

Subsampling MCMC

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The Research Project

- ▶ **Scaling up** *Metropolis-Hastings* (MH) for **tall** (and somewhat wide) datasets.
- ▶ Scalability by **subsampling** the data.
- ▶ Talk based on four papers ...
 - ▶ Speeding Up MCMC by Efficient Data Subsampling
 - ▶ The Block Pseudo-Marginal Sampler
 - ▶ Exact Subsampling MCMC
 - ▶ Hamiltonian Monte Carlo with Energy Conserving Subsampling
(main author Khue-Dung Dang)
- ▶ All papers are on **arXiv**.

The Metropolis-Hastings algorithm

- ▶ The **workhorse** for Bayesians for nearly **three decades**.
- ▶ Let θ and $y = (y_1, \dots, y_n)$ denote the **parameter** and **data**.
- ▶ **Distribution** of interest

$$\pi(\theta) := p(\theta|y) = \frac{p(y|\theta)p(\theta)}{p(y)}$$

- ▶ **Idea**: Simulate a Markov chain $\{\theta^{(j)}\}_{j=1}^N$ with invariant distribution $\pi(\theta)$.

The Metropolis-Hastings algorithm

► Initialize $\theta^{(0)}$ and iterate for $t = 1, 2, \dots$

1. Sample $\theta' \sim q(\cdot | \theta^{(t-1)})$ (the **proposal distribution**)

2. Compute the **acceptance probability**

$$\alpha = \min \left(1, \frac{p(\mathbf{y} | \theta') p(\theta')}{p(\mathbf{y} | \theta^{(t-1)}) p(\theta^{(t-1)})} \frac{q(\theta^{(t-1)} | \theta')}{q(\theta' | \theta^{(t-1)})} \right)$$

3. With probability α set $\theta^{(t)} = \theta'$ and $\theta^{(t)} = \theta^{(t-1)}$ otherwise.

Subsampling the data to speed up computations

- **The likelihood** [data: $y = (y_1, \dots, y_n)$]

$$p(y|\theta) = \exp(\ell_{(n)}(\theta)), \text{ where } \ell_{(n)}(\theta) = \sum_{k=1}^n \ell_k(\theta) \text{ with } \ell_k(\theta) = \log p(y_k|\theta),$$

- **MH computationally demanding** because **complete scan of the data** for each $\theta^{(j)}$.
- **Subsampling**: in each iteration
 1. Let $u = (u_1, \dots, u_m)$, $u_i \in \{1, \dots, n\}$
 2. Sample m observations by Simple Random Sampling (SRS): $\ell_{u_1}(\theta), \dots, \ell_{u_m}(\theta)$.
 3. Replace the log-likelihood $\ell_{(n)}(\theta)$ in α_{MH} by an **estimate** $\hat{\ell}_m(\theta)$.
- If $m \ll n$, a single iteration becomes much **faster**.
- **Computational Cost**: $\text{CC}[\ell_{(n)}(\theta)] = O(n)$ and $\text{CC}[\hat{\ell}_m(\theta)] = O(m)$.

OK to plug in an estimated likelihood in MH?

- ▶ **Pseudo-marginal MH** (Andrieu and Roberts, 2009).
- ▶ Targets the **augmented** posterior

$$\bar{\pi}(\theta, u) = \frac{\hat{p}_m(y|\theta, u)p(u)p(\theta)}{p_m(y)}$$

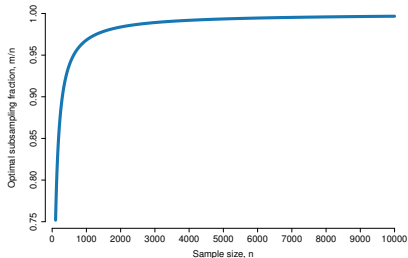
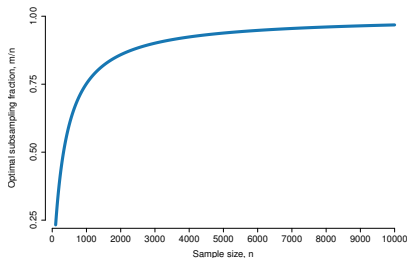
by constructing a **Markov Chain** $\{\theta^{(j)}, u^{(j)}\}_{j=1}^N$ on an **augmented space**.

- ▶ θ -draws converges to $\pi(\theta)$ in distribution if the **likelihood estimator** is **unbiased**

$$\mathbb{E}_u[\hat{p}_m(y|\theta, u)] = p(y|\theta).$$

Estimator variance is crucial in pseudo-marginal MH

- ▶ **Too large** $V[\hat{\ell}_m] \Rightarrow$ the chain gets **stuck**
- ▶ **Too small** $V[\hat{\ell}_m] \Rightarrow$ unnecessarily **expensive** ($V[\hat{\ell}_m] \propto 1/m$)
- ▶ Optimal: $V[\hat{\ell}_m] \approx 1$ (Pitt et al., 2012). Gives a rule for tuning m .
- ▶ Targeting $V[\hat{\ell}_m] \approx 1$ with Simple Random Sampling only obtainable by unreasonably large m .



Difference estimator and control variates

- Quiroz et al. (2016) achieve a small $V[\hat{\ell}_m]$ using the difference estimator

$$\hat{\ell}_{DE}(\mathbf{y}|\theta, \mathbf{u}) \equiv \sum_{i=1}^n q_i(\theta) + \frac{n}{m} \sum_{k=1}^m d_{u_k}(\theta), \quad (1)$$

where $d_i(\theta) = \ell_i(\mathbf{y}_i|\theta) - q_i(\theta)$ and $q_i(\theta)$ is a **control variate** for $\ell_i(\mathbf{y}_i|\theta)$.

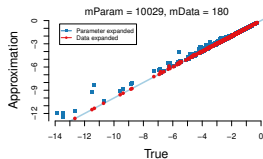
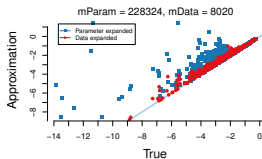
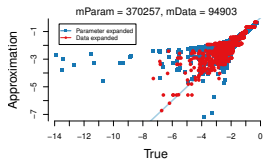
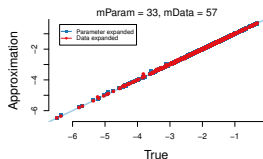
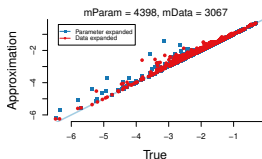
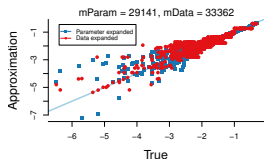
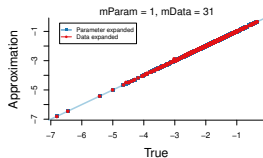
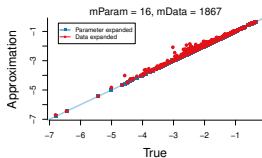
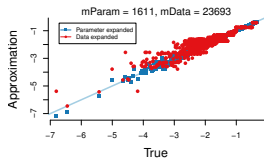
- **Data-expanded control variates** - clusters the data and Taylor expands around centroids

$$\ell_i(\mathbf{y}_i|\theta) \approx \ell_i(\mathbf{y}_{c_i}|\theta) + (\mathbf{y}_i - \mathbf{y}_{c_i})^T \nabla_{\mathbf{y}} \ell_i(\mathbf{y}|\theta)|_{\mathbf{y}=\mathbf{y}_{c_i}} + \frac{1}{2} (\mathbf{y}_i - \mathbf{y}_{c_i})^T \nabla_{\mathbf{y}\mathbf{y}}^2 \ell_i(\mathbf{y}|\theta)|_{\mathbf{y}=\mathbf{y}_{c_i}} (\mathbf{y}_i - \mathbf{y}_{c_i}) \quad (2)$$

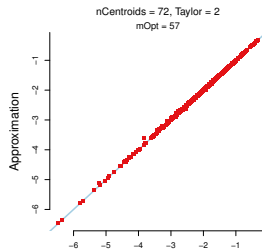
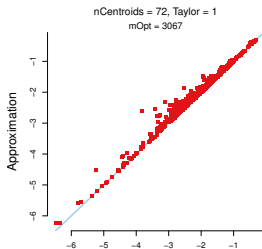
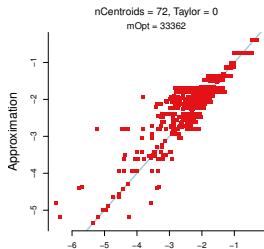
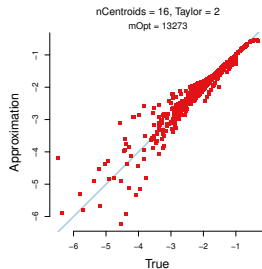
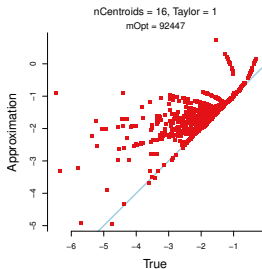
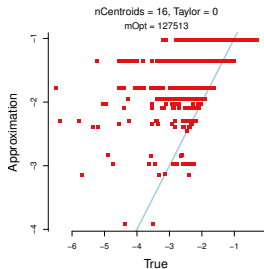
- **Parameter-expanded control variates** - Taylor expands around θ^* (Bardenet et al. 2017)

$$\ell_i(\mathbf{y}_i|\theta) \approx \ell_i(\mathbf{y}_i|\theta^*) + (\theta^* - \theta)^T \nabla_{\theta} \ell_i(\mathbf{y}_i|\theta)|_{\theta=\theta^*} + \frac{1}{2} (\theta^* - \theta)^T \nabla_{\theta\theta}^2 \ell_i(\mathbf{y}_i|\theta)|_{\theta=\theta^*} (\theta^* - \theta) \quad (3)$$

Parameter-expanded control variates sensitive to θ^*



Data-expanded control variates sensitive to number of clusters



Take it easy - dependent subsampling

- ▶ So far: completely new subsample in each MCMC iteration. Easy to get stuck.
- ▶ Deligiannidis et al. (2016) propose to **correlate the \mathbf{u}** over iterations using an autoregressive proposal:

$$\mathbf{u}' = \phi \mathbf{u}^{(i-1)} + \sqrt{1 - \phi^2} \varepsilon, \quad \varepsilon \sim N(0, 1). \quad (4)$$

- ▶ Quiroz et al. (2016) extend this to a subsampling context using a copula to correlate the binary u_i sampling selection indicators.
- ▶ Tran et al. (2017) propose an alternative approach to generate dependent subsampling. Partition \mathbf{u} in blocks: $\mathbf{u} = (\mathbf{u}^{(1)}, \dots, \mathbf{u}^{(G)})$. **Update a single block** jointly with θ in each iteration.
- ▶ By correlating the \mathbf{u} over iterations we can tolerate a much larger $V[\hat{\ell}_m]$ (Deligiannidis et al., 2016; Tran et al., 2017)
- ▶ Optimal with correlation (blocking): $V[\hat{\ell}_m] \approx 234$ (Tran et al., 2017).

Approximate MCMC: near bias-correction

- ▶ The **Difference Estimator** (DE) is **unbiased for the log-likelihood**

$$\mathbb{E}[\hat{\ell}_{DE}(\mathbf{y}|\theta)] = \ell_{(n)}(\theta)$$

... **but biased for the likelihood.**

- ▶ Quiroz et al. (2016) propose an **approximate bias-correction**:

$$\exp\left(\hat{\ell}_{DE}(\mathbf{y}|\theta) - \sigma_{\hat{\ell}_{DE}}^2(\theta)/2\right), \quad (5)$$

where $\sigma_{\hat{\ell}_{DE}}^2 = \text{Var}(\hat{\ell}_{DE}(\mathbf{y}|\theta))$, which is estimated unbiasedly.

- ▶ Gives samples from a **perturbed posterior** $\pi_m(\theta) \neq \pi(\theta)$.
- ▶ Quiroz et al. (2016) show that

$$\int_{\Theta} |\pi_m(\theta) - \pi(\theta)| d\theta \leq O\left(\frac{p^3}{nm^2}\right),$$

where d is the dimension of θ .

- ▶ Example: $d = O(\sqrt{n})$ and $m = O(\sqrt{n})$ gives an $O(n^{-1/2})$ error.
- ▶ Example: d and n fixed gives an $O(m^{-2})$ error.
- ▶ Quiroz et al. (2016) also give a simple practical formula for the error.

- ▶ **The Poisson Estimator (PE)** (e.g. Papaspiliopoulos, 2009):
 - ▶ Sample $G \sim \text{Poisson}(\lambda)$
 - ▶ Sample the selected observations within each batch: $u^{(g)}, g = 1, \dots, G$.
 - ▶ Compute a log-likelihood estimator $\hat{\ell}^{(g)}$ for each batch.
 - ▶ Let a be a constant and compute

$$\hat{p}_m(y|\theta, u, G) = \exp(a + \lambda) \prod_{g=1}^G \left(\frac{\hat{\ell}^{(g)} - a}{\lambda} \right)$$

- ▶ Two sources of randomness in PE: i) **G** and ii) $u^{(g)}, g = 1, \dots, G$.
- ▶ **PE is unbiased for the likelihood**, but usually $V[\hat{\ell}_{PE}] > V[\hat{\ell}_{DE}]$.
- ▶ We do **correlated Pseudo-marginal** on both G (copula) and $u^{(g)}$.
- ▶ The Rhee-Glynn estimator (Bardenet et al. 2017) has larger variance.

Pseudo-marginal MH with the Poisson Estimator

- ▶ Plug in the **Poisson Estimator** in the **pseudo-marginal MH algorithm**.
- ▶ Pseudo-marginal is just MH on an **extended target**

$$\bar{\pi}(\theta, u, G) \propto \hat{p}_m(y|\theta, u, G)p(u, G)p(\theta).$$

- ▶ **Jacob and Thiery (2015)**: PE is a.s. **nonnegative if only if** a is a lower bound for $\hat{\ell}^{(g)}$ for all $g = 1, \dots, G$.
- ▶ **Two problems with obtaining a lower bound a** :
 1. We need to know ℓ_k , for $k = 1, \dots, n$. **No point in subsampling!**
 2. Too conservative a . Gives **HUGE** variance.
- ▶ **Quiroz et al. (2017)**: Use soft lower bound \tilde{a} such that $\Pr(\hat{p}_m(y|\theta, u) \geq 0)$ is close, but not equal, to unity.
- ▶ Soft lower bound \Rightarrow Poisson estimator can be negative.

Pseudo-marginal MH with a non-positive estimator

► Lyne et al. (2015):

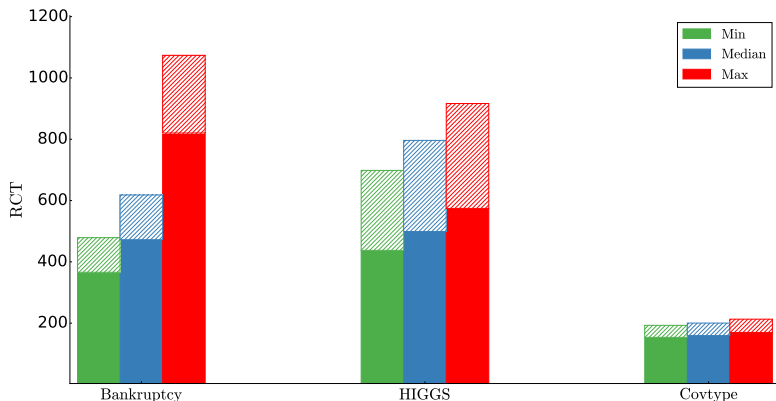
- Run **Pseudo-marginal** on absolute measure $|\bar{\pi}(\theta, u, G)|$, but store the sign of $\bar{\pi}(\theta, u, G)$ in each iteration.
- Use **importance sampling** on the iterates to correct for the sign, $s(\theta^{(j)})$, to estimate $I = E_{\theta}[\psi(\theta)]$ for any function $\psi(\theta)$

$$\hat{I} = \frac{\sum_{j=1}^N \psi(\theta^{(j)}) s(\theta^{(j)})}{\sum_{j=1}^N s(\theta^{(j)})}.$$

- **Optimal** $V[\hat{I}]$: All signs positive (or negative). **Worst when 50-50.**
- Decreasing $\tilde{a} \Rightarrow$ increases probability of positive signs, but increases $V[\hat{\ell}_{PE}]$.
- Increasing $\tilde{a} \Rightarrow$ decreasing $V[\hat{\ell}_{PE}]$, but prob of positive signs closer to 0.5.

Logistic Regression examples

- ▶ Logistic regression on three datasets:
 - ▶ Bankruptcy - $n = 4.7$ millions and $d = 9$
 - ▶ HIGGS - $n = 1.1$ millions and $d = 21$
 - ▶ CovType - $n = 550K$ and $d = 11$
- ▶ Combination of data- and parameter expanded control variates.
- ▶ Blocking u.



HMC with energy conserving subsampling

- ▶ **Hamiltonian Monte Carlo** (HMC) has proven to be successful in **high-dimensional spaces**.
- ▶ HMC augments the posterior $\pi(\theta)$ with fictitious **momentum variables** $\mathbf{m} \in \mathbb{R}^d$, and targets

$$\bar{\pi}(\theta, \mathbf{m}) \propto \exp(-\mathcal{H}(\theta, \mathbf{m})), \quad (6)$$

where \mathcal{H} is the so called **Hamiltonian**

$$\mathcal{H}(\theta, \mathbf{m}) = \mathcal{U}(\theta) + \mathcal{K}(\mathbf{m}), \quad (7)$$

where in HMC

$$\mathcal{U}(\theta) = -\log[p(\mathbf{y}|\theta)p(\theta)] \text{ and } \mathcal{K}(\mathbf{m}) = \frac{1}{2}\mathbf{m}^T \mathbf{M}^{-1}\mathbf{m}, \quad (8)$$

and \mathbf{M} is a $d \times d$ positive definite matrix.

- ▶ Initial momentum from $\mathbf{m} \sim N(0, \mathbf{M})$ is used to propagate both θ and \mathbf{m} over time t along a trajectory mapped out by the Hamiltonian dynamics

$$\nabla_t \theta = \nabla_{\mathbf{m}} \mathcal{H}(\theta, \mathbf{m}) = \mathbf{M}^{-1}\mathbf{m} \quad (9)$$

$$\nabla_t \mathbf{m} = -\nabla_{\theta} \mathcal{H}(\theta, \mathbf{m}) = -\nabla_{\theta} \mathcal{U}(\theta). \quad (10)$$

HMC with energy conserving subsampling

- ▶ HMC requires evaluating the gradient throughout the many steps of simulated dynamics. **Computationally costly**, especially for large data sets.
- ▶ Betancourt (2015) **estimates the gradient** in the simulated dynamics from a random **subsample**. MH acceptance probability is computed on the full dataset. Conclusion: α_{MH} decreases quickly with d .
- ▶ **Our approach**: Pseudo-marginal with α_{MH} evaluated using likelihood estimates on the **same data subset** as used in simulating the dynamics.
- ▶ HMC-within-Gibbs Algorithm
 - i $u|\theta, \mathbf{m}, y$ - MH-step for **subsample**
 - ii $\theta, \mathbf{m}|u, y$ - HMC-step for **parameters** θ and **momentum variables** p
- ▶ Our **HMC-ECS** algorithm **conserves the energy** (α_{MH} doesn't drop).
- ▶ **Approximate** (Quiroz et al., 2016) or **Exact** (Quiroz et al., 2017).

► Before:

- $n = 4.7$ millions data points.
- **logistic regression** with $d = 9$ parameters.

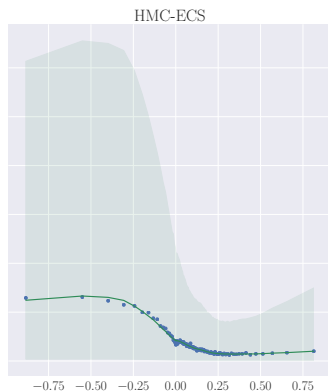
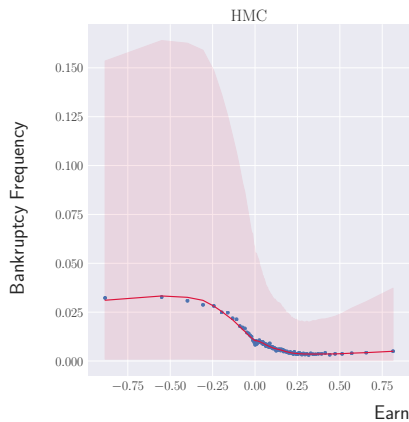
► Here:

- $n = 4.7$ millions data points.
- **additive splines logistic regression** with $d = 89$ parameters
(10 knots + linear term for each covariate + intercept)

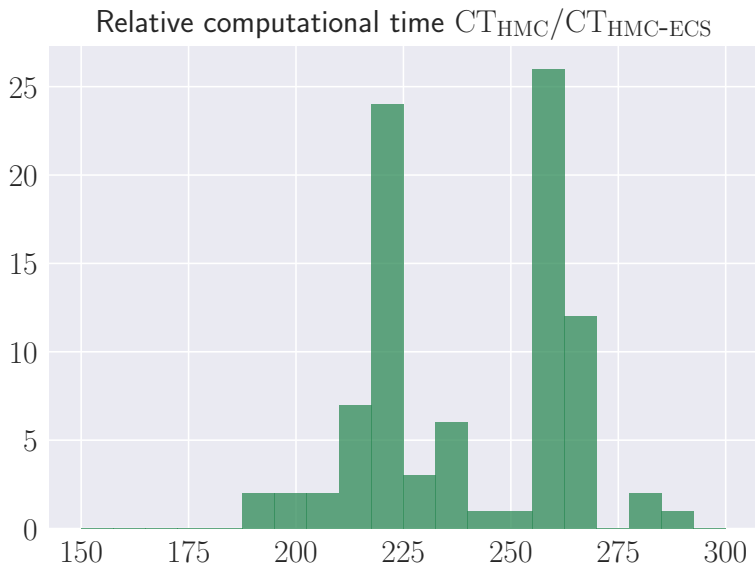
► HMC: $\alpha_{MH} = 81.8\%$

► HMC-ECS: $\alpha_{MH} = 79.3\%$

Approximate HMC-ECS on firm bankruptcy data



Approximate HMC-ECS on firm bankruptcy data



- ▶ Scalable frameworks for efficient data subsampling to speed up MCMC:
 - ▶ **Approximate** - Faster, approximate but controlled error
 - ▶ **Exact** - Slower than approximate, but guaranteed to be exact.
- ▶ **Variance reduction** by:
 - ▶ control variates
 - ▶ dependent subsamples
- ▶ **HMC with energy conserving subsampling** for high-dimensional parameter spaces.
- ▶ 1-3 orders of magnitude as many effective draws per computational time compared to MH on full dataset.

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- **Model** M_1 :

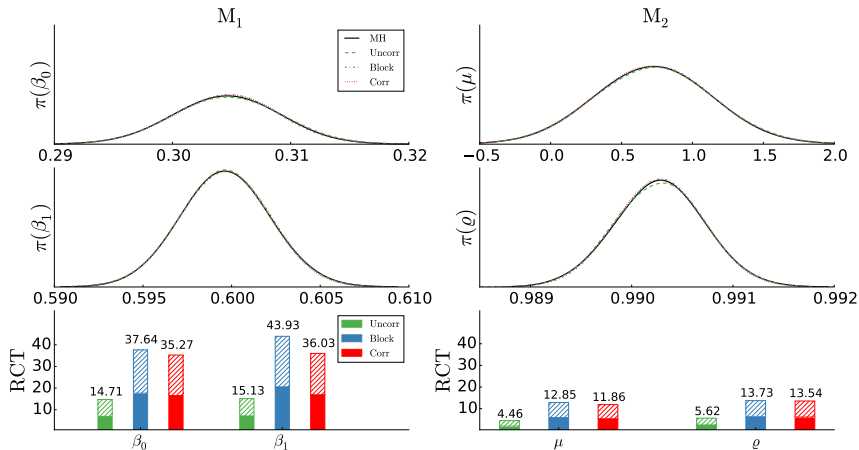
$$y_t = \beta_0 + \beta_1 y_{t-1} + \epsilon_t, \quad \epsilon_t \sim t(\nu = 5) \text{ iid.}$$

- **Model** M_2 :

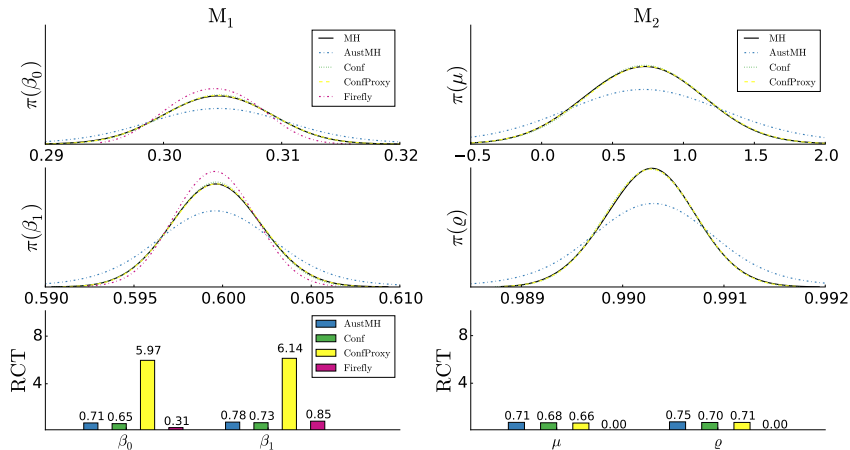
$$y_t = \mu + \rho(y_{t-1} - \mu) + \epsilon_t, \quad \epsilon_t \sim t(\nu = 5) \text{ iid.}$$

- **Generate** 100,000 observations from the DGP.

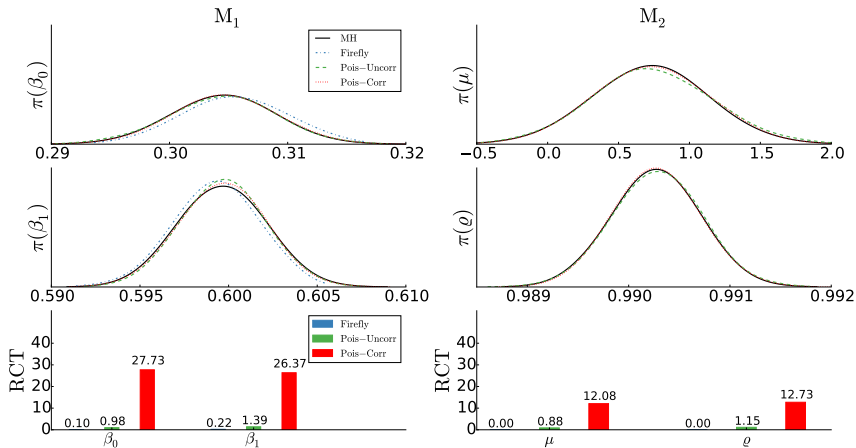
AR process example - approximate approaches



AR process example - alternative approaches



AR process example - exact approaches



AR process example - exact approaches

