# BAYESIAN ANALYSIS OF VARS, STATE-SPACE MODELS AND DSGES PART II: PREDICTION, MODEL INFERENCE, DECISIONS

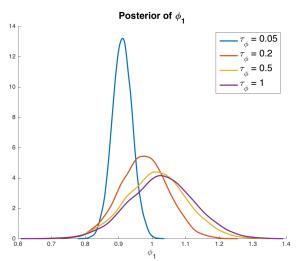
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#### LECTURE OVERVIEW

- ► Bayesian prediction
- ► Model comparison
- ► Model evaluation
- ► Bayesian decision making

# Univariate AR(4) posterior Foreign interest rate 1980Q2-2005Q4



#### MARGINALIZATION

- ▶ Wait! How could I plot  $p(\phi_1|y_1, ..., y_T)$  in the AR(4). What happend to  $\phi_2, \phi_3, \phi_4, c$  and  $\sigma^2$ ?
- ► Example: Regression model:

$$\mathbf{y}|\mathbf{X}, \boldsymbol{\beta} \sim N\left(\mathbf{X}\boldsymbol{\beta}, \sigma^2 I_n\right)$$
.

- ▶ Posterior  $p(\beta, \sigma^2 | \mathbf{y}, \mathbf{X})$  is a (k+1)-dimensional posterior distribution. Hard to visualize!
- ▶ Marginal posterior of  $\beta_i$

$$p(\beta_i|\mathbf{y},\mathbf{X}) = \int_{\beta_{-i}} \int_{\sigma^2} p(\beta,\sigma^2|\mathbf{y},\mathbf{X}) d\sigma^2 d\beta_{-i}$$

▶ Marginal posteriors are immediately available when we approximate the joint posterior by simulation (MCMC).

## PREDICTION/FORECASTING

► Example: Regression model:

$$\mathbf{y}|\mathbf{X}, \boldsymbol{\beta} \sim N(\mathbf{X}\boldsymbol{\beta}, \sigma^2 I_n)$$
.

**Posterior predictive distribution** for new observation  $\tilde{y}$  given  $\tilde{x}$  and estimation sample (y, X):

$$p(\tilde{y}|\tilde{\mathbf{x}},\mathbf{y},\mathbf{X}) = \int_{\beta} p(\tilde{y}|\tilde{\mathbf{x}},\beta) p(\beta|\mathbf{y},\mathbf{X}) d\beta$$

- ► The parameter uncertainty is represented in  $p(\tilde{y}|\tilde{x}, y, X)$  by averaging over posterior  $p(\beta|y, X)$ .
- ▶ It can be shown that  $p(\tilde{y}|\tilde{x}, y, X)$  is a student-t density.
- ▶ When the integral cannot be computed analytically: simulation!

# EXAMPLE: BAYESIAN PREDICTION IN STEADY-STATE AR PROCESSES

► Autoregressive process

$$y_t = \phi_1(y_{t-1} - \mu) + ... + \phi_p(y_{t-p} - \mu) + \varepsilon_t, \ \varepsilon_t \stackrel{iid}{\sim} N(0, \sigma^2)$$

- ▶ Simulate a draw from  $p(\phi_1, \phi_2, ..., \phi_p, \mu, \sigma|y)$  [Gibbs sampling, Part III]
  - ► Conditional on that draw  $\theta^{(1)} = (\phi_1^{(1)}, \phi_2^{(1)}, ..., \phi_p^{(1)}, \mu^{(1)}, \sigma^{(1)})$ , simulate
  - $\tilde{y}_{T+1} \sim p(y_{T+1}|y_T, y_{T-1}, ..., y_{T-p}, \theta^{(1)})$
  - $\tilde{y}_{T+2} \sim p(y_{T+2}|\tilde{y}_{T+1}, y_T, ..., y_{T-p}, \theta^{(1)})$
  - and so on.
- ightharpoonup Repeat for new  $\theta$  draws.

## BAYESIAN MODEL COMPARISON [1]

- ▶ Consider two models for the data  $\mathbf{y} = (y_1, ..., y_n)$ :  $M_1$  and  $M_2$ .
- **Estimated likelihoods**  $p_1(\mathbf{y}|\hat{\theta}_1)$  and  $p_2(\mathbf{y}|\hat{\theta}_2)$  can not be used directly for model comparison. Bigger models always win.
- **B** Bayesian: the marginal likelihood for model  $M_k$  with parameters  $\theta_k$

$$p(\mathbf{y}|M_k) = \int p_k(\mathbf{y}|\theta_k) p_k(\theta_k) d\theta_k.$$

- $\blacktriangleright$   $\theta_k$  is "removed" by the prior. Not a magic bullet. Priors matter!
- Often reported on log scale:
  - ▶ Strong evidence for  $M_1$  if  $3 < \ln p(y|M_1) \ln p(y|M_2) \le 5$
  - ▶ Very strong evidence for  $M_1$  if  $\ln p(y|M_1) \ln p(y|M_2) > 5$ .

## DSGE EXAMPLE [2]

Parameter	Prior distribution		Posterior distributions										
			Instrument rule without policy break		Fixed exchange rate rule		Semi-fixed exchange rate rule		Instrument rule with policy break				
	Type	Mean	Std. dev./df	Median	Std.	Median	Std.	Median	Std.	UIP		Modifie	d UIP
										Median	Std.	Median	Std.
Calvo wages ξ <sub>w</sub>	beta	0.750	0.050	0.751	0.047	0.518	0.041	0.669	0.046	0.743	0.049	0.752	0.049
Calvo domestic prices $\xi_d$	beta	0.750	0.050	0.862	0.046	0.852	0.048	0.885	0.027	0.868	0.044	0.838	0.044
Calvo import cons. prices ξ <sub>me</sub>	beta	0.750	0.050	0.896	0.017	0.922	0.013	0.900	0.014	0.900	0.017	0.901	0.017
Calvo import inv. prices $\xi_{mi}$	beta	0.750	0.050	0.946	0.010	0.948	0.008	0.943	0.007	0.946	0.010	0.944	0.010
Calvo export prices $\xi_x$	beta	0.750	0.050	0.868	0.021	0.870	0.016	0.874	0.020	0.869	0.021	0.883	0.020
Indexationwages Kw	beta	0.500	0.150	0.290	0.098	0.238	0.086	0.287	0.098	0.292	0.100	0.313	0.103
Indexation prices $\kappa_d$	beta	0.500	0.150	0.213	0.059	0.163	0.069	0.194	0.052	0.212	0.061	0.218	0.061
					:								
Output response $r_{v,1}$	normal	0.125	0.050	0.129	0.046			0.216	0.051	0.113	0.044	0.138	0.048
Diff. output response $r_{\Delta v, 1}$	normal	0.063	0.050	0.152	0.036			0.142	0.050	0.127	0.041	0.120	0.046
Monetary policy shock $\sigma_{R,1}$	invgamma	0.150	2	0.249	0.024			2.335	0.778	0.398	0.060	0.398	0.066
Inflation target shock σ <sub>g</sub> c <sub>1</sub>	invgamma	0.050		0.116	0.041			0.083	0.054	0.148	0.067		0.085
Interest rate smoothing $\rho_B$ ,	beta	0.800	0.050			0.884	0.018	0.864	0.021	0.896	0.018	0.874	0.022
Inflation response $r_{\pi,2}$	truncnormal	1.700	0.100			1.725	0.090	1 747	0.089	1 709	0.099	1.718	0.097
Diff. infl response $r_{\Delta \pi}$ ?	normal	0.300				0.127	0.023	0.143	0.025	0.104	0.026		
Real exch. rate response $r_{x,2}$	normal	0.000				0.022	0.019	-0.001	0.003	0.038	0.026		
Output response r <sub>v,2</sub>	normal	0.125				0.269	0.040	0.274	0.039	0.107	0.041		0.041
Diff. output response $r_{\Delta v,2}$	normal	0.063	0.050			0.099	0.031	0.107	0.030	0.104	0.030	0.105	0.030
Monetarypolicy shock $\sigma_{R,2}$	invgamma	0.150				0.102	0.013	0.094	0.011	0.104	0.013		
Inflation target shock $\sigma_{4^c,2}$	invgamma	0.050				0.065	0.030	0.069	0.035	0.080	0.038		0.038
Log marginal likelihood				-2285.8		-2636.7	12	-2348.2	4	-2268.	33	-2252.	57

#### **BAYESIAN MODEL COMPARISON**

► The Bayes factor

$$B_{12}(y) = \frac{p(\mathbf{y}|M_1)}{p(\mathbf{y}|M_2)}.$$

Posterior model probabilities

$$\underbrace{\Pr(M_k|\mathbf{y})}_{\text{posterior model prob.}} \propto \underbrace{p(\mathbf{y}|M_k)}_{\text{marginal likelihood prior model prob.}} \cdot \underbrace{\Pr(M_k)}_{\text{prior model prob.}}$$

where

$$p(\mathbf{y}|M_k) = \int p_k(\mathbf{y}|\theta_k) p_k(\theta_k) d\theta_k.$$

- ► Two different priors:
  - priors over the models  $Pr(M_k)$
  - prior  $p_k(\theta_k)$  for the parameters  $\theta_k$  within model  $M_k$ .

## MODEL CHOICE IN MULTIVARIATE TIME SERIES [3]

Multivariate time series

$$\mathbf{x}_t = \alpha \beta' \mathbf{z}_t + \Phi_1 \mathbf{x}_{t-1} + ... \Phi_k \mathbf{x}_{t-k} + \Psi_1 + \Psi_2 t + \Psi_3 t^2 + \varepsilon_t$$

- ► Need to choose:
  - ▶ Lag length, (k = 1, 2..., 4)
  - ▶ **Trend model** (s = 1, 2, ..., 5)
  - ▶ Long-run (cointegration) relations (r = 0, 1, 2, 3, 4).

THE MOST PROF	BABLE	(k, r, s)	COM	BINATI	ONS IN	THE	Danish	MON	ETARY	DATA.
k	1	1	1	1	1	1	1	1	0	1
r	3	3	2	4	2	1	2	3	4	3
s	3	2	2	2	3	3	4	4	4	5
p(k, r, s y, x, z)	.106	.093	.091	.060	.059	.055	.054	.049	.040	.038

### **EXAMPLE: GEOMETRIC VS POISSON**

- ► Model 1 **Geometric** with Beta prior:
  - $ightharpoonup y_1,...,y_n|\theta_1 \sim Geo(\theta_1)$
  - $\theta_1 \sim Beta(\alpha_1, \beta_1)$
- ► Model 2 Poisson with Gamma prior:
  - $y_1, ..., y_n | \theta_2 \sim Poisson(\theta_2)$
  - $\theta_2 \sim Gamma(\alpha_2, \beta_2)$
- ightharpoonup Marginal likelihood for  $M_1$

$$p_1(y_1, ..., y_n) = \int p_1(y_1, ..., y_n | \theta_1) p(\theta_1) d\theta_1$$

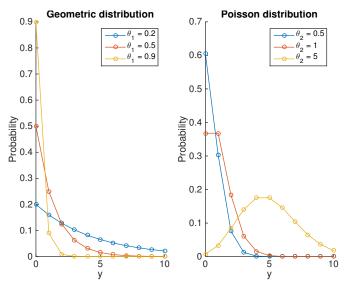
$$= \frac{\Gamma(\alpha_1 + \beta_1)}{\Gamma(\alpha_1) \Gamma(\beta_1)} \frac{\Gamma(n + \alpha_1) \Gamma(n\bar{y} + \beta_1)}{\Gamma(n + n\bar{y} + \alpha_1 + \beta_1)}$$

► Marginal likelihood for M<sub>2</sub>

$$p_2(y_1,...,y_n) = \frac{\Gamma(n\bar{y} + \alpha_2)\beta_2^{\alpha_2}}{\Gamma(\alpha_2)(n + \beta_2)^{n\bar{y} + \alpha_2}} \frac{1}{\prod_{i=1}^n y_i!}$$



### GEOMETRIC AND POISSON



## GEOMETRIC VS POISSON, CONT.

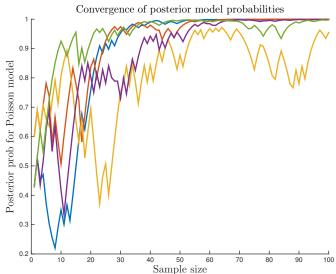
Priors match prior predictive means:

$$E(y_i|M_1) = E(y_i|M_2) \iff \alpha_1\alpha_2 = \beta_1\beta_2$$

**Data**:  $y_1 = 0$ ,  $y_2 = 0$ .

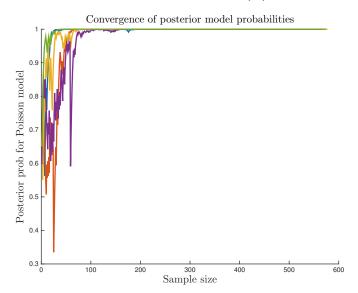
Data: $y_1 = 3$ , $y_2 = 3$ .							
	$\alpha_1 = 1, \beta_1 = 2$	$lpha_1=1$ 0, $eta_1=2$ 0	$\alpha_1 = 100, \beta_1 = 200$				
	$\alpha_2 = 2$ , $\beta_2 = 1$	$lpha_2=$ 20, $eta_2=$ 10	$\alpha_2 = 200, \beta_2 = 100$				
$BF_{12}$	0.26	0.29	0.30				
$\Pr(M_1 \mathbf{y})$	0.21	0.22	0.23				
$\Pr(M_2 \mathbf{y})$	0.79	0.78	0.23 0.77 <b>VOID</b>				

## GEOMETRIC VS POISSON FOR POIS(1) DATA





## GEOMETRIC VS POISSON FOR POIS(1) DATA



#### PROPERTIES OF BAYESIAN MODEL COMPARISON

▶ Consistency when true model is in  $\mathcal{M} = \{M_1, ..., M_K\}$ 

$$\Pr\left(M = M_{TRUE}|\mathbf{y}\right) \to 1 \quad \text{as} \quad n \to \infty$$

▶ "KL-consistency" when  $M_{TRUE} \notin \mathcal{M}$ 

$$\Pr\left(M = M^* | \mathbf{y}\right) \to 1 \quad \text{as} \quad n \to \infty$$

where  $M^*$  is the model that minimizes Kullback-Leibler distance between  $p_M(\mathbf{y})$  and  $p_{TRUF}(\mathbf{y})$ .

- 1. Smaller models always win when priors are very vague.
- ▶ Improper priors can't be used for model comparison.



# MARGINAL LIKELIHOOD MEASURES OUT-OF-SAMPLE PREDICTIVE PERFORMANCE

► The marginal likelihood can be decomposed as

$$p(y_1,...,y_n) = p(y_1)p(y_2|y_1)\cdots p(y_n|y_1,y_2,...,y_{n-1})$$

▶ If we assume that  $y_i$  is independent of  $y_1, ..., y_{i-1}$  conditional on  $\theta$ :

$$p(y_i|y_1,...,y_{i-1}) = \int p(y_i|\theta)p(\theta|y_1,...,y_{i-1})d\theta$$

- ▶ The prediction of  $y_1$  is based on the prior of  $\theta$ , and is therefore sensitive to the prior.
- ▶ The prediction of  $y_n$  uses almost all the data to infer  $\theta$ . Very little influenced by the prior when n is not small.

#### NORMAL EXAMPLE

- ▶ Model:  $y_1, ..., y_n | \theta \sim N(\theta, \sigma^2)$  with  $\sigma^2$  known.
- ▶ Prior:  $\theta | \sigma^2 \sim N(0, \kappa^2 \sigma^2)$ .
- ▶ Intermediate posterior at time i-1

$$\theta | y_1, ..., y_{i-1} \sim N \left[ w_i(\kappa) \cdot \bar{y}_{i-1}, \frac{\sigma^2}{i - 1 + \kappa^{-2}} \right]$$

where  $w_i(\kappa) = \frac{i-1}{i-1+\kappa^{-2}}$ .

ightharpoonup Predictive density at time i-1

$$y_i|y_1,...,y_{i-1} \sim N\left[w_i(\kappa) \cdot \bar{y}_{i-1}, \sigma^2\left(1 + \frac{1}{i-1+\kappa^{-2}}\right)\right]$$

- ► Terms with *i* large:  $y_i|y_1,...,y_{i-1} \stackrel{approx}{\sim} N(\bar{y}_{i-1},\sigma^2)$ , not sensitive to  $\kappa$
- For i=1,  $y_1\sim N\left[0,\sigma^2\left(1+\frac{1}{\kappa^{-2}}\right)
  ight]$  can be very sensitive to N



## LOG PREDICTIVE SCORE - LPS [4, 5]

- ▶ To reduce sensitivity to the prior: sacrifice  $n^*$  observations to train the prior into a better posterior.
- ► Predictive density score: PS

$$PS(n^*) = p(y_{n^*+1}|y_1,...,y_{n^*}) \cdots p(y_n|y_1,...,y_{n-1})$$

- Usually report on log scale: Log Predictive Score (LPS).
- ▶ But which observations to train on (and which to test on)?
- Straightforward for time series.
- ► Cross-sectional data: cross-validation.

#### MODEL AVERAGING

- Let  $\gamma$  be a quanitity with an interpretation which stays the same across the two models.
- ▶ Example: Prediction  $\gamma = (y_{T+1}, ..., y_{T+h})'$ .
- ightharpoonup The marginal posterior distribution of  $\gamma$  reads

$$p(\gamma|\mathbf{y}) = p(M_1|\mathbf{y})p_1(\gamma|\mathbf{y}) + p(M_2|\mathbf{y})p_2(\gamma|\mathbf{y}),$$

where  $p_k(\gamma|\mathbf{y})$  is the marginal posterior of  $\gamma$  conditional on model k.

- Predictive distribution includes three sources of uncertainty:
  - ▶ Future errors/disturbances (e.g. the  $\varepsilon$ 's in a regression)
  - ► Parameter uncertainty (the predictive distribution has the parameters integrated out by their posteriors)
  - Model uncertainty (by model averaging)

## DECOMPOSE PREDICTION UNCERTAINTY - DSGE [6]

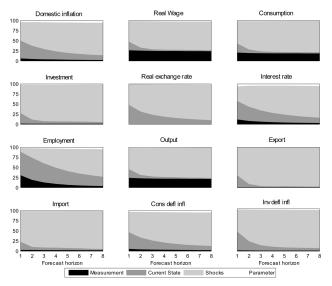


FIGURE 4 Decomposition of the forecast uncertainty. The subgraphs display the relative contribution to the predictive variances of the observed variables at different forecast horizons.

#### BAYESIAN FORECAST AVERAGING

- Available: forecasts  $\hat{x}_{t+h|t}^{(1)},...,\hat{x}_{t+h|t}^{(k)}$  from k different institutes/models.
- ▶ How to combine the forecasts to a single forecast?
- Bayesian solution assuming

$$\hat{\mathbf{x}}_{t+h|t}^{(1)} \sim N\left(x_t \mathbf{1}, \Sigma\right)$$

where  $\Sigma$  describes the covariance between institutes' forecasts.

► Optimal forecast combination [7, 8]:

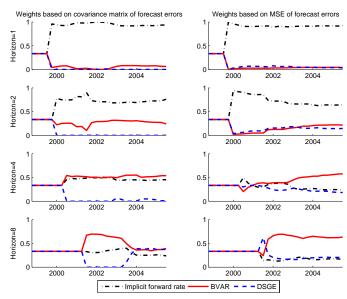
$$\sum_{j=1}^{K} w_{jt} \hat{x}_{t+h|t}^{(j)}$$

$$(w_{1t}, w_{2t}, ..., w_{kt}) = \frac{\mathbf{1}' \tilde{\Sigma}_{t}^{-1}}{\mathbf{1}' \tilde{\Sigma}_{t}^{-1} \mathbf{1}}$$

$$\tilde{\Sigma}_{t} = \frac{v}{t+V} \Sigma_{0} + \frac{t}{t+V} \hat{\Sigma}_{t},$$



#### BAYESIAN FORECAST AVERAGING





#### COMPUTING THE MARGINAL LIKELIHOOD

► Usually difficult to evaluate the integral

$$p(\mathbf{y}) = \int p(\mathbf{y}|\theta)p(\theta)d\theta = E_{p(\theta)}[p(\mathbf{y}|\theta)].$$

▶ Draw from the prior  $\theta^{(1)}, ..., \theta^{(N)}$  and use the Monte Carlo estimate

$$\hat{\rho}(\mathbf{y}) = \frac{1}{N} \sum_{i=1}^{N} \rho(\mathbf{y} | \theta^{(i)}).$$

Unstable if the posterior is somewhat different from the prior.

▶ Importance sampling. Let  $\theta^{(1)}$ , ...,  $\theta^{(N)}$  be iid draws from  $g(\theta)$ .

$$\int p(\mathbf{y}|\theta)p(\theta)d\theta = \int \frac{p(\mathbf{y}|\theta)p(\theta)}{g(\theta)}g(\theta)d\theta \approx N^{-1}\sum_{i=1}^{N} \frac{p(\mathbf{y}|\theta^{(i)})p(\theta^{(i)})}{g(\theta^{(i)})}$$

▶ Modified Harmonic mean:  $g(\theta) = N(\tilde{\theta}, \tilde{\Sigma}) \cdot I_c(\theta)$ , where  $\tilde{\theta}$  and  $\tilde{\Sigma}$  is the posterior mean and covariance matrix estimated from an MCMC chain, and  $I_c(\theta) = 1$  if  $(\theta - \tilde{\theta})'\tilde{\Sigma}^{-1}(\theta - \tilde{\theta}) \leq c$ .

#### APPROXIMATE MARGINAL LIKELIHOODS

► The Laplace approximation:

$$\ln \hat{p}(\mathbf{y}) = \ln p(\mathbf{y}|\hat{\theta}) + \ln p(\hat{\theta}) + \frac{1}{2} \ln |\Sigma| + \frac{p}{2} \ln(2\pi),$$

where  $\Sigma = -H^{-1}$  and p is the number of unrestricted parameters in the model.

- Note that  $\hat{\theta}$  and H can be obtained with **numerical optimization** with BFGS update of Hessian.
- ► The BIC approximation

$$\ln \hat{p}(\mathbf{y}) = \ln p(\mathbf{y}|\hat{\theta}) + \ln p(\hat{\theta}) - \frac{p}{2} \ln n.$$

#### POSTERIOR PREDICTIVE ANALYSIS

- ▶ If  $p(y|\theta)$  is a 'good' model, then the data actually observed should not differ 'too much' from simulated data from  $p(y|\theta)$ .
- ► Bayesian: simulate data from the **posterior predictive distribution** [9]:

$$p(y^{rep}|y) = \int p(y^{rep}|\theta)p(\theta|y)d\theta.$$

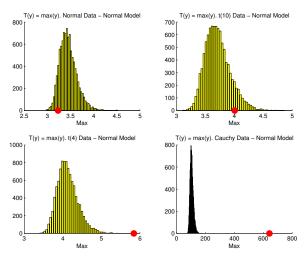
- $\triangleright$  Difficult to compare y and  $y^{rep}$  because of dimensionality.
- ▶ Solution: compare **low-dimensional statistic**  $T(y, \theta)$  to  $T(y^{rep}, \theta)$ .
- ► Evaluates the full probability model consisting of both the likelihood and prior distribution.

## POSTERIOR PREDICTIVE ANALYSIS, CONT.

- ▶ **Algorithm** for simulating from the posterior predictive density  $p[T(y^{rep})|y]$ :
- 1 Draw a  $\theta^{(1)}$  from the posterior  $p(\theta|y)$ .
- 2 Simulate a data-replicate  $y^{(1)}$  from  $p(y^{rep}|\theta^{(1)})$ .
- 3 Compute  $T(y^{(1)})$ .
- 4 Repeat steps 1-3 a large number of times to obtain a sample from  $T(y^{rep})$ .
- ▶ We may now compare the observed statistic T(y) with the distribution of  $T(v^{rep})$ .
- ▶ Posterior predictive p-value:  $Pr[T(y^{rep}) \ge T(y)]$
- ► Informal graphical analysis.

# POSTERIOR PREDICTIVE ANALYSIS - NORMAL MODEL, MAX STATISTIC

▶ Model:  $y_1, ..., y_n \stackrel{iid}{\sim} N(\mu, \sigma^2)$ .  $T(y) = \max_i |y_i|$ .





#### **DECISION THEORY**

- Let  $\theta$  be an unknown quantity. State of nature. Examples: Future inflation, Global temperature, Disease.
- ▶ Let  $a \in A$  be an action. Ex: Interest rate, Energy tax, Surgery.
- ▶ Choosing action a when state of nature turns out to be  $\theta$  gives utility

$$U(a, \theta)$$

► Utility table:

	$ heta_1$	$ heta_2$
$a_1$	$U(a_1, \theta_1)$	$U(a_1, \theta_2)$
$a_2$	$U(a_2, \theta_1)$	$U(a_2, \theta_2)$

► Example:

	Rainy	Sunny
Umbrella	50	70
No umbrella	0	100

#### **DECISION THEORY**

- **Example loss functions** when both a and  $\theta$  are continuous:
  - ► Linear:  $L(a, \theta) = |a \theta|$ ► Quadratic:  $L(a, \theta) = (a - \theta)^2$
  - ► Lin-Lin:

$$L(a,\theta) = \begin{cases} c_1 \cdot |a - \theta| & \text{if } a \le \theta \\ c_2 \cdot |a - \theta| & \text{if } a > \theta \end{cases}$$

- Example:
  - $\triangleright$   $\theta$  is the number of items demanded of a product
  - a is the number of items in stock
  - Utility

$$U(a, \theta) = \begin{cases} p \cdot \theta - c_1(a - \theta) & \text{if } a > \theta \text{ [too much stock]} \\ p \cdot a - c_2(\theta - a)^2 & \text{if } a \le \theta \text{ [too little stock]} \end{cases}$$

#### **OPTIMAL DECISION**

- Ad hoc decision rules:
  - Minimax. Choose the decision that minimizes the maximum loss.
  - ► Minimax-regret ... bla bla bla ...
- Bayesian theory: Just maximize the posterior expected utility:

$$a_{bayes} = \operatorname{argmax}_{a \in \mathcal{A}} E_{p(\theta|\mathbf{y})}[U(a, \theta)],$$

where  $E_{p(\theta|y)}$  denotes the posterior expectation.

▶ Using simulated draws  $\theta^{(1)}, \theta^{(2)}, ..., \theta^{(N)}$  from  $p(\theta|\mathbf{y})$ :

$$E_{p(\theta|\mathbf{y})}[U(a,\theta)] \approx N^{-1} \sum_{i=1}^{N} U(a,\theta^{(i)})$$

- Separation principle:
- 1. First obtain  $p(\theta|y)$
- 2. then form  $U(a, \theta)$  and finally
- 3. choose a that maximes  $E_{p(\theta|\mathbf{v})}[U(a,\theta)]$ .

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