## What is NumPy, and why is it important in the Python ecosystem?

=> Numpy (Numerical Python) is a powerful library for scientific computing in Python, providing efficient storage and manipulation of large datasets.

#### Important of Numpy are as below:

- 1. Efficient numerical operations:NumPy provides high-performance multidimensional array objects and functions for efficient numerical computations.
- 2. Data manipulation: It offers powerful tools for manipulating arrays, such as slicing, indexing, reshaping, and broadcasting, which are essential for data preprocessing and analysis.
- 3. Integration with other libraries: NumPy seamlessly integrates with many other libraries and frameworks in the scientific computing ecosystem, such as SciPy, pandas, and scikit-learn.
- 4. Performance optimization: NumPy's array-oriented computing paradigm and implementation in optimized C code lead to faster execution compared to traditional Python lists.
- 5. Foundation for scientific computing: It serves as a foundational library for scientific computing in Python, providing the building blocks for implementing algorithms in areas like mathematics, statistics, physics, and engineering.

# Difference between numpy array and python list

=> The following table shows the difference between numpy array and python list:

Aspect	NumPy Arrays	Python Lists
Data Structure	Homogeneous (same data type for all elements)	Heterogeneous (can contain elements of different types)
Memory Usage	More memory-efficient due to contiguous storage	Less memory-efficient due to overhead and fragmentation
Speed/Performance	Faster execution for numerical operations	Slower for numerical computations, especially with large datasets

Functionality	Optimized for numerical computations with extensive mathematical functions	Č 1 1
Ease of use	May have a steeper learning curve but powerful for numerical tasks	1 7

Time complexity comparison of NumPy arrays and Python list:

```
[1] import numpy as np

[2] array_number = np.random.randint(low=1, high=50, size=50000)
    list_number = array_number.tolist()

    # checking computing time
    XXtime
    cb = [item ** 3 for item in list_number ]XXtime

    CPU times: user 20.3 ms, sys: 2.74 ms, total: 23 ms
    Wall time: 25.6 ms

[4] XXtime
    cb = array_number ** 3

CPU times: user 1.27 ms, sys: 887 μs, total: 2.16 ms
```

Here, array\_number take 1.59ms to calculate cube where list\_number takes 25.6 ms to calculate cube. Hence, numpy array operation is faster than python list

#### Explain the following with appropriate examples:

1. np.empty:

"np.empty" is a function provided by the NumPy library in Python. It creates an uninitialized array of specified shape and data type, but its elements are not initialized.

Syntax:

## numpy.empty(shape, dtype=float, order='C', \*, like=None)

Return a new array of given shape and type, without initializing entries.

```
import numpy as np

# Create an empty array of shape (3, 4)
empty_array = np.empty((3, 4))

print(empty_array)

[[4.76585388e-310 0.00000000e+000 0.00000000e+000 0.00000000e+000]
[0.00000000e+000 0.00000000e+000 0.00000000e+000]
[0.00000000e+000 0.00000000e+000 0.00000000e+000]
[0.00000000e+000 0.00000000e+000 0.00000000e+000]]
```

## 2. np.arange:

"np.arange" is a function provided by the NumPy library in Python. It creates an array containing evenly spaced values within a specified range.

Syntax:

numpy.arange([start, ]stop, [step, ]dtype=None, \*, like=None)

Return evenly spaced values within a given interval.

```
import numpy as np

# Create an array containing values from 0 to 9
array = np.arange(10)

print(array)

[0 1 2 3 4 5 6 7 8 9]
```

## 3. np.eye:

"np.eye" is a function provided by the NumPy library in Python. It is used to create a 2-dimensional array (or matrix) with diagonal elements set to 1 and the remaining elements set to 0.

Syntax:

numpy.eye(N, M=None, k=0, dtype=<class 'float'>, order='C', \*, device=None, like=None)

Return a 2-D array with ones on the diagonal and zeros elsewhere.

```
import numpy as np

# Create a 3x3 identity matrix
identity_matrix = np.eye(3)

print(identity_matrix)

[[1. 0. 0.]
  [0. 1. 0.]
  [0. 0. 1.]]
```

## 4. Np.linspace:

np.linspace is a function provided by the NumPy library in Python. It is used to create an array of evenly spaced numbers over a specified interval.

## Syntax:

# numpy.linspace(start, stop, num=50, endpoint=True, retstep=False, dtype=None, axis=0)

Return evenly spaced numbers over a specified interval.

Returns num evenly spaced samples, calculated over the interval [start, stop].

The endpoint of the interval can optionally be excluded.

```
import numpy as np
# Create an array of 10 evenly spaced numbers between 0 and 1
array = np.linspace(0, 1, num=10)
print(array)

[0.      0.11111111   0.22222222   0.33333333   0.444444444   0.55555556
      0.666666667   0.77777778   0.888888889   1.  ]
```

## 5. Shape vs reshape:

#### Shape:

- shape refers to the dimensions (or size) of an array. It is a tuple indicating the number of elements along each dimension of the array.
- For example, for a 2D array with 3 rows and 4 columns, the shape would be (3, 4).

# Reshape:

- reshape is a method in NumPy used to change the shape of an array without changing its data. It returns a new array with a modified shape.
- The total number of elements in the original array must be the same as the total number of elements in the reshaped array, otherwise, a ValueError will be raised.
- Reshaping does not change the original array; it returns a new array with the specified shape.

Here's an example demonstrating the difference between shape and reshape:

```
import numpy as np
# Creating an array with shape (3, 4)
arr = np.array([[1, 2, 3, 4],
print("Original array:")
print(arr)
print("Shape of the array:", arr.shape)
# Reshaping the array to shape (2, 6)
reshaped_arr = arr.reshape(2, 6)
print("\nReshaped array:")
print(reshaped_arr)
print("Shape of the reshaped array:", reshaped_arr.shape)
Original array:
[[ 1 2 3 4]
[ 5 6 7 8]
 [ 9 10 11 12]]
Shape of the array: (3, 4)
Reshaped array:
[[ 1 2 3 4 5 6]
[ 7 8 9 10 11 12]]
Shape of the reshaped array: (2, 6)
```

## 6. Broadcasting:

Broadcasting is a concept in NumPy that allows arrays of different shapes to be combined in arithmetic operations. It enables efficient computation and reduces the need for explicit looping over array elements.

## 7. Numpy stacking:

NumPy stacking refers to the process of combining multiple arrays along a new axis to create a new array. It allows you to stack arrays horizontally or vertically to form a larger array.

NumPy provides several functions for stacking arrays, including np.vstack() for vertical stacking and np.hstack() for horizontal stacking.

Here's a brief overview of each stacking function:

Vertical stacking (np.vstack()):

- np.vstack() stacks arrays vertically, meaning it combines arrays along the vertical axis (rows).
- The arrays being stacked must have the same number of columns (i.e., the same shape along the second axis).
- It creates a new array with the stacked arrays placed one below the other.

Horizontal stacking (np.hstack()):

- np.hstack() stacks arrays horizontally, meaning it combines arrays along the horizontal axis (columns).
- The arrays being stacked must have the same number of rows (i.e., the same shape along the first axis).
- It creates a new array with the stacked arrays placed side by side.

Here's an example demonstrating both vertical and horizontal stacking:

```
import numpy as np
array2 = np.array([[7, 8, 9],
                   [10, 11, 12]])
vertical_stack = np.vstack((array1, array2))
print("Vertical Stack:")
print(vertical_stack)
# Horizontal stacking
horizontal_stack = np.hstack((array1, array2))
print("\nHorizontal Stack:")
print(horizontal_stack)
Vertical Stack:
[[ 1 2 3]
[ 4 5 6]
[ 7 8 9]
 [10 11 12]]
Horizontal Stack:
[[ 1 2 3 7 8 9]
[ 4 5 6 10 11 12]]
```

## 8. np.block:

np.block is a function provided by the NumPy library in Python that allows you to construct arrays by stacking blocks of arrays along different dimensions. It provides more flexibility than np.vstack() and np.hstack() as it allows for the creation of multi-dimensional arrays by combining arrays of different shapes and sizes. Syntax:

## numpy.block(arrays)

Assemble an nd-array from nested lists of blocks.

```
import numpy as np

# Create individual arrays
A = np.array([[1, 2], [3, 4]])
B = np.array([[5, 6], [7, 8]])
C = np.array([[9, 10]])

# Stack the arrays using np.block
result = np.block([[A, B], [C, C]])
print(result)

[[ 1  2  5  6]
  [ 3  4  7  8]
  [ 9 10  9 10]]
```

## 9. np.hsplit VS np.vsplit VS np.dsplit:

- a. np.hsplit (Horizontal Split):
  - i. np.hsplit is a function in NumPy used to split an array horizontally along its horizontal axis (axis 1), resulting in multiple sub-arrays.
  - ii. The syntax is np.hsplit(array, indices or sections).
  - iii. array: The array to be split.
  - iv. indices\_or\_sections: Either an integer specifying the number of equally-sized sub-arrays to create, or a list of indices at which to split the array.
  - v. It returns a list of sub-arrays.
- b. np.vsplit (Vertical Split):
  - i. np.vsplit is a function in NumPy used to split an array vertically along its vertical axis (axis 0), resulting in multiple sub-arrays.
  - ii. The syntax is np.vsplit(array, indices or sections).
  - iii. array: The array to be split.

- iv. indices\_or\_sections: Either an integer specifying the number of equally-sized sub-arrays to create, or a list of indices at which to split the array.
- v. It returns a list of sub-arrays.
- c. np.dsplit (Depth Split):
  - i. np.dsplit is a function in NumPy used to split an array along its third dimension (depth-wise), resulting in multiple sub-arrays.
  - ii. The syntax is **np.dsplit(array, indices\_or\_sections).**
  - iii. array: The 3D array to be split.
  - iv. indices\_or\_sections: Either an integer specifying the number of equally-sized sub-arrays to create, or a list of indices at which to split the array.
  - v. It returns a list of sub-arrays.

Here's an example demonstrating the usage of these functions:

```
import numpy as np
# Create a 2D array
array = np.array([[1, 2, 3],
                 [4, 5, 6],
                  [7, 8, 9]])
# Horizontal split
horizontal split = np.hsplit(array, 3) # Split into 3 equal parts along axis 1
print("Horizontal split:")
print(horizontal split)
# Vertical split
vertical split = np.vsplit(array, 3) # Split into 3 equal parts along axis 0
print("\nVertical split:")
print(vertical split)
# Create a 3D array
array_3d = np.arange(27).reshape(3, 3, 3)
# Depth split
depth split = np.dsplit(array_3d, 3) # Split into 3 equal parts along the third dimension
print("\nDepth split:")
print(depth split)
```

```
Depth split:
[array([[[ 0],
         [3],
[6]],
        [[ 9],
         [12],
         [15]],
        [[18],
         [21],
         [24]]]), array([[[ 1],
         [ 4],
[ 7]],
        [[10],
         [13],
        [16]],
        [[19],
         [22],
         [25]]]), array([[[ 2],
        [ 5],
[ 8]],
        [[11],
         [14],
        [17]],
        [[20],
         [23],
[26]]])]
```

#### 10. np.searchsorted:

np.searchsorted is a function provided by the NumPy library in Python. It is used to find the indices where elements should be inserted into a sorted array to maintain the order of the array.

Syntax:

## numpy.searchsorted(a, v, side='left', sorter=None)

Find indices where elements should be inserted to maintain order.

```
import numpy as np

# Create a sorted array
sorted_array = np.array([10, 20, 30, 40, 50])

# Values to be inserted
values = np.array([25, 35, 45])

# Find insertion points for values in the sorted array
insertion_points = np.searchsorted(sorted_array, values)

print("Insertion points:", insertion_points)
```

#### 11. np.sort and argsort:

- a. np.sort:
  - i. np.sort is a function used to sort elements of an array along a specified axis.
  - ii. The syntax is np.sort(array, axis=-1, kind='quicksort', order=None).
  - iii. array: The input array to be sorted.
  - iv. axis: Optional. The axis along which to sort the array. Default is -1, indicating the last axis.
  - v. kind: Optional. The sorting algorithm to be used. Default is 'quicksort'.
  - vi. order: Optional. If the array is structured (i.e., it has fields defined), this parameter specifies the field(s) to use when sorting.
  - vii. It returns a new array containing the sorted elements.

#### b. np.argsort:

- i. np.argsort is a function used to return the indices that would sort an array.
- ii. The syntax is **np.argsort(array, axis=-1, kind='quicksort', order=None)**.
- iii. array: The input array to be sorted.
- iv. axis: Optional. The axis along which to sort the array. Default is -1, indicating the last axis.
- v. kind: Optional. The sorting algorithm to be used. Default is 'quicksort'.
- vi. order: Optional. If the array is structured (i.e., it has fields defined), this parameter specifies the field(s) to use when sorting.
- vii. It returns an array of indices that would sort the input array.

Here's an example illustrating the usage of np.sort and np.argsort:

```
import numpy as np

# Create an array
array = np.array([4, 2, 1, 3, 5])

# Sorting the array
sorted_array = np.sort(array)
print("Sorted array:", sorted_array)

# Indices that would sort the array
indices = np.argsort(array)
print("Indices that would sort the array:", indices)

Sorted array: [1 2 3 4 5]
Indices that would sort the array: [2 1 3 0 4]
```

## 12. np.flatten vs np.ravel:

- a. np.flatten:
  - i. np.flatten is a method of NumPy arrays that returns a copy of the array collapsed into one dimension.
  - ii. The syntax is array.flatten(order='C').
  - iii. array: The input array to be flattened.
  - iv. order: Optional. Specifies the order of flattening. It can be 'C' (row-major, default) or 'F' (column-major).
  - v. It returns a one-dimensional copy of the input array, and modifying the flattened array does not affect the original array.

#### b. np.ravel:

- i. np.ravel is a function in NumPy that returns a flattened array without making a copy if possible. If a copy is required, it returns one.
- ii. The syntax is np.ravel(array, order='C').
- iii. array: The input array to be flattened.
- iv. order: Optional. Specifies the order of flattening. It can be 'C' (row-major, default) or 'F' (column-major).
- v. It returns a one-dimensional view of the input array, and modifying the flattened array may affect the original array.

Here's an example illustrating the usage of np.flatten and np.ravel:

```
import numpy as np
# Create a 2D array
array = np.array([[1, 2, 3],
                 [4, 5, 6]])
# Flatten the array using np.flatten
flattened_array_flatten = array.flatten()
print("Flattened array using np.flatten:")
print(flattened_array_flatten)
# Flatten the array using np.ravel
flattened array ravel = np.ravel(array)
print("\nFlattened array using np.ravel:")
print(flattened array ravel)
Flattened array using np.flatten:
[1 2 3 4 5 6]
Flattened array using np.ravel:
[1 2 3 4 5 6]
```

## 13. Np.shuffle:

"np.shuffle" is a function provided by NumPy that shuffles the elements of an array in-place, meaning it modifies the original array. This function randomly reorders the elements along the first axis of the array.

Syntax:

```
import numpy as np

# Create an array
array = np.array([1, 2, 3, 4, 5])

# Shuffle the array in-place
np.random.shuffle(array)

print("Shuffled array:", array)

Shuffled array: [3 5 4 2 1]
```

#### random.shuffle(x)

Modify a sequence in-place by shuffling its contents.

# 14. np.unique:

"np.unique" is a function provided by NumPy that returns the unique elements of an array. It returns the sorted unique elements of an array along with the indices that can be used to reconstruct the original array.

Syntax:

numpy.unique(ar, return\_index=False, return\_counts=False, axis=None, \*, equal\_nan=True)

Find the unique elements of an array.

```
import numpy as np

# Create an array with duplicate elements
array = np.array([1, 2, 2, 3, 3, 4, 4, 5])

# Find unique elements
unique_elements = np.unique(array)
print("Unique elements:", unique_elements)

# Find unique elements along with their counts
unique_elements, counts = np.unique(array, return_counts=True)
print("Unique elements with counts:", unique_elements)
print("Counts:", counts)

Unique elements: [1 2 3 4 5]
Unique elements with counts: [1 2 3 4 5]
Counts: [1 2 2 2 1]
```

#### 15. np.resize:

np.resize is a function provided by NumPy that changes the shape of an array without changing its data. It can increase or decrease the size of the array as needed, either by adding elements or by removing them.

Syntax:

#### numpy.resize(a, new shape)

Return a new array with the specified shape.

```
import numpy as np
# Create an array
array = np.array([[1, 2], [3, 4]])
# Resize the array to a larger size
larger_array = np.resize(array, (3, 3))
print("Larger array:")
print(larger_array)
# Resize the array to a smaller size
smaller_array = np.resize(array, (1, 1))
print("\nSmaller array:")
print(smaller_array)
Larger array:
[[1 2 3]
[4 1 2]
 [3 4 1]]
Smaller array:
[[1]]
```

#### 16. Transpose VS Swapaxes:

Transpose (transpose):

- transpose is a method of NumPy arrays used to permute the dimensions of an array.
- The syntax is array.transpose(\*axes).
- array: The input array to be transposed.
- \*axes: Optional. The new order of dimensions. By default, the axes are reversed.
- It returns a view of the input array with its axes permuted according to the specified order.

Swapaxes (swapaxes):

- swapaxes is a method of NumPy arrays used to swap the two specified axes of an array.
- The syntax is array.swapaxes(axis1, axis2).
- array: The input array to be operated on.
- axis1 and axis2: The two axes to be swapped.
- It returns a view of the input array with the specified axes swapped.

Here's an example illustrating the usage of both transpose and swapaxes:

#### 17. Inverse:

In NumPy, the term "inverse" typically refers to finding the inverse of a square matrix. NumPy provides the function **np.linalg.inv()** to compute the inverse of a matrix.

#### 18. Power VS determinant:

Power of a Matrix:

- a. NumPy provides the numpy.linalg.matrix\_power() function to compute the power of a square matrix.
- b. The syntax is numpy.linalg.matrix power(matrix, n).
- c. matrix: The input square matrix.
- d. n: The exponent to which the matrix is raised.
- e. It returns the result of raising the input matrix to the power of n.

Here's an example of computing the power of a matrix using NumPy:

Determinant of a Matrix:

- a. NumPy provides the numpy.linalg.det() function to compute the determinant of a square matrix.
- b. The syntax is numpy.linalg.det(matrix).
- c. matrix: The input square matrix.
- d. It returns the determinant of the input matrix as a scalar value.

Here's an example of computing the determinant of a matrix using NumPy: