Counterdiabatic driving

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1 Introduction

Our Hamiltonian would be controlled using a control parameter called λ . Our aim would be drive the system without any transition.

2 Adiabatic gauge potential: derivation

Let Hamiltonian $H_0(\lambda(t))$ satisfy the following equation

$$H_0(\lambda(t))|\psi\rangle = i\partial_t |\psi\rangle \tag{1}$$

Let us go to rotating frame so as to diagonalize our Hamiltonian. Required unitary transformation $U(\lambda)$ would depend on parameter λ . Wave function in moving frame is $|\tilde{\psi}\rangle = U^{\dagger}|\tilde{\psi}\rangle$. In this basis, Hamiltonian is diagonal: $\tilde{H}_0 = U^{\dagger}H_0U = \sum_n \epsilon(\lambda)|n(\lambda)\rangle\langle n(\lambda)|$.

How does the wave function evolve in new basis?

$$i\partial_t |\tilde{\psi}\rangle = (\tilde{H}_0(\lambda(t)) - \dot{\lambda}\tilde{\mathcal{A}}_{\lambda})|\psi\rangle$$
 (2)

3 Free interacting fermions in an external potential

$$H_0 = -J \sum_{j=1}^{L-1} (c_j^{\dagger} c_{j+1} + c_{j+1}^{\dagger} c_j) + \sum_{j=1}^{L} V_j(\lambda) c_j^{\dagger} c_j$$
 (3)

$$\mathcal{A}_{\lambda}^{*} = i \sum_{j=1}^{L-1} \alpha_{j} (c_{j}^{\dagger} c_{j+1} - c_{j+1}^{\dagger} c_{j})$$
(4)

A Spin 1/2 particle in a time-dependent magnetic field

I would include a derivation from lecture notes to gain an intuition her. I also plan to understand Berry's paper and reproduce some of his calculations in this appendix.

¹Note that expectation value should remain same in both basis, i.e. $\langle \tilde{\psi} | \tilde{H_0} | \tilde{\psi} \rangle = \langle \psi | H_0 | \psi \rangle$