

# Sematic Segmentation using Resource Efficient Deep Learning

Naresh Kumar Gurulingan  
naresh.gurulingan@smail.inf.h-brs.de

Hochschule Bonn-Rhein-Sieg

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**Hochschule  
Bonn-Rhein-Sieg**  
University of Applied Sciences

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## Semantic segmentation

Divide an input image into different regions which contain a desired object or background.



*Left: Input image; Right: Segmentation result.*

# Applications

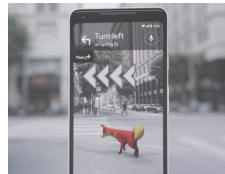
- a Autonomous cars
- b Robotics
- c Augmented reality



(a) Street scene

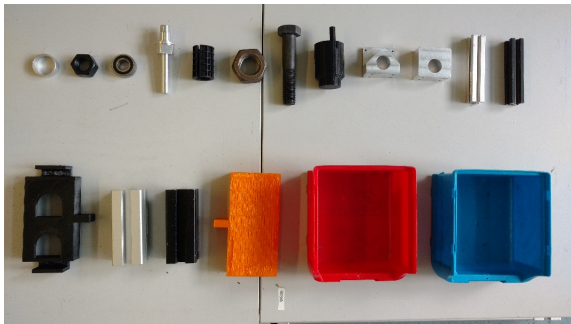


(b) Indoor scene



(c) Augmented guide

## Objects in the dataset



*This figure shows all the 18 objects in the dataset. First row from left: "distance\_tube", "m20", "bearing", "axis", "r20", "m30", "m20\_100", "motor", "bearing\_box\_ax16", "bearing\_box\_ax01", "f20\_20\_B", "f20\_20\_G". Second row from left: "em\_01", "s40\_40\_B", "s40\_40\_G", "em\_02", "container\_box\_red", "container\_box\_blue".*

# Annotation process

# Artificial image generation

# Dataset variants



# Dataset analysis







# Results

# Results

# Results

# Results



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## Contributions

- ▶ Artificial image generation algorithm.
- ▶ Segmentation dataset with 18 atWork objects.
- ▶ Evaluation of DeepLabv3+ with resource efficient encoders MobileNetv2 and Xception.

## Future work

- ▶ Model interpretability.
- ▶ Architecture search.
- ▶ Fusion of 2D image data with point cloud information.

Thank you very much!

Are there any questions?



# References