# American International University, Bangladesh



## **Data Communication**

Section: E

Semester: Summer 2021-22

**Course Instructor:** Tanjil Amin

Experiment no: 01

**Experiment Name:** Introduction to MATLAB

## Submitted by:

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So,

A=2

B=0

C=4

D=2

E=6

F=0

G=0

H=1

## Answer to the question no a:

## MATLAB code:

```
k1=2;
k2=3;
j1=(11*pi)/90;
j2=pi/6;
t=0:0.1001:4;
x1=k1*cos(2*pi*(11*t)+j1);
x2=k2*cos(2*pi*(11*t)+j2);
plot(t,x1)
xlabel2('Time');
ylabel('Amplitute');
title('x1=k1*cos(2*pi*(11*t)+j1);')
plot(t,x2)
title('x2=k2*cos(2*pi*(11*t)+j2);')
```

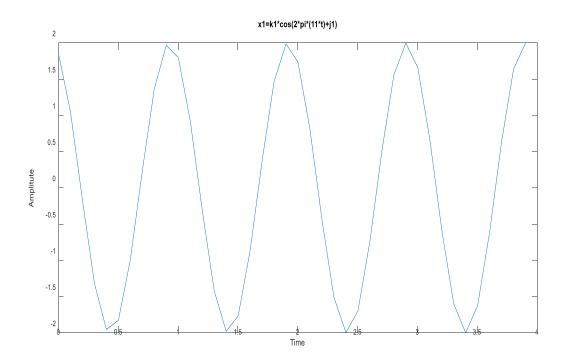


Fig 01: Signal of x1(t)

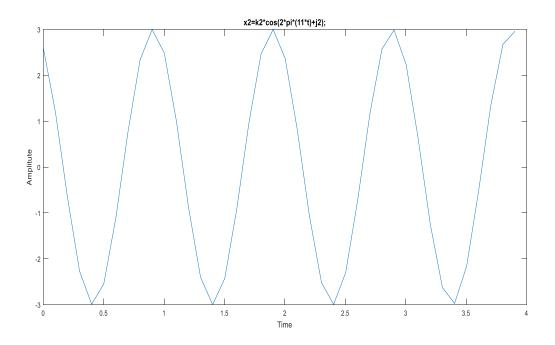


Fig 02: Signal of x2(t)

## Answer to the question no b:

### MATLAB Code:

```
k1=2;
k2=3;
j1=(11*pi)/90;
j2=pi/6;
t=0:0.1001:4;
x1=k1*cos(2*pi*(11*t)+j1);
x2=k2*cos(2*pi*(11*t)+j2);
%plot(t,x1)
%xlabel2('Time');
%ylabel('Amplitute');
title('x1=k1*cos(2*pi*(11*t)+j1);')
plot(t, x2)
title('x2=k2*cos(2*pi*(11*t)+j2);')
x3=x1+x2;
plot(t, x3)
title('x3=x1+x2')
```

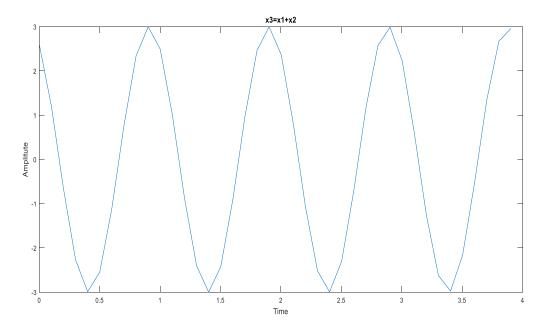


Fig 03: Signal of x3(t)

#### Answer to the question no c:

#### MATLAB Code:

```
k1=2;
k2=3;
j1=(11*pi)/90;
j2=pi/6;
t=0:0.1001:4;
x1=k1*cos(2*pi*(11*t)+j1);
x2=k2*cos(2*pi*(11*t)+j2);
%plot(t,x1)
%xlabel2('Time');
%ylabel('Amplitute');
title('x1=k1*cos(2*pi*(11*t)+j1);')
plot(t, x2)
title('x2=k2*cos(2*pi*(11*t)+j2);')
x3=x1+x2;
%plot(t,x3)
%title('x3=x1+x2')
subplot(3,1,1)
plot(t, x1)
title('x1=k1*cos(2*pi*(11*t)+j1);')
%xlabel1=('Time');
%ylabel1=('Amplitute');
subplot(3,1,2)
plot(t, x2)
xlabel2=('Time');
ylabel2=('Amplitute');
title('x2=k2*cos(2*pi*(11*t)+j2);')
subplot(3,1,3)
plot(t, x3)
xlabel3=('Time');
ylabel3=('Amplitute');
title('x3=x1+x2')
```

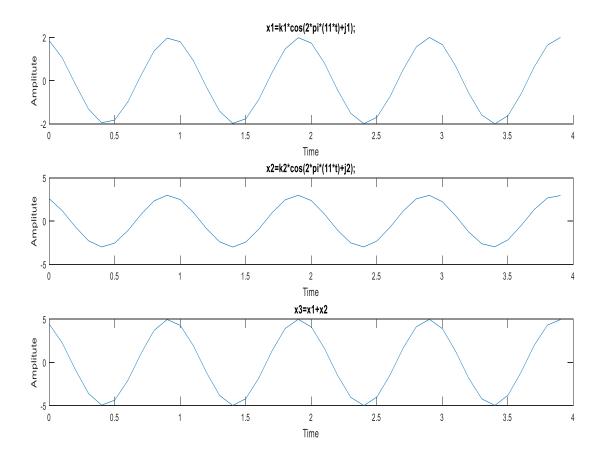


Fig 04: Signal using subplot