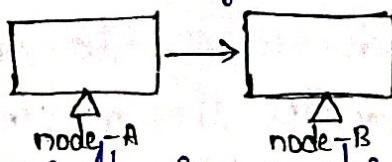
(i) simplex

(ii) half duplex

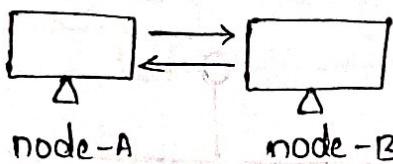
(iii) full duplex

(iv) Unidirectional transmission: It is a uni directional data transmission only one of the devices send data and

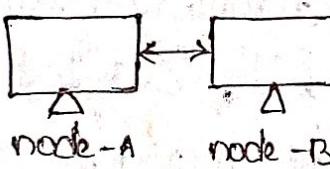
other one can only receive data.



iii) Half Duplex: It is a bi-directional, the linked devices cannot send and receive data at the same time. When one device is sending data the other one can receive.



iv) Full duplex: It is a bi-directional, the linked device can send and receive data simultaneously. The linked device can send the data at the same time it receives data.



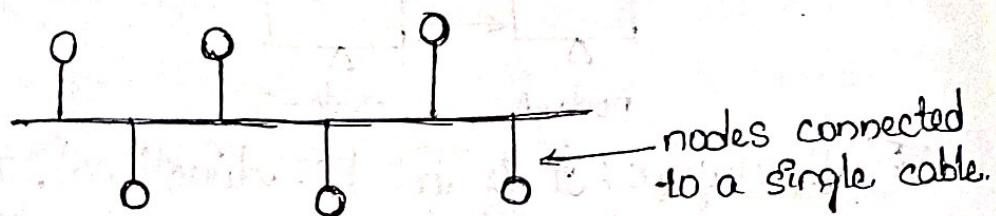
Network Topologies: Network topology refers to the schematic description of a network arrangement connecting various nodes through links i.e., actual geometric layout of computers and other devices connected to the network. They are

- 1, Bus topology.
- 2, Star topology.
- 3, Ring topology.
- 4, Mesh topology.
- 5, Hybrid topology.

1, Bus topology: In a bus topology each node (i.e., computer or server) is connected to a single cable called "Bus". All the nodes share the same

communication channel.

When a node wants to send a message to another node it creates the message and adds the address of the recipient to it. Then it checks whether the line (bus) is free (or) not. If the bus is free, it plays the message on the line (bus) else it wait until the bus (channel) becomes available.



When the message is placed on the bus (line), each and every node connected to it checks the destination address mentioned on it. If the node address does not match the intended address, it ignores the message. The message is picked up and open only by the receiver. The receiving device also sends acknowledgement to the sending device before it frees the line.

Advantages:

- 1, Easy to install and to connect a new device to the network.
- 2, Requires less cable length than other topologies.
- 3, Inexpensive as only one cable is required.
- 4, Failure of a single node does not affect the network.

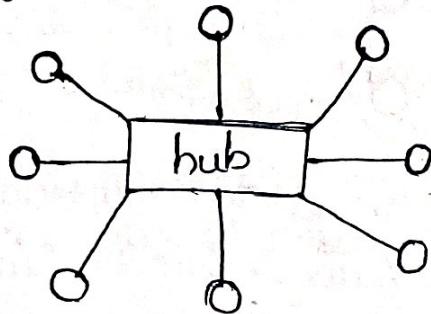
Disadvantages:

- 1, Damage in the cable results in shutting down of the entire network.
- 2, In the case of network shut down it becomes very

difficult to identify the problem.

(3) As the number of nodes increases, the speed of the network slows down.

Q3) Star topology: In a star topology, each node is connected to a central hub with a point to point connection.



The hub (host node) controls the communication between other nodes. The hub acts as a signal repeater. When a node has to send a message to another node connected to the network. It will first send that message to the hub. The hub will regenerate the message and then send it to the destination node.

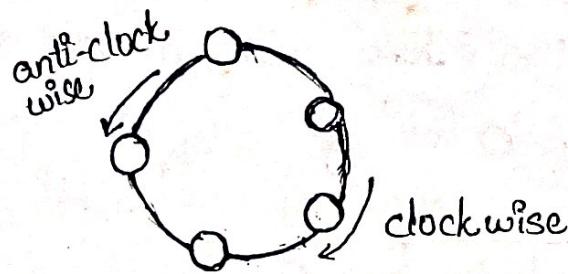
Advantages:

- 1) Easy to install.
- 2) New nodes can be connected easily.
- 3) Network does not get disturbed when a device is added (or) removed from it.
- 4) Easy to detect faults.
- 5) Failure of any node (except the hub) does not affect the network.

Disadvantages:

- 1) It requires more cable length than bus topology.
- 2) If the central hub fails, entire network shut down.
- 3) More expensive than bus topology because of the cost of hub, cables etc.

③ Ring topology: In a ring topology, all the nodes connected to each other in the shape of closed loop, so that every node is connected directly to two other nodes.



In a ring topology, messages travel through the ring in a circular shape. In the same direction (either clockwise or anti-clockwise).

In a ring topology, each device acts as a repeater to regenerate the signal. If a node receives the data (or) message from any of its two adjacent nodes then it checks the destination address. If the message is addressed to it, it accepts the data and processes it otherwise, it just regenerates the signals and passes it to the next node in the sequence.

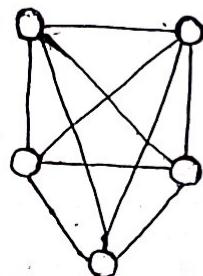
Advantages:

- 1) Ring topology is best suited for networks that do not have hub.
- 2) It is more reliable than star topology, as the communication does not depend upon a single hub.
- 3) It is easy to install.
- 4) Every node has equal chance to transmit data.
- 5) It can span over longer distances.

Disadvantages:

- 1) Ring topology causes delay in communication.
- 2) In case of network failure, it is difficult to find the fault.

- 3, If one node fails, the entire network is shut down.
Because, the ring is not complete.
- 4, It is difficult to add (or) ~~remove~~ nodes from the network.
- 5, Mesh topology: It is also known as "completely connected network"; each node is connected to other nodes in the network using a separate physical link i.e., if there are 'n' nodes then there would be $\frac{n(n-1)}{2}$ physical links are required. A message can be pass any of the several possible paths from source to destination.



Advantages:

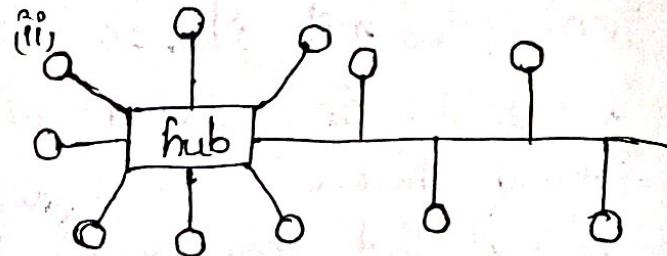
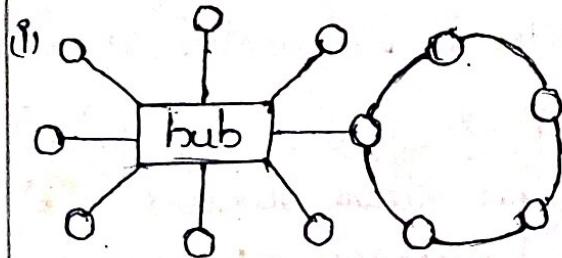
- 1, Failure of a node does not affects the entire network. Only the communication with that particular nodes are affected.
- 2, Communication is fast as there is a direct link between the nodes.
- 3, Each connection can have its own data load, so that the traffic problem is eliminated.
- 4, Ensures security of the data because every message travels along the direct link.
- 5, It is easy to detect the network errors.

Disadvantages:

- 1, It is most expensive network as for 'n' nodes $\frac{n(n-1)}{2}$ physical links are required.
- 2, It is difficult to install.

5) Hybrid topology: Hybrid topology is a combination of two or more topologies very commonly used. Two hybrid topologies are:

- Star-ring topology
- Star-bus topology.



Advantages:

- Trouble shooting is easy.
- Easily expandable network.
- Very reliable.

Disadvantages:

- Complex design.
- Very costly.

Types of networks: Network can be categorised into different types depending on size, complexity level of security, geographical range.

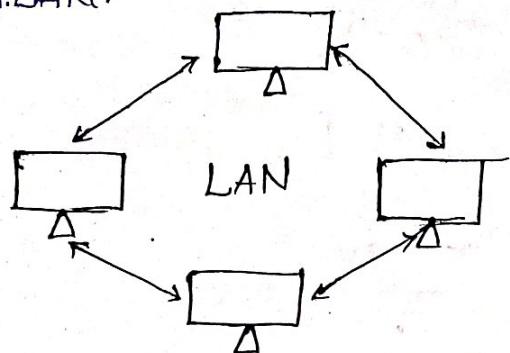
- Local Area Network (LAN)
- Metropolitan Area Network (MAN)
- Wide Area Network (WAN)
- Personal Area Network (PAN).
- Campus Area Network (CAN).

Local Area Network (LAN):

* LAN is a computer network widely used for local communication.

* LAN connects computers in a small area like a room, building, office (or) a small area like a room upto few kilometers.

- * LAN can be connected to other LAN's over any distance via telephone lines or radio waves.
- * A LAN may be setup as wired (or) wireless connections.
- * A LAN that is completely wire is called wireless LAN (or) WLAN.



- * LAN's are privately owned networks, with a purpose to share resources and to exchange information.
- * LAN runs at a speed of "10 Mbps to 100Mbps" and has low delays.
- * LAN are generally connected using the star, bus & ring topologies.

Advantages:

- 1, The data is transferred at an extremely faster than in LAN.
- 2, LAN provides higher security.
- 3, They cannot extended to the wide area.

Metropolitan Area Networks (MAN):

- * MAN is a computer network spread over a city, the cable television network is an example of MAN.
- * The computers in a MAN are connected using co-axial cables (or) optical fibre cables.
- * The MAN connects several LAN spread over city.

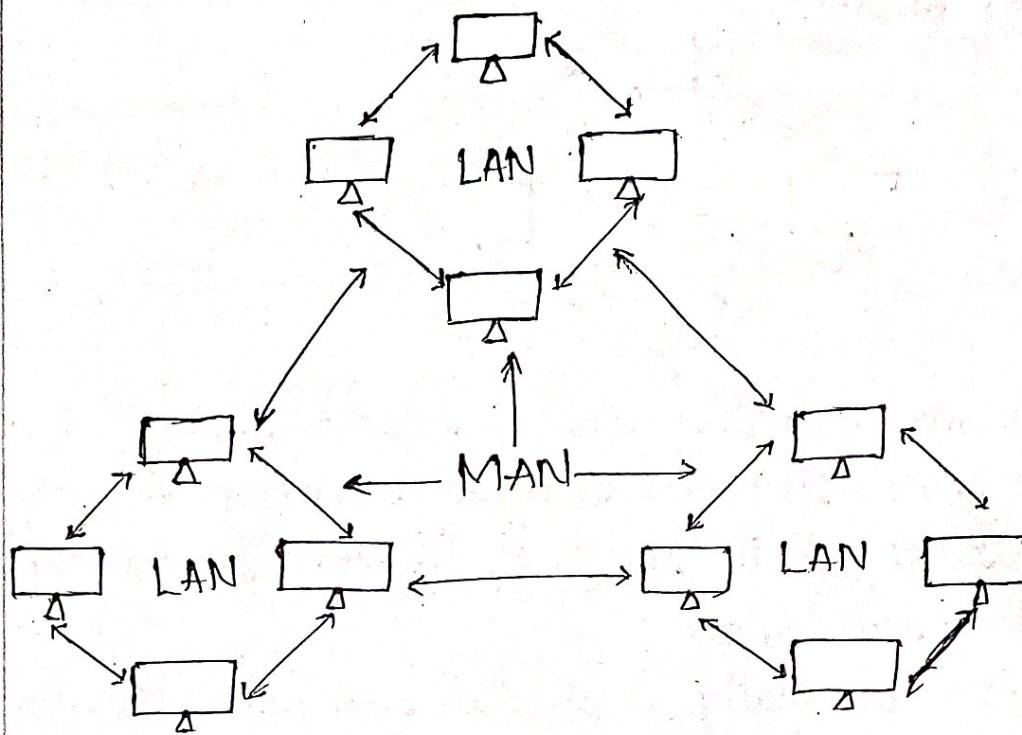
Advantages:

- 1, MAN gives the good efficiency of data.
- 2, Local E-mails can be sent fast and free.

(3) MAN provides a high security.

Disadvantages:

1. Difficult to manage.
2. Additional cables are required to connect LAN's.



Wide Area Network (WAN):

* WAN is a network that connects computers over long distances like cities, countries, continents for worldwide.

* WAN uses public leased or private communication links to spread over long distances.

* WAN uses telephone lines, satellite link and microwave etc. to connect computers.

* Internet is a common example of WAN.

Advantages:

1. WAN provides a large geographical area.

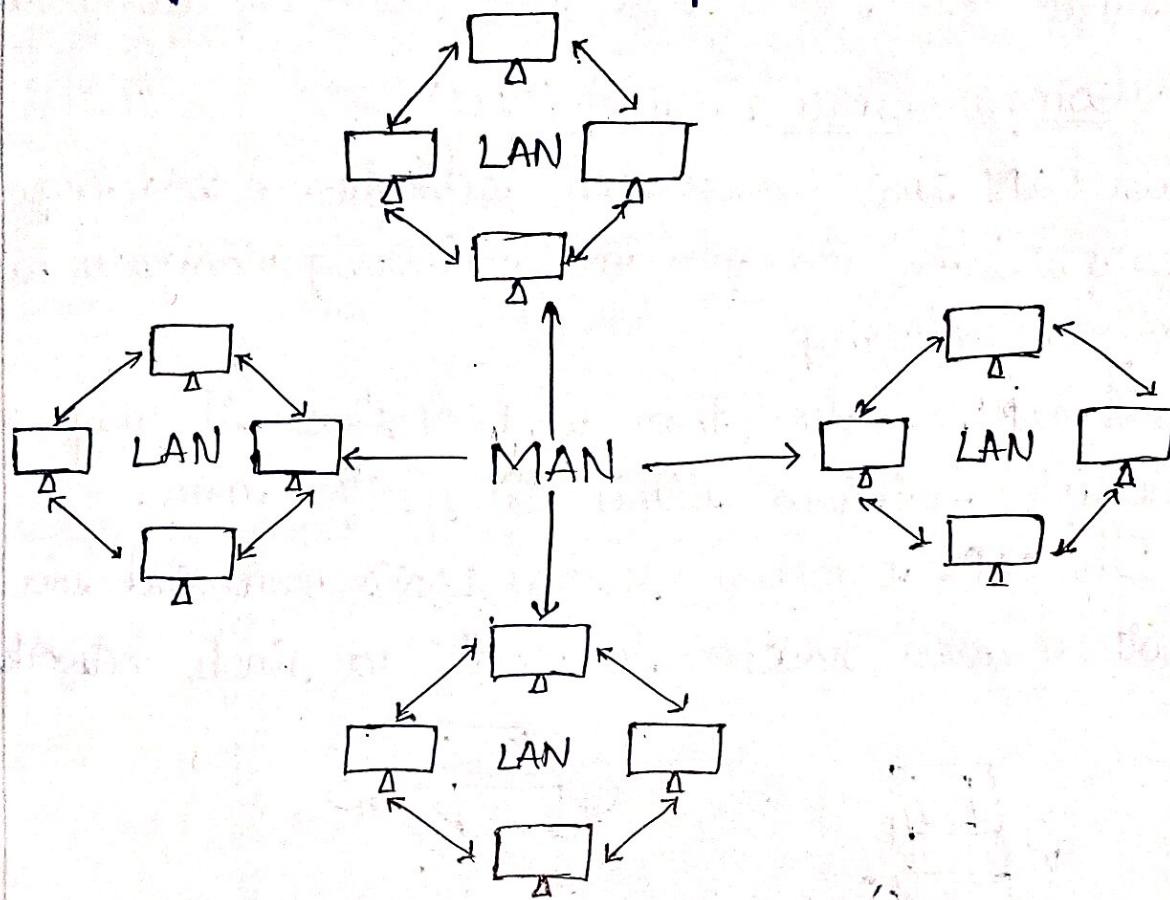
2. The data is centralised.

3. Sharing software resources.

4. High bandwidth increases the data transfer rate.

Disadvantages:

- 1, WAN's need fire wall and antivirus software.
- 2, Installation cost is very high.
- 3, Fixing the problem is very difficult.

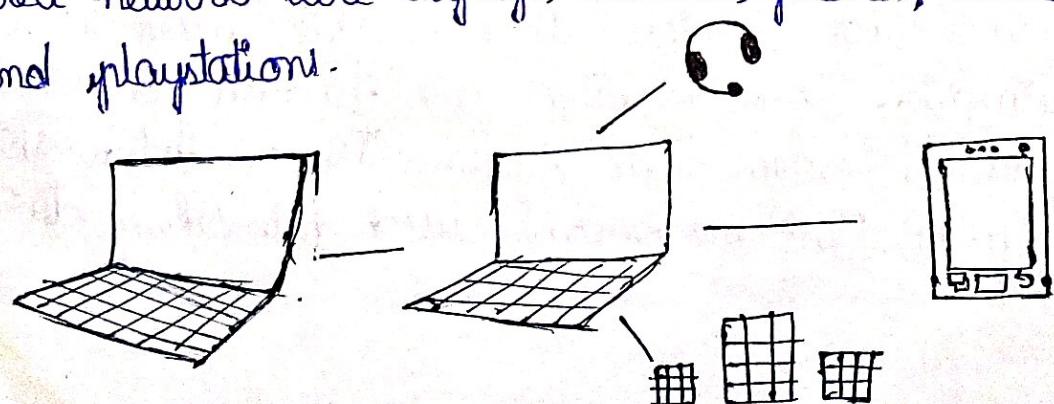


4, Personal Area Network (PAN):

* PAN is the interconnected between devices written within the range of a person's private space, typically within a range of 10mtrs to 30mtrs.

* PAN is used for connecting the computer devices for personal use.

* The devices that are used to develop the personal area network are laptop, mobiles, phones, media players and playstations.

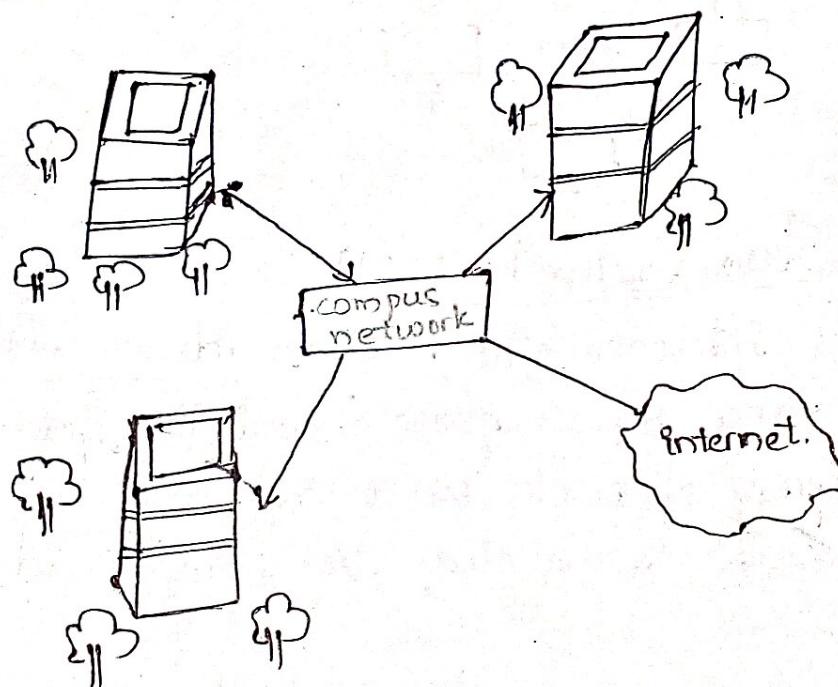


These are two types of personal area network.

- (i) Wireless PAN: wireless PAN is developed by using wireless technology like WiFi, bluetooth. It is low range network.
- (ii) Wired PAN: wired PAN is created by using the ^{universal serial bus} (a) corporate

5. Campus Area Network (CAN):

- * A CAN that covers an educational or corporate campus. The examples are university computers and corporate buildings.
- * A CAN is larger than a LAN since it may span multiple buildings within a specific area.
- * The CAN combines several LAN's connected via switches and routers to create a single network.



Network devices: Computer networking devices are communication devices that enable users to create a network. These devices are known as network equipment; intermediate systems (IS) or Interworking unit (IWU). The commonly used networking devices are

→ hub → router
→ repeater → gateway
→ switch → network interface card.
→ bridge

Hub: A hub is device to which different devices are connected so that they can communicate with other. Every computer in a network directly connected to the hub. When the data packets arrive at the hub, it broadcasts them to all the devices connected to it. Hence, every device picks the message but only the destined device processes the packet and all the other computer just doesn't discard it.

The main function of the hub is amplify the signals and broadcast them to all the devices connect to it. There are two types of hub.

1, Active hub

2, Passive hub

3, Active hub: Active hubs have their own power supply and can clean, boost and relay the signal along with the network. It serves as both a repeater as well as wiring centre.

Passive hub: These hubs takes power supply from the active hub. These does not cleaning and boosting along with the network.

Repeater: Network repeaters are electronic devices that regenerate incoming, electrical, wireless or optical signals.

Repeaters are used to extend LAN. It has only two ports and can connect only two segments of a network. The repeater regenerates the signals before sending them to the other segments. This can cause a propagation

delay without a repeater the data can only span a limited distance.

For sending signals longer distance repeater regenerates for increasing the signal strength, the signals and removing unwanted noise.

Switch: A switch is a device that can be used in all places where a hub is used it is much better than the hub because it has a switching table within it. The switching table store the address of every computer (or) device connected to it and sends the data only to the destined device rather than broadcasting. Due to this, the network traffic is reduced.

Bridge: A bridge is a device that connects two (or) more LAN's. A bridge receives data from one LAN to forward it to another LAN, it first regenerates the signals and then forwards the data to the other LAN.

A bridge reads the address of the receiving device specified on the data packet to identify the destination of the packet. It forwards the packet only to the network to which the receiving device is connected, thereby reducing the traffic on other network segments.

Router: A router is an intelligent device that routes data to destination computers. It is used to connect two logically and physically different networks, two LAN's, two WAN's and a LAN with a WAN.

Routers use special software known as routing table that stores the address of devices connected to the network. The major task of a router is to route the data packets between two networks on

the best possible path for data transmission.

Gateway: A gateway is a very complicated networking device that is used to connect two (or) more dissimilar networks that use entirely different protocols. A gateway acts as a translator between two dissimilar networks. It accepts data formatted by one network and converts it into a format that can be accepted by other network.

A gateway can be used to monitor incoming, outgoing traffic to check for any malicious activity within the network.

Network Interface Card: The network interface card is also known as a "Network adapter" or a "LAN card". The computer or communicate with other device by properly installed and configured LAN card. The communication cables that connect different devices to form a network are connected via this card.

Network interface cards are of two varieties
wired
wireless.

Most modern desktop computers use a wired NIC, laptops are connected with both wired and wireless LAN cards.

Open system interconnection model: The open system interconnection model (OSI) developed by the International standards organisation (ISO) in 1984. The OSI model has the following layers, with each layer performing a particular task.

- * Physical layer
- * Data link layer
- * Network layer
- * Transport layer
- * Session layer
- * Presentation layer
- * Application layer.

Application Layer

Message format, human-machine interface

Presentation Layer

Translation (coding into 0's & 1's), compression, encryption.

Session Layer

Authentication, permission, session restoration

Transport Layer

Reliable, message delivery from process to process

Network Layer

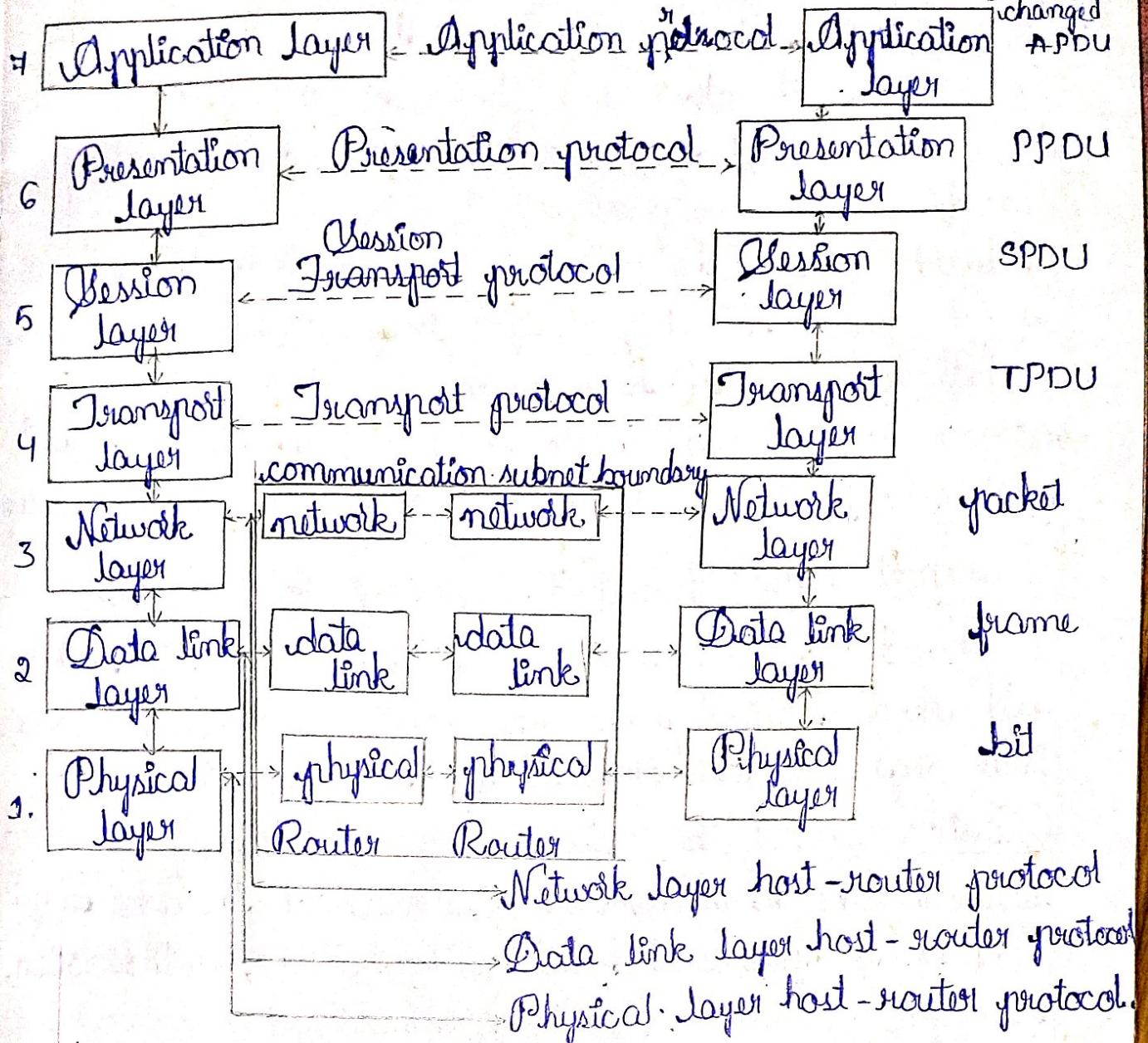
Network addressing, Routing (or) Switching

Data Link Layer

Error detection, flow control.

Physical Layer

Bit stream, Physical medium, method of representing bits.



Physical layer: The physical layer is connected with transmitting raw bits 0's and 1's. It converts the raw system stream bits into electric signals, optical signals (or) electromagnetic signals depending on whether the underlying network uses the cable.

The physical layer establishes maintains and terminates physical connection between computers. It decides how many volts should be used to represent 0 and 1. It decides data rate (No. of bits transmitted per second). It decides the mode of data transmission (simplex, half duplex (or) full duplex).

Data link layer: The data link layer converts data packets into a stream of bits (1's & 0's) called as 'Frames'. The data link layer is also responsible for error control, flow control and reliable data transfer.

Network layer: The network layer controls the operation of the subnet. A key design issue is determining how packets are routed from source to destination. The network layer accepts data packets, determines the best path (or) reach a device that is closer to the receiver.

Transport layer: Transport layer specifies the details to handle reliable transfer of data. It handles end-to-end error control and flow control breaking up data into segments and reassembling the segments.

Session layer: The session layer maintains a session between the communicating devices. It includes applications for password and authentication, authorization, dialogue control maintain synchronization between sender and receiver.

Presentation layer: This layer specifies the presentation and representation of data. Its function include translation of representation of the data into a common identifiable format at the receiver end, encryption and decryption of data.

Application layer: This layer specifies how can application uses a network.

The application layer provides services to support end user applications such as web browsing, e-mail, file transfer and remote access by using the protocols HTTP and HTTPS, SMTP, FTP, Telnet.

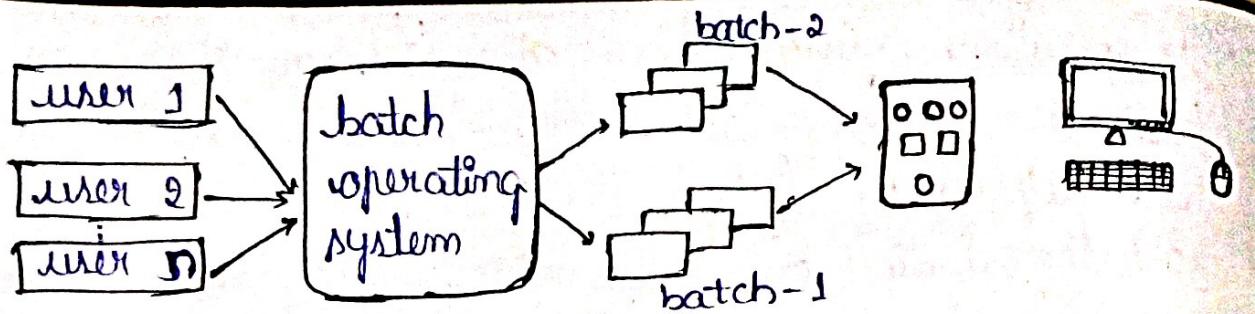
Operating system: An operating system is an interface between a computer user and computer hardware. An operating system is a software which performs all the basic tasks like file management, memory management, process management, handling input and output, and controlling peripheral devices such as disk drives and printers. Some popular operating systems are windows, LINUX, UNIX etc.

The following are some of the important functions.

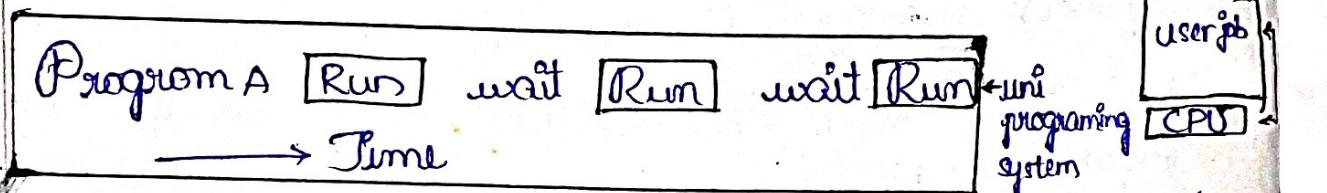
- * memory management.
- * process management.
- * devices management.
- * file management.
- * security management.
- * control over system performance.
- * provides user interface.
- * controlling peripheral devices.

Evolution of operating system: The evolution of various types of operating systems can be briefly described follows.

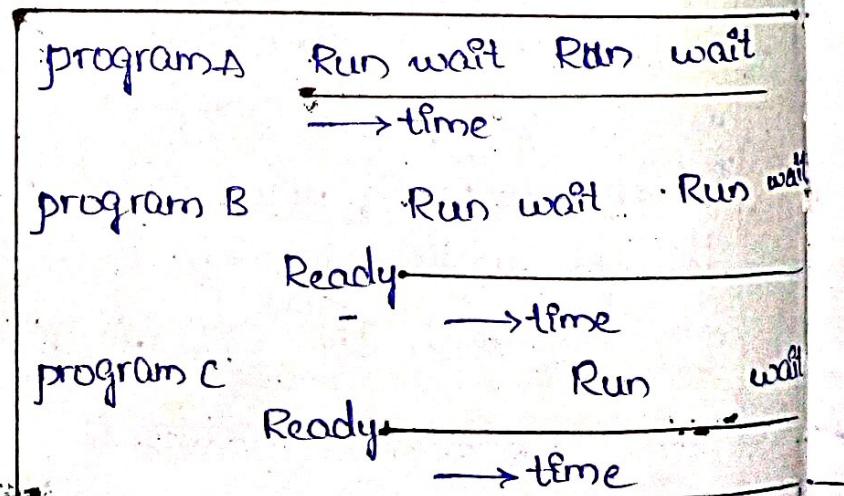
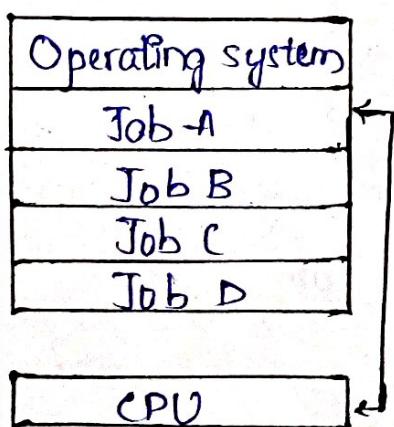
Batch system: This type of O.S was used in earlier age. To speed up processing jobs with similar needs were batched together was run through the computer as a group. The definite feature of a batch system is the lack of interaction between the user and the job while the job is executing. In this execution environment, the CPU is often idle.



Single user - single tasking operating system: As the name indicates, single user, single tasking O.S. allowed one person to be executed at a time. They were designed to enable a single user to do a single job effectively at any point of time.



Multi programming operating system: In this type of bay operating system, more than one programme will reside into main memory. The operating system picks and begins to execute one of the jobs in the memory. Eventually, the job may have to wait for some task. The operating system simple switches to and executes another job. When the first job finishes waiting and gets the CPU back. As long as there is always some job to execute, the CPU will never be idle.



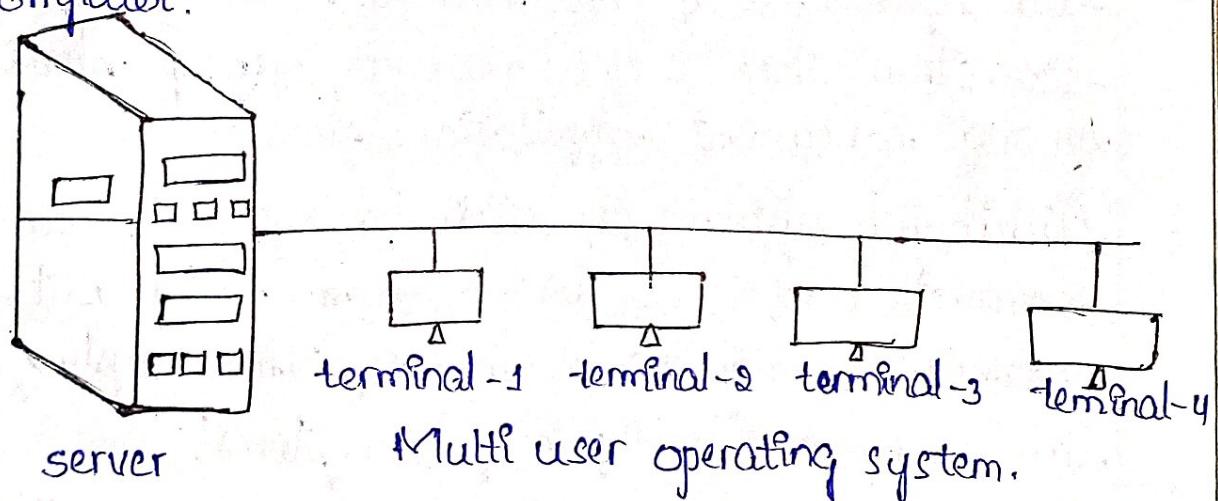
multi programming system with multiple programming systems (P.e., 3 programs).

Single user multi tasking operating system: A single user multi tasking operating system allows a single user to simultaneously perform several tasks. This operating system normally used in our desktops and laptops.

For example when we are typing a document in microsoft word while listening to a song and downloading a file from the internet, we are actually doing three jobs at the same time.

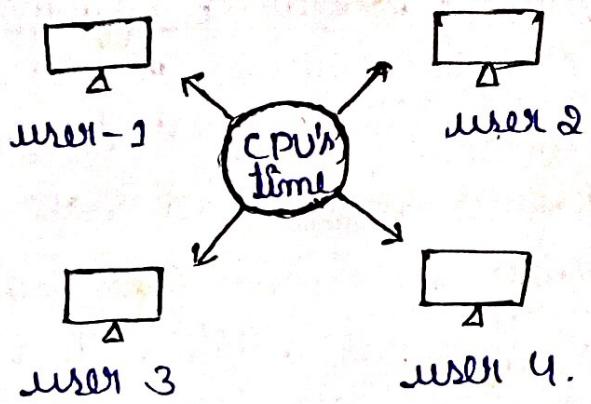
Multi user Multi tasking Operating system:

A multi user operating system enables multiple users on different computers to access a single system. It allows more than one user to connect to the main computer to perform more than one job at a time. Hence users on multiple terminals can access the same data and application programs that are stored on the main computer.



Multi user operating system.

Time sharing systems: A time sharing operating system allows the many users to share the computer simultaneously. A time-shared operating system uses CPU scheduling and multi-programming to provide each user with small portion of a time shared computers.



Real time operating systems:

Real time operating system is a special purpose operating systems, used when there are rigid time requirements on the operation of a purpose for) the flow of the RTOS is used in embedded system such as cell phones, air conditioners, digital homes, cars and so on.

Process control system: Process controls are dedicated systems. They are dedicated to single application. Thus there is no need to manage sharing among concurrent application programs.

Distributed system: A distributed system is an interconnection of two (or) more nodes but the processes do not share memory. These systems are also called as 'loosely coupled systems'.

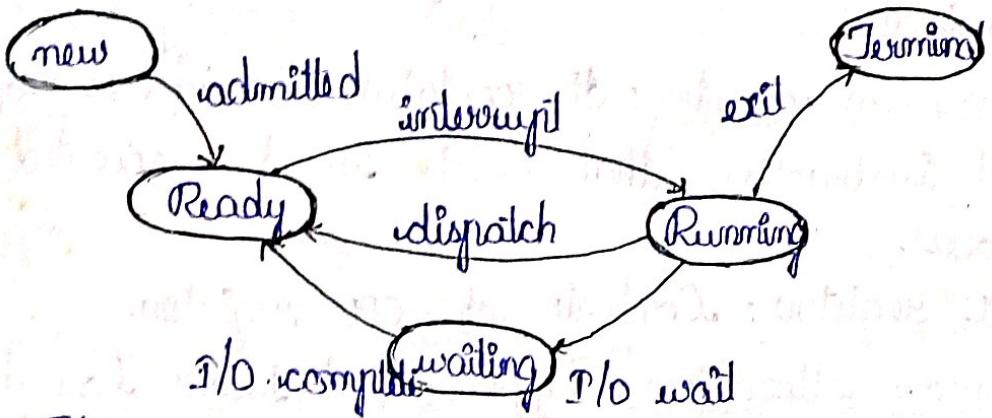
Process management: A process is an active program i.e., the program under execution is known "process". The execution of a process must progress in a sequential fashion.

(or)

A process is defined as an entity which represents the basic unit of work to be implemented

in the program.

* Process states: The different states that a process is in during its execution are explained below.



New: The process is new state when it has just been created.

Ready: The process is waiting to be assigned the processor by the short term schedule.

Running: The process instructions are being executed by the processor.

Waiting: The process is waiting for some event such as I/O to occur.

Terminated: The process has completed its execution.

* Process Control Block: A process control block is associated with each of the processor. It contains important details about that particular process. These are as follows:

Pointer	Process state
Process number	
Program counter	
CPU register	
Memory allocation	
Event information	
List of open files	
⋮	

Process control block

Pointer: Which point do the PCB of other process.

Process state: It specifies the control current state of the process (i.e., new, ready, running, waiting (or) terminated).

Program counter: It contains the address of the next instruction that needs to be executed in the process.

CPU registers: Contents of CPU registers.

Memory allocation: Upper and lower bounds of the memory required for the process.

Event information: States of various flags and switches, priority of the process.

List of open files: These are the different files that are associated with the process.

* Ops Process operations: There are many operations that can be performed i.e. some of these are process creation, process pre-emption, process blocking and process termination.

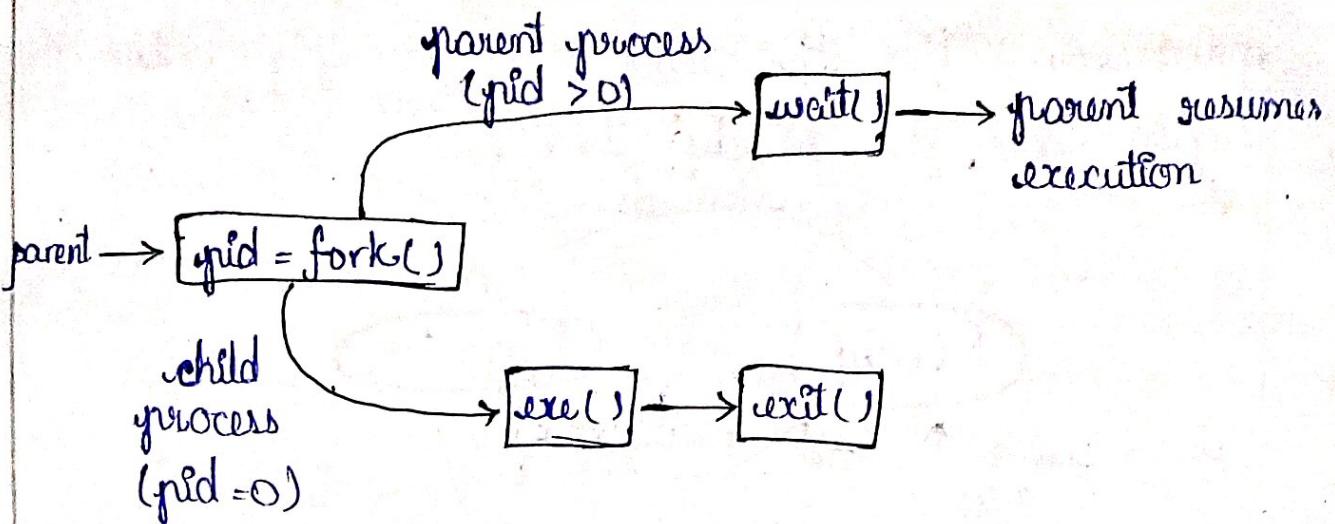
Process creation: Process need to be created in the system for different operations. This can be done by the following events.

* User request for process creation.

* System initialization.

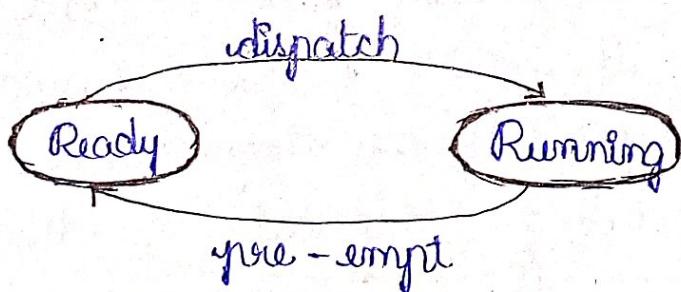
* Execution of a process creation system called by a running process.

* Batch job initialization.



Process creation using fork(): A process may be created by another process using `fork()`. The creating process is called the "parent process" and the created process is "child process". A child process can have only one parent but a parent process may have many children.

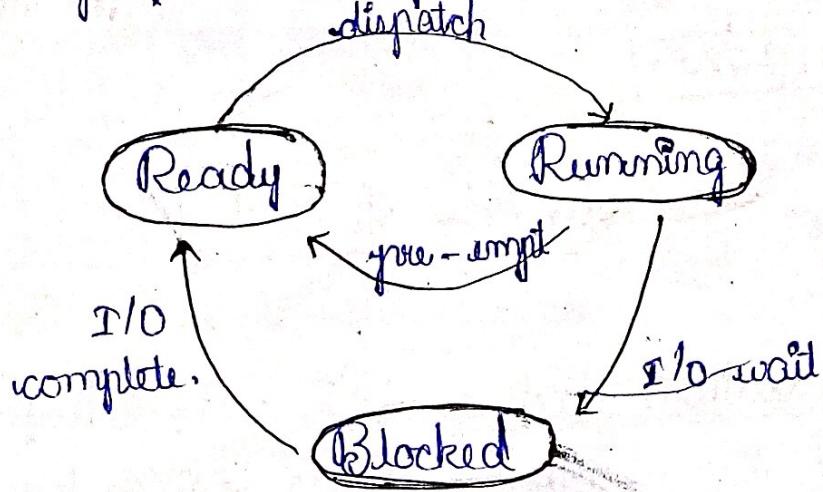
Process Pre-emption: An interrupt mechanism is used in pre-emption that suspends the process executing currently and the next process to execute is determined by the short-term scheduler. Pre-emption makes sure that all processes get some CPU time for execution.



Process pre-emption.

Process Blocking: The process is blocked if it is waiting for some event to occur. This event may be I/O as the I/O events are executed in the main memory and don't require the

processor. After the events is complete, the process again goes to the ready state.



Process Termination: After the process has completed. The execution of its last instruction, it is completed or terminated. The resource held by a process are released after it is terminated.

A child process can be terminated by its parent process if its task is no longer relevant. The child process sends its status information to the parent process before it terminates. Also, when a parent processes are terminated as well as the child processes cannot run if the parent processes are terminated.

* Process Scheduling: The act of determining which process is in the ready state and should be moved to the running state is known as "process scheduling".

The prime aim of the process scheduling system is to keep the CPU busy all the time and to deliver minimum response time for

all programs. For achieving this the scheduler must apply appropriate rules for swapping process IN and OUT of CPU. There are two types of process scheduling.

- 1, Non pre-emptive scheduling.
- 2, Pre-emptive scheduling.

1, Non pre-emptive scheduling: When the currently executing process gives up the CPU voluntarily. The first process is completely executed and then the CPU executes the next process. The process is repeated until all the processes are executed. There is no need for a CPU scheduling policy in a non pre-emptive scheduling. The execution of second job will strictly follow the execution of the first.

2, Pre-emptive scheduling: The O.S. decides to favour of another process, pre-empting the currently executing process. In pre-emptive scheduling, each process is given a small amount of time to execute. When the time slice expires, the currently executing process is suspended and the CPU is allotted to another process for the same amount of time. This process repeats until all priority process comes, the lower priority process is suspended and the higher priority is executed. Some pre-emptive scheduling are as follows.

First come-first serve: In the first come first serve (FCFS) the process that enters the memory.

first will be executed first. A ready queue is maintained such that it contains all the processes that need the CPU time. The scheduling is just take first process and executes it and then allocates CPU to the next process in the sequence. The main drawback of the FCFS policy is poor performance as long waiting times for small processes.

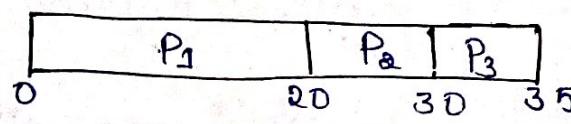
Shortest job first: In this technique, the CPU time requirement of each process must be known in advance so that a ready queue can be maintainable such that it stores the processes increasing order of their CPU time requirements. This is the best approach to follow, it is very difficult to implement, as prior knowledge of the time required cannot always be known in advance. It may lead to "Starvation" of long jobs that had entered very early in the system.

Round Robin: In this technique, the CPU is allotted to each process on the FCFS basis for a specified time (called the time quantum). If the first process is completely executed in this quantum, it is suspended and CPU is allocated to the second process for the same time quantum. This technique is repeated until all the processes are completely executed.

Ex: Consider three processes P_1 , P_2 and P_3 with CPU time requirements given as 20ms, 10ms and 5ms

Show the scheduling process using FCFS, SJF and round robin policies. Take time quantum as 5ms.

FCFS

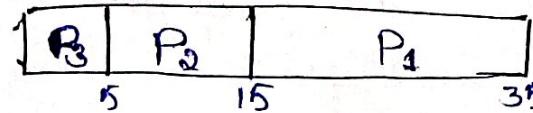


P.N I

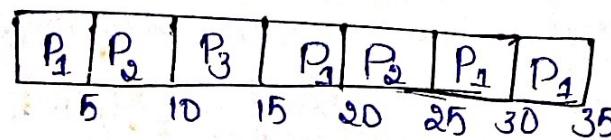
P₁ 20

P₂ 10

SJF



Round Robin



P₃ 5.

Command Interpreter: A command interpreter is the part of a computer operating system. A command interpreter understands and executes commands that are entered interactively by a human being or from a program. In some operating systems, the command interpreter is called the "shell".

A command interpreter allows the user to interact with a program using commands in the form of text files. It was frequently used until the 1970's. However, in modern times, many command interpreters are replaced by graphical user interfaces and menu-driven interfaces.

Purpose of command interpreter:

Command interpreters serve many purposes and are more useful than graphical user interfaces in some cases.

* Command interpreters have large range of commands and queries available for different operations. Also, it is much faster to type than to click as is done using graphical user interfaces.

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to control hardware devices.

DOS commands can be typed in either upper (or) lower case.

Features of DOS:

- * It is a single user operating system.
- * It controls program.
- * It is machine independence.
- * It manages computer files.
- * It manages computer memory.
- * It manages computer input and output operations.

Types of DOS commands:

- * Internal commands: Commands such as DEL, COPY, TYPE etc are the internal commands that remain stored in computer memory.
- * External commands: Commands like FORMAT, DISKCOPY etc are the external commands and remain stored on the disk.

Windows Operating System: The windows operating system is the extension of the disk operating system.

It is the most popular and simplest operating system. It can be used by any person who can read and understand basic English, as it does not require any special training.

However, the windows operating system requires DOS to run the various application programs initially. Because of this reason, DOS should be install into the memory and then

Windows operating system can be executed.

Elements of windows operating system:

- * Graphical user interface.
- * Icons (pictures, documents, applications, program icons). etc).
- * Task bar.
- * Start button.
- * Hardware compatibility.
- * Software compatibility.
- * Help etc.

Unix Operating Systems: Unix is computer O.S which is capable of handling activities from multiple users.

Unix was developed in 1969 by a group of AT & T employees as "Ken Thompson, Dennis Ritchie, Douglas McIlroy and Joe Bassanna" at Bell Labs.

The unix operating system is a set of programs that act as a link between the computer and the user.

Computer programs that allocate the system resources and co-ordinates all the details of the computer's internals is called the "Operating system (or) the Kernel".

* It is a multi user and multitasking operating system several users can use a unix O.S at the same time, each user can also run multiple programs at the same time.

* It has comparative complex functionality and hence an untrained user cannot use it only the one who was taken training can use this system.

Linux Operating system: Linux is one of popular version of unix operating system. It is open source as its source code is freely available. It is free to use. Linux was designed considering unix compatibility. Its functionality list can is quite similar to that of unix.